# Contents

1 Introduction 3
   1.1 Motivation 3
   1.2 StarPU in a Nutshell 3
      1.2.1 Codelet and Tasks 3
      1.2.2 StarPU Data Management Library 4
   1.3 Application Taskification 4
   1.4 Glossary 4
   1.5 Research Papers 4
   1.6 StarPU Applications 4
   1.7 Further Reading 5

I StarPU Basics 7

2 Building and Installing StarPU 9
   2.1 Installing a Binary Package 9
   2.2 Installing from Source 9
      2.2.1 Optional Dependencies 9
      2.2.2 Getting Sources 9
      2.2.3 Configuring StarPU 10
      2.2.4 Building StarPU 10
      2.2.5 Installing StarPU 10
   2.3 Setting up Your Own Code 10
      2.3.1 Setting Flags for Compiling, Linking and Running Applications 10
      2.3.2 Integrating StarPU in a Build System 11
      2.3.3 Running a Basic StarPU Application 12
      2.3.4 Running a Basic StarPU Application on Microsoft Visual C 13
      2.3.5 Kernel Threads Started by StarPU 13
      2.3.6 Enabling OpenCL 13
   2.4 Benchmarking StarPU 14
      2.4.1 Task Size Overhead 14
      2.4.2 Data Transfer Latency 14
      2.4.3 Matrix-Matrix Multiplication 14
      2.4.4 Cholesky Factorization 14
      2.4.5 LU Factorization 14
      2.4.6 Simulated benchmarks 14

3 Basic Examples 17
   3.1 Hello World 17
      3.1.1 Required Headers 17
      3.1.2 Defining A Codelet 17
      3.1.3 Submitting A Task 17
      3.1.4 Execution Of Hello World 18
      3.1.5 Passing Arguments To The Codelet 18
      3.1.6 Defining A Callback 19
      3.1.7 Where To Execute A Codelet 19
   3.2 Vector Scaling 20
3.2.1 Source Code of Vector Scaling .................................................. 20
3.2.2 Execution of Vector Scaling .................................................... 21
3.3 Vector Scaling on an Hybrid CPU/GPU Machine .............................. 21
   3.3.1 Definition of the CUDA Kernel .............................................. 21
   3.3.2 Definition of the OpenCL Kernel ............................................ 21
   3.3.3 Definition of the Main Code ................................................ 22
   3.3.4 Execution of Hybrid Vector Scaling ...................................... 24

II StarPU Quick Programming Guide .................................................. 25
4 Advanced Examples ........................................................................ 27
5 Check List When Performance Are Not There .................................... 29
   5.1 Check Task Size ......................................................................... 29
   5.2 Configuration Which May Improve Performance ............................ 29
   5.3 Data Related Features Which May Improve Performance ............... 29
   5.4 Task Related Features Which May Improve Performance ............... 29
   5.5 Scheduling Related Features Which May Improve Performance ....... 29
   5.6 CUDA-specific Optimizations .................................................... 30
   5.7 OpenCL-specific Optimizations .................................................. 31
   5.8 Detecting Stuck Conditions ....................................................... 31
   5.9 How to Limit Memory Used By StarPU And Cache Buffer Allocations 31
   5.10 How To Reduce The Memory Footprint Of Internal Data Structures .. 32
   5.11 How To Reuse Memory ............................................................. 32
   5.12 Performance Model Calibration ............................................... 34
   5.13 Profiling .................................................................................. 34
   5.14 Overhead Profiling ................................................................. 34

III StarPU Inside ................................................................................. 37
6 Tasks In StarPU ................................................................................. 39
   6.1 Task Granularity ......................................................................... 39
   6.2 Task Submission ......................................................................... 39
   6.3 Task Priorities ............................................................................ 39
   6.4 Task Dependencies ..................................................................... 39
      6.4.1 Sequential Consistency ....................................................... 39
      6.4.2 Tasks And Tags Dependencies ............................................ 40
   6.5 Setting Many Data Handles For a Task ....................................... 40
   6.6 Setting a Variable Number Of Data Handles For a Task ............... 41
   6.7 Using Multiple Implementations Of A Codelet ............................ 41
   6.8 Enabling Implementation According To Capabilities ................... 41
   6.9 Insert Task Utility .................................................................... 42
   6.10 Getting Task Children .............................................................. 44
   6.11 Parallel Tasks .......................................................................... 44
      6.11.1 Fork-mode Parallel Tasks .................................................. 44
      6.11.2 SPMD-mode Parallel Tasks ............................................... 45
      6.11.3 Parallel Tasks Performance .............................................. 45
      6.11.4 Combined Workers .......................................................... 45
      6.11.5 Concurrent Parallel Tasks ............................................... 45
      6.11.6 Synchronization Tasks ...................................................... 46

7 Data Management ............................................................................ 47
   7.1 Data Interface ........................................................................... 47
      7.1.1 Variable Data Interface ..................................................... 47
      7.1.2 Vector Data Interface ......................................................... 47
      7.1.3 Matrix Data Interface ........................................................ 47
      7.1.4 Block Data Interface .......................................................... 47

Generated by Doxygen
11.6 Debugging Scheduling
11.5 Graph-based Scheduling
11.4 Defining A New Modular Scheduling Policy
11.3 Defining A New Basic Scheduling Policy
11.2 Helper functions for defining a scheduling policy (Basic or modular)
11.1 Introduction

10.6 Defining A New Hypervisor Policy
10.5 Resizing Strategies
10.4 Trigger the Hypervisor
10.3 Interrogate The Runtime
10.2 Start the Hypervisor
10.1 What Is The Hypervisor

9.7 Emptying A Context
9.6 Deleting A Context
9.5 Submitting Tasks To A Context
9.4 Modifying A Context
9.3 Creating A Context
9.2 Creating A Context With The Default Behavior
9.1 General Ideas

8.7 Heteroprio
8.6 Static Scheduling
8.5 Modularized Schedulers
8.4 Energy-based Scheduling
8.3 Task Distribution Vs Data Transfer
8.2 Performance Model-Based Task Scheduling Policies
8.1 Task Scheduling Policies

7.14 Specifying A Target Node For Task Data
7.13 Defining A New Data Interface
7.12 The Multiformat Interface
7.11.2 Scratch Data
7.11.1 Temporary Data
7.11 Temporary Buffers
7.10 Concurrent Data Accesses
7.9 Commute Data Access
7.8 Data Reduction
7.7 Defining A New Data Filter
7.6 Asynchronous Partitioning
7.5 Manual Partitioning
7.4 Partitioning Data
7.3 Data Prefetch
7.2 Data Management

6.7 Defining A New Application
6.6 Creating A New Task
6.5 Asynchronous Partitioning
6.4 Defining A New Modular Scheduling Policy
6.3 Defining A New Basic Scheduling Policy
6.2 Defining A New Basic Scheduling Policy
6.1 Creating A Context

5.8 Manage Data Interoperability
5.7 Task Migration Policy
5.6 Asynchronous Partitioning
5.5 Task Distribution Vs Data Transfer
5.4 Energy-based Scheduling
5.3 Task Scheduling Policies
5.2 Performance Model-Based Task Scheduling Policies
5.1 Task Scheduling Policies

4.6 Debugging Tools
4.5 Debugging Tools
4.4 Debugging Tools
4.3 Debugging Tools
4.2 Debugging Tools
4.1 Debugging Tools
12.1 TroubleShooting In General ................................................. 81
12.2 Using The Gdb Debugger .................................................. 81
12.3 Using Other Debugging Tools ............................................. 82
12.4 Using The Temanejo Task Debugger ..................................... 82

13 Online Performance Tools 85
13.1 On-line Performance Feedback ........................................... 85
  13.1.1 Enabling On-line Performance Monitoring ............................. 85
  13.1.2 Per-task Feedback .................................................... 85
  13.1.3 Per-codelet Feedback ................................................ 85
  13.1.4 Per-worker Feedback ................................................ 86
  13.1.5 Bus-related Feedback ............................................... 87
  13.1.6 MPI-related Feedback .............................................. 87
13.2 Task And Worker Profiling .............................................. 87
13.3 Performance Model Example ............................................. 87
13.4 Data trace and tasks length ............................................ 90

14 Offline Performance Tools 91
14.1 Off-line Performance Feedback ......................................... 91
  14.1.1 Generating Traces With FxT ......................................... 91
  14.1.2 Limiting The Scope Of The Trace ................................... 93
14.2 Performance Of Codelets ................................................ 94
14.3 Trace Statistics .......................................................... 98
14.4 Theoretical Lower Bound On Execution Time ......................... 100
14.5 Theoretical Lower Bound On Execution Time Example .............. 101
14.6 Memory Feedback ....................................................... 101
14.7 Data Statistics .......................................................... 102

15 Frequently Asked Questions 103
15.1 How To Initialize A Computation Library Once For Each Worker? ................................................. 103
15.2 Using The Driver API .................................................... 103
15.3 On-GPU Rendering ....................................................... 104
15.4 Using StarPU With MKL 11 (Intel Composer XE 2013) ............. 105
15.5 Thread Binding on NetBSD .............................................. 105
15.6 StarPU permanently eats 100% of all CPUs ............................ 105
15.7 Interleaving StarPU and non-StarPU code ............................. 105
15.8 When running with CUDA or OpenCL devices, I am seeing less CPU cores ................................. 105
15.9 StarPU does not see my CUDA device .................................. 106
15.10 StarPU does not see my OpenCL device ............................... 106
15.11 I keep getting a "Incorrect performance model file" error ....... 107

IV StarPU Extensions 109
16 Out Of Core 111
  16.1 Introduction ............................................................. 111
  16.2 Use a new disk memory ................................................ 111
  16.3 Data Registration ....................................................... 112
  16.4 Using Wont Use ......................................................... 112
  16.5 Examples: disk_copy ................................................... 112
  16.6 Examples: disk_compute .............................................. 114
  16.7 Performances ........................................................... 116
  16.8 Feedback Figures ...................................................... 116
  16.9 Disk functions ........................................................ 116

17 MPI Support 117
  17.1 Example Used In This Documentation ................................. 117
  17.2 About Not Using The MPI Support .................................... 117
  17.3 Simple Example ........................................................ 118
<table>
<thead>
<tr>
<th>Chapter</th>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>17.4</td>
<td>How to Initialize StarPU-MPI</td>
<td>119</td>
</tr>
<tr>
<td>17.5</td>
<td>Point To Point Communication</td>
<td>119</td>
</tr>
<tr>
<td>17.6</td>
<td>Exchanging User Defined Data Interface</td>
<td>120</td>
</tr>
<tr>
<td>17.7</td>
<td>MPI Insert Task Utility</td>
<td>121</td>
</tr>
<tr>
<td>17.8</td>
<td>Pruning MPI Task Insertion</td>
<td>123</td>
</tr>
<tr>
<td>17.9</td>
<td>Temporary Data</td>
<td>123</td>
</tr>
<tr>
<td>17.10</td>
<td>Per-node Data</td>
<td>124</td>
</tr>
<tr>
<td>17.11</td>
<td>Priorities</td>
<td>124</td>
</tr>
<tr>
<td>17.12</td>
<td>MPI Cache Support</td>
<td>125</td>
</tr>
<tr>
<td>17.13</td>
<td>MPI Data Migration</td>
<td>125</td>
</tr>
<tr>
<td>17.14</td>
<td>MPI Collective Operations</td>
<td>126</td>
</tr>
<tr>
<td>17.15</td>
<td>Make StarPU-MPI Progression Thread Execute Tasks</td>
<td>126</td>
</tr>
<tr>
<td>17.16</td>
<td>Debugging MPI</td>
<td>127</td>
</tr>
<tr>
<td>17.17</td>
<td>More MPI examples</td>
<td>128</td>
</tr>
<tr>
<td>17.18</td>
<td>Notes about the Implementation</td>
<td>128</td>
</tr>
<tr>
<td>17.19</td>
<td>MPI Master Slave Support</td>
<td>129</td>
</tr>
<tr>
<td>18</td>
<td>FFT Support</td>
<td>131</td>
</tr>
<tr>
<td>18.1</td>
<td>Compilation</td>
<td>131</td>
</tr>
<tr>
<td>19</td>
<td>MIC Xeon Phi Support</td>
<td>133</td>
</tr>
<tr>
<td>19.1</td>
<td>Compilation</td>
<td>133</td>
</tr>
<tr>
<td>19.2</td>
<td>Porting Applications To MIC Xeon Phi</td>
<td>133</td>
</tr>
<tr>
<td>19.3</td>
<td>Launching Programs</td>
<td>134</td>
</tr>
<tr>
<td>20</td>
<td>Native Fortran Support</td>
<td>135</td>
</tr>
<tr>
<td>20.1</td>
<td>Implementation Details and Specificities</td>
<td>135</td>
</tr>
<tr>
<td>20.1.1</td>
<td>Prerequisites</td>
<td>135</td>
</tr>
<tr>
<td>20.1.2</td>
<td>Configuration</td>
<td>135</td>
</tr>
<tr>
<td>20.1.3</td>
<td>Examples</td>
<td>135</td>
</tr>
<tr>
<td>20.1.4</td>
<td>Compiling a Native Fortran Application</td>
<td>135</td>
</tr>
<tr>
<td>20.2</td>
<td>Fortran Translation for Common StarPU API Idioms</td>
<td>136</td>
</tr>
<tr>
<td>20.3</td>
<td>Uses, Initialization and Shutdown</td>
<td>137</td>
</tr>
<tr>
<td>20.4</td>
<td>Fortran Flavor of StarPU's Variadic Insert_task</td>
<td>137</td>
</tr>
<tr>
<td>20.5</td>
<td>Functions and Subroutines Expecting Data Structures Arguments</td>
<td>137</td>
</tr>
<tr>
<td>20.6</td>
<td>Additional Notes about the Native Fortran Support</td>
<td>138</td>
</tr>
<tr>
<td>20.6.1</td>
<td>Using StarPU with Older Fortran Compilers</td>
<td>138</td>
</tr>
<tr>
<td>20.6.2</td>
<td>Valid API Mixes and Language Mixes</td>
<td>138</td>
</tr>
<tr>
<td>21</td>
<td>SOCL OpenCL Extensions</td>
<td>139</td>
</tr>
<tr>
<td>22</td>
<td>SimGrid Support</td>
<td>141</td>
</tr>
<tr>
<td>22.1</td>
<td>Preparing Your Application For Simulation</td>
<td>141</td>
</tr>
<tr>
<td>22.2</td>
<td>Calibration</td>
<td>141</td>
</tr>
<tr>
<td>22.3</td>
<td>Simulation</td>
<td>142</td>
</tr>
<tr>
<td>22.4</td>
<td>Simulation On Another Machine</td>
<td>142</td>
</tr>
<tr>
<td>22.5</td>
<td>Simulation Examples</td>
<td>142</td>
</tr>
<tr>
<td>22.6</td>
<td>Simulations On Fake Machines</td>
<td>142</td>
</tr>
<tr>
<td>22.7</td>
<td>Tweaking Simulation</td>
<td>143</td>
</tr>
<tr>
<td>22.8</td>
<td>MPI Applications</td>
<td>143</td>
</tr>
<tr>
<td>22.9</td>
<td>Debugging Applications</td>
<td>143</td>
</tr>
<tr>
<td>22.10</td>
<td>Memory Usage</td>
<td>143</td>
</tr>
<tr>
<td>23</td>
<td>The StarPU OpenMP Runtime Support (SORS)</td>
<td>145</td>
</tr>
<tr>
<td>23.1</td>
<td>Implementation Details and Specificities</td>
<td>145</td>
</tr>
<tr>
<td>23.1.1</td>
<td>Main Thread</td>
<td>145</td>
</tr>
<tr>
<td>23.1.2</td>
<td>Extended Task Semantics</td>
<td>145</td>
</tr>
<tr>
<td>23.2</td>
<td>Configuration</td>
<td>145</td>
</tr>
<tr>
<td>23.3</td>
<td>Uses, Initialization and Shutdown</td>
<td>145</td>
</tr>
</tbody>
</table>
### CONTENTS

23.4 Parallel Regions and Worksharing .................................................. 146  
  23.4.1 Parallel Regions ................................................................. 146  
  23.4.2 Parallel For ................................................................. 146  
  23.4.3 Sections ................................................................. 147  
  23.4.4 Single ................................................................. 147  

23.5 Tasks ................................................................................................. 148  
  23.5.1 Explicit Tasks ................................................................................. 148  
  23.5.2 Data Dependencies ........................................................................... 149  
  23.5.3 TaskWait and TaskGroup ................................................................. 149  

23.6 Synchronization Support ..................................................................... 150  
  23.6.1 Simple Locks .................................................................................. 150  
  23.6.2 Nestable Locks .............................................................................. 150  
  23.6.3 Critical Sections ............................................................................. 150  
  23.6.4 Barriers ......................................................................................... 151  

24 Clustering a Machine ........................................................................... 153  
  24.1 General Ideas .................................................................................... 153  
  24.2 Creating Clusters ............................................................................... 153  
  24.3 Example Of Constraining OpenMP .................................................... 154  
  24.4 Creating Custom Clusters ................................................................... 155  
  24.5 Clusters With Scheduling ................................................................... 155  

25 Interoperability Support ........................................................................ 157  
  25.1 StarPU Resource Management ............................................................. 157  
    25.1.1 Linking a program with the starpurm module ................................. 157  
    25.1.2 Uses, Initialization and Shutdown ................................................. 157  
    25.1.3 Default Context ........................................................................... 158  
    25.1.4 Temporary Contexts .................................................................... 158  

V StarPU Reference API ........................................................................... 159  

26 Execution Configuration Through Environment Variables .................. 161  
  26.1 Configuring Workers ........................................................................ 161  
  26.2 Configuring The Scheduling Engine .................................................. 164  
  26.3 Extensions ...................................................................................... 164  
  26.4 Miscellaneous And Debug ............................................................... 165  
  26.5 Configuring The Hypervisor .............................................................. 169  

27 Compilation Configuration ..................................................................... 171  
  27.1 Common Configuration ..................................................................... 171  
  27.2 Configuring Workers ....................................................................... 172  
  27.3 Extension Configuration .................................................................... 173  
  27.4 Advanced Configuration .................................................................... 173  

28 Module Index .......................................................................................... 177  
  28.1 Modules .......................................................................................... 177  

29 Deprecated List .................................................................................... 179  

30 Module Documentation a.k.a StarPU’s API ......................................... 181  
  30.1 Versioning ........................................................................................ 181  
    30.1.1 Detailed Description ....................................................................... 181  
    30.1.2 Macro Definition Documentation .................................................. 181  
    30.1.3 Function Documentation ............................................................... 181  
  30.2 Initialization and Termination ............................................................. 182  
    30.2.1 Detailed Description ....................................................................... 182  
    30.2.2 Data Structure Documentation ...................................................... 182  
    30.2.3 Macro Definition Documentation .................................................. 186  
    30.2.4 Function Documentation ............................................................... 186

Generated by Doxygen
## CONTENTS

<table>
<thead>
<tr>
<th>Section</th>
<th>Description</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>30.3</td>
<td>Standard Memory Library</td>
<td>189</td>
</tr>
<tr>
<td>30.3.1</td>
<td>Detailed Description</td>
<td>189</td>
</tr>
<tr>
<td>30.3.2</td>
<td>Macro Definition Documentation</td>
<td>189</td>
</tr>
<tr>
<td>30.3.3</td>
<td>Function Documentation</td>
<td>190</td>
</tr>
<tr>
<td>30.4</td>
<td>Toolbox</td>
<td>193</td>
</tr>
<tr>
<td>30.4.1</td>
<td>Detailed Description</td>
<td>193</td>
</tr>
<tr>
<td>30.4.2</td>
<td>Macro Definition Documentation</td>
<td>193</td>
</tr>
<tr>
<td>30.5</td>
<td>Threads</td>
<td>195</td>
</tr>
<tr>
<td>30.5.1</td>
<td>Detailed Description</td>
<td>197</td>
</tr>
<tr>
<td>30.5.2</td>
<td>Macro Definition Documentation</td>
<td>197</td>
</tr>
<tr>
<td>30.5.3</td>
<td>Function Documentation</td>
<td>200</td>
</tr>
<tr>
<td>30.6</td>
<td>Bitmap</td>
<td>205</td>
</tr>
<tr>
<td>30.6.1</td>
<td>Detailed Description</td>
<td>205</td>
</tr>
<tr>
<td>30.6.2</td>
<td>Function Documentation</td>
<td>205</td>
</tr>
<tr>
<td>30.7</td>
<td>Workers' Properties</td>
<td>207</td>
</tr>
<tr>
<td>30.7.1</td>
<td>Detailed Description</td>
<td>209</td>
</tr>
<tr>
<td>30.7.2</td>
<td>Data Structure Documentation</td>
<td>209</td>
</tr>
<tr>
<td>30.7.3</td>
<td>Macro Definition Documentation</td>
<td>210</td>
</tr>
<tr>
<td>30.7.4</td>
<td>Enumeration Type Documentation</td>
<td>211</td>
</tr>
<tr>
<td>30.7.5</td>
<td>Function Documentation</td>
<td>212</td>
</tr>
<tr>
<td>30.8</td>
<td>Data Management</td>
<td>216</td>
</tr>
<tr>
<td>30.8.1</td>
<td>Detailed Description</td>
<td>218</td>
</tr>
<tr>
<td>30.8.2</td>
<td>Macro Definition Documentation</td>
<td>218</td>
</tr>
<tr>
<td>30.8.3</td>
<td>Typedef Documentation</td>
<td>218</td>
</tr>
<tr>
<td>30.8.4</td>
<td>Enumeration Type Documentation</td>
<td>219</td>
</tr>
<tr>
<td>30.8.5</td>
<td>Function Documentation</td>
<td>219</td>
</tr>
<tr>
<td>30.9</td>
<td>Data Interfaces</td>
<td>226</td>
</tr>
<tr>
<td>30.9.1</td>
<td>Detailed Description</td>
<td>230</td>
</tr>
<tr>
<td>30.9.2</td>
<td>Data Structure Documentation</td>
<td>230</td>
</tr>
<tr>
<td>30.9.3</td>
<td>Macro Definition Documentation</td>
<td>240</td>
</tr>
<tr>
<td>30.9.4</td>
<td>Enumeration Type Documentation</td>
<td>247</td>
</tr>
<tr>
<td>30.9.5</td>
<td>Function Documentation</td>
<td>248</td>
</tr>
<tr>
<td>30.10</td>
<td>Data Partition</td>
<td>260</td>
</tr>
<tr>
<td>30.10.1</td>
<td>Detailed Description</td>
<td>262</td>
</tr>
<tr>
<td>30.10.2</td>
<td>Data Structure Documentation</td>
<td>262</td>
</tr>
<tr>
<td>30.10.3</td>
<td>Function Documentation</td>
<td>263</td>
</tr>
<tr>
<td>30.11</td>
<td>Out Of Core</td>
<td>270</td>
</tr>
<tr>
<td>30.11.1</td>
<td>Detailed Description</td>
<td>271</td>
</tr>
<tr>
<td>30.11.2</td>
<td>Data Structure Documentation</td>
<td>271</td>
</tr>
<tr>
<td>30.11.3</td>
<td>Macro Definition Documentation</td>
<td>273</td>
</tr>
<tr>
<td>30.11.4</td>
<td>Function Documentation</td>
<td>273</td>
</tr>
<tr>
<td>30.11.5</td>
<td>Variable Documentation</td>
<td>274</td>
</tr>
<tr>
<td>30.12</td>
<td>Codelet And Tasks</td>
<td>274</td>
</tr>
<tr>
<td>30.12.1</td>
<td>Detailed Description</td>
<td>276</td>
</tr>
<tr>
<td>30.12.2</td>
<td>Data Structure Documentation</td>
<td>276</td>
</tr>
<tr>
<td>30.12.3</td>
<td>Macro Definition Documentation</td>
<td>288</td>
</tr>
<tr>
<td>30.12.4</td>
<td>Typedef Documentation</td>
<td>291</td>
</tr>
<tr>
<td>30.12.5</td>
<td>Enumeration Type Documentation</td>
<td>292</td>
</tr>
<tr>
<td>30.12.6</td>
<td>Function Documentation</td>
<td>292</td>
</tr>
<tr>
<td>30.13</td>
<td>Task Insert Utility</td>
<td>296</td>
</tr>
<tr>
<td>30.13.1</td>
<td>Detailed Description</td>
<td>297</td>
</tr>
<tr>
<td>30.13.2</td>
<td>Data Structure Documentation</td>
<td>297</td>
</tr>
<tr>
<td>30.13.3</td>
<td>Macro Definition Documentation</td>
<td>298</td>
</tr>
<tr>
<td>30.13.4</td>
<td>Function Documentation</td>
<td>300</td>
</tr>
<tr>
<td>30.14</td>
<td>Explicit Dependencies</td>
<td>302</td>
</tr>
<tr>
<td>30.14.1</td>
<td>Detailed Description</td>
<td>303</td>
</tr>
<tr>
<td>30.14.2</td>
<td>Typedef Documentation</td>
<td>303</td>
</tr>
<tr>
<td>30.14.3</td>
<td>Function Documentation</td>
<td>303</td>
</tr>
</tbody>
</table>
30.15 Performance Model .......................................................... 306
  30.15.1 Detailed Description ............................................... 308
  30.15.2 Data Structure Documentation ................................. 308
  30.15.3 Enumeration Type Documentation .............................. 311
  30.15.4 Function Documentation ........................................ 312
  30.15.5 Variable Documentation ........................................ 315
30.16 Profiling ......................................................................... 315
  30.16.1 Detailed Description ............................................... 316
  30.16.2 Data Structure Documentation ................................. 316
  30.16.3 Macro Definition Documentation .............................. 317
  30.16.4 Function Documentation ........................................ 317
30.17 Theoretical Lower Bound on Execution Time ..................... 319
  30.17.1 Detailed Description ............................................... 319
  30.17.2 Function Documentation ........................................ 319
30.18 CUDA Extensions .......................................................... 320
  30.18.1 Detailed Description ............................................... 321
  30.18.2 Macro Definition Documentation .............................. 321
  30.18.3 Function Documentation ........................................ 321
30.19 OpenCL Extensions ....................................................... 323
  30.19.1 Detailed Description ............................................... 324
  30.19.2 Data Structure Documentation ................................. 324
  30.19.3 Macro Definition Documentation .............................. 324
  30.19.4 Function Documentation ........................................ 325
30.20 OpenMP Runtime Support .............................................. 329
  30.20.1 Detailed Description ............................................... 332
  30.20.2 Data Structure Documentation ................................. 332
  30.20.3 Macro Definition Documentation .............................. 334
  30.20.4 Enumeration Type Documentation .............................. 334
  30.20.5 Function Documentation ........................................ 335
30.21 MIC Extensions ............................................................ 353
  30.21.1 Detailed Description ............................................... 353
  30.21.2 Macro Definition Documentation .............................. 353
  30.21.3 Typedef Documentation .......................................... 353
  30.21.4 Function Documentation ........................................ 353
30.22 Miscellaneous Helpers .................................................. 354
  30.22.1 Detailed Description ............................................... 354
  30.22.2 Macro Definition Documentation .............................. 354
  30.22.3 Function Documentation ........................................ 355
30.23 FxT Support ................................................................. 356
  30.23.1 Detailed Description ............................................... 356
  30.23.2 Data Structure Documentation ................................. 356
  30.23.3 Function Documentation ........................................ 357
30.24 FFT Support ............................................................... 358
  30.24.1 Detailed Description ............................................... 358
  30.24.2 Function Documentation ........................................ 358
30.25 MPI Support ............................................................... 360
  30.25.1 Detailed Description ............................................... 362
  30.25.2 Macro Definition Documentation .............................. 362
  30.25.3 Typedef Documentation .......................................... 364
  30.25.4 Function Documentation ........................................ 364
30.26 Task Bundles .............................................................. 376
  30.26.1 Detailed Description ............................................... 376
  30.26.2 Typedef Documentation .......................................... 376
  30.26.3 Function Documentation ........................................ 376
30.27 Task Lists ...................................................................... 377
  30.27.1 Detailed Description ............................................... 378
  30.27.2 Data Structure Documentation ................................. 378
  30.27.3 Function Documentation ........................................ 378
Chapter 1

Introduction

1.1 Motivation

The use of specialized hardware such as accelerators or coprocessors offers an interesting approach to overcome the physical limits encountered by processor architects. As a result, many machines are now equipped with one or several accelerators (e.g. a GPU), in addition to the usual processor(s). While a lot of efforts have been devoted to offload computation onto such accelerators, very little attention has been paid to portability concerns on the one hand, and to the possibility of having heterogeneous accelerators and processors to interact on the other hand.

StarPU is a runtime system that offers support for heterogeneous multicore architectures, it not only offers a unified view of the computational resources (i.e. CPUs and accelerators at the same time), but it also takes care of efficiently mapping and executing tasks onto an heterogeneous machine while transparently handling low-level issues such as data transfers in a portable fashion.

1.2 StarPU in a Nutshell

StarPU is a software tool aiming to allow programmers to exploit the computing power of the available CPUs and GPUs, while relieving them from the need to specially adapt their programs to the target machine and processing units.

At the core of StarPU is its runtime support library, which is responsible for scheduling application-provided tasks on heterogeneous CPU/GPU machines. In addition, StarPU comes with programming language support, in the form of an OpenCL front-end (SOCL OpenCL Extensions).

StarPU’s runtime and programming language extensions support a task-based programming model. Applications submit computational tasks, with CPU and/or GPU implementations, and StarPU schedules these tasks and associated data transfers on available CPUs and GPUs. The data that a task manipulates are automatically transferred among accelerators and the main memory, so that programmers are freed from the scheduling issues and technical details associated with these transfers.

StarPU takes particular care of scheduling tasks efficiently, using well-known algorithms from the literature (Task Scheduling Policies). In addition, it allows scheduling experts, such as compiler or computational library developers, to implement custom scheduling policies in a portable fashion (How To Define A New Scheduling Policy).

The remainder of this section describes the main concepts used in StarPU.

1.2.1 Codelet and Tasks

One of the StarPU primary data structures is the **codelet**. A codelet describes a computational kernel that can possibly be implemented on multiple architectures such as a CPU, a CUDA device or an OpenCL device.

Another important data structure is the **task**. Executing a StarPU task consists in applying a codelet on a data set, on one of the architectures on which the codelet is implemented. A task thus describes the codelet that it uses, but also which data are accessed, and how they are accessed during the computation (read and/or write). StarPU tasks are asynchronous: submitting a task to StarPU is a non-blocking operation. The task structure can also specify a **callback** function that is called once StarPU has properly executed the task. It also contains optional fields that the application may use to give hints to the scheduler (such as priority levels).

By default, task dependencies are inferred from data dependency (sequential coherency) by StarPU. The application can however disable sequential coherency for some data, and dependencies can be specifically expressed. A task...
may be identified by a unique 64-bit number chosen by the application which we refer as a **tag**. Task dependencies can be enforced either by the means of callback functions, by submitting other tasks, or by expressing dependencies between tags (which can thus correspond to tasks that have not yet been submitted).

### 1.2.2 StarPU Data Management Library

Because StarPU schedules tasks at runtime, data transfers have to be done automatically and “just-in-time” between processing units, relieving application programmers from explicit data transfers. Moreover, to avoid unnecessary transfers, StarPU keeps data where it was last needed, even if it was modified there, and it allows multiple copies of the same data to reside at the same time on several processing units as long as it is not modified.

### 1.3 Application Taskification

TODO

### 1.4 Glossary

A **codelet** records pointers to various implementations of the same theoretical function.

A **memory node** can be either the main RAM, GPU-embedded memory or a disk memory.

A **bus** is a link between memory nodes.

A **data handle** keeps track of replicates of the same data (**registered** by the application) over various memory nodes. The data management library manages to keep them coherent.

The **home** memory node of a data handle is the memory node from which the data was registered (usually the main memory node).

A **task** represents a scheduled execution of a codelet on some data handles.

A **tag** is a rendez-vous point. Tasks typically have their own tag, and can depend on other tags. The value is chosen by the application.

A **worker** execute tasks. There is typically one per CPU computation core and one per accelerator (for which a whole CPU core is dedicated).

A **driver** drives a given kind of workers. There are currently CPU, CUDA, and OpenCL drivers. They usually start several workers to actually drive them.

A **performance model** is a (dynamic or static) model of the performance of a given codelet. Codelets can have execution time performance model as well as energy consumption performance models.

A **data interface** describes the layout of the data: for a vector, a pointer for the start, the number of elements and the size of elements ; for a matrix, a pointer for the start, the number of elements per row, the offset between rows, and the size of each element ; etc. To access their data, codelet functions are given interfaces for the local memory node replicates of the data handles of the scheduled task.

**Partitioning** data means dividing the data of a given data handle (called **father**) into a series of **children** data handles which designate various portions of the former.

A **filter** is the function which computes children data handles from a father data handle, and thus describes how the partitioning should be done (horizontal, vertical, etc.)

**Acquiring** a data handle can be done from the main application, to safely access the data of a data handle from its home node, without having to unregister it.

### 1.5 Research Papers

Research papers about StarPU can be found at [http://starpu.gforge.inria.fr/publications/](http://starpu.gforge.inria.fr/publications/).

A good overview is available in the research report at [http://hal.archives-ouvertes.fr/inria-00467677](http://hal.archives-ouvertes.fr/inria-00467677).

### 1.6 StarPU Applications

You can first have a look at the chapters **Basic Examples** and **Advanced Examples**. A tutorial is also installed in the directory `share/doc/starpu/tutorial/`.

Many examples are also available in the StarPU sources in the directory `examples/`. Simple examples include:

`incrementer/` Trivial incrementation test.
1.7 Further Reading

**basic_examples/** Simple documented Hello world and vector/scalar product (as shown in Basic Examples), matrix product examples (as shown in Performance Model Example), an example using the blocked matrix data interface, an example using the variable data interface, and an example using different formats on CPUs and GPUs.

**matvecmult/** OpenCL example from NVidia, adapted to StarPU.

**axpy/** AXPY CUBLAS operation adapted to StarPU.

**native_fortran/** Example of using StarPU’s native Fortran support.

**fortran90/** Example of Fortran 90 bindings, using C marshalling wrappers.

**fortran/** Example of Fortran 77 bindings, using C marshalling wrappers.

More advanced examples include:

**filters/** Examples using filters, as shown in Partitioning Data.

**lu/** LU matrix factorization, see for instance `xlu_implicit.c`

**cholesky/** Cholesky matrix factorization, see for instance `cholesky_implicit.c`.

## 1.7 Further Reading

The documentation chapters include

- Part 1: StarPU Basics
  - Building and Installing StarPU
  - Basic Examples
- Part 2: StarPU Quick Programming Guide
  - Advanced Examples
  - Check List When Performance Are Not There
- Part 3: StarPU Inside
  - Tasks In StarPU
  - Data Management
  - Scheduling
  - Scheduling Contexts
  - Scheduling Context Hypervisor
  - How To Define A New Scheduling Policy
  - Debugging Tools
  - Online Performance Tools
  - Offline Performance Tools
  - Frequently Asked Questions
- Part 4: StarPU Extensions
  - Out Of Core
  - MPI Support
  - FFT Support
  - MIC Xeon Phi Support
  - The StarPU Native Fortran Support
  - SOCL OpenCL Extensions

Generated by Doxygen
– SimGrid Support
– The StarPU OpenMP Runtime Support (SORS)
– Clustering A Machine

• Part 5: StarPU Reference API
  – Execution Configuration Through Environment Variables
  – Compilation Configuration
  – Module Documentation
  – File Documentation
  – Deprecated List

• Part: Appendix
  – Full source code for the ‘Scaling a Vector’ example
  – The GNU Free Documentation License

Make sure to have had a look at those too!
Part I

StarPU Basics
Chapter 2

Building and Installing StarPU

2.1 Installing a Binary Package

One of the StarPU developers being a Debian Developer, the packages are well integrated and very uptodate. To see which packages are available, simply type:

$ apt-cache search starpu

To install what you need, type for example:

$ sudo apt-get install libstarpu-1.3 libstarpu-dev

2.2 Installing from Source

StarPU can be built and installed by the standard means of the GNU autotools. The following chapter is intended to briefly remind how these tools can be used to install StarPU.

2.2.1 Optional Dependencies

The `hwloc` ([http://www.open-mpi.org/software/hwloc](http://www.open-mpi.org/software/hwloc)) topology discovery library is not mandatory to use StarPU but strongly recommended. It allows for topology aware scheduling, which improves performance. `libhwloc` is available in major free operating system distributions, and for most operating systems. If `libhwloc` is installed in a standard location, no option is required, it will be detected automatically, otherwise `--with-hwloc=<directory>` should be used to specify its location. If `libhwloc` is not available on your system, the option `--without-hwloc` should be explicitly given when calling the configure script.

2.2.2 Getting Sources

StarPU's sources can be obtained from the download page of the StarPU website ([http://starpu.gforge.inria.fr/files/](http://starpu.gforge.inria.fr/files/)). All releases and the development tree of StarPU are freely available on Inria's gforge under the LGPL license. Some releases are available under the BSD license. The latest release can be downloaded from the Inria's gforge ([http://gforge.inria.fr/frs/?group_id=1570](http://gforge.inria.fr/frs/?group_id=1570)) or directly from the StarPU download page ([http://starpu.gforge.inria.fr/files/](http://starpu.gforge.inria.fr/files/)). The latest nightly snapshot can be downloaded from the StarPU gforge website ([http://starpu.gforge.inria.fr/testing/](http://starpu.gforge.inria.fr/testing/)).

$ wget http://starpu.gforge.inria.fr/testing/starpu-nightly-latest.tar.gz

And finally, current development version is also accessible via git. It should only be used if you need the very latest changes (i.e. less than a day old!).

$ git clone https://scm.gforge.inria.fr/anonscm/git/starpu/starpu.git
2.2.3 Configuring StarPU

Running `autogen.sh` is not necessary when using the tarball releases of StarPU. However when using the source code from the git repository, you first need to generate the configure scripts and the Makefiles. This requires the availability of `autoconf` and `automake` >= 2.60.

```
$ ./autogen.sh
```

You then need to configure StarPU. Details about options that are useful to give to `configure` are given in Compilation Configuration.

```
$ ./configure
```

If `configure` does not detect some software or produces errors, please make sure to post the contents of the file `config.log` when reporting the issue.

By default, the files produced during the compilation are placed in the source directory. As the compilation generates a lot of files, it is advised to put them all in a separate directory. It is then easier to cleanup, and this allows to compile several configurations out of the same source tree. To do so, simply enter the directory where you want the compilation to produce its files, and invoke the `configure` script located in the StarPU source directory.

```
$ mkdir build
$ cd build
$ ../configure
```

By default, StarPU will be installed in `/usr/local/bin`, `/usr/local/lib`, etc. You can specify an installation prefix other than `/usr/local` using the option `-prefix`, for instance:

```
$ ../configure --prefix=$HOME/starpu
```

2.2.4 Building StarPU

```
$ make
```

Once everything is built, you may want to test the result. An extensive set of regression tests is provided with StarPU. Running the tests is done by calling `make check`. These tests are run every night and the result from the main profile is publicly available ([http://starpu.gforge.inria.fr/testing/](http://starpu.gforge.inria.fr/testing/)).

```
$ make check
```

2.2.5 Installing StarPU

In order to install StarPU at the location which was specified during configuration:

```
$ make install
```

Libtool interface versioning information are included in libraries names (`libstarpu-1.3.so`, `libstarpumpi-1.3.so`, and `libstarpufft-1.3.so`).

2.3 Setting up Your Own Code

2.3.1 Setting Flags for Compiling, Linking and Running Applications

StarPU provides a `pkg-config` executable to obtain relevant compiler and linker flags. As compiling and linking an application against StarPU may require to use specific flags or libraries (for instance CUDA or libspe2).

If StarPU was not installed at some standard location, the path of StarPU's library must be specified in the environment variable `PKG_CONFIG_PATH` to allow `pkg-config` to find it. For example if StarPU was installed in `$STARPU_PATH`:

```
$ export PKG_CONFIG_PATH=$PKG_CONFIG_PATH:$STARPU_PATH/lib/pkgconfig
```

The flags required to compile or link against StarPU are then accessible with the following commands:

```
$ pkg-config --cflags starpu-1.3  # options for the compiler
$ pkg-config --libs starpu-1.3    # options for the linker
```
2.3 Setting up Your Own Code

Note that it is still possible to use the API provided in the version 1.0 of StarPU by calling `pkg-config` with the `starpu-1.0` package. Similar packages are provided for `starpumpi-1.0` and `starpufft-1.0`. It is also possible to use the API provided in the version 0.9 of StarPU by calling `pkg-config` with the `libstarpu` package. Similar packages are provided for `libstarpumpi` and `libstarpufft`.

Make sure that `pkg-config --libs starpu-1.3` actually produces some output before going further. `PK_CONFIG_PATH` has to point to the place where `starpu-1.3.pc` was installed during `make install`. Also pass the option `-static` if the application is to be linked statically.

It is also necessary to set the environment variable `LD_LIBRARY_PATH` to locate dynamic libraries at runtime.

```bash
$ export LD_LIBRARY_PATH=*$STARPU_PATH/lib:$LD_LIBRARY_PATH
```

And it is useful to get access to the StarPU tools:

```bash
$ export PATH=PATH:*$STARPU_PATH/bin
```

It is then useful to check that StarPU executes correctly and finds your hardware:

```bash
$ starpu_machine_display
```

If it does not, please check the output of `lstopo` from `hwloc` and report the issue to the `hwloc` project, since this is what StarPU uses to detect the hardware.

### 2.3.2 Integrating StarPU in a Build System

#### 2.3.2.1 Integrating StarPU in a Make Build System

When using a Makefile, the following lines can be added to set the options for the compiler and the linker:

```bash
CFLAGS += $(pkg-config --cflags starpu-1.3)
LDLIBS += $(pkg-config --libs starpu-1.3)
```

If you have a `test-starpu.c` file containing for instance:

```c
#include <starpu.h>
#include <stdio.h>
int main(void)
{
    int ret;
    ret = starpu_init(NULL);
    if (ret != 0)
    {
        return 1;
    }
    printf("%d CPU coress\n", starpu_worker_get_count_by_type(STARPU_CPU_WORKER));
    printf("%d CUDA GPUs\n", starpu_worker_get_count_by_type(STARPU_CUDA_WORKER));
    printf("%d OpenCL GPUs\n", starpu_worker_get_count_by_type(STARPU_OPENCL_WORKER));
    starpu_shutdown();
    return 0;
}
```

You can build it with `make test-starpu` and run it with `.test-starpu`

#### 2.3.2.2 Integrating StarPU in a CMake Build System

This section shows a minimal example integrating StarPU in an existing application’s CMake build system. Let’s assume we want to build an executable from the following source code using CMake:

```c
#include <starpu.h>
#include <stdio.h>
int main(void)
{
    int ret;
    ret = starpu_init(NULL);
    if (ret != 0)
    {
        return 1;
    }
    printf("%d CPU coress\n", starpu_worker_get_count_by_type(STARPU_CPU_WORKER));
```

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Building and Installing StarPU

The CMakeLists.txt file below uses the Pkg-Config support from CMake to autodetect the StarPU installation and library dependences (such as libhwloc) provided that the PKG_CONFIG_PATH variable is set, and is sufficient to build a statically-linked executable. This example has been successfully tested with CMake 3.2, though it may work with earlier CMake 3.x versions.

```cmake
# This section must appear before `add_executable`
if (STARPU_FOUND)
    include_directories (${STARPU_INCLUDE_DIRS})
    link_directories (${STARPU_STATIC_LIBRARY_DIRS})
    link_libraries (${STARPU_STATIC_LIBRARIES})
else (STARPU_FOUND)
    message(FATAL_ERROR "StarPU not found")
endif()
```

The following CMakeLists.txt implements an alternative, more complex strategy, still relying on Pkg-Config, but also taking into account additional flags. While more complete, this approach makes CMake’s build types (Debug, Release, ...) unavailable because of the direct affectation to variable CMAKE_C_FLAGS. If both the full flags support and the build types support are needed, the CMakeLists.txt below may be altered to work with CMAKE_C_FLAGS_RELEASE, CMAKE_C_FLAGS_DEBUG, and others as needed. This example has been successfully tested with CMake 3.2, though it may work with earlier CMake 3.x versions.

```cmake
# This section must appear after `add_executable`
if (STARPU_FOUND)
    target_include_directories(hello_starpu PRIVATE ${STARPU_INCLUDE_DIRS})
    target_link_libraries(hello_starpu PRIVATE ${STARPU_STATIC_LIBRARIES})
endif()
```

2.3.3 Running a Basic StarPU Application

Basic examples using StarPU are built in the directory `examples/basic_examples/` and installed in `STARPU_PATH/lib/starpu/examples/`. You can for example run the example `vector_scal`.

```bash
$ ./examples/basic_examples/vector_scal
```
When StarPU is used for the first time, the directory $STARPU_HOME/.starpu/ is created, performance models will be stored in this directory (STARPU_HOME).

Please note that buses are benchmarked when StarPU is launched for the first time. This may take a few minutes, or less if libhwloc is installed. This step is done only once per user and per machine.

### 2.3.4 Running a Basic StarPU Application on Microsoft Visual C

Batch files are provided to run StarPU applications under Microsoft Visual C. They are installed in $STARPU_PATH/ATH/bin/msvc.

To execute a StarPU application, you first need to set the environment variable STARPU_PATH.

```bash
c:\....> cd c:\cygwin\home\ci\starpu\nc:\....> set STARPU_PATH=c:\cygwin\home\ci\starpu\nc:\....> cd bin\msvcnc:\....> starpu_open.bat starpu_simple.c
```

The batch script will run Microsoft Visual C with a basic project file to run the given application.

The batch script starpu_clean.bat can be used to delete all compilation generated files.

The batch script starpu_exec.bat can be used to compile and execute a StarPU application from the command prompt.

```bash
c:\....> cd c:\cygwin\home\ci\starpu\nc:\....> set STARPU_PATH=c:\cygwin\home\ci\starpu\nc:\....> cd bin\msvcc:\....> starpu_exec.bat ..\..\..\..\..\examples\basic_examples\hello_world.c
```

**MSVC StarPU Execution**

```
... /out:hello_world.exe
...Hello world {params = {1, 2.00000}}
Callback function got argument 0000042
```

### 2.3.5 Kernel Threads Started by StarPU

StarPU automatically binds one thread per CPU core. It does not use SMT/hyperthreading because kernels are usually already optimized for using a full core, and using hyperthreading would make kernel calibration rather random.

Since driving GPUs is a CPU-consuming task, StarPU dedicates one core per GPU.

While StarPU tasks are executing, the application is not supposed to do computations in the threads it starts itself, tasks should be used instead.

If the application needs to reserve some cores for its own computations, it can do so with the `starpu_conf::reserve←_ncpus` field, get the core IDs with `starpu_get_next_bindid()`, and bind to them with `starpu_bind_thread_on()`.

Another option is for the application to put the whole StarPU on pause with `starpu_pause()` before performing its own computations, and let StarPU resume executing tasks with `starpu_resume()`.

### 2.3.6 Enabling OpenCL

When both CUDA and OpenCL drivers are enabled, StarPU will launch an OpenCL worker for NVIDIA GPUs only if CUDA is not already running on them. This design choice was necessary as OpenCL and CUDA can not run at the same time on the same NVIDIA GPU, as there is currently no interoperability between them.

To enable OpenCL, you need either to disable CUDA when configuring StarPU:

```bash
$ ./configure --disable-cuda
```

or when running applications:

```bash
$ STARPU_NCUDA=0 ./application
```

OpenCL will automatically be started on any device not yet used by CUDA. So on a machine running 4 GPUS, it is therefore possible to enable CUDA on 2 devices, and OpenCL on the 2 other devices by doing so:

```bash
$ STARPU_NCUDA=2 ./application
```
### 2.4 Benchmarking StarPU

Some interesting benchmarks are installed among examples in `$STARPU_PATH/lib/starpu/examples/`. Make sure to try various schedulers, for instance `STARPU_SCHED=dmda`.

#### 2.4.1 Task Size Overhead

This benchmark gives a glimpse into how long a task should be (in µs) for StarPU overhead to be low enough to keep efficiency. Running `tasks_size_overhead.sh` generates a plot of the speedup of tasks of various sizes, depending on the number of CPUs being used.

![Task Size Overhead Plot](image)

#### 2.4.2 Data Transfer Latency

`local_pingpong` performs a ping-pong between the first two CUDA nodes, and prints the measured latency.

#### 2.4.3 Matrix-Matrix Multiplication

`sgemm` and `dgemm` perform a blocked matrix-matrix multiplication using BLAS and cuBLAS. They output the obtained GFlops.

#### 2.4.4 Cholesky Factorization

`cholesky_` perform a Cholesky factorization (single precision). They use different dependency primitives.

#### 2.4.5 LU Factorization

`lu_` perform an LU factorization. They use different dependency primitives.

#### 2.4.6 Simulated benchmarks

It can also be convenient to try simulated benchmarks, if you want to give a try at CPU-GPU scheduling without actually having a GPU at hand. This can be done by using the simgrid version of StarPU: first install the simgrid simulator from [http://simgrid.gforge.inria.fr/](http://simgrid.gforge.inria.fr/) (we tested with simgrid from 3.11 to 3.16, and 3.18 to 3.22, other versions may have compatibility issues, 3.17 notably does not build at all. MPI simulation does not...
work with version 3.22), then configure StarPU with `--enable-simgrid` and rebuild and install it, and then you can simulate the performance for a few virtualized systems shipped along StarPU: attila, mirage, idgraf, and sirocco. For instance:

```bash
$ export STARPU_PERF_MODEL_DIR=$STARPU_PATH/share/starpu/perfmodels/sampling
$ export STARPU_HOSTNAME=attila
$ $STARPU_PATH/lib/starpu/examples/cholesky_implicit -size $((960*20)) -nblocks 20
```

Will show the performance of the cholesky factorization with the attila system. It will be interesting to try with different matrix sizes and schedulers.

Performance models are available for `cholesky_*`, `lu_*`, `gemm`, with block sizes 320, 640, or 960 (plus 1440 for sirocco), and for `stencil` with block size `128x128x128`, `192x192x192`, and `256x256x256`. 
Chapter 3

Basic Examples

3.1 Hello World

This section shows how to implement a simple program that submits a task to StarPU.

3.1.1 Required Headers

The header starpu.h should be included in any code using StarPU.

```c
#include <starpu.h>
```

3.1.2 Defining A Codelet

A codelet is a structure that represents a computational kernel. Such a codelet may contain an implementation of the same kernel on different architectures (e.g. CUDA, x86, ...). For compatibility, make sure that the whole structure is properly initialized to zero, either by using the function starpu_codelet_init(), or by letting the compiler implicitly do it as exemplified below.

The field `starpu_codelet::nbuffers` specifies the number of data buffers that are manipulated by the codelet: here the codelet does not access or modify any data that is controlled by our data management library.

We create a codelet which may only be executed on CPUs. When a CPU core will execute a codelet, it will call the function `cpu_func`, which must have the following prototype:

```c
void (*cpu_func)(void *buffers[], void *cl_arg);
```

In this example, we can ignore the first argument of this function which gives a description of the input and output buffers (e.g. the size and the location of the matrices) since there is none. We also ignore the second argument which is a pointer to optional arguments for the codelet.

```c
void cpu_func(void *buffers[], void *cl_arg)
{
    printf("Hello world\n");
}
```

```c
struct starpu_codelet cl =
{
    .cpu_funcs = { cpu_func },
    .nbuffers = 0
};
```

3.1.3 Submitting A Task

Before submitting any tasks to StarPU, `starpu_init()` must be called. The NULL argument specifies that we use the default configuration. Tasks can then be submitted until the termination of StarPU – done by a call to `starpu←shutdown()`.

In the example below, a task structure is allocated by a call to `starpu_task_create()`. This function allocates and fills the task structure with its default settings, it does not submit the task to StarPU.

The field `starpu_task::cl` is a pointer to the codelet which the task will execute: in other words, the codelet structure describes which computational kernel should be offloaded on the different architectures, and the task structure is a wrapper containing a codelet and the piece of data on which the codelet should operate.
If the field `starpu_task::synchronous` is non-zero, task submission will be synchronous: the function `starpu_task_submit()` will not return until the task has been executed. Note that the function `starpu_shutdown()` does not guarantee that asynchronous tasks have been executed before it returns, `starpu_task_wait_for_all()` can be used to this effect, or data can be unregistered (`starpu_data_unregister()`), which will implicitly wait for all the tasks scheduled to work on it, unless explicitly disabled thanks to `starpu_data_set_default_sequential_consistency_flag()` or `starpu_data_set_sequential_consistency_flag()`.

```c
int main(int argc, char **argv)
{
    /* initialize StarPU */
    starpu_init(NULL);
    struct starpu_task *task = starpu_task_create();
    task->cl = &cl; /* Pointer to the codelet defined above */
    /* submit the task to StarPU */
    starpu_task_submit(task);
    /* terminate StarPU */
    starpu_shutdown();
    return 0;
}
```

### 3.1.4 Execution Of Hello World

$ make hello_world
cc $(pkg-config --cflags starpu-1.3) hello_world.c -o hello_world $(pkg-config --libs starpu-1.3)
$ ./hello_world
Hello world

### 3.1.5 Passing Arguments To The Codelet

The optional field `starpu_task::cl_arg` field is a pointer to a buffer (of size `starpu_task::cl_arg_size`) with some parameters for the kernel described by the codelet. For instance, if a codelet implements a computational kernel that multiplies its input vector by a constant, the constant could be specified by the means of this buffer, instead of registering it as a StarPU data. It must however be noted that StarPU avoids making copy whenever possible and rather passes the pointer as such, so the buffer which is pointed at must be kept allocated until the task terminates, and if several tasks are submitted with various parameters, each of them must be given a pointer to their own buffer.

```c
struct params
{   int i;
    float f;
};
void cpu_func(void *buffers[], void *cl_arg)
{   struct params *params = cl_arg;
    printf("Hello world (params = {%i, %f}) \n", params->i, params->f);
}
```

As said before, the field `starpu_codelet::nbuffers` specifies the number of data buffers which are manipulated by the codelet. It does not count the argument — the parameter `cl_arg` of the function `cpu_func` — since it is not managed by our data management library, but just contains trivial parameters. Be aware that this may be a pointer to a copy of the actual buffer, and not the pointer given by the programmer: if the codelet modifies this buffer, there is no guarantee that the initial buffer will be modified as well: this for instance implies that the buffer cannot be used as a synchronization medium. If synchronization is needed, data has to be registered to StarPU, see Vector Scaling.

```c
int main(int argc, char **argv)
{
    /* initialize StarPU */
    starpu_init(NULL);
    struct starpu_task *task = starpu_task_create();
    task->cl = &cl; /* Pointer to the codelet defined above */
}```
struct params params = { 1, 2.0f };  
task->cl_arg = &params;  
task->cl_arg_size = sizeof(params);  
/* starpu_task_submit will be a blocking call */  
task->synchronous = 1;  
/* submit the task to StarPU */  
starpu_task_submit(task);  
/* terminate StarPU */  
starpu_shutdown();  
return 0;  
}

$ make hello_world  
cc $(pkg-config --cflags starpu-1.3) hello_world.c -o hello_world $(pkg-config --libs starpu-1.3)  
$ ./hello_world  
Hello world (params = {1, 2.000000} )

3.1.6 Defining A Callback

Once a task has been executed, an optional callback function starpu_task::callback_func is called when defined.  
While the computational kernel could be offloaded on various architectures, the callback function is always executed  
on a CPU. The pointer starpu_task::callback_arg is passed as an argument of the callback function. The prototype  
of a callback function must be:

void (*callback_function)(void *);

void callback_func(void *callback_arg)  
{  
    printf("Callback function (arg %x)\n", callback_arg);  
}

int main(int argc, char **argv)  
{  
    /* initialize StarPU */  
    starpu_init(NULL);  
    struct starpu_task *task = starpu_task_create();  
    task->cl = &cl; /* Pointer to the codelet defined above */  
    task->callback_func = callback_func;  
    task->callback_arg = 0x42;  
    /* starpu_task_submit will be a blocking call */  
    task->synchronous = 1;  
    /* submit the task to StarPU */  
    starpu_task_submit(task);  
    /* terminate StarPU */  
    starpu_shutdown();  
    return 0;  
}

$ make hello_world  
cc $(pkg-config --cflags starpu-1.3) hello_world.c -o hello_world $(pkg-config --libs starpu-1.3)  
$ ./hello_world  
Hello world  
Callback function (arg 42)

3.1.7 Where To Execute A Codelet

struct starpu_codelet cl =  
{  
    .where = STARPU_CPU,  
    .cpu_funcs = { cpu_func },  
    .cpu_funcs_name = { "cpu_func" },  
    .nbuffers = 0  
};  

We create a codelet which may only be executed on the CPUs. The optional field starpu_codelet::where is a  
bitmask which defines where the codelet may be executed. Here, the value STARPU_CPU means that only CPUs
can execute this codelet. When the optional field `starpu_codelet::where` is unset, its value is automatically set based on the availability of the different fields `XXX_funcs`.

TODO: explain `starpu_codelet::cpu_funcs_name`

## 3.2 Vector Scaling

The previous example has shown how to submit tasks. In this section, we show how StarPU tasks can manipulate data.

The full source code for this example is given in Full source code for the ‘Scaling a Vector’ example.

### 3.2.1 Source Code of Vector Scaling

Programmers can describe the data layout of their application so that StarPU is responsible for enforcing data coherency and availability across the machine. Instead of handling complex (and non-portable) mechanisms to perform data movements, programmers only declare which piece of data is accessed and/or modified by a task, and StarPU makes sure that when a computational kernel starts somewhere (e.g. on a GPU), its data are available locally.

Before submitting those tasks, the programmer first needs to declare the different pieces of data to StarPU using the functions `starpu_*data_register`. To ease the development of applications for StarPU, it is possible to describe multiple types of data layout. A type of data layout is called an interface. There are different predefined interfaces available in StarPU: here we will consider the vector interface.

The following lines show how to declare an array of `NX` elements of type `float` using the vector interface:

```c
float vector[NX];
starpu_data_handle_t vector_handle;
starpu_vector_data_register(&vector_handle, STARPU_MAIN_RAM, (uintptr_t)vector, NX, sizeof(vector[0]));
```

The first argument, called the data handle, is an opaque pointer which designates the array within StarPU. This is also the structure which is used to describe which data is used by a task. The second argument is the node number where the data originally resides. Here it is `STARPU_MAIN_RAM` since the array `vector` is in the main memory. Then comes the pointer `vector` where the data can be found in main memory, the number of elements in the vector and the size of each element. The following shows how to construct a StarPU task that will manipulate the vector and a constant factor.

```c
float factor = 3.14;
struct starpu_task *task = starpu_task_create();
task->cl = &cl; /* Pointer to the codelet defined below */
task->handles[0] = vector_handle; /* First parameter of the codelet */
task->cl_arg = &factor;
task->cl_arg_size = sizeof(factor);
task->synchronous = 1;
starpu_task_submit(task);
```

Since the factor is a mere constant float value parameter, it does not need a preliminary registration, and can just be passed through the pointer `starpu_task::cl_arg` like in the previous example. The vector parameter is described by its handle. `starpu_task::handles` should be set with the handles of the data, the access modes for the data are defined in the field `starpu_codelet::modes` (`STARPU_R` for read-only, `STARPU_W` for write-only and `STARPU_RW` for read and write access).

The definition of the codelet can be written as follows:

```c
voidscal_cpu_func(void *buffers[], void *cl_arg)
{
    unsigned i;
    float *factor = cl_arg;
    /* length of the vector */
    unsigned n = STARPU_VECTOR_GET_NX(buffers[0]);
    /* CPU copy of the vector pointer */
    float *val = (float *)STARPU_VECTOR_GET_PTR(buffers[0]);
    for (i = 0; i < n; i++)
        val[i] *= *factor;
}
```

```c
struct starpu_codelet cl =
```

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3.3 Vector Scaling on an Hybrid CPU/GPU Machine

The first argument is an array that gives a description of all the buffers passed in the array starpu_task::handles. The size of this array is given by the field starpu_codelet::nbuffers. For the sake of genericity, this array contains pointers to the different interfaces describing each buffer. In the case of the vector interface, the location of the vector (resp. its length) is accessible in the starpu_vector_interface::ptr (resp. starpu_vector_interface::nx) of this interface. Since the vector is accessed in a read-write fashion, any modification will automatically affect future accesses to this vector made by other tasks.

The second argument of the function scal_cpu_func contains a pointer to the parameters of the codelet (given in starpu_task::cl_arg), so that we read the constant factor from this pointer.

3.2.2 Execution of Vector Scaling

$ make vector_scal
cc $(pkg-config --cflags starpu-1.3) vector_scal.c -o vector_scal $(pkg-config --libs starpu-1.3)
$ ./vector_scal
0.000000 3.000000 6.000000 9.000000 12.000000

3.3 Vector Scaling on an Hybrid CPU/GPU Machine

Contrary to the previous examples, the task submitted in this example may not only be executed by the CPUs, but also by a CUDA device.

3.3.1 Definition of the CUDA Kernel

The CUDA implementation can be written as follows. It needs to be compiled with a CUDA compiler such as nvcc, the NVIDIA CUDA compiler driver. It must be noted that the vector pointer returned by STARPU_VECTOR_GET_PTR is a pointer in GPU memory, so that it can be passed as such to the kernel call vector_mult_cuda.

```c
#include <starpu.h>

static __global__ void vector_mult_cuda(unsigned n, float *val, float factor)
{
    unsigned i = blockIdx.x * blockDim.x + threadIdx.x;
    if (i < n)
        val[i] *= factor;
}

extern "C" void scal_cuda_func(void *buffers[], void *args)
{
    float *factor = (float *)args;
    /* length of the vector */
    unsigned n = STARPU_VECTOR_GET_NX(buffers[0]);
    /* local copy of the vector pointer */
    float *val = (float *)STARPU_VECTOR_GET_PTR(buffers[0]);
    unsigned threads_per_block = 64;
    unsigned nblocks = (n + threads_per_block - 1) / threads_per_block;
    vector_mult_cuda<<<nblocks,threads_per_block, 0, starpu_cuda_get_local_stream()>>>(n, val, *factor);
    cudaStreamSynchronize(starpu_cuda_get_local_stream());
}
```

3.3.2 Definition of the OpenCL Kernel

The OpenCL implementation can be written as follows. StarPU provides tools to compile a OpenCL kernel stored in a file.

```c
__kernel void vector_mult_opencl(int nx, __global float *val, float factor)
{
    const int i = get_global_id(0);
    if (i < nx)
        val[i] *= factor;
}
```
Contrary to CUDA and CPU, `STARPU_VECTOR_GET_DEV_HANDLE` has to be used, which returns a `cl_mem` (which is not a device pointer, but an OpenCL handle), which can be passed as such to the OpenCL kernel. The difference is important when using partitioning, see Partitioning Data.

```c
#include <starpu.h>
extern struct starpu_opencl_program programs;

void scal_opencl_func(void *buffers[], void *args)
{
    float *factor = args;
    int id, devid, err; /* OpenCL specific code */
    cl_kernel kernel; /* OpenCL specific code */
    cl_command_queue queue; /* OpenCL specific code */
    cl_event event; /* OpenCL specific code */

    /* length of the vector */
    unsigned n = STARPU_VECTOR_GET_NX(buffers[0]);
    /* OpenCL copy of the vector pointer */
    cl_mem val = reinterpret_cast<cl_mem>(STARPU_VECTOR_GET_DEV_HANDLE(buffers[0]));

    { /* OpenCL specific code */
        id = starpu_worker_get_id();
        devid = starpu_worker_get_devid(id);
        err = starpu_opencl_load_kernel(&kernel, &queue, &programs,
            "vector_mult_opencl", /* Name of the codelet */
            devid);
        if (err != CL_SUCCESS) STARPU_OPENCL_REPORT_ERROR(err);
        err = clSetKernelArg(kernel, 0, sizeof(n), &n);
        err |= clSetKernelArg(kernel, 1, sizeof(val), &val);
        err |= clSetKernelArg(kernel, 2, sizeof(*factor), factor);
        if (err) STARPU_OPENCL_REPORT_ERROR(err);
    }

    { /* OpenCL specific code */
        size_t global=n;
        size_t local;
        size_t s;
        cl_device_id device;
        starpu_opencl_get_device(devid, &device);
        err = clGetKernelWorkGroupInfo (kernel, device, CL_KERNEL_WORK_GROUP_SIZE, sizeof(local), &local, &s);
        if (err != CL_SUCCESS) STARPU_OPENCL_REPORT_ERROR(err);
        if (local > global) local=global;
        err = clEnqueueNDRangeKernel(queue, kernel, 1, NULL, &global, &local, 0, NULL, &event);
        if (err != CL_SUCCESS) STARPU_OPENCL_REPORT_ERROR(err);
    }

    { /* OpenCL specific code */
        clFinish(queue);
        starpu_opencl_collect_stats(event);
        clReleaseEvent(event);
        starpu_opencl_release_kernel(kernel);
    }
}
```

### 3.3.3 Definition of the Main Code

The CPU implementation is the same as in the previous section. Here is the source of the main application. You can notice that the fields `starpu_codelet::cuda_funcs` and `starpu_codelet::opencl_funcs` are set to define the pointers to the CUDA and OpenCL implementations of the task.

```c
#include <starpu.h>
#define NX 2048

extern void scal_cpu_func(void *buffers[], void *args);
extern void scal_sse_func(void *buffers[], void *args);
extern void scal_cuda_func(void *buffers[], void *args);
extern void scal_opencl_func(void *buffers[], void *args);
```
static struct starpu_codelet cl =
{
    .where = STARPU_CPU | STARPU_CUDA | STARPU_OPENCL,
    /* CPU implementation of the codelet */
    .cpu_funcs = { scal_cpu_func, scal_sse_func },
    .cpu_funcs_name = { "scal_cpu_func", "scal_sse_func" },
#ifdef STARPU_USE_CUDA
    /* CUDA implementation of the codelet */
    .cuda_funcs = { scal_cuda_func },
#endif
#ifdef STARPU_USE_OPENCL
    /* OpenCL implementation of the codelet */
    .opencl_funcs = { scal_opencl_func },
#endif
    .nbuffers = 1,
    .modes = { STARPU_RW }
};

#ifdef STARPU_USE_OPENCL
struct starpu_opencl_program programs;
#endif

int main(int argc, char **argv)
{
    /* We consider a vector of float that is initialized just as any of C */
    data */
    float vector[NX];
    unsigned i;
    for (i = 0; i < NX; i++)
        vector[i] = 1.0f;
    fprintf(stderr, "BEFORE: First element was %f\n", vector[0]);
    /* Initialize StarPU with default configuration */
    starpu_init(NULL);
    #ifdef STARPU_USE_OPENCL
    starpu_opencl_load_opencl_from_file("examples/basic_examples/vector_scal_opencl_kernel.cl", &programs, NULL);
    #endif
    /* Tell StarPU to associate the "vector" vector with the "vector_handle" */
    identifier. When a task needs to access a piece of data, it should
    * refer to the handle that is associated to it.
    * In the case of the "vector" data interface:
    * - the first argument of the registration method is a pointer to the
    *   handle that should describe the data
    * - the second argument is the memory node where the data (ie. "vector")
    *   resides initially: STARPU_MAIN_RAM stands for an address in main memory, as
    *   opposed to an adress on a GPU for instance.
    * - the third argument is the adress of the vector in RAM
    * - the fourth argument is the number of elements in the vector
    * - the fifth argument is the size of each element.
    */
    starpu_data_handle_t vector_handle;
    starpu_vector_data_register(&vector_handle, STARPU_MAIN_RAM,
        (uintptr_t)vector, NX, sizeof(vector[0]));
    float factor = 3.14;
    /* create a synchronous task: any call to starpu_task_submit will block */
    * until it is terminated */
    struct starpu_task *task = starpu_task_create();
    task->synchronous = 1;
    task->cl = &cl;
    /* the codelet manipulates one buffer in RW mode */
    task->handles[0] = vector_handle;
    /* an argument is passed to the codelet, beware that this is a */
    * READ-ONLY buffer and that the codelet may be given a pointer to a */
    * COPY of the argument */
    task->cl_arg = &factor;
    task->cl_arg_size = sizeof(factor);
    /* execute the task on any eligible computational resource */
    starpu_task_submit(task);
    /* StarPU does not need to manipulate the array anymore so we can stop */
    * monitoring it */
    starpu_data_unregister(vector_handle);
#ifdef STARPU_USE_OPENCL
    starpu_opencl_unload_opencl(&programs);
#endif
}
/* terminate StarPU, no task can be submitted after */
starpu_shutdown();

fprintf(stderr, "AFTER First element is \f\n", vector[0]);
return 0;
}

3.3.4 Execution of Hybrid Vector Scaling

The Makefile given at the beginning of the section must be extended to give the rules to compile the CUDA source code. Note that the source file of the OpenCL kernel does not need to be compiled now, it will be compiled at run-time when calling the function starpu_opencl_load_opencl_from_file().

CFLAGS += $(shell pkg-config --cflags starpu-1.3)
LDLIBS += $(shell pkg-config --libs starpu-1.3)
CC = gcc

vector_scal: vector_scal.o vector_scal_cpu.o vector_scal_cuda.o vector_scal_opencl.o
%.o: %.cu
    nvcc $(CFLAGS) $< -c $@

clean:
    rm -f vector_scal *.o

$ make

and to execute it, with the default configuration:

$ ./vector_scal
0.000000 3.000000 6.000000 9.000000 12.000000

or for example, by disabling CPU devices:

$ STARPU_NCPU=0 ./vector_scal
0.000000 3.000000 6.000000 9.000000 12.000000

or by disabling CUDA devices (which may permit to enable the use of OpenCL, see Enabling OpenCL):

$ STARPU_NCUDA=0 ./vector_scal
0.000000 3.000000 6.000000 9.000000 12.000000

Part II

StarPU Quick Programming Guide
Chapter 4

Advanced Examples

TODO
Chapter 5

Check List When Performance Are Not There

TODO: improve!
To achieve good performance, we give below a list of features which should be checked.
For a start, you can use Offline Performance Tools to get a Gantt chart which will show roughly where time is spent, and focus correspondingly.

5.1 Check Task Size

Make sure that your tasks are not too small, because the StarPU runtime overhead is not completely zero. You can run the tasks_size_overhead.sh script to get an idea of the scalability of tasks depending on their duration (in µs), on your own system.
Typically, 10µs-ish tasks are definitely too small, the CUDA overhead itself is much bigger than this. 1ms-ish tasks may be a good start, but will not necessarily scale to many dozens of cores, so it's better to try to get 10ms-ish tasks.
Tasks durations can easily be observed when performance models are defined (see Performance Model Example) by using the starpu_perfmodel_plot or starpu_perfmodel_display tool (see Performance Of Codelets)
When using parallel tasks, the problem is even worse since StarPU has to synchronize the execution of tasks.

5.2 Configuration Which May Improve Performance

The --enable-fast configure option disables all assertions. This makes StarPU more performant for really small tasks by disabling all sanity checks. Only use this for measurements and production, not for development, since this will drop all basic checks.

5.3 Data Related Features Which May Improve Performance

link to Data Management
link to Data Prefetch

5.4 Task Related Features Which May Improve Performance

link to Task Granularity
link to Task Submission
link to Task Priorities

5.5 Scheduling Related Features Which May Improve Performance

link to Task Scheduling Policies
link to Task Distribution Vs Data Transfer
link to Energy-based Scheduling
5.6 CUDA-specific Optimizations

For proper overlapping of asynchronous GPU data transfers, data has to be properly pinned by CUDA. Data allocated with starpu_malloc() is always properly pinned. If the application is registering to StarPU some data which has not been allocated with starpu_malloc(), it should use starpu_memory_pin() to pin it.

Due to CUDA limitations, StarPU will have a hard time overlapping its own communications and the codelet computations if the application does not use a dedicated CUDA stream for its computations instead of the default stream, which synchronizes all operations of the GPU. StarPU provides one by the use of starpu_cuda_get_local_stream() which can be used by all CUDA codelet operations to avoid this issue. For instance:

```c
func <<<grid,block,0,starpu_cuda_get_local_stream()>>> (foo, bar);
cudaStreamSynchronize(starpu_cuda_get_local_stream());
```

as well as the use of cudaMemcpyAsync(), etc. for each CUDA operation one needs to use a version that takes the a stream parameter.

Unfortunately, some CUDA libraries do not have stream variants of kernels. This will seriously lower the potential for overlapping. If some CUDA calls are made without specifying this local stream, synchronization needs to be explicit with cudaThreadSynchronize() around these calls, to make sure that they get properly synchronized with the calls using the local stream. Notably, cudaMemcpy() and cudaMemcpyAsync() are actually asynchronous and need such explicit synchronization! Use cudaMemcpyAsync() and cudaMemcpyAsync() instead.

Calling starpu_cublas_init() makes StarPU already do appropriate calls for the CUBLAS library. Some libraries like Magma may however change the current stream of CUBLAS v1, one then has to call cublasSetKernelExecutionStream(starpu_cuda_get_local_stream()) at the beginning of the codelet to make sure that CUBLAS is really using the proper stream. When using CUBLAS v2, starpu_cublas_get_local_handle() can be called to queue CUBLAS kernels with the proper configuration.

Similarly, calling starpu_cusparse_init() makes StarPU create CUSPARSE handles on each CUDA device, starpu_cusparse_get_local_handle() can then be used to queue CUSPARSE kernels with the proper configuration.

If the kernel can be made to only use this local stream or other self-allocated streams, i.e. the whole kernel submission can be made asynchronous, then one should enable asynchronous execution of the kernel. This means setting the flag STARPU_CUDA_ASYNC in the corresponding field starpu_codelet::cuda_flags, and dropping the cudaStreamSynchronize() call at the end of the cuda_func function, so that it returns immediately after having queued the kernel to the local stream. That way, StarPU will be able to submit and complete data transfers while kernels are executing, instead of only at each kernel submission. The kernel just has to make sure that StarPU can use the local stream to synchronize with the kernel startup and completion.

If the kernel uses its own non-default stream, one can synchronize this stream with the StarPU-provided stream this way:

```c
cudaEvent_t event;
call_kernel_with_its_own_stream();
cudaEventCreateWithFlags(&event, cudaEventDisableTiming);
cudaEventRecord(event, get_kernel_stream());
cudaStreamWaitEvent(starpu_cuda_get_local_stream(), event, 0);
cudaEventDestroy(event);
```

This code makes the StarPU-provided stream wait for a new event, which will be triggered by the completion of the kernel.

Using the flag STARPU_CUDA_ASYNC also permits to enable concurrent kernel execution, on cards which support it (Kepler and later, notably). This is enabled by setting the environment variable STARPU_NWORKER_PER_CUDA to the number of kernels to execute concurrently. This is useful when kernels are small and do not feed the whole GPU with threads to run.

Concerning memory allocation, you should really not use cudaMalloc/ cudaFree within the kernel, since cudaFree introduces a awfully lot of synchronizations within CUDA itself. You should instead add a parameter to the codelet with the STARPU_SCRATCH mode access. You can then pass to the task a handle registered with the desired size but with the NULL pointer, that handle can even be the shared between tasks, StarPU will allocate per-task data on the fly before task execution, and reuse the allocated data between tasks.

See examples/pi/pi Redux.c for an example of use.
5.7 OpenCL-specific Optimizations

If the kernel can be made to only use the StarPU-provided command queue or other self-allocated queues, i.e. the whole kernel submission can be made asynchronous, then one should enable asynchronous execution of the kernel. This means setting the flag \texttt{STARPU\_OPENCL\_ASYNC} in the corresponding field \texttt{starpu\_codelet\_:opencl\_flags} and dropping the \texttt{clFinish()} and \texttt{starpu\_opencl\_collect\_stats()} calls at the end of the kernel, so that it returns immediately after having queued the kernel to the provided queue. That way, StarPU will be able to submit and complete data transfers while kernels are executing, instead of only at each kernel submission. The kernel just has to make sure that StarPU can use the command queue it has provided to synchronize with the kernel startup and completion.

5.8 Detecting Stuck Conditions

It may happen that for some reason, StarPU does not make progress for a long period of time. Reason are sometimes due to contention inside StarPU, but sometimes this is due to external reasons, such as stuck MPI driver, or CUDA driver, etc.

\begin{verbatim}
export STARPU\_WATCHDOG\_TIMEOUT=10000 (STARPU\_WATCHDOG\_TIMEOUT)
\end{verbatim}

allows to make StarPU print an error message whenever StarPU does not terminate any task for 10ms, but lets the application continue normally. In addition to that,

\begin{verbatim}
export STARPU\_WATCHDOG\_CRASH=1 (STARPU\_WATCHDOG\_CRASH)
\end{verbatim}

raises SIGABRT in this condition, thus allowing to catch the situation in gdb. It can also be useful to type \texttt{handle SIGABRT nopass} in gdb to be able to let the process continue, after inspecting the state of the process.

5.9 How to Limit Memory Used By StarPU And Cache Buffer Allocations

By default, StarPU makes sure to use at most 90% of the memory of GPU devices, moving data in and out of the device as appropriate and with prefetch and writeback optimizations. Concerning the main memory, by default it will not limit its consumption, since by default it has nowhere to push the data to when memory gets tight. This also means that by default StarPU will not cache buffer allocations in main memory, since it does not know how much of the system memory it can afford.

In the case of GPUs, the \texttt{STARPU\_LIMIT\_CUDA\_MEM}, \texttt{STARPU\_LIMIT\_CUDA\_devid\_MEM}, \texttt{STARPU\_LIMIT\_OPENCL\_MEM}, and \texttt{STARPU\_LIMIT\_OPENCL\_devid\_MEM} environment variables can be used to control how much (in MiB) of the GPU device memory should be used at most by StarPU (their default values are 90% of the available memory).

In the case of the main memory, the \texttt{STARPU\_LIMIT\_CPU\_MEM} environment variable can be used to specify how much (in MiB) of the main memory should be used at most by StarPU for buffer allocations. This way, StarPU will be able to cache buffer allocations (which can be a real benefit if a lot of buffers are involved, or if allocation fragmentation can become a problem), and when using Out Of Core, StarPU will know when it should evict data out to the disk.

It should be noted that by default only buffer allocations automatically done by StarPU are accounted here, i.e. allocations performed through \texttt{starpu\_malloc\_on\_node()} which are used by the data interfaces (matrix, vector, etc.). This does not include allocations performed by the application through e.g. \texttt{malloc()}. It does not include allocations performed through \texttt{starpu\_malloc()} either, only allocations performed explicitly with the \texttt{STARPU\_MALLOC\_COUNT} flag, i.e. by calling

\begin{verbatim}
starpu\_malloc\_flags\_refs(STARPU\_MALLOC\_COUNT)
\end{verbatim}

are taken into account. If the application wants to make StarPU aware of its own allocations, so that StarPU knows precisely how much data is allocated, and thus when to evict allocation caches or data out to the disk, \texttt{starpu\_memory\_allocate()} can be used to specify an amount of memory to be accounted for. \texttt{starpu\_memory\_deallocate()} can be used to account freed memory back. Those can for instance be used by data interfaces with dynamic data buffers: instead of using \texttt{starpu\_malloc\_on\_node()}, they would dynamically allocate data with \texttt{malloc/realloc}, and notify starpu of the delta thanks to \texttt{starpu\_memory\_allocate()} and \texttt{starpu\_memory\_deallocate()} calls.

\texttt{starpu\_memory\_get\_total()} and \texttt{starpu\_memory\_get\_available()} can be used to get an estimation of how much memory is available. \texttt{starpu\_memory\_wait\_available()} can also be used to block until an amount of memory becomes available, but it may be preferrable to call

\begin{verbatim}
starpu\_memory\_allocate\_wait\_available(STARPU\_MEMORY\_WAIT)
\end{verbatim}

to reserve this amount immediately.
5.10 How To Reduce The Memory Footprint Of Internal Data Structures

It is possible to reduce the memory footprint of the task and data internal structures of StarPU by describing the shape of your machine and/or your application at the `configure` step. To reduce the memory footprint of the data internal structures of StarPU, one can set the `--enable-maxcpus`, `--enable-maxnumanodes`, `--enable-maxcudadev`, `--enable-maxopencldev` and `--enable-maxnodes` configure parameters to give StarPU the architecture of the machine it will run on, thus tuning the size of the structures to the machine. To reduce the memory footprint of the task internal structures of StarPU, one can set the `--enable-maxbuffers` configure parameter to give StarPU the maximum number of buffers that a task can use during an execution. For example, in the Cholesky factorization (dense linear algebra application), the GEMM task uses up to 3 buffers, so it is possible to set the maximum number of task buffers to 3 to run a Cholesky factorization on StarPU. The size of the various structures of StarPU can be printed by `tests/microbenchs/display Structures_size`.

It is also often useless to submit `all` the tasks at the same time. One can make the `starpu_task_submit()` function block when a reasonable given number of tasks have been submitted, by setting the `STARPU_LIMIT_MIN_SUBMITTED_TASKS` and `STARPU_LIMIT_MAX_SUBMITTED_TASKS` environment variables, for instance:

```bash
export STARPU_LIMIT_MIN_SUBMITTED_TASKS=9000
export STARPU_LIMIT_MAX_SUBMITTED_TASKS=10000
```

To make StarPU block submission when 10000 tasks are submitted, and unblock submission when only 9000 tasks are still submitted, i.e. 1000 tasks have completed among the 10000 which were submitted when submission was blocked. Of course this may reduce parallelism if the threshold is set too low. The precise balance depends on the application task graph.

An idea of how much memory is used for tasks and data handles can be obtained by setting the `STARPU_MAX_MEMORY_USE` environment variable to 1.

5.11 How To Reuse Memory

When your application needs to allocate more data than the available amount of memory usable by StarPU (given by `starpu_memory_get_available()`), the allocation cache system can reuse data buffers used by previously executed tasks. For this system to work with MPI tasks, you need to submit tasks progressively instead of as soon as possible, because in the case of MPI receives, the allocation cache check for reusing data buffers will be done at submission time, not at execution time.

You have two options to control the task submission flow. The first one is by controlling the number of submitted tasks during the whole execution. This can be done whether by setting the environment variables `STARPU_LIMIT_MAX_SUBMITTED_TASKS` and `STARPU_LIMIT_MIN_SUBMITTED_TASKS` to tell StarPU when to stop submitting tasks and when to wake up and submit tasks again, or by explicitly calling `starpu_task_wait_for_n_submitted()` in your application code for finest grain control (for example, between two iterations of a submission loop).

The second option is to control the memory size of the allocation cache. This can be done in the application by using jointly `starpu_memory_get_available()` and `starpu_memory_wait_available()` to submit tasks only when there is enough memory space to allocate the data needed by the task, i.e when enough data are available for reuse in the allocation cache.

5.12 Performance Model Calibration

Most schedulers are based on an estimation of codelet duration on each kind of processing unit. For this to be possible, the application programmer needs to configure a performance model for the codelets of the application (see Performance Model Example for instance). History-based performance models use on-line calibration. StarPU will automatically calibrate codelets which have never been calibrated yet, and save the result in $STARPU_HOME/.starpu/sampling/codelets. The models are indexed by machine name. By default, StarPU stores separate performance models according to the hostname of the system. To avoid having to calibrate performance models for each node of a homogeneous cluster for instance, the model can be shared by using `export STARPU_HOSTNAME=some_global_name` (STARPU_HOSTNAME), where `some_global_name` is the name of the cluster for instance, which thus overrides the hostname of the system.

By default, StarPU stores separate performance models for each GPU. To avoid having to calibrate performance models for each GPU of a homogeneous set of GPU devices for instance, the model can be shared
by setting `export STARPU_PERF_MODEL_HOMOGENEOUS_CUDA=1` (STARPU_PERF_MODEL_HOMOGENEOUS_CUDA), `export STARPU_PERF_MODEL_HOMOGENEOUS_OPENCL=1` (STARPU_PERF_MODEL_HOMOGENEOUS_OPENCL), `export STARPU_PERF_MODEL_HOMOGENEOUS_MIC=1` (STARPU_PERF_MODEL_HOMOGENEOUS_MIC), `export STARPU_PERF_MODEL_HOMOGENEOUS_MPI_MS=1` (STARPU_PERF_MODEL_HOMOGENEOUS_MPI_MS) depending on your GPU device type.

To force continuing calibration, use `export STARPU_CALIBRATE=1` (STARPU_CALIBRATE). This may be necessary if your application has not-so-stable performance. StarPU will force calibration (and thus ignore the current result) until `10 (_STARPU_CALIBRATION_MINIMUM)` measurements have been made on each architecture, to avoid badly scheduling tasks just because the first measurements were not so good. Details on the current performance model status can be obtained from the tool `starpu_perfmodel_display`: the `-l` option lists the available performance models, and the `-s` option permits to choose the performance model to be displayed. The result looks like:

```
$ starpu_perfmodel_display -s starpu_slu_lu_model_11
performance model for cpu_impl_0
  # hash size  flops  mean  dev  n
  914f3bef 1048576  0.000000e+00  2.503577e+04  1.982465e+02  8
  3e921964  65536  0.000000e+00  5.527003e+02  1.848114e+01  7
  e5a07e31  4096  0.000000e+00  1.717457e+01  5.190038e+00 14
  ...
```

Which shows that for the LU 11 kernel with a 1MiB matrix, the average execution time on CPUs was about 25ms, with a 0.2ms standard deviation, over 8 samples. It is a good idea to check this before doing actual performance measurements.

A graph can be drawn by using the tool `starpu_perfmodel_plot`:

```
$ starpu_perfmodel_plot -s starpu_slu_lu_model_11
4096  16384  65536  262144  1048576  4194304
$ gnuplot starpu_starpu_slu_lu_model_11.gp
$ gv starpu_starpu_slu_lu_model_11.eps
```

If a kernel source code was modified (e.g. performance improvement), the calibration information is stale and should be dropped, to re-calibrate from start. This can be done by using `export STARPU_CALIBRATE=2` (STARPU_CALIBRATE):
Note: history-based performance models get calibrated only if a performance-model-based scheduler is chosen. The history-based performance models can also be explicitly filled by the application without execution, if e.g. the application already has a series of measurements. This can be done by using `starpu_perfmodel_update_history()`, for instance:

```c
static struct starpu_perfmodel perf_model =
{
    .type = STARPU_HISTORY_BASED,
    .symbol = "my_perfmodel",
};

struct starpu_codelet cl =
{
    .cuda_funcs = { cuda_func1, cuda_func2 },
    .nbuffers = 1,
    .modes = {STARPU_W},
    .model = &perf_model
};

void feed(void)
{
    struct my_measure *measure;
    struct starpu_task task;
    starpu_task_init(&task);
    task.cl = &cl;
    for (measure = &measures[0]; measure < measures[last]; measure++)
    {
        starpu_data_handle_t handle;
        starpu_vector_data_register(&handle, -1, 0, measure->size, sizeof(float));
        task.handles[0] = handle;
        starpu_perfmodel_update_history(&perf_model, &task, STARPU_CUDA_DEFAULT + measure->cudadev, 0, measure->implementation, measure->time);
        starpu_task_clean(&task);
        starpu_data_unregister(handle);
    }
}
```

Measurement has to be provided in milliseconds for the completion time models, and in Joules for the energy consumption models.

### 5.13 Profiling

A quick view of how many tasks each worker has executed can be obtained by setting `export STARPU_WORKER_STATS=1` (STARPU_WORKER_STATS). This is a convenient way to check that execution did happen on accelerators, without penalizing performance with the profiling overhead.

A quick view of how much data transfers have been issued can be obtained by setting `export STARPU_BUS_STATS=1` (STARPU_BUS_STATS).

More detailed profiling information can be enabled by using `export STARPU_PROFILING=1` (STARPU_PROFILING) or by calling `starpu_profiling_status_set()` from the source code. Statistics on the execution can then be obtained by using `export STARPU_BUS_STATS=1` and `export STARPU_WORKER_STATS=1`. More details on performance feedback are provided in the next chapter.

### 5.14 Overhead Profiling

**Offline Performance Tools** can already provide an idea of to what extent and which part of StarPU bring overhead on the execution time. To get a more precise analysis of the parts of StarPU which bring most overhead, `gprof` can be used.

First, recompile and reinstall StarPU with `gprof` support:

```
./configure --enable-perf-debug --disable-shared --disable-build-tests --disable-build-examples
```

Make sure not to leave a dynamic version of StarPU in the target path: remove any remaining `libstarpu-*.so` Then relink your application with the static StarPU library, make sure that running `ldd` on your application does not mention any libstarpu (i.e. it's really statically-linked).

```
gcc test.c -o test $(pkg-config --cflags starpu-1.3) $(pkg-config --libs starpu-1.3)
```
Now you can run your application, and a `gmon.out` file should appear in the current directory, you can process it by running `gprof` on your application:

```bash
gprof ./test
```

This will dump an analysis of the time spent in StarPU functions.
Part III

StarPU Inside
Chapter 6

Tasks In StarPU

6.1 Task Granularity

Like any other runtime, StarPU has some overhead to manage tasks. Since it does smart scheduling and data management, this overhead is not always neglectable. The order of magnitude of the overhead is typically a couple of microseconds, which is actually quite smaller than the CUDA overhead itself. The amount of work that a task should do should thus be somewhat bigger, to make sure that the overhead becomes neglectable. The offline performance feedback can provide a measure of task length, which should thus be checked if bad performance are observed. To get a grasp at the scalability possibility according to task size, one can run `tests/microbenches/tasks_size_overhead.sh` which draws curves of the speedup of independent tasks of very small sizes. The choice of scheduler also has impact over the overhead: for instance, the scheduler `dmda` takes time to make a decision, while `eager` does not. `tasks_size_overhead.sh` can again be used to get a grasp at how much impact that has on the target machine.

6.2 Task Submission

To let StarPU make online optimizations, tasks should be submitted asynchronously as much as possible. Ideally, all the tasks should be submitted, and mere calls to `starpu_task_wait_for_all()` or `starpu_data_unregister()` be done to wait for termination. StarPU will then be able to rework the whole schedule, overlap computation with communication, manage accelerator local memory usage, etc.

6.3 Task Priorities

By default, StarPU will consider the tasks in the order they are submitted by the application. If the application programmer knows that some tasks should be performed in priority (for instance because their output is needed by many other tasks and may thus be a bottleneck if not executed early enough), the field `starpu_task::priority` should be set to transmit the priority information to StarPU.

6.4 Task Dependencies

6.4.1 Sequential Consistency

By default, task dependencies are inferred from data dependency (sequential coherency) by StarPU. The application can however disable sequential coherency for some data, and dependencies can be specifically expressed. Setting (or unsetting) sequential consistency can be done at the data level by calling `starpu_data_set_sequential_consistency_flag()` for a specific data or `starpu_data_set_default_sequential_consistency_flag()` for all datas. Setting (or unsetting) sequential consistency can also be done at task level by setting the field `starpu_task::sequential_consistency` to 0. Sequential consistency can also be set (or unset) for each handle of a specific task, this is done by using the field `starpu_task::handles_sequential_consistency`. When set, its value should be a array with the number of elements being the number of handles for the task, each element of the array being the sequential consistency for the i-th
handle of the task. The field can easily be set when calling `starpu_task_insert()` with the flag `STARPU_HANDLE_S_SEQUENTIAL_CONSISTENCY`.

```c
char *seq_consistency = malloc(cl.nbuffers * sizeof(char));
seq_consistency[0] = 1;
seq_consistency[1] = 1;
seq_consistency[2] = 0;
ret = starpu_task_insert(&cl,
                    STARPU_RW, handleA, STARPU_RW, handleB, STARPU_RW, handleC,
                    STARPU_HANDLES_SEQUENTIAL_CONSISTENCY, seq_consistency,
                    0);
free(seq_consistency);
```

The internal algorithm used by StarPU to set up implicit dependency is as follows:

```c
if (sequential_consistency(task) == 1)
  for(i=0 ; i<STARPU_TASK_GET_NBUFFERS(task) ; i++)
    if (sequential_consistency(i-th data, task) == 1)
      if (sequential_consistency(i-th data) == 1)
        create_implicit_dependency(...)
```

### 6.4.2 Tasks And Tags Dependencies

One can explicitly set dependencies between tasks using `starpu_task_declare_deps()` or `starpu_task_declare_deps_array()`. Dependencies between tasks can be expressed through tags associated to a tag with the field `starpu_task::tag_id` and using the function `starpu_tag_declare_deps()` or `starpu_tag_declare_deps_array()`. The termination of a task can be delayed through the function `starpu_task_end_dep_add()` which specifies the number of calls to the function `starpu_task_end_dep_release()` needed to trigger the task termination. One can also use `starpu_task_declare_end_deps()` or `starpu_task_declare_end_deps_array()` to delay the termination of a task until the termination of other tasks.

### 6.5 Setting Many Data Handles For a Task

The maximum number of data a task can manage is fixed by the environment variable `STARPU_NMAXBUFS` which has a default value which can be changed through the `configure` option `--enable-maxbuffers`. However, it is possible to define tasks managing more data by using the field `starpu_task::dyn_handles` when defining a task and the field `starpu_codelet::dyn_modes` when defining the corresponding codelet.

```c
codelet struct dummy_big_cl =
{
  .cuda_funcs = { dummy_big_kernel },
  .opencl_funcs = { dummy_big_kernel },
  .cpu_funcs = { dummy_big_kernel },
  .cpu_funcs_name = { "dummy_big_kernel" },
  .nbuffers = STARPU_NMAXBUFS+1,
  .dyn_modes = modes
};
```

```c
for(i=0 ; i<dummy_big_cl.nbuffers ; i++)
  handles[i] = handle;
```

The whole code for this complex data interface is available in the directory `examples/basic_dynamic_handles.c`.

---

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6.6 Setting a Variable Number Of Data Handles For a Task

Normally, the number of data handles given to a task is fixed in the `starpu_codelet::nbuffers` codelet field. This field can however be set to `STARPU_VARIABLE_NBUFFERS`, in which case the `starpu_task::nbuffers` task field must be set, and the `starpu_task::modes` field (or `starpu_task::dyn_modes` field, see Setting Many Data Handles For a Task) should be used to specify the modes for the handles.

6.7 Using Multiple Implementations Of A Codelet

One may want to write multiple implementations of a codelet for a single type of device and let StarPU choose which one to run. As an example, we will show how to use SSE to scale a vector. The codelet can be written as follows:

```c
#include <xmmintrin.h>

void scal_sse_func(void *buffers[], void *cl_arg)
{
    float *vector = (float *) STARPU_VECTOR_GET_PTR(buffers[0]);
    unsigned int n = STARPU_VECTOR_GET_NX(buffers[0]);
    unsigned int n_iterations = n/4;
    if (n % 4 != 0)
        n_iterations++;

    __m128 *VECTOR = (__m128*) vector;
    __m128 factor __attribute__((aligned(16)));
    factor = _mm_set1_ps(*(float *) cl_arg);

    unsigned int i;
    for (i = 0; i < n_iterations; i++)
        VECTOR[i] = _mm_mul_ps(factor, VECTOR[i]);
}
```

```c
struct starpu_codelet cl =
{
    .cpu_funcs = { scal_cpu_func, scal_sse_func },
    .cpu_funcs_name = { "scal_cpu_func", "scal_sse_func" },
    .nbuffers = 1,
    .modes = { STARPU_RW }
};
```

Schedulers which are multi-implementation aware (only dmda and pheft for now) will use the performance models of all the implementations it was given, and pick the one which seems to be the fastest.

6.8 Enabling Implementation According To Capabilities

Some implementations may not run on some devices. For instance, some CUDA devices do not support double floating point precision, and thus the kernel execution would just fail; or the device may not have enough shared memory for the implementation being used. The field `starpu_codelet::can_execute` permits to express this. For instance:

```c
static int can_execute(unsigned workerid, struct starpu_task *task, unsigned nimpl)
{
    const struct cudaDeviceProp *props;
    if (starpu_worker_get_type(workerid) == STARPU_CPU_WORKER)
        return 1;
    /* Cuda device */
    props = starpu_cuda_get_device_properties(workerid);
    if (props->major >= 2 || props->minor >= 3)
        /* At least compute capability 1.3, supports doubles */
        return 1;
    /* Old card, does not support doubles */
    return 0;
}
```

```c
struct starpu_codelet cl =
{
    .can_execute = can_execute,
    .cpu_funcs = { cpu_func },
    .cpu_funcs_name = { "cpu_func" },
    .cuda_funcs = { gpu_func },
    .nbuffers = 1,
    .modes = { STARPU_RW }
};
```

This can be essential e.g. when running on a machine which mixes various models of CUDA devices, to take benefit from the new models without crashing on old models.
Note: the function `starpu_codelet::can_execute` is called by the scheduler each time it tries to match a task with a worker, and should thus be very fast. The function `starpu_cuda_get_device_properties()` provides a quick access to CUDA properties of CUDA devices to achieve such efficiency.

Another example is to compile CUDA code for various compute capabilities, resulting with two CUDA functions, e.g. `scal_gpu_13` for compute capability 1.3, and `scal_gpu_20` for compute capability 2.0. Both functions can be provided to StarPU by using `starpu_codelet::cuda_funcs`, and `starpu_codelet::can_execute` can then be used to rule out the `scal_gpu_20` variant on a CUDA device which will not be able to execute it:

```c
static int can_execute(unsigned workerid, struct starpu_task *task, unsigned nimpl)
{
    const struct cudaDeviceProp *props;
    if (starpu_worker_get_type(workerid) == STARPU_CPU_WORKER)
        return 1;
    /* Cuda device */
    if (nimpl == 0)
        /* Trying to execute the 1.3 capability variant, we assume it is ok in all cases. */
        return 1;
    /* Trying to execute the 2.0 capability variant, check that the card can do it. */
    props = starpu_cuda_get_device_properties(workerid);
    if (props->major == 2 || props->minor > 0)
        /* At least compute capability 2.0, can run it */
        return 1;
    /* Old card, does not support 2.0, will not be able to execute the 2.0 variant. */
    return 0;
}

struct starpu_codelet cl =
{
    .can_execute = can_execute,
    .cpu_funcs = { cpu_func },
    .cpu_funcs_name = { "cpu_func" },
    .cuda_funcs = { scal_gpu_13, scal_gpu_20 },
    .nbuffers = 1,
    .modes = { STARPU_RW }
};
```

Another example is having specialized implementations for some given common sizes, for instance here we have a specialized implementation for 1024x1024 matrices:

```c
static int can_execute(unsigned workerid, struct starpu_task *task, unsigned nimpl)
{
    const struct cudaDeviceProp *props;
    if (starpu_worker_get_type(workerid) == STARPU_CPU_WORKER)
        return 1;
    /* Cuda device */
    switch (nimpl)
    {
        case 0:
            /* Trying to execute the generic capability variant. */
            return 1;
        case 1:
            /* Trying to execute the size == 1024 specific variant. */
            struct starpu_matrix_interface *interface = starpu_data_get_interface_on_node
                (task->handles[0]);
            return STARPU_MATRIX_GET_NX(interface) == 1024 && STARPU_MATRIX_GET_NY
                (interface) == 1024;
    }
}

struct starpu_codelet cl =
{
    .can_execute = can_execute,
    .cpu_funcs = { cpu_func },
    .cpu_funcs_name = { "cpu_func" },
    .cuda_funcs = { potrf_gpu_generic, potrf_gpu_1024 },
    .nbuffers = 1,
    .modes = { STARPU_RW }
};
```

Note: the most generic variant should be provided first, as some schedulers are not able to try the different variants.

### 6.9 Insert Task Utility

StarPU provides the wrapper function `starpu_task_insert()` to ease the creation and submission of tasks. Here the implementation of the codelet:

```c
Generated by Doxygen
```
6.9 Insert Task Utility

```c
void func_cpu(void *descr[], void *_args)
{
    int *x0 = (int *)STARPU_VARIABLE_GET_PTR(descr[0]);
    float *x1 = (float *)STARPU_VARIABLE_GET_PTR(descr[1]);
    int ifactor;
    float ffactor;
    starpu_codelet_unpack_args(_args, &ifactor, &ffactor);
    *x0 = *x0 * ifactor;
    *x1 = *x1 * ffactor;
}
```

```c
struct starpu_codelet mycodelet =
{
    .cpu_funcs = { func_cpu },
    .cpu_funcs_name = { "func_cpu" },
    .nbuffers = 2,
    .modes = { STARPU_RW, STARPU_RW }
};
```

And the call to the function `starpu_task_insert()`:

```c
starpu_task_insert(&mycodelet,
    STARPU_VALUE, &ifactor, sizeof(ifactor),
    STARPU_VALUE, &ffactor, sizeof(ffactor),
    STARPU_RW, data_handles[0],
    STARPU_RW, data_handles[1],
    0);
```

The call to `starpu_task_insert()` is equivalent to the following code:

```c
struct starpu_task *task = starpu_task_create();
task->cl = &mycodelet;
for (i = 0; i < 2; i++)
    task->handles[i] = data_handles[i];
char *arg_buffer;
size_t arg_buffer_size;
starpu_codelet_pack_args(&arg_buffer, &arg_buffer_size,
    STARPU_VALUE, &ifactor, sizeof(ifactor),
    STARPU_VALUE, &ffactor, sizeof(ffactor),
    0);
```

```c
int ret = starpu_task_submit(task);
```

Here a similar call using `::STARPU_DATA_ARRAY`:

```c
starpu_task_insert(&mycodelet,
    STARPU_DATA_ARRAY, data_handles, 2,
    STARPU_VALUE, &ifactor, sizeof(ifactor),
    STARPU_VALUE, &ffactor, sizeof(ffactor),
    0);
```

If some part of the task insertion depends on the value of some computation, the macro `STARPU_DATA_ACQUIRE_CB` can be very convenient. For instance, assuming that the index variable `i` was registered as handle `A_handle[i]`:

```c
/* Compute which portion we will work on, e.g. pivot */
starpu_task_insert(which_index, STARPU_R, i_handle, 0);
/* And submit the corresponding task */
STARPU_DATA_ACQUIRE_CB(i_handle, STARPU_R,
    starpu_task_insert(work, STARPU_RW, A_handle[i], 0));
```

The macro `STARPU_DATA_ACQUIRE_CB` submits an asynchronous request for acquiring data `i` for the main application, and will execute the code given as third parameter when it is acquired. In other words, as soon as the value of `i` computed by the codelet `which_index` can be read, the portion of code passed as third parameter of `STARPU_DATA_ACQUIRE_CB` will be executed, and is allowed to read from `i` to use it e.g. as an index. Note that this macro is only available when compiling StarPU with the compiler `gcc`.

StarPU also provides a utility function `starpu_codelet_unpack_args()` to retrieve the `STARPU_VALUE` arguments passed to the task. There is several ways of calling this function `starpu_codelet_unpack_args()`.

```c
void func_cpu(void *descr[], void *_args)
{
    int ifactor;
    float ffactor;
    starpu_codelet_unpack_args(_args, &ifactor, &ffactor);
}
```
void func_cpu(void *descr[], void *_args)
{
    int ifactor;
    float ffactor;

    starpu_codelet_unpack_args(_args, &ifactor, 0);
    starpu_codelet_unpack_args(_args, &ifactor, &ffactor);
}

void func_cpu(void *descr[], void *_args)
{
    int ifactor;
    float ffactor;
    char buffer[100];

    starpu_codelet_unpack_args_and_copyleft(_args, buffer, 100, &ifactor, 0);
    starpu_codelet_unpack_args(buffer, &ffactor);
}

6.10 Getting Task Children

It may be interesting to get the list of tasks which depend on a given task, notably when using implicit dependencies, since this list is computed by StarPU. starpu_task_get_task_succs() provides it. For instance:

```c
struct starpu_task *tasks[4];
ret = starpu_task_get_task_succs(task, sizeof(tasks)/sizeof(*tasks), tasks);
```

6.11 Parallel Tasks

StarPU can leverage existing parallel computation libraries by the means of parallel tasks. A parallel task is a task which gets worked on by a set of CPUs (called a parallel or combined worker) at the same time, by using an existing parallel CPU implementation of the computation to be achieved. This can also be useful to improve the load balance between slow CPUs and fast GPUs: since CPUs work collectively on a single task, the completion time of tasks on CPUs become comparable to the completion time on GPUs, thus relieving from granularity discrepancy concerns. hwloc support needs to be enabled to get good performance, otherwise StarPU will not know how to better group cores.

Two modes of execution exist to accomodate with existing usages.

6.11.1 Fork-mode Parallel Tasks

In the Fork mode, StarPU will call the codelet function on one of the CPUs of the combined worker. The codelet function can use starpu_combined_worker_get_size() to get the number of threads it is allowed to start to achieve the computation. The CPU binding mask for the whole set of CPUs is already enforced, so that threads created by the function will inherit the mask, and thus execute where StarPU expected, the OS being in charge of choosing how to schedule threads on the corresponding CPUs. The application can also choose to bind threads by hand, using e.g. sched_getaffinity to know the CPU binding mask that StarPU chose.

For instance, using OpenMP (full source is available in examples/openmp/vector_scal.c):

```c
void scal_cpu_func(void *buffers[], void *args)
{
    unsigned i;
    float *factor = args;
    struct starpu_vector_interface *vector = buffers[0];
    unsigned n = STARPU_VECTOR_GET_N(vector);
    float *val = (float *)STARPU_VECTOR_GET_PTR(vector);

    #pragma omp parallel for num_threads(starpu_combined_worker_get_size())
    for (i = 0; i < n; i++)
        val[i] *= *factor;
}

static struct starpu_codelet cl =
{
    .modes = { STARPU_RW },
    .where = STARPU_CPU,
    .type = STARPU_FORKJOIN,
    .max_parallelism = INT_MAX,
    .cpu_funcs = {scal_cpu_func},
    .cpu_funcs_name = {"scal_cpu_func"},
    .nbuffers = 1,
};
```
Other examples include for instance calling a BLAS parallel CPU implementation (see examples/mult/xgemm.c).

### 6.11.2 SPMD-mode Parallel Tasks

In the SPMD mode, StarPU will call the codelet function on each CPU of the combined worker. The codelet function can use \texttt{starpu\_combined\_worker\_get\_size()} to get the total number of CPUs involved in the combined worker, and thus the number of calls that are made in parallel to the function, and \texttt{starpu\_combined\_worker\_get\_rank()} to get the rank of the current CPU within the combined worker. For instance:

```c
static void func(void *buffers[], void *args)
{
    unsigned i;
    float *factor = _args;
    struct starpu\_vector\_interface *vector = buffers[0];
    unsigned n = STARPU\_VECTOR\_GET\_NX(vector);
    float *val = (float *)STARPU\_VECTOR\_GET\_PTR(vector);

    /* Compute slice to compute */
    unsigned m = starpu\_combined\_worker\_get\_size();
    unsigned j = starpu\_combined\_worker\_get\_rank();
    unsigned slice = (n+m-1)/m;

    for (i = j * slice; i < (j+1) * slice && i < n; i++)
        val[i] *= *factor;
}
```

Of course, this trivial example will not really benefit from parallel task execution, and was only meant to be simple to understand. The benefit comes when the computation to be done is so that threads have to e.g. exchange intermediate results, or write to the data in a complex but safe way in the same buffer.

### 6.11.3 Parallel Tasks Performance

To benefit from parallel tasks, a parallel-task-aware StarPU scheduler has to be used. When exposed to codelets with a flag \texttt{STARPU\_FORKJOIN} or \texttt{STARPU\_SPMD}, the schedulers \texttt{pheft} (parallel-heft) and \texttt{peager} (parallel eager) will indeed also try to execute tasks with several CPUs. It will automatically try the various available combined worker sizes (making several measurements for each worker size) and thus be able to avoid choosing a large combined worker if the codelet does not actually scale so much.

### 6.11.4 Combined Workers

By default, StarPU creates combined workers according to the architecture structure as detected by \texttt{hwloc}. It means that for each object of the \texttt{hwloc} topology (NUMA node, socket, cache, ...) a combined worker will be created. If some nodes of the hierarchy have a big arity (e.g. many cores in a socket without a hierarchy of shared caches), StarPU will create combined workers of intermediate sizes. The variable \texttt{STARPU\_SYNTHESIZE\_ARYTY\_COMBINED\_WORKER} permits to tune the maximum arity between levels of combined workers.

The combined workers actually produced can be seen in the output of the tool \texttt{starpu\_machine\_display} (the environment variable \texttt{STARPU\_SCHED} has to be set to a combined worker-aware scheduler such as \texttt{pheft} or \texttt{peager}).

### 6.11.5 Concurrent Parallel Tasks

Unfortunately, many environments and libraries do not support concurrent calls. For instance, most OpenMP implementations (including the main ones) do not support concurrent \texttt{pragma omp parallel} statements without nesting them in another \texttt{pragma omp parallel} statement, but StarPU does not yet support creating its CPU workers by using such pragma.

Other parallel libraries are also not safe when being invoked concurrently from different threads, due to the use of global variables in their sequential sections for instance.

---

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The solution is then to use only one combined worker at a time. This can be done by setting the field `starpu_conf::single_combined_worker` to 1, or setting the environment variable `STARPU_SINGLE_COMBINED_WORKER` to 1. StarPU will then run only one parallel task at a time (but other CPU and GPU tasks are not affected and can be run concurrently). The parallel task scheduler will however still try varying combined worker sizes to look for the most efficient ones.

### 6.11.6 Synchronization Tasks

For the application conveniency, it may be useful to define tasks which do not actually make any computation, but wear for instance dependencies between other tasks or tags, or to be submitted in callbacks, etc.

The obvious way is of course to make kernel functions empty, but such task will thus have to wait for a worker to become ready, transfer data, etc.

A much lighter way to define a synchronization task is to set its `starpu_task::cl` field to `NULL`. The task will thus be a mere synchronization point, without any data access or execution content: as soon as its dependencies become available, it will terminate, call the callbacks, and release dependencies.

An intermediate solution is to define a codelet with its `starpu_codelet::where` field set to `STARPU_NOWHERE`, for instance:

```c
struct starpu_codelet cl =
{
    .where = STARPU_NOWHERE,
    .nbuffers = 1,
    .modes = { STARPU_R },
}

task = starpu_task_create();
task->cl = &cl;
task->handles[0] = handle;
starpu_task_submit(task);
```

will create a task which simply waits for the value of `handle` to be available for read. This task can then be depended on, etc.
Chapter 7

Data Management

TODO: intro which mentions consistency among other things

7.1 Data Interface

StarPU provides several data interfaces for programmers to describe the data layout of their application. There are predefined interfaces already available in StarPU. Users can define new data interfaces as explained in Defining A New Data Interface. All functions provided by StarPU are documented in Data Interfaces. You will find a short list below.

7.1.1 Variable Data Interface

A variable is a given size byte element, typically a scalar. Here an example of how to register a variable data to StarPU by using starpu_variable_data_register().

```c
float var = 42.0;
starpu_data_handle_t var_handle;
starpu_variable_data_register(&var_handle, STARPU_MAIN_RAM, (uintptr_t)&var, sizeof(var));
```

7.1.2 Vector Data Interface

A vector is a fixed number of elements of a given size. Here an example of how to register a vector data to StarPU by using starpu_vector_data_register().

```c
float vector[NX];
starpu_data_handle_t vector_handle;
starpu_vector_data_register(&vector_handle, STARPU_MAIN_RAM, (uintptr_t)vector, NX, sizeof(vector[0]));
```

7.1.3 Matrix Data Interface

To register 2-D matrices with a potential padding, one can use the matrix data interface. Here an example of how to register a matrix data to StarPU by using starpu_matrix_data_register().

```c
float *matrix;
starpu_data_handle_t matrix_handle;
matrix = (float*)malloc(width * height * sizeof(float));
starpu_matrix_data_register(&matrix_handle, STARPU_MAIN_RAM, (uintptr_t)matrix, width, width, height, sizeof(float));
```

7.1.4 Block Data Interface

To register 3-D blocks with potential paddings on Y and Z dimensions, one can use the block data interface. Here an example of how to register a block data to StarPU by using starpu_block_data_register().

```c
float *block;
starpu_data_handle_t block_handle;
block = (float*)malloc(nx*ny*nz*sizeof(float));
starpu_block_data_register(&block_handle, STARPU_MAIN_RAM, (uintptr_t)block, nx, nx*ny, nx, ny, nz, sizeof(float));
```
7.1.5 BCSR Data Interface

BCSR (Blocked Compressed Sparse Row Representation) sparse matrix data can be registered to StarPU using the bcsr data interface. Here an example on how to do so by using starpu_bcsr_data_register().

```c
/*
 * We use the following matrix:
 * +----------------+
 * | 0 1 0 0 |
 * | 2 3 0 0 |
 * | 4 5 8 9 |
 * | 6 7 10 11 |
 * +----------------+

 * nzval = [0, 1, 2, 3] ++ [4, 5, 6, 7] ++ [8, 9, 10, 11]
 * colind = [0, 0, 1]
 * rowptr = [0, 1, 3]
 * r = c = 2
 */

/* Size of the blocks */
int R = 2;
int C = 2;

int NROWS = 2;
int NNZ_BLOCKS = 3; /* out of 4 */
int NZVAL_SIZE = (R*C*NNZ_BLOCKS);

int nzval[NZVAL_SIZE] =
{ 0, 1, 2, 3, /* First block */
  4, 5, 6, 7, /* Second block */
  8, 9, 10, 11 / * Third block */
};

uint32_t colind[NNZ_BLOCKS] =
{ 0, /* block-column index for first block in nzval */
  0, /* block-column index for second block in nzval */
  1 /* block-column index for third block in nzval */
};

uint32_t rowptr[NROWS+1] =
{ 0, /* block-index in nzval of the first block of the first row. */
  1, /* block-index in nzval of the first block of the second row. */
  NNZ_BLOCKS /* number of blocks, to allow an easier element’s access for the kernels */
};

starpu_data_handle_t bcsr_handle;
starpu_bcsr_data_register(&bcsr_handle,
    STARPU_MAIN_RAM,
    STARPU_MAIN_RAM,
    NNZ_BLOCKS,
    NROWS,
    (uintptr_t) nzval,
    colind,
    rowptr,
    0, /* firstentry */
    R,
    C,
    sizeof(nzval[0]));
```

StarPU provides an example on how to deal with such matrices in examples/spmv.

7.1.6 CSR Data Interface

TODO

7.1.7 Data Interface with Variable Size

Tasks are actually allowed to change the size of data interfaces. The simplest case is changing the amount of data actually used within the allocated buffer. This is for instance implemented for the matrix interface: one can set the new NX/NY values with STARPU_MATRIX_SET_NX(), STARPU_MATRIX_SET_NY(), and STARPU_MATRIX_SET_LD() at the end of the task implementation. Data transfers achieved by StarPU will then use these values instead of the whole allocated size. The values of course need to be set within the original allocation. To reserve room for increasing the NX/NY values, one can use starpu_matrix_data_register_allocsize() instead of starpu_matrix_data_register(), to specify the allocation size to be used instead of the default NX*NY*ELEMSIZE. To support this, the data interface has to implement the starpu_data
interface_ops::alloc_footprint and starpu_data_interface_ops::alloc_compare methods, for proper StarPU allocation management.

A more involved case is changing the amount of allocated data. The task implementation can just reallocate the buffer during its execution, and set the proper new values in the interface structure, e.g. nx, ny, ld, etc. so that the StarPU core knows the new data layout. The starpu_data_interface_ops structure however then needs to have the starpu_data_interface_ops::dontcache field set to 1, to prevent StarPU from trying to perform any cached allocation, since the allocated size will vary. An example is available in tests/datawizard/variable_size.c

7.2 Data Management

When the application allocates data, whenever possible it should use the starpu_malloc() function, which will ask CUDA or OpenCL to make the allocation itself and pin the corresponding allocated memory, or to use the starpu←_memory_pin() function to pin memory allocated by other ways, such as local arrays. This is needed to permit asynchronous data transfer, i.e. permit data transfer to overlap with computations. Otherwise, the trace will show that the DriverCopyAsync state takes a lot of time, this is because CUDA or OpenCL then reverts to synchronous transfers.

The application can provide its own allocation function by calling starpu_malloc_set_hooks(). StarPU will then use them for all data handle allocations in the main memory.

By default, StarPU leaves replicates of data wherever they were used, in case they will be re-used by other tasks, thus saving the data transfer time. When some task modifies some data, all the other replicates are invalidated, and only the processing unit which ran this task will have a valid replicate of the data. If the application knows that this data will not be re-used by further tasks, it should advise StarPU to immediately replicate it to a desired list of memory nodes (given through a bitmask). This can be understood like the write-through mode of CPU caches.

starpu_data_set_wt_mask(img_handle, 1<<0);

will for instance request to always automatically transfer a replicate into the main memory (node 0), as bit 0 of the write-through bitmask is being set.

starpu_data_set_wt_mask(img_handle, ~0U);

will request to always automatically broadcast the updated data to all memory nodes.

Setting the write-through mask to ~0U can also be useful to make sure all memory nodes always have a copy of the data, so that it is never evicted when memory gets scarce.

Implicit data dependency computation can become expensive if a lot of tasks access the same piece of data. If no dependency is required on some piece of data (e.g. because it is only accessed in read-only mode, or because write accesses are actually commutative), use the function starpu_data_set_sequential_consistency_flag() to disable implicit dependencies on this data.

In the same vein, accumulation of results in the same data can become a bottleneck. The use of the mode STA←RPU_REDUX permits to optimize such accumulation (see Data Reduction). To a lesser extent, the use of the flag STARPU_COMMUTE keeps the bottleneck (see Commute Data Access), but at least permits the accumulation to happen in any order.

Applications often need a data just for temporary results. In such a case, registration can be made without an initial value, for instance this produces a vector data:

starpu_vector_data_register(&handle, -1, 0, n, sizeof(float));

StarPU will then allocate the actual buffer only when it is actually needed, e.g. directly on the GPU without allocating in main memory.

In the same vein, once the temporary results are not useful any more, the data should be thrown away. If the handle is not to be reused, it can be unregistered:

starpu_data_unregister_submit(handle);

actual unregistration will be done after all tasks working on the handle terminate.

If the handle is to be reused, instead of unregistering it, it can simply be invalidated:

starpu_data_invalidate_submit(handle);

the buffers containing the current value will then be freed, and reallocated only when another task writes some value to the handle.
7.3 Data Prefetch

The scheduling policies heft, dmda, and pheft perform data prefetch (see STARPU_PREFETCH): as soon as a scheduling decision is taken for a task, requests are issued to transfer its required data to the target processing unit, if needed, so that when the processing unit actually starts the task, its data will hopefully be already available and it will not have to wait for the transfer to finish.

The application may want to perform some manual prefetching, for several reasons such as excluding initial data transfers from performance measurements, or setting up an initial statically-computed data distribution on the machine before submitting tasks, which will thus guide StarPU toward an initial task distribution (since StarPU will try to avoid further transfers).

This can be achieved by giving the function starpu_data_prefetch_on_node() the handle and the desired target memory node. The starpu_data_idle_prefetch_on_node() variant can be used to issue the transfer only when the bus is idle.

Conversely, one can advise StarPU that some data will not be useful in the close future by calling starpu_data_wont_use(). StarPU will then write its value back to its home node, and evict it from GPUs when room is needed.

7.4 Partitioning Data

An existing piece of data can be partitioned in sub parts to be used by different tasks, for instance:

```c
#define NX 1048576
#define PARTS 16
int vector[NX];
starpu_data_handle_t handle;

// Declare data to StarPU */
starpu_vector_data_register(&handle, STARPU_MAIN_RAM, (uintptr_t)
 vector, NX, sizeof(vector[0]));

// Partition the vector in PARTS sub-vectors */
struct starpu_data_filter f =
    {
        .filter_func = starpu_vector_filter_block,
        .nchildren = PARTS
    };
starpu_data_partition(handle, &f);
```

The task submission then uses the function starpu_data_get_sub_data() to retrieve the sub-handles to be passed as tasks parameters.

```c
/* Submit a task on each sub-vector */
for (i=0; i<starpu_data_get_nb_children(handle); i++)
{
    /* Get subdata number i (there is only 1 dimension) */
    starpu_data_handle_t sub_handle = starpu_data_get_sub_data{
        handle, 1, i};
    struct starpu_task *task = starpu_task_create();
    task->handles[0] = sub_handle;
    task->cl = &cl;
    task->synchronous = 1;
    task->cl_arg = &factor;
    task->cl_arg_size = sizeof(factor);
    starpu_task_submit(task);
}
```

Partitioning can be applied several times, see examples/basic_examples/mult.c and examples/filters/.

Wherever the whole piece of data is already available, the partitioning will be done in-place, i.e. without allocating new buffers but just using pointers inside the existing copy. This is particularly important to be aware of when using OpenCL, where the kernel parameters are not pointers, but cl_mem handles. The kernel thus needs to be also passed the offset within the OpenCL buffer:

```c
void opencl_func(void *buffers[], void *cl_arg)
{
    cl_mem vector = (cl_mem) STARPU_VECTOR_GET_DEV_HANDLE(buffers[0]);
    unsigned offset = STARPU_BLOCK_GET_OFFSET(buffers[0]);
    ...
    clSetKernelArg(kernel, 0, sizeof(vector), &vector);
    clSetKernelArg(kernel, 1, sizeof(offset), &offset);
    ...
}
```
And the kernel has to shift from the pointer passed by the OpenCL driver:

```c
__kernel void opencl_kernel(__global int *vector, unsigned offset)
{
    block = (__global void *)block + offset;
    ...
}
```

When the sub-data is not of the same type as the original data, the `starpu_data_filter::get_child_ops` field needs to be set appropriately for StarPU to know which type should be used. StarPU provides various interfaces and filters for matrices, vectors, etc., but applications can also write their own data interfaces and filters, see examples/interface and examples/filters/custom_mf for an example, and see Defining A New Data Interface and Defining A New Data Filter for documentation.

### 7.5 Asynchronous Partitioning

The partitioning functions described in the previous section are synchronous: `starpu_data_partition()` and `starpu_data_unpartition()` both wait for all the tasks currently working on the data. This can be a bottleneck for the application.

An asynchronous API also exists, it works only on handles with sequential consistency. The principle is to first plan the partitioning, which returns data handles of the partition, which are not functional yet. When submitting tasks, one can mix using the handles of the partition, of the whole data. One can even partition recursively and mix using handles at different levels of the recursion. Of course, StarPU will have to introduce coherency synchronization.

`fmultiple_submit_implicit` is a complete example using this technique. One can also look at `fmultiple_submit_readonly` which contains the explicit coherency synchronization which are automatically introduced by StarPU for `fmultiple_submit_implicit`.

In short, we first register a matrix and plan the partitioning:

```c
cstruct starpu_data_filter f_vert =
{   .filter_func = starpu_matrix_filter_block,
    .nchildren = PARTS
};;
starpu_data_partition_plan(handle, &f_vert, vert_handle);
```

`starpu_data_partition_plan()` returns the handles for the partition in `vert_handle`. One can then submit tasks working on the main handle, and tasks working on `vert_handle` handles. Between using the main handle and `vert_handle` handles, StarPU will automatically call `starpu_data_partition_submit()` and `starpu_data_unpartition_submit()`.

All this code is asynchronous, just submitting which tasks, partitioning and unpartitioning will be done at runtime. Planning several partitioning of the same data is also possible, StarPU will unpartition and repartition as needed when mixing accesses of different partitions. If data access is done in read-only mode, StarPU will allow the different partitioning to coexist. As soon as a data is accessed in read-write mode, StarPU will automatically unpartition everything and activate only the partitioning leading to the data being written to.

For instance, for a stencil application, one can split a subdomain into its interior and halos, and then just submit a task updating the whole subdomain, then submit MPI sends/receives to update the halos, then submit again a task updating the whole subdomain, etc. and StarPU will automatically partition/unpartition each time.

### 7.6 Manual Partitioning

One can also handle partitioning by hand, by registering several views on the same piece of data. The idea is then to manage the coherency of the various views through the common buffer in the main memory. `fmultiple_manual` is a complete example using this technique.

In short, we first register the same matrix several times:

```c
for (i = 0; i < PARTS; i++)
    starpu_matrix_data_register(&vert_handle[i], STARPU_MAIN_RAM, nx, nx, ny, sizeof(matrix[0][0]));
```

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Since StarPU is not aware that the two handles are actually pointing to the same data, we have a danger of inadvertently submitting tasks to both views, which will bring a mess since StarPU will not guarantee any coherency between the two views. To make sure we don't do this, we invalidate the view that we will not use:

```c
for (i = 0; i < PARTS; i++)
    starpu_data_invalidate(vert_handle[i]);
```

Then we can safely work on `handle`.

When we want to switch to the vertical slice view, all we need to do is bring coherency between them by running an empty task on the home node of the data:

```c
void empty(void *buffers[], void *cl_arg)
{
}
struct starpu_codelet cl_switch =
{
    .cpu_funcs = {empty},
    .nbuffers = STARPU_VARIABLE_NBUFFERS,
};
ret = starpu_task_insert(&cl_switch, STARPU_RW, handle,
    STARPU_W, vert_handle[0],
    STARPU_W, vert_handle[1],
    0);
```

The execution of the `switch` task will get back the matrix data into the main memory, and thus the vertical slices will get the updated value there.

Again, we prefer to make sure that we don't accidentally access the matrix through the whole-matrix handle:

```c
starpu_data_invalidate_submit(handle);
```

And now we can start using vertical slices, etc.

### 7.7 Defining A New Data Filter

StarPU provides a series of predefined filters in Data Partition, but additional filters can be defined by the application. The principle is that the filter function just fills the memory location of the `i`-th subpart of a data. Examples are provided in `src/datawizard/interfaces/*_filters.c`, and see `starpu_data_filter::filter_func` for the details. The `starpu_filter_nparts_compute_chunk_size_and_offset()` helper can be used to compute the division of pieces of data.

### 7.8 Data Reduction

In various cases, some piece of data is used to accumulate intermediate results. For instances, the dot product of a vector, maximum/minimum finding, the histogram of a photograph, etc. When these results are produced along the whole machine, it would not be efficient to accumulate them in only one place, incurring data transmission each and access concurrency.

StarPU provides a mode `STARPU_REDUX`, which permits to optimize this case: it will allocate a buffer on each memory node, and accumulate intermediate results there. When the data is eventually accessed in the normal mode `STARPU_R`, StarPU will collect the intermediate results in just one buffer.

For this to work, the user has to use the function `starpu_data_set_reduction_methods()` to declare how to initialize these buffers, and how to assemble partial results.

For instance, `cg` uses that to optimize its dot product: it first defines the codelets for initialization and reduction:

```c
struct starpu_codelet bzero_variable_cl =
{
    .cpu_funcs = { bzero_variable_cpu },
    .cpu_funcs_name = { "bzero_variable_cpu" },
    .cuda_funcs = { bzero_variable_cuda },
    .nbuffers = 1,
};
static void accumulate_variable_cpu(void *descr[], void *cl_arg)
{
    double *v_dst = (double *)STARPU_VARIABLE_GET_PTR(descr[0]);
    double *v_src = (double *)STARPU_VARIABLE_GET_PTR(descr[1]);
    *v_dst = *v_dst + *v_src;
}
static void accumulate_variable_cuda(void *descr[], void *cl_arg)
```
7.9 Commute Data Access

By default, the implicit dependencies computed from data access use the sequential semantic. Notably, write accesses are always serialized in the order of submission. In some applicative cases, the write contributions can actually be performed in any order without affecting the eventual result. In this case it is useful to drop the strictly sequential semantic, to improve parallelism by allowing StarPU to reorder the write accesses. This can be done by using the STARPU_COMMUTE data access flag. Accesses without this flag will however properly be serialized against accesses with this flag. For instance:

```c
starpu_task_insert(&cl1, STARPU_R, h, STARPU_RW, handle, 0);
starpu_task_insert(&cl2, STARPU_R, handle1, STARPU_RW|STARPU_COMMUTE, handle, 0);
starpu_task_insert(&cl2, STARPU_R, handle2, STARPU_RW|STARPU_COMMUTE, handle, 0);
starpu_task_insert(&cl3, STARPU_R, g, STARPU_RW, handle, 0);
```

The two tasks running `cl2` will be able to commute: depending on whether the value of `handle1` or `handle2` becomes available first, the corresponding task running `cl2` will start first. The task running `cl1` will however always be run before them, and the task running `cl3` will always be run after them.

If a lot of tasks use the commute access on the same set of data and a lot of them are ready at the same time, it may become interesting to use an arbiter, see Concurrent Data Accesses.
7.10 Concurrent Data Accesses

When several tasks are ready and will work on several data, StarPU is faced with the classical Dining Philosophers problem, and has to determine the order in which it will run the tasks. Data accesses usually use sequential ordering, so data accesses are usually already serialized, and thus by default StarPU uses the Dijkstra solution which scales very well in terms of overhead: tasks will just acquire data one by one by data handle pointer value order.

When sequential ordering is disabled or the STARPU_COMMUTE flag is used, there may be a lot of concurrent accesses to the same data, and the Dijkstra solution gets only poor parallelism, typically in some pathological cases which do happen in various applications. In this case, one can use a data access arbiter, which implements the classical centralized solution for the Dining Philosophers problem. This is more expensive in terms of overhead since it is centralized, but it opportunistically gets a lot of parallelism. The centralization can also be avoided by using several arbiters, thus separating sets of data for which arbitration will be done. If a task accesses data from different arbiters, it will acquire them arbiter by arbiter, in arbiter pointer value order.

See the tests/datawizard/test_arbiter.cpp example.

Arbiters however do not support the STARPU_REDUX flag yet.

7.11 Temporary Buffers

There are two kinds of temporary buffers: temporary data which just pass results from a task to another, and scratch data which are needed only internally by tasks.

7.11.1 Temporary Data

Data can sometimes be entirely produced by a task, and entirely consumed by another task, without the need for other parts of the application to access it. In such case, registration can be done without prior allocation, by using the special memory node number $-1$, and passing a zero pointer. StarPU will actually allocate memory only when the task creating the content gets scheduled, and destroy it on unregistration.

In addition to this, it can be tedious for the application to have to unregister the data, since it will not use its content anyway. The unregistration can be done lazily by using the function starpu_data_unregisterSubmit(), which will record that no more tasks accessing the handle will be submitted, so that it can be freed as soon as the last task accessing it is over.

The following code examplifies both points: it registers the temporary data, submits three tasks accessing it, and records the data for automatic unregistration.

```c
starpu_vector_data_register(&handle, -1, 0, n, sizeof(float));
starpu_task_insert(&produce_data, STARPU_W, handle, 0);
starpu_task_insert(&compute_data, STARPU_RW, handle, 0);
starpu_task_insert(&summarize_data, STARPU_R, handle, STARPU_W, result_handle, 0);
starpu_data_unregister_submit(handle);
```

The application may also want to see the temporary data initialized on the fly before being used by the task. This can be done by using starpu_data_set_reduction_methods() to set an initialization codelet (no redux codelet is needed).

7.11.2 Scratch Data

Some kernels sometimes need temporary data to achieve the computations, i.e. a workspace. The application could allocate it at the start of the codelet function, and free it at the end, but this would be costly. It could also allocate one buffer per worker (similarly to How To Initialize A Computation Library Once For Each Worker?), but this would make them systematic and permanent. A more optimized way is to use the data access mode STA→RPU_SCRATCH, as examplified below, which provides per-worker buffers without content consistency. The buffer is registered only once, using memory node $-1$, i.e. the application didn't allocate memory for it, and StarPU will allocate it on demand at task execution.

```c
starpu_vector_data_register(&workspace, -1, 0, sizeof(float));
for (i = 0; i < N; i++)
  starpu_task_insert(&compute, STARPU_RW, input[i], STARPU_SCRATCH , workspace, STARPU_W, output[i], 0);
```

StarPU will make sure that the buffer is allocated before executing the task, and make this allocation per-worker: for CPU workers, notably, each worker has its own buffer. This means that each task submitted above will actually have
7.12 The Multiformat Interface

It may be interesting to represent the same piece of data using two different data structures: one only used on CPUs, and one only used on GPUs. This can be done by using the multiformat interface. StarPU will be able to convert data from one data structure to the other when needed. Note that the scheduler dmda is the only one optimized for this interface. The user must provide StarPU with conversion codelets:

```c
#define NX 1024
struct point array_of_structs[NX];
starpu_data_handle_t handle;

/*
 * The conversion of a piece of data is itself a task, though it is created,
 * submitted and destroyed by StarPU internals and not by the user. Therefore,
 * we have to define two codelets.
 * Note that for now the conversion from the CPU format to the GPU format has to
 * be executed on the GPU, and the conversion from the GPU to the CPU has to be
 * executed on the CPU.
 */
#ifdef STARPU_USE_OPENCL
void cpu_to_opencl_opencl_func(void *buffers[], void *args);
struct starpu_codelet cpu_to_opencl_cl =
{
    .where = STARPU_OPENCL,
    .opencl_funcs = { cpu_to_opencl_opencl_func },
    .nbuffers = 1,
    .modes = { STARPU_RW }
};
void opencl_to_cpu_func(void *buffers[], void *args);
struct starpu_codelet opencl_to_cpu_cl =
{
    .where = STARPU_CPU,
    .cpu_funcs = { opencl_to_cpu_func },
    .cpu_funcs_name = { "opencl_to_cpu_func" },
    .nbuffers = 1,
    .modes = { STARPU_RW }
};
#endif

struct starpu_multiformat_data_interface_ops format_ops =
{
    #ifdef STARPU_USE_OPENCL
    .opencl_elemsize = 2 * sizeof(float),
    .cpu_to_opencl_cl = &cpu_to_opencl_cl,
    .opencl_to_cpu_cl = &opencl_to_cpu_cl,
    #endif
    .cpu_elemsize = 2 * sizeof(float),
    ...
};

starpu_multiformat_data_register(handle, STARPU_MAIN_RAM, &
array_of_structs, NX, &format_ops);

Kernels can be written almost as for any other interface. Note that STARPU_MULTIFORMAT_GET_CPU_PTR shall only be used for CPU kernels. CUDA kernels must use STARPU_MULTIFORMAT_GET_CUDA_PTR, and OpenCL kernels must use STARPU_MULTIFORMAT_GET_OPENCL_PTR. STARPU_MULTIFORMAT_GET_NX may be used in any kind of kernel.

static void
multiformat_scal_cpu_func(void *buffers[], void *args)
{
    struct point *aos;
    unsigned int n;
    aos = STARPU_MULTIFORMAT_GET_CPU_PTR(buffers[0]);
    n = STARPU_MULTIFORMAT_GET_NX(buffers[0]);
    ...
}

extern "C" void multiformat_scal_cuda_func(void *buffers[], void *args)
{
    unsigned int n;
    struct struct_of_arrays *soa;
}
```
A full example may be found in examples/basic_examples/multiformat.c.

### 7.13 Defining A New Data Interface

Let's define a new data interface to manage complex numbers.

```c
/* interface for complex numbers */
struct starpu_complex_interface
{
    double *real;
    double *imaginary;
    int nx;
};
```

Registering such a data to StarPU is easily done using the function `starpu_data_register()`. The last parameter of the function, `interface_complex_ops`, will be described below.

```c
void starpu_complex_data_register(starpu_data_handle_t *handle, unsigned home_node, double *real, double *imaginary, int nx)
{
    struct starpu_complex_interface complex =
    {
        .real = real,
        .imaginary = imaginary,
        .nx = nx
    };

    if (interface_complex_ops.interfaceid == STARPU_UNKNOWN_INTERFACE_ID)
    {
        interface_complex_ops.interfaceid = starpu_data_interface_get_next_id();
    }

    starpu_data_register(handle, home_node, &complex, &interface_complex_ops);
}
```

The `starpu_complex_interface` structure is here used just to store the parameters that the user provided to `starpu_complex_data_register`. `starpu_data_register()` will first allocate the handle, and then pass the `starpu_complex_interface` structure to the `starpu_data_interface_ops::register_data_handle` method, which records them within the data handle (it is called once per node by `starpu_data_register()`).

Different operations need to be defined for a data interface through the type `starpu_data_interface_ops`. We only define here the basic operations needed to run simple applications. The source code for the different functions can be found in the file `examples/interface/complex_interface.c`, the details of the hooks to be provided are documented in `starpu_data_interface_ops`.

```c
static struct starpu_data_interface_ops interface_complex_ops =
{
    .register_data_handle = complex_register_data_handle,
    .allocate_data_on_node = complex_allocate_data_on_node,
    .copy_methods = &complex_copy_methods,
    .get_size = complex_get_size,
    .footprint = complex_footprint,
    .interfaceid = STARPU_UNKNOWN_INTERFACE_ID,
    .interface_size = sizeof(struct starpu_complex_interface),
};
```

Functions need to be defined to access the different fields of the complex interface from a StarPU data handle.

```c
double *starpu_complex_get_real(starpu_data_handle_t handle)
{
    struct starpu_complex_interface *complex_interface =
        (struct starpu_complex_interface *) starpu_data_get_interface_on_node
        (handle, STARPU_MAIN_RAM);
    return complex_interface->real;
}
double *starpu_complex_get_imaginary(starpu_data_handle_t handle);
int starpu_complex_get_nx(starpu_data_handle_t handle);
```
Similar functions need to be defined to access the different fields of the complex interface from a `void *` pointer to be used within codelet implementations.

```c
#define STARPU_COMPLEX_GET_REAL(interface) (((struct starpu_complex_interface *)(interface))->real)
#define STARPU_COMPLEX_GET_IMAGINARY(interface) (((struct starpu_complex_interface *)(interface))->imaginary)
#define STARPU_COMPLEX_GET_NX(interface) (((struct starpu_complex_interface *)(interface))->nx)
```

Complex data interfaces can then be registered to StarPU.

```c
double real = 45.0;
double imaginary = 12.0;
starpu_complex_data_register(&handle1, STARPU_MAIN_RAM, &real, &imaginary, 1);
starpu_task_insert(&cl_display, STARPU_R, handle1, 0);
```

and used by codelets.

```c
void display_complex_codelet(void *descr[], void *-_args)
{
    int nx = STARPU_COMPLEX_GET_NX(descr[0]);
    double *real = STARPU_COMPLEX_GET_REAL(descr[0]);
    double *imaginary = STARPU_COMPLEX_GET_IMAGINARY(descr[0]);
    int i;
    for(i=0 ; i<nx ; i++)
    {
        fprintf(stderr, "Complex[%d] = %3.2f + %3.2f i\n", i, real[i], imaginary[i]);
    }
}
```

The whole code for this complex data interface is available in the directory `examples/interface/`.

### 7.14 Specifying A Target Node For Task Data

When executing a task on a GPU for instance, StarPU would normally copy all the needed data for the tasks on the embedded memory of the GPU. It may however happen that the task kernel would rather have some of the data kept in the main memory instead of copied in the GPU, a pivoting vector for instance. This can be achieved by setting the `starpu_codelet::specific_nodes` flag to 1, and then fill the `starpu_codelet::nodes` array (or `starpu_codelet::dyn_nodes` when `starpu_codelet::nbuffers` is greater than `STARPU_NMAXBUFS`) with the node numbers where data should be copied to, or `STARPU_SPECIFIC_NODE_LOCAL` to let StarPU copy it to the memory node where the task will be executed.

`:STARPU_SPECIFIC_NODE_CPU` can also be used to request data to be put in CPU-accessible memory (and let StarPU choose the NUMA node). `:STARPU_SPECIFIC_NODE_FAST` and `:STARPU_SPECIFIC_NODE_SLOW` can also be used.

For instance, with the following codelet:

```c
struct starpu_codelet cl =
{
    .cuda_funcs = { kernel },
    .nbuffers = 2,
    .modes = {STARPU_RW, STARPU_RW},
    .specific_nodes = 1,
    .nodes = {STARPU_SPECIFIC_NODE_CPU, STARPU_SPECIFIC_NODE_LOCAL},
};
```

the first data of the task will be kept in the CPU memory, while the second data will be copied to the CUDA GPU as usual. A working example is available in `tests/datawizard/specific_node.c`

With the following codelet:

```c
struct starpu_codelet cl =
{
    .cuda_funcs = { kernel },
    .nbuffers = 2,
    .modes = {STARPU_RW, STARPU_RW},
    .specific_nodes = 1,
    .nodes = {STARPU_SPECIFIC_NODE_LOCAL, STARPU_SPECIFIC_NODE_SLOW},
};
```

The first data will be copied into fast (but probably size-limited) local memory while the second data will be left in slow (but large) memory. This makes sense when the kernel does not make so many accesses to the second data, and thus data being remote e.g. over a PCI bus is not a performance problem, and avoids filling the fast local memory with data which does not need the performance.
Chapter 8

Scheduling

8.1 Task Scheduling Policies

The basics of the scheduling policy are the following:

- The scheduler gets to schedule tasks \( (\text{push operation}) \) when they become ready to be executed, i.e. they are not waiting for some tags, data dependencies or task dependencies.
- Workers pull tasks \( (\text{pop operation}) \) one by one from the scheduler.

This means scheduling policies usually contain at least one queue of tasks to store them between the time when they become available, and the time when a worker gets to grab them.

By default, StarPU uses the work-stealing scheduler \( \text{lws} \). This is because it provides correct load balance and locality even if the application codelets do not have performance models. Other non-modelling scheduling policies can be selected among the list below, thanks to the environment variable \( \text{STARPU_SCHED} \). For instance \( \text{export STARPU_SCHED=dmda} \). Use \text{help} to get the list of available schedulers.

**Non Performance Modelling Policies:**
- The \text{eager} scheduler uses a central task queue, from which all workers draw tasks to work on concurrently. This however does not permit to prefetch data since the scheduling decision is taken late. If a task has a non-0 priority, it is put at the front of the queue.
- The \text{random} scheduler uses a queue per worker, and distributes tasks randomly according to assumed worker overall performance.
- The \text{ws} (work stealing) scheduler uses a queue per worker, and schedules a task on the worker which released it by default. When a worker becomes idle, it steals a task from the most loaded worker.
- The \text{lws} (locality work stealing) scheduler uses a queue per worker, and schedules a task on the worker which released it by default. When a worker becomes idle, it steals a task from neighbour workers. It also takes into account priorities.
- The \text{prio} scheduler also uses a central task queue, but sorts tasks by priority specified by the programmer (between -5 and 5).
- The \text{heteroprio} scheduler uses different priorities for the different processing units. This scheduler must be configured to work correctly and to expect high-performance as described in the corresponding section.

8.2 Performance Model-Based Task Scheduling Policies

If \( \text{(and only if)} \) your application codelets have performance models \( \text{(Performance Model Example)} \), you should change the scheduler thanks to the environment variable \( \text{STARPU_SCHED} \), to select one of the policies below, in order to take advantage of StarPU's performance modelling. For instance \( \text{export STARPU_SCHED=dmda} \). Use \text{help} to get the list of available schedulers.

**Note:** Depending on the performance model type chosen, some preliminary calibration runs may be needed for the model to converge. If the calibration has not been done, or is insufficient yet, or if no performance model is specified for a codelet, every task built from this codelet will be scheduled using an \text{eager} fallback policy.

**Troubleshooting:** Configuring and recompiling StarPU using the \text{--enable-verbose} configure option displays some statistics at the end of execution about the percentage of tasks which have been scheduled by a DM* family policy using performance model hints. A low or zero percentage may be the sign that performance models are not converging or that codelets do not have performance models enabled.
Performance Modelling Policies:

The dm (deque model) scheduler takes task execution performance models into account to perform a HEFT-similar scheduling strategy: it schedules tasks where their termination time will be minimal. The difference with HEFT is that dm schedules tasks as soon as they become available, and thus in the order they become available, without taking priorities into account.

The dmda (deque model data aware) scheduler is similar to dm, but it also takes into account data transfer time.

The dmdar (deque model data aware ready) scheduler is similar to dmda, but it also privileges tasks whose data buffers are already available on the target device.

The dmdas (deque model data aware sorted) scheduler is similar to dmdar, except that it sorts tasks by priority order, which allows to become even closer to HEFT by respecting priorities after having made the scheduling decision (but it still schedules tasks in the order they become available).

The dmdasd (deque model data aware sorted decision) scheduler is similar to dmdas, except that when scheduling a task, it takes into account its priority when computing the minimum completion time, since this task may get executed before others, and thus the latter should be ignored.

The heft (heterogeneous earliest finish time) scheduler is a deprecated alias for dmda.

The pheft (parallel HEFT) scheduler is similar to dmda, it also supports parallel tasks (still experimental). Should not be used when several contexts using it are being executed simultaneously.

The peager (parallel eager) scheduler is similar to eager, it also supports parallel tasks (still experimental). Should not be used when several contexts using it are being executed simultaneously.

TODO: describe modular schedulers

8.3 Task Distribution Vs Data Transfer

Distributing tasks to balance the load induces data transfer penalty. StarPU thus needs to find a balance between both. The target function that the scheduler dmda of StarPU tries to minimize is \( \alpha \cdot T_{\text{execution}} + \beta \cdot T_{\text{data transfer}} \), where \( T_{\text{execution}} \) is the estimated execution time of the codelet (usually accurate), and \( T_{\text{data transfer}} \) is the estimated data transfer time. The latter is estimated based on bus calibration before execution start, i.e. with an idle machine, thus without contention. You can force bus re-calibration by running the tool starpu_calibrate_bus. The beta parameter defaults to 1, but it can be worth trying to tweak it by using export STARPU_SCHED_BETA=2 (STARPU_SCHED_BETA) for instance, since during real application execution, contention makes transfer times bigger. This is of course imprecise, but in practice, a rough estimation already gives the good results that a precise estimation would give.

8.4 Energy-based Scheduling

If the application can provide some energy consumption performance model (through the field starpu_codelet::<energy_model>), StarPU will take it into account when distributing tasks. The target function that the scheduler dmda minimizes becomes \( \alpha \cdot T_{\text{execution}} + \beta \cdot T_{\text{data transfer}} + \gamma \cdot \text{Consumption} \), where \( \text{Consumption} \) is the estimated task consumption in Joules. To tune this parameter, use export STARPU_SCHED_GAMMA=3000 (STARPU_SCHED_GAMMA) for instance, to express that each Joule (i.e kW during 1000us) is worth 3000us execution time penalty. Setting \( \alpha \) and \( \beta \) to zero permits to only take into account energy consumption.

This is however not sufficient to correctly optimize energy: the scheduler would simply tend to run all computations on the most energy-conservative processing unit. To account for the consumption of the whole machine (including idle processing units), the idle power of the machine should be given by setting export STARPU_IDLE_POWER=200 (STARPU_IDLE_POWER) for 200W, for instance. This value can often be obtained from the machine power supplier.

The energy actually consumed by the total execution can be displayed by setting export STARPU_PROFILING=1 STARPU_WORKER_STATS=1.

For OpenCL devices, on-line task consumption measurement is currently supported through the CL_PROFILING_INFO_OPENCL extension, implemented in the MoviSim simulator.

For CUDA devices, on-line task consumption measurement is supported on V100 cards and beyond. This however only works for quite long tasks, since the measurement granularity is about 10ms.

Applications can however provide explicit measurements by using the function starpu_perfmodel_update_history() (exampled in Performance Model Example with the energy_model performance model). Fine-grain measurement is often not feasible with the feedback provided by the hardware, so the user can for instance run a given task a thousand times, measure the global consumption for that series of tasks, divide it by a thousand, repeat for varying
kinds of tasks and task sizes, and eventually feed StarPU with these manual measurements through starpu←permodel_update_history(). For instance, for CUDA devices, nvidia-smi -q -d POWER can be used to get the current consumption in Watt. Multiplying this value by the average duration of a single task gives the consumption of the task in Joules, which can be given to starpu_permodel_update_history().

Another way to provide the energy performance is to define a perfmodel with starpu_perfmodel::type STARPU←PER_ARCH, and set the starpu_perfmodel::arch_cost_function field to a function which shall return the estimated consumption of the task in Joules. Such a function can for instance use starpu_task_expected_length() on the task (in µs), multiplied by the typical power consumption of the device, e.g. in W, and divided by 1000000 to get Joules.

8.5 Modularized Schedulers

StarPU provides a powerful way to implement schedulers, as documented in Defining A New Modular Scheduling Policy. It is currently shipped with the following pre-defined Modularized Schedulers:

- **Eager-based Schedulers** (with/without prefetching: modular-eager, modular-eager-prefetching):
  - Naive scheduler, which tries to map a task on the first available resource it finds.

- **Prio-based Schedulers** (with/without prefetching: modular-prio, modular-prio-prefetching):
  - Similar to Eager-Based Schedulers. Can handle tasks which have a defined priority and schedule them accordingly.

  - Selects randomly a resource to be mapped on for each task.

- **Work Stealing** (modular-ws):
  - Maps tasks to workers in round robin, but allows workers to steal work from other workers.

- **HEFT Scheduler**:
  - Maps tasks to workers using a heuristic very close to Heterogeneous Earliest Finish Time. It needs that every task submitted to StarPU have a defined performance model (Performance Model Calibration) to work efficiently, but can handle tasks without a performance model. modular-heft just takes tasks by priority order. modular-heft takes at most 5 tasks of the same priority and checks which one fits best. modular-heft-prio is similar to modular-heft, but only decides the memory node, not the exact worker, just pushing tasks to one central queue per memory node.

To use one of these schedulers, one can set the environment variable STARPU_SCHED.

8.6 Static Scheduling

In some cases, one may want to force some scheduling, for instance force a given set of tasks to GPU0, another set to GPU1, etc. while letting some other tasks be scheduled on any other device. This can indeed be useful to guide StarPU into some work distribution, while still letting some degree of dynamism. For instance, to force execution of a task on CUDA0:

```c
    task->execute_on_a_specific_worker = 1;
    task->workerid = starpu_worker_get_by_type(STARPU_CUDA_WORKER, 0);
```

or equivalently

```c
    starpu_task_insert(tcl, ..., STARPU_EXECUTE_ON_WORKER,
                        starpu_worker_get_by_type(STARPU_CUDA_WORKER, 0), ...);
```

One can also specify a set worker(s) which are allowed to take the task, as an array of bit, for instance to allow workers 2 and 42:

```c
    task->workerids = calloc(2, sizeof(uint32_t));
    task->workerids[2/32] |= (1 << (2%32));
    task->workerids[42/32] |= (1 << (42%32));
    task->workerids_len = 2;
```
One can also specify the order in which tasks must be executed by setting the `starpu_task::workerorder` field. If this field is set to a non-zero value, it provides the per-worker consecutive order in which tasks will be executed, starting from 1. For a given of such task, the worker will thus not execute it before all the tasks with smaller order value have been executed, notably in case those tasks are not available yet due to some dependencies. This eventually gives total control of task scheduling, and StarPU will only serve as a "self-timed" task runtime. Of course, the provided order has to be runnable, i.e. a task should not depend on another task bound to the same worker with a bigger order.

Note however that using scheduling contexts while statically scheduling tasks on workers could be tricky. Be careful to schedule the tasks exactly on the workers of the corresponding contexts, otherwise the workers’ corresponding scheduling structures may not be allocated or the execution of the application may deadlock. Moreover, the hypervisor should not be used when statically scheduling tasks.

### 8.7 Heteroprio

Within Heteroprio, one priority per processing unit type is assigned to each task, such that a task has several priorities. Each worker pops the task that has the highest priority for the hardware type it uses, which could be CPU or CUDA for example. Therefore, the priorities has to be used to manage the critical path, but also to promote the consumption of tasks by the more appropriate workers. The tasks are stored inside buckets, where each bucket corresponds to a priority set. Then each worker uses an indirect access array to know the order in which it should access the buckets. Moreover, all the tasks inside a bucket must be compatible with all the processing units that may access it (at least).

As an example, see the following code where we have 5 types of tasks. CPU workers can compute all of them, but CUDA workers can only execute tasks of types 0 and 1, and is expected to go 20 and 30 time faster than the CPU, respectively.

```c
#include <starpu_heteroprio.h>

struct starpu_conf conf;
starpu_conf_init(&conf);
conf.sched_policy_name = "heteroprio";
conf.sched_policy_init = &init_heteroprio;
starpu_init(&conf);

void init_heteroprio(unsigned sched_ctx) {
    // CPU uses 5 buckets and visits them in the natural order
    starpu_heteroprio_set_nb_prios(ctx, STARPU_CPU_IDX, 5);
    // It uses direct mapping idx => idx
    for(unsigned idx = 0; idx < 5; ++idx){
        starpu_heteroprio_set_mapping(ctx, STARPU_CPU_IDX, idx, idx);
        // If there is no CUDA worker we must tell that CPU is faster
        starpu_heteroprio_set_faster_arch(ctx, STARPU_CPU_IDX, idx);
    }
    if(starpu_cuda_worker_get_count()) {
        // CUDA is enabled and uses 2 buckets
        starpu_heteroprio_set_nb_prios(ctx, STARPU_CUDA_IDX, 2);
        // CUDA will first look at bucket 1
        starpu_heteroprio_set_mapping(ctx, STARPU_CUDA_IDX, 0, 1);
        // CUDA will then look at bucket 2
        starpu_heteroprio_set_mapping(ctx, STARPU_CUDA_IDX, 1, 2);
        // For bucket 1 CUDA is the fastest
        starpu_heteroprio_set_faster_arch(ctx, STARPU_CUDA_IDX, 1);
        // And CPU is 30 times slower
        starpu_heteroprio_set_arch_slow_factor(ctx, STARPU_CPU_IDX, 1, 30.0f);
        // For bucket 0 CUDA is the fastest
        starpu_heteroprio_set_faster_arch(ctx, STARPU_CUDA_IDX, 0);
        // And CPU is 20 times slower
        starpu_heteroprio_set_arch_slow_factor(ctx, STARPU_CPU_IDX, 0, 20.0f);
    }
}
```

Then, when a task is inserted the priority of the task will be used to select in which bucket is has to be stored. So, in the given example, the priority of a task will be between 0 and 4 included. However, tasks of priorities 0-1
must provide CPU and CUDA kernels, and tasks of priorities 2-4 must provide CPU kernels (at least).
Chapter 9

Scheduling Contexts

TODO: improve!

9.1 General Ideas

Scheduling contexts represent abstract sets of workers that allow the programmers to control the distribution of computational resources (i.e. CPUs and GPUs) to concurrent kernels. The main goal is to minimize interferences between the execution of multiple parallel kernels, by partitioning the underlying pool of workers using contexts. Scheduling contexts additionally allow a user to make use of a different scheduling policy depending on the target resource set.

9.2 Creating A Context

By default, the application submits tasks to an initial context, which disposes of all the computation resources available to StarPU (all the workers). If the application programmer plans to launch several kernels simultaneously, by default these kernels will be executed within this initial context, using a single scheduler policy (see Task Scheduling Policies). Meanwhile, if the application programmer is aware of the demands of these kernels and of the specificity of the machine used to execute them, the workers can be divided between several contexts. These scheduling contexts will isolate the execution of each kernel and they will permit the use of a scheduling policy proper to each one of them.

Scheduling Contexts may be created in two ways: either the programmers indicates the set of workers corresponding to each context (providing he knows the identifiers of the workers running within StarPU), or the programmer does not provide any worker list and leaves the Hypervisor assign workers to each context according to their needs (Scheduling Context Hypervisor).

Both cases require a call to the function starpu_sched_ctx_create(), which requires as input the worker list (the exact list or a NULL pointer), the amount of workers (or −1 to designate all workers on the platform) and a list of optional parameters such as the scheduling policy, terminated by a 0. The scheduling policy can be a character list corresponding to the name of a StarPU predefined policy or the pointer to a custom policy. The function returns an identifier of the context created which you will use to indicate the context you want to submit the tasks to.

```c
/* the list of resources the context will manage */
int workerids[3] = {1, 3, 10};

/* indicate the list of workers assigned to it, the number of workers,
the name of the context and the scheduling policy to be used within
the context */
int id_ctx = starpu_sched_ctx_create(workerids, 3, "my_ctx",
                                     STARPU_SCHED_CTX_POLICY_NAME, "dmda", 0);

/* let StarPU know that the following tasks will be submitted to this context */
starpu_sched_ctx_set_context(id);

/* submit the task to StarPU */
starpu_task_submit(task);
```

Note: Parallel greedy and parallel heft scheduling policies do not support the existence of several disjoint contexts on the machine. Combined workers are constructed depending on the entire topology of the machine, not only the one belonging to a context.
9.2.1 Creating A Context With The Default Behavior

If no scheduling policy is specified when creating the context, it will be used as another type of resource: a cluster. A cluster is a context without scheduler (eventually delegated to another runtime). For more information see Clustering A Machine. It is therefore mandatory to stipulate a scheduler to use the contexts in this traditional way.

To create a context with the default scheduler, that is either controlled through the environment variable STARPU_U_SCHED or the StarPU default scheduler, one can explicitly use the option STARPU_SCHED_CTX_POLICY as in the following example:

```c
/* the list of resources the context will manage */
int workerids[3] = {1, 3, 10};
/* indicate the list of workers assigned to it, the number of workers, and use the default scheduling policy. */
int id_ctx = starpu_sched_ctx_create(workerids, 3, "my_ctx",
STARPU_SCHED_CTX_POLICY_NAME, "", 0);
/* .... */
```

9.3 Creating A Context

The contexts can also be used to group set of SMs of an NVIDIA GPU in order to isolate the parallel kernels and allow them to coexecution on a specified partition of the GPU.

Each context will be mapped to a stream and the user can indicate the number of SMs. The context can be added to a larger context already grouping CPU cores. This larger context can use a scheduling policy that assigns tasks to both CPUs and contexts (partitions of the GPU) based on performance models adjusted to the number of SMs. The GPU implementation of the task has to be modified accordingly and receive as a parameter the number of SMs.

```c
/* get the available streams (suppose we have nstreams = 2 by specifying them with
STARPU_NWORKER_PER_CUDA=2 */
int nstreams = starpu_worker_get_stream_workerids(gpu_devvid, stream_workerids, STARPU_CUDA_WORKER);
int sched_ctx[nstreams];
sched_ctx[0] = starpu_sched_ctx_create(&stream_workerids[0], 1, "subctx",
STARPU_SCHED_CTX_CUDA_NSMS, 6, 0);
sched_ctx[1] = starpu_sched_ctx_create(&stream_workerids[1], 1, "subctx",
STARPU_SCHED_CTX_CUDA_NSMS, 7, 0);
int ncpus = 4;
int workers[ncpus*nstreams];
workers[ncpus+0] = stream_workerids[0];
workers[ncpus+1] = stream_workerids[1];
big_sched_ctx = starpu_sched_ctx_create(workers, ncpus*nstreams, "ctx1",
STARPU_SCHED_CTX_SUB_CTXS, sched_ctxs, nstreams, STARPU_SCHED_CTX_POLICY_NAME,
"dmdas", 0);
starpu_task_submit_to_ctx(task, big_sched_ctx);
```

9.4 Modifying A Context

A scheduling context can be modified dynamically. The application may change its requirements during the execution and the programmer can add additional workers to a context or remove those no longer needed. In the following example we have two scheduling contexts sched_ctx1 and sched_ctx2. After executing a part of the tasks some of the workers of sched_ctx1 will be moved to context sched_ctx2.

```c
/* the list of resources that context 1 will give away */
int workerids[3] = {1, 3, 10};
/* add the workers to context 1 */
starpu_sched_ctx_add_workers(workerids, 3, sched_ctx2);
/* remove the workers from context 2 */
starpu_sched_ctx_remove_workers(workerids, 3, sched_ctx1);
```

9.5 Submitting Tasks To A Context

The application may submit tasks to several contexts either simultaneously or sequeuntially. If several threads of submission are used the function starpu_sched_ctx_set_context() may be called just before starpu_task_submit(). Thus StarPU considers that the current thread will submit tasks to the corresponding context.
9.6 Deleting A Context

When the application may not assign a thread of submission to each context, the id of the context must be indicated by using the function `starpu_task_submit_to_ctx()` or the field `STARPU_SCHED_CTX` for `starpu_task_insert()`.

9.6 Deleting A Context

When a context is no longer needed it must be deleted. The application can indicate which context should keep the resources of a deleted one. All the tasks of the context should be executed before doing this. Thus, the programmer may use either a barrier and then delete the context directly, or just indicate that other tasks will not be submitted later on to the context (such that when the last task is executed its workers will be moved to the inheritor) and delete the context at the end of the execution (when a barrier will be used eventually).

```c
/* when the context 2 is deleted context 1 inherits its resources */
starpu_sched_ctx_set_inheritor(sched_ctx2, sched_ctx1);

/* submit tasks to context 2 */
for (i = 0; i < ntasks; i++)
  starpu_task_submit_to_ctx(task[i], sched_ctx2);

/* indicate that context 2 finished submitting and that */
/* as soon as the last task of context 2 finished executing */
/* its workers can be moved to the inheritor context */
starpu_sched_ctx_finished_submit(sched_ctx1);

/* wait for the tasks of both contexts to finish */
starpu_task_wait_for_all();

/* delete context 2 */
starpu_sched_ctx_delete(sched_ctx2);

/* delete context 1 */
starpu_sched_ctx_delete(sched_ctx1);
```

9.7 Emptying A Context

A context may have no resources at the beginning or at a certain moment of the execution. Tasks can still be submitted to these contexts and they will be executed as soon as the contexts will have resources. A list of tasks pending to be executed is kept and will be submitted when workers are added to the contexts.

```c
/* create a empty context */
unsigned sched_ctx_id = starpu_sched_ctx_create(NULL, 0, "ctx", 0);

/* submit a task to this context */
starpu_sched_ctx_set_context(&sched_ctx_id);
ret = starpu_task_insert(&codelet, 0);
STARPU_CHECK_RETURN_VALUE(ret, "starpu_task_insert");

/* add CPU workers to the context */
int procs[STARPU_NMAXWORKERS];
int nprocs = starpu_cpu_worker_get_count();
starpu_worker_get_ids_by_type(STARPU_CPU_WORKER, procs, nprocs);
starpu_sched_ctx_add_workers(procs, nprocs, sched_ctx_id);

/* and wait for the task termination */
starpu_task_wait_for_all();
```

However, if resources are never allocated to the context, the application will not terminate. If these tasks have low priority, the application can inform StarPU to not submit them by calling the function `starpu_sched_ctx_stop_task_submission()`.
Chapter 10

Scheduling Context Hypervisor

10.1 What Is The Hypervisor

StarPU proposes a platform to construct Scheduling Contexts, to delete and modify them dynamically. A parallel kernel, can thus be isolated into a scheduling context and interferences between several parallel kernels are avoided. If users know exactly how many workers each scheduling context needs, they can assign them to the contexts at their creation time or modify them during the execution of the program.

The Scheduling Context Hypervisor Plugin is available for users who do not dispose of a regular parallelism, who cannot know in advance the exact size of the context and need to resize the contexts according to the behavior of the parallel kernels.

The Hypervisor receives information from StarPU concerning the execution of the tasks, the efficiency of the resources, etc. and it decides accordingly when and how the contexts can be resized. Basic strategies of resizing scheduling contexts already exist but a platform for implementing additional custom ones is available.

10.2 Start the Hypervisor

The Hypervisor must be initialized once at the beginning of the application. At this point a resizing policy should be indicated. This strategy depends on the information the application is able to provide to the hypervisor as well as on the accuracy needed for the resizing procedure. For example, the application may be able to provide an estimation of the workload of the contexts. In this situation the hypervisor may decide what resources the contexts need. However, if no information is provided the hypervisor evaluates the behavior of the resources and of the application and makes a guess about the future. The hypervisor resizes only the registered contexts.

10.3 Interrogate The Runtime

The runtime provides the hypervisor with information concerning the behavior of the resources and the application. This is done by using the `performance_counters` which represent callbacks indicating when the resources are idle or not efficient, when the application submits tasks or when it becomes to slow.

10.4 Trigger the Hypervisor

The resizing is triggered either when the application requires it (`sc_hypervisor_resize_ctxs()`) or when the initial distribution of resources alters the performance of the application (the application is to slow or the resource are idle for too long time). If the environment variable `SC_HYPERVISOR_TRIGGER_RESIZE` is set to `speed` the monitored speed of the contexts is compared to a theoretical value computed with a linear program, and the resizing is triggered whenever the two values do not correspond. Otherwise, if the environment variable is set to `idle` the hypervisor triggers the resizing algorithm whenever the workers are idle for a period longer than the threshold indicated by the programmer. When this happens different resizing strategy are applied that target minimizing the total execution of the application, the instant speed or the idle time of the resources.
10.5 Resizing Strategies

The plugin proposes several strategies for resizing the scheduling context.

The **Application driven** strategy uses users' input concerning the moment when they want to resize the contexts. Thus, users tag the task that should trigger the resizing process. One can set directly the field `task.hypervisor_tag` or use the macro `::STARPU_HYPERVISOR_TAG` in the function `starpu_task_insert()`.

```c
task.hypervisor_tag = 2;
```

or

```c
starpu_task_insert(&codelet,
    ...,
    STARPU_HYPERVISOR_TAG, 2,
    0);
```

Then users have to indicate that when a task with the specified tag is executed the contexts should resize.

```c
sc_hypervisor_resize(sched_ctx, 2);
```

Users can use the same tag to change the resizing configuration of the contexts if they consider it necessary.

```c
sc_hypervisor_ctl(sched_ctx, SC_HYPERVISOR_MIN_WORKERS, 6,
    SC_HYPERVISOR_MAX_WORKERS, 12,
    SC_HYPERVISOR_TIME_TO_APPLY, 2,
    NULL);
```

The **Idleness** based strategy moves workers unused in a certain context to another one needing them. (see Scheduling Context Hypervisor - Regular usage)

```c
int workerids[3] = {1, 3, 10};
int workerids2[9] = {0, 2, 4, 5, 6, 7, 8, 9, 11};
sc_hypervisor_ctl(sched_ctx_id, SC_HYPERVISOR_MAX_IDLE, workerids, 3, 10000.0,
    SC_HYPERVISOR_MAX_IDLE, workerids2, 9, 50000.0,
    NULL);
```

The **Gflops rate** based strategy resizes the scheduling contexts such that they all finish at the same time. The speed of each of them is computed and once one of them is significantly slower the resizing process is triggered. In order to do these computations users have to input the total number of instructions needed to be executed by the parallel kernels and the number of instruction to be executed by each task.

The number of flops to be executed by a context are passed as parameter when they are registered to the hypervisor, `sc_hypervisor_register_ctx(sched_ctx_id, flops)` and the one to be executed by each task are passed when the task is submitted. The corresponding field is `task.flops` and the corresponding macro in the function `starpu_task_insert()` is `STARPU_FLOPS` (Caution: but take care of passing a double, not an integer, otherwise parameter passing will be bogus). When the task is executed the resizing process is triggered.

```c
task.flops = 100;
```

or

```c
starpu_task_insert(&codelet,
    ...,
    STARPU_FLOPS, (double) 100,
    0);
```

The **Felt** strategy uses a linear program to predict the best distribution of resources such that the application finishes in a minimum amount of time. As for the **Gflops rate** strategy the programmers has to indicate the total number of flops to be executed when registering the context. This number of flops may be updated dynamically during the execution of the application whenever this information is not very accurate from the beginning. The function `sc_hypervisor_update_diff_total_flops()` is called in order to add or to remove a difference to the flops left to be executed. Tasks are provided also the number of flops corresponding to each one of them. During the execution of the application the hypervisor monitors the consumed flops and recomputes the time left and the number of resources to use. The speed of each type of resource is (re)evaluated and inserter in the linear program in order to better adapt to the needs of the application.
The Teff strategy uses a linear program too, that considers all the types of tasks and the number of each of them and it tries to allocates resources such that the application finishes in a minimum amount of time. A previous calibration of StarPU would be useful in order to have good predictions of the execution time of each type of task. The types of tasks may be determined directly by the hypervisor when they are submitted. However there are applications that do not expose all the graph of tasks from the beginning. In this case in order to let the hypervisor know about all the tasks the function `sc_hypervisor_set_type_of_task()` will just inform the hypervisor about future tasks without submitting them right away.

The Ispeed strategy divides the execution of the application in several frames. For each frame the hypervisor computes the speed of the contexts and tries making them run at the same speed. The strategy requires less contribution from users as the hypervisor requires only the size of the frame in terms of flops.

```c
int workerids[3] = {1, 3, 10};
int workerids2[9] = {0, 2, 4, 5, 6, 7, 8, 9, 11};
sc_hypervisor_ctl(sched_ctx_id,
    SC_HYPERVISOR_ISPEED_W_SAMPLE, workerids, 3, 2000000000.0,
    SC_HYPERVISOR_ISPEED_W_SAMPLE, workerids2, 9, 200000000000.0,
    SC_HYPERVISOR_ISPEED_CTX_SAMPLE, 60000000000.0,
    NULL);
```

The Throughput strategy focuses on maximizing the throughput of the resources and resizes the contexts such that the machine is running at its maximum efficiency (maximum instant speed of the workers).

10.6 Defining A New Hypervisor Policy

While Scheduling Context Hypervisor Plugin comes with a variety of resizing policies (see Resizing Strategies), it may sometimes be desirable to implement custom policies to address specific problems. The API described below allows users to write their own resizing policy.

Here an example of how to define a new policy

```c
struct sc_hypervisor_policy dummy_policy =
    {
        .handle_poped_task = dummy_handle_poped_task,
        .handle_pushed_task = dummy_handle_pushed_task,
        .handle_idle_cycle = dummy_handle_idle_cycle,
        .handle_idle_end = dummy_handle_idle_end,
        .handle_post_exec_hook = dummy_handle_post_exec_hook,
        .custom = 1,
        .name = "dummy"
    };
```
Chapter 11

How To Define a New Scheduling Policy

11.1 Introduction

StarPU provides two ways of defining a scheduling policy, a basic monolithic way, and a modular way. The basic monolithic way is directly connected with the core of StarPU, which means that the policy then has to handle all performance details, such as data prefetching, task performance model calibration, worker locking, etc. examples/scheduler/dummy_sched.c is a trivial example which does not handle this, and thus e.g. does not achieve any data prefetching or smart scheduling.

The modular way allows to implement just one component, and reuse existing components to cope with all these details. examples/scheduler/dummy_modular_sched.c is a trivial example very similar to dummy_sched.c, but implemented as a component, which allows to assemble it with other components, and notably get data prefetching support for free, and task performance model calibration is properly performed, which allows to easily extend it into taking task duration into account, etc.

11.2 Helper functions for defining a scheduling policy (Basic or modular)

Make sure to have a look at the Scheduling Policy section, which provides a complete list of the functions available for writing advanced schedulers.

This includes getting an estimation for a task computation completion with starpu_task_expected_length(), for the required data transfers with starpu_task_expected_data_transfer_time_for(), for the required energy with starpu_task_expected_energy(), etc. Other useful functions include starpu_transfer_bandwidth(), starpu_transfer_latency(), starpu_transfer_predict(), ... One can also directly test the presence of a data handle with starpu_data_is_on_node(). Prefetches can be triggered by calling either starpu_prefetch_task_input_for(), starpu_idle_prefetch_task_input_for_prio(), or starpu_idle_prefetch_task_input_for_prio(). The _prio versions allow to specify a priority for the transfer (instead of taking the task priority by default). These prefetches are only processed when there are no fetch data requests (i.e. a task is waiting for it) to process. The _idle versions queue the transfers on the idle prefetch queue, which is only processed when there are no non-idle prefetch to process. starpu_get_prefetch_flag() is a convenient helper for checking the value of the STARPU_PREFETCH environment variable.

Usual functions can be used on tasks, for instance one can use the following to get the data size for a task.

```c
size = 0;
write = 0;
if (task->cl)
    for (i = 0; i < STARPU_TASK_GET_NBUFFERS(task); i++)
        {
            starpu_data_handle_t data = STARPU_TASK_GET_HANDLE(task, i);
            size += starpu_data_get_size(data);
            if (STARPU_TASK_GET_MODE(task, i) & STARPU_W)
                write += size;
        }
```

Task queues can be implemented with the starpu_task_list functions.

Access to the hwloc topology is available with starpu_worker_get_hwloc_obj().
11.3 Defining A New Basic Scheduling Policy

A full example showing how to define a new scheduling policy is available in the StarPU sources in examples/scheduler/dummy_sched.c. The scheduler has to provide methods:

```c
static struct starpu_sched_policy dummy_sched_policy =
{
   .init_sched = init_dummy_sched,
   .deinit_sched = deinit_dummy_sched,
   .add_workers = dummy_sched_add_workers,
   .remove_workers = dummy_sched_remove_workers,
   .push_task = push_task_dummy,
   .pop_task = pop_task_dummy,
   .policy_name = "dummy",
   .policy_description = "dummy scheduling strategy"
};
```

The idea is that when a task becomes ready for execution, the `starpu_sched_policy::push_task` method is called to give the ready task to the scheduler. When a worker is idle, the `starpu_sched_policy::pop_task` method is called to get a task from the scheduler. It is up to the scheduler to implement what is between. A simple eager scheduler is for instance to make `starpu_sched_policy::push_task` push the task to a global list, and make `starpu_sched_policy::pop_task` pop from this list. A scheduler can also use `starpu_push_local_task()` directly push tasks to a per-worker queue, and then starpu does not even need to implement `starpu_sched_policy::pop_task`. If there are no ready tasks within the scheduler, it can just return `NULL`, and the worker will sleep. The `starpu_sched_policy` section provides the exact rules that govern the methods of the policy.

One can enumerate the workers with this iterator:

```c
struct starpu_worker_collection *workers = starpu_sched_ctx_get_worker_collection(sched_ctx_id);
struct starpu_sched_ctx_iterator it;
workers->init_iterator(workers, &it);
while(workers->has_next(workers, &it))
{
   unsigned worker = workers->get_next(workers, &it);
   ...
}
```

To provide synchronization between workers, a per-worker lock exists to protect the data structures of a given worker. It is acquired around scheduler methods, so that the scheduler does not need any additional mutex to protect its per-worker data.

In case the scheduler wants to access another scheduler’s data, it should use `starpu_worker_lock()` and `starpu_worker_unlock()`.

Calling

```c
starpu_worker_lock(B)
```

from a worker A will however thus make worker A wait for worker B to complete its scheduling method. That may be a problem if that method takes a long time, because it is e.g. computing a heuristic or waiting for another mutex, or even cause deadlocks if worker B is calling

```c
starpu_worker_lock(B)
```

at the same time. In such a case, worker B must call `starpu_worker_relax_on()` and `starpu_worker_relax_off()` around the section which potentially blocks (and does not actually need protection). While a worker is in relaxed mode, e.g. between a pair of `starpu_worker_relax_on()` and `starpu_worker_relax_off()` calls, its state can be altered by other threads: for instance, worker A can push tasks for worker B. In consequence, worker B must re-assess its state after

```c
starpu_worker_relax_off(B)
```

, such as taking possible new tasks pushed to its queue into account.

When the `starpu_sched_policy::push_task` method has pushed a task for another worker, one has to call `starpu_worker_wake_worker_relax_light()` so that the worker wakes up and picks it. If the task was pushed on a shared queue, one may want to only wake one idle worker. An example doing this is available in `src/sched_policies/eager-central_policy.c`.

A pointer to one data structure specific to the scheduler can be set with `starpu_sched_ctx_set_policy_data()` and fetched with `starpu_sched_ctx_get_policy_data()`. Per-worker data structures can then be store in it by allocating a `STARPU_NMAXWORKERS`-sized array of structures indexed by workers.
A variety of examples of advanced schedulers can be read in src/sched_policies, for instance random←_policy.c, eager_central_policy.c, work_stealing_policy.c. Code protected by if (_←starpu_get_nsched_ctxs() > 1) can be ignored, this is for scheduling contexts, which is an experimental feature.

11.4 Defining A New Modular Scheduling Policy

StarPU’s Modularized Schedulers are made of individual Scheduling Components Modularizedly assembled as a Scheduling Tree. Each Scheduling Component has an unique purpose, such as prioritizing tasks or mapping tasks over resources. A typical Scheduling Tree is shown below.

```
<p>| |</p>
<table>
<thead>
<tr>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>starpu_push_task</td>
</tr>
<tr>
<td></td>
</tr>
</tbody>
</table>
|       v
| Fifo_Component |
|       | ^
| Push   | | Can_Push
|       v |
| Eager_Component |
|       | ^
| | |
| ---------->|<-------------------><---------
| | ^ | ^
| Push | | Can_Push Push | | Can_Push
| v | v |
| Fifo_Component Fifo_Component
| | ^ | ^
| Pull | | Can_Pull Pull | | Can_Pull
| v | v |
| Worker_Component Worker_Component
| | | |
| starpu_pop_task |
|       v
```

When a task is pushed by StarPU in a Modularized Scheduler, the task moves from a Scheduling Component to an other, following the hierarchy of the Scheduling Tree, and is stored in one of the Scheduling Components of the strategy. When a worker wants to pop a task from the Modularized Scheduler, the corresponding Worker Component of the Scheduling Tree tries to pull a task from its parents, following the hierarchy, and gives it to the worker if it succeeded to get one.

11.4.1 Interface

Each Scheduling Component must follow the following pre-defined Interface to be able to interact with other Scheduling Components.

- **push_task (child_component, Task)**
  - The calling Scheduling Component transfers a task to its Child Component. When the Push function returns, the task no longer belongs to the calling Component. The Modularized Schedulers’ model relies on this function to perform prefetching. See starpu_sched_component::push_task for more details.

- **pull_task (parent_component, caller_component) -> Task**
  - The calling Scheduling Component requests a task from its Parent Component. When the Pull function ends, the returned task belongs to the calling Component. See starpu_sched_component::pull_task for more details.

- **can_push (caller_component, parent_component)**
  - The calling Scheduling Component notifies its Parent Component that it is ready to accept new tasks. See starpu_sched_component::can_push for more details.
• can_pull (caller_component, child_component)
The calling Scheduling Component notifies its Child Component that it is ready to give new tasks. See
starpu_sched_component::can_pull for more details

The components also provide the following useful methods:
• starpu_sched_component::estimated_load provides an estimated load of the component
• starpu_sched_component::estimated_end provides an estimated date of availability of workers behind the
  component, after processing tasks in the component and below. This is computed only if the estimated field
  of the tasks have been set before passing it to the component.

11.4.2 Building a Modularized Scheduler
11.4.2.1 Pre-implemented Components
StarPU is currently shipped with the following four Scheduling Components:
• Storage Components : Fifo, Prio
  Components which store tasks. They can also prioritize them if they have a defined priority. It is possible to
  define a threshold for those Components following two criterias: the number of tasks stored in the Compo-
  nent, or the sum of the expected length of all tasks stored in the Component. When a push operation tries
  to queue a task beyond the threshold, the push fails. When some task leaves the queue (and thus possibly
  more tasks can fit), this component calls can_push from ancestors.
• Resource-Mapping Components : Mct, Heft, Eager, Random, Work-Stealing
  "Core" of the Scheduling Strategy, those Components are the ones who make scheduling choices between
  their children components.
• Worker Components : Worker
  Each Worker Component modelizes a concrete worker, and copes with the technical tricks of interacting with
  the StarPU core. Modular schedulers thus usually have them at the bottom of their component tree.
• Special-Purpose Components : Perfmodel_Select, Best_Implementation
  Components dedicated to original purposes. The Perfmodel_Select Component decides which Resource-
  Mapping Component should be used to schedule a task: a component that assumes tasks with a calibrated
  performance model; a component for non-yet-calibrated tasks, that will distribute them to get measurements
  done as quickly as possible; and a component that takes the tasks without performance models.
  The Best_Implementation Component chooses which implementation of a task should be used on the chosen
  resource.

11.4.2.2 Progression And Validation Rules
Some rules must be followed to ensure the correctness of a Modularized Scheduler:
• At least one Storage Component without threshold is needed in a Modularized Scheduler, to store incoming
  tasks from StarPU. It can for instance be a global component at the top of the tree, or one component per
  worker at the bottom of the tree, or intermediate assemblies. The important point is that the starpu_sched-
  component::push_task call at the top can not fail, so there has to be a storage component without threshold
  between the top of the tree and the first storage component with threshold, or the workers themselves.
• At least one Resource-Mapping Component is needed in a Modularized Scheduler. Resource-Mapping Com-
  ponents are the only ones which can make scheduling choices, and so the only ones which can have several
  child.

11.4.2.3 Locking in modularized schedulers
Most often, components do not need to take locks. This allows e.g. the push operation to be called in parallel when
tasks get released in parallel from different workers which have completed different ancestor tasks.
When a component has internal information which needs to be kept coherent, the component can define its own lock
at take it as it sees fit, e.g. to protect a task queue. This may however limit scalability of the scheduler. Conversely,
since push and pull operations will be called concurrently from different workers, the component might prefer to use
a central mutex to serialize all scheduling decisions to avoid pathological cases (all push calls decide to put their
task on the same target)
11.4 Defining A New Modular Scheduling Policy

11.4.2.4 Implementing a Modularized Scheduler

The following code shows how to implement a Tree-Eager-Prefetching Scheduler.

```c
static void initialize_eager_prefetching_center_policy(unsigned sched_ctx_id)
{
  /* The eager component will decide for each task which worker will run it,
   * and we want fifos both above and below the component */
  starpu_sched_component_initialize_simple_scheduler(
    starpu_sched_component_eager_create, NULL,
    STARPU_SCHED_SIMPLE_DECIDE_WORKERS |
    STARPU_SCHED_SIMPLE_FIFO_ABOVE |
    STARPU_SCHED_SIMPLE_FIFOS_BELOW,
    sched_ctx_id);
}

/* Properly destroy the Scheduling Tree and all its Components */
static void deinitialize_eager_prefetching_center_policy(unsigned sched_ctx_id)
{
  struct starpu_sched_tree * tree = (struct starpu_sched_tree*)
      starpu_sched_ctx_get_policy_data(sched_ctx_id);
  starpu_sched_tree_destroy(tree);
}

/* Initializing the starpu_sched_policy struct associated to the Modularized
 * Scheduler : only the init_sched and deinit_sched needs to be defined to
 * implement a Modularized Scheduler */
struct starpu_sched_policy _starpu_sched_tree_eager_prefetching_policy =
{
  .init_sched = initialize_eager_prefetching_center_policy,
  .deinit_sched = deinitialize_eager_prefetching_center_policy,
  .add_workers = starpu_sched_tree_add_workers,
  .remove_workers = starpu_sched_tree_remove_workers,
  .push_task = starpu_sched_tree_push_task,
  .pop_task = starpu_sched_tree_pop_task,
  .pre_exec_hook = starpu_sched_component_worker_pre_exec_hook,
  .post_exec_hook = starpu_sched_component_worker_post_execHook,
  .pop_every_task = NULL,
  .policy_name = "tree-eager-prefetching",
  .policy_description = "eager with prefetching tree policy"
};
```

starpu_sched_component_initialize_simple_scheduler() is a helper function which makes it very trivial to assemble a modular scheduler around a scheduling decision component as seen above (here, a dumb eager decision component). Most often a modular scheduler can be implemented that way.

A modular scheduler can also be constructed hierarchically with starpu_sched_component_composed_recipe_create().

That modular scheduler can also be built by hand in the following way:

```c
#define _STARPU_SCHED_NTASKS_THRESHOLD_DEFAULT 2
#define _STARPU_SCHED_EXP_LEN_THRESHOLD_DEFAULT 1000000000.0

static void initialize_eager_prefetching_center_policy(unsigned sched_ctx_id)
{
  unsigned ntasks_threshold = _STARPU_SCHED_NTASKS_THRESHOLD_DEFAULT;
  double exp_len_threshold = _STARPU_SCHED_EXP_LEN_THRESHOLD_DEFAULT;
  ...
  starpu_sched_ctx_create_worker_collection
    (sched_ctx_id, STARPU_WORKER_LIST);
  /* Create the Scheduling Tree */
  struct starpu_sched_tree * t = starpu_sched_tree_create{
    sched_ctx_id};
  /* The Root Component is a Flow-control Fifo Component */
  t->root = starpu_sched_component_fifo_create(NULL);
  /* The Resource-mapping Component of the strategy is an Eager Component */
  struct starpu_sched_component *eager_component =
      starpu_sched_component_eager_create(NULL);
  /* Create links between Components : the Eager Component is the child
   * of the Root Component */
  starpu_sched_component_connect(t->root, eager_component);
  /* A task threshold is set for the Flow-control Components which will
   * be connected to Worker Components. By doing so, this Modularized
   * Scheduler will be able to perform some prefetching on the resources */
  struct starpu_sched_component_fifo_data fifo_data =
```
struct starpu_sched_component * worker_component = starpu_sched_component_worker_new(i);
struct starpu_sched_component * fifo_component = starpu_sched_component_fifo_create(&fifo_data);
starpu_sched_component_connect(fifo_component, worker_component);

starpu_sched_component_connect(eager_component, fifo_component);
}

starpu_sched_tree_update_workers(t);
starpu_sched_ctx_set_policy_data(sched_ctx_id, (void*)t);

Other modular scheduler examples can be seen in src/sched_policies/modular_*.c
For instance, modular-heft-prio needs performance models, decides memory nodes, uses prioritized fifos above and below, and decides the best implementation.
If unsure on the result of the modular scheduler construction, you can run a simple application with FxT enabled (see Generating Traces With FxT), and open the generated file trace.html in a web-browser.

11.4.3 Management of parallel task

At the moment, parallel tasks can be managed in modularized schedulers through combined workers: instead of connecting a scheduling component to a worker component, one can connect it to a combined worker component (i.e. a worker component created with a combined worker id). That component will handle creating task aliases for parallel execution and push them to the different workers components.

11.4.4 Writing a Scheduling Component

11.4.4.1 Generic Scheduling Component

Each Scheduling Component is instantiated from a Generic Scheduling Component, which implements a generic version of the Interface. The generic implementation of Pull, Can_Pull and Can_Push functions are recursive calls to their parents (respectively to their children). However, as a Generic Scheduling Component do not know how much children it will have when it will be instantiated, it does not implement the Push function.
11.4.4.2 Instantiation: Redefining the Interface

A Scheduling Component must implement all the functions of the Interface. It is so necessary to implement a Push function to instantiate a Scheduling Component. The implemented Push function is the "fingerprint" of a Scheduling Component. Depending on how functionalities or properties programmers want to give to the Scheduling Component they are implementing, it is possible to reimplement all the functions of the Interface. For example, a Flow-control Component reimplements the Pull and the Can_Push functions of the Interface, allowing to catch the generic recursive calls of these functions. The Pull function of a Flow-control Component can, for example, pop a task from the local storage queue of the Component, and give it to the calling Component which asks for it.

11.4.4.3 Detailed Progression and Validation Rules

- A Reservoir is a Scheduling Component which redefines a Push and a Pull function, in order to store tasks into it. A Reservoir delimit Scheduling Areas in the Scheduling Tree.
- A Pump is the engine source of the Scheduler: it pushes/pulls tasks to/from a Scheduling Component to another. Native Pumps of a Scheduling Tree are located at the root of the Tree (incoming Push calls from StarPU), and at the leafs of the Tree (Pop calls coming from StarPU Workers). Pre-implemented Scheduling Components currently shipped with Pumps are Flow-Control Components and the Resource-Mapping Component Heft, within their defined Can_Push functions.
- A correct Scheduling Tree requires a Pump per Scheduling Area and per Execution Flow.

The Tree-Eager-Prefetching Scheduler shown in Section Implementing a Modularized Scheduler follows the previous assumptions:

```
starpu_push_task
    Pump

Area 1
    |
    v
-----------------Fifo_Component-----------------------------
    |
    |
    |
    |
    v

Area 2
    Eager_Component
    |
    v
    |
    v

Area 3
    |
    v
    |
    v

Worker_Component
```

11.5 Graph-based Scheduling

For performance reasons, most of the schedulers shipped with StarPU use simple list-scheduling heuristics, assuming that the application has already set priorities. This is why they do their scheduling between when tasks become available for execution and when a worker becomes idle, without looking at the task graph. Other heuristics can however look at the task graph. Recording the task graph is expensive, so it is not available by default, the scheduling heuristic has to set _starpu_graph_record to 1 from the initialization function, to make it available. Then the _starpu_graph* functions can be used.

src/sched_policies/graph_test_policy.c is an example of simple greedy policy which automatically computes priorities by bottom-up rank.
The idea is that while the application submits tasks, they are only pushed to a bag of tasks. When the application is finished with submitting tasks, it calls starpu_do_schedule() (or starpu_task_wait_for_all(), which calls starpu__do_schedule()), and the starpu_sched_policy::do_schedule method of the scheduler is called. This method calls _starpu_graph_compute_depths() to compute the bottom-up ranks, and then uses these ranks to set priorities over tasks.

It then has two priority queues, one for CPUs, and one for GPUs, and uses a dumb heuristic based on the duration of the task over CPUs and GPUs to decide between the two queues. CPU workers can then pop from the CPU priority queue, and GPU workers from the GPU priority queue.

### 11.6 Debugging Scheduling

All the Online Performance Tools and Offline Performance Tools can be used to get information about how well the execution proceeded, and thus the overall quality of the execution.

Precise debugging can also be performed by using the STARPU_TASK_BREAK_ON_PUSH, STARPU_TASK_BREAK_ON_SCHED, STARPU_TASK_BREAK_ON_POP, and STARPU_TASK_BREAK_ON_EXEC environment variables. By setting the job_id of a task in these environment variables, StarPU will raise SIGTRAP when the task is being scheduled, pushed, or popped by the scheduler. This means that when one notices that a task is being scheduled in a seemingly odd way, one can just reexecute the application in a debugger, with some of those variables set, and the execution will stop exactly at the scheduling points of this task, thus allowing to inspect the scheduler state, etc.
Chapter 12

Debugging Tools

StarPU provides several tools to help debugging applications. Execution traces can be generated and displayed graphically, see Generating Traces With FxT.

12.1 TroubleShooting In General

Generally-speaking, if you have troubles, pass --enable-debug to configure to enable some checks which impact performance, but will catch common issues, possibly earlier than the actual problem you are observing, which may just be a consequence of a bug that happened earlier. Also, make sure not to have the --enable-fast configure option which drops very useful catchup assertions. If your program is valgrind-safe, you can use it, see Using Other Debugging Tools.

Depending on your toolchain, it might happen that you get undefined reference to '__stack_chk←_guard' errors. In that case, use the --disable-fstack-protector-all option to avoid the issue.

Then, if your program crashes with an assertion error, a segfault, etc. you can send us the result of

\texttt{thread apply all bt}

run in \texttt{gdb} at the point of the crash.

In case your program just hangs, but it may also be useful in case of a crash too, it helps to source \texttt{gdbinit} as described in the next section to be able to run and send us the output of the following commands:

\texttt{starpu-workers}  
\texttt{starpu-tasks}  
\texttt{starpu-print-requests}  
\texttt{starpu-print-prequests}  
\texttt{starpu-print-frrequests}  
\texttt{starpu-print-irrequests}  

To give us an idea of what is happening within StarPU. If the outputs are not too long, you can even run

\texttt{starpu-all-tasks}  
\texttt{starpu-print-all-tasks}  
\texttt{starpu-print-datas-summary}  
\texttt{starpu-print-datas}  

12.2 Using The Gdb Debugger

Some \texttt{gdb} helpers are provided to show the whole StarPU state:

\texttt{(gdb) source tools/gdbinit}  
\texttt{(gdb) help starpu}  

For instance,

\begin{itemize}
\item one can print all tasks with \texttt{starpu-print-all-tasks},  
\item print all datas with \texttt{starpu-print-datas},
\end{itemize}
• print all pending data transfers with starpu-print-prequests, starpu-print-requests, starpu-print-frequests, starpu-print-irequests,

• print pending MPI requests with starpu-mpi-print-detached-requests

Some functions can only work if --enable-debug was passed to configure (because they impact performance)

12.3 Using Other Debugging Tools

Valgrind can be used on StarPU: valgrind.h just needs to be found at configure time, to tell valgrind about some known false positives and disable host memory pinning. Other known false positives can be suppressed by giving the suppression files in tools/valgrind/*.suppr to valgrind’s --suppressions option.

The environment variable STARPU_DISABLE_KERNELS can also be set to 1 to make StarPU does everything (schedule tasks, transfer memory, etc.) except actually calling the application-provided kernel functions, i.e. the computation will not happen. This permits to quickly check that the task scheme is working properly.

12.4 Using The Temanejo Task Debugger

StarPU can connect to Temanejo >= 1.0rc2 (see http://www.hlrs.de/temanejo), to permit nice visual task debugging. To do so, build Temanejo’s libayudame.so, install Ayudame.h to e.g. /usr/local/include, apply the tools/patch-ayudame to it to fix C build, re-configure, make sure that it found it, rebuild StarPU. Run the Temanejo GUI, give it the path to your application, any options you want to pass it, the path to libayudame.so.

It permits to visualize the task graph, add breakpoints, continue execution task-by-task, and run gdb on a given task, etc.

Make sure to specify at least the same number of CPUs in the dialog box as your machine has, otherwise an error will happen during execution. Future versions of Temanejo should be able to tell StarPU the number of CPUs to use.
Tag numbers have to be below 4000000000000000000ULL to be usable for Temanejo (so as to distinguish them from tasks).
Chapter 13

Online Performance Tools

13.1 On-line Performance Feedback

13.1.1 Enabling On-line Performance Monitoring

In order to enable online performance monitoring, the application can call `starpu_profiling_status_set()` with the parameter `STARPU_PROFILING_ENABLE`. It is possible to detect whether monitoring is already enabled or not by calling `starpu_profiling_status_get()`. Enabling monitoring also reinitialize all previously collected feedback. The environment variable `STARPU_PROFILING` can also be set to 1 to achieve the same effect. The function `starpu_profiling_init()` can also be called during the execution to reinitialize performance counters and to start the profiling if the environment variable `STARPU_PROFILING` is set to 1.

Likewise, performance monitoring is stopped by calling `starpu_profiling_status_set()` with the parameter `STARPU_PROFILING_DISABLE`. Note that this does not reset the performance counters so that the application may consult them later on.

More details about the performance monitoring API are available in Profiling.

13.1.2 Per-task Feedback

If profiling is enabled, a pointer to a structure `starpu_profiling_task_info` is put in the field `starpu_task::profiling_info` when a task terminates. This structure is automatically destroyed when the task structure is destroyed, either automatically or by calling `starpu_task_destroy()`.

The structure `starpu_profiling_task_info` indicates the date when the task was submitted (`starpu_profiling_task_info::submit_time`), started (`starpu_profiling_task_info::start_time`), and terminated (`starpu_profiling_task_info::end_time`), relative to the initialization of StarPU with `starpu_init()`. It also specifies the identifier of the worker that has executed the task (`starpu_profiling_task_info::workerid`). These date are stored as `timespec` structures which the user may convert into micro-seconds using the helper function `starpu_timing_timespec_to_us()`.

It it worth noting that the application may directly access this structure from the callback executed at the end of the task. The structure `starpu_task` associated to the callback currently being executed is indeed accessible with the function `starpu_task_get_current()`.

13.1.3 Per-codelet Feedback

The field `starpu_codelet::per_worker_stats` is an array of counters. The \( i \)-th entry of the array is incremented every time a task implementing the codelet is executed on the \( i \)-th worker. This array is not reinitialized when profiling is enabled or disabled.

13.1.4 Per-worker Feedback

The second argument returned by the function `starpu_profiling_worker_get_info()` is a structure `starpu_profiling_worker_info` that gives statistics about the specified worker. This structure specifies when StarPU started collecting profiling information for that worker (`starpu_profiling_worker_info::start_time`), the duration of the profiling measurement interval (`starpu_profiling_worker_info::total_time`), the time spent executing kernels (`starpu_profiling_worker_info::executing_time`), the time spent sleeping because there is no task to execute at all (`starpu_profiling_worker_info::sleeping_time`), and the number of tasks that were executed while profiling was enabled. These values give
an estimation of the proportion of time spent do real work, and the time spent either sleeping because there are not
enough executable tasks or simply wasted in pure StarPU overhead.

Calling `starpu_profiling_worker_get_info()` resets the profiling information associated to a worker.

To easily display all this information, the environment variable `STARPU_WORKER_STATS` can be set to 1 (in
addition to setting `STARPU_PROFILING` to 1). A summary will then be displayed at program termination:

Worker stats:
CUDA 0.0 (4.7 GiB)
480 task(s)
total: 1574.82 ms executing: 1510.72 ms sleeping: 0.00 ms overhead 64.10 ms
325.217970 GFlop/s

CPU 0
22 task(s)
total: 1574.82 ms executing: 1364.81 ms sleeping: 0.00 ms overhead 210.01 ms
7.512057 GFlop/s

CPU 1
14 task(s)
total: 1574.82 ms executing: 1500.13 ms sleeping: 0.00 ms overhead 74.69 ms
6.675853 GFlop/s

CPU 2
14 task(s)
total: 1574.82 ms executing: 1553.12 ms sleeping: 0.00 ms overhead 21.70 ms
7.152886 GFlop/s

The number of GFlops is available because the `starpu_task::flops` field of the tasks were filled (or `STARPU_FLOPS`
used in `starpu_task_insert()`).

When an FxT trace is generated (see Generating Traces With FxT), it is also possible to use the tool `starpu_r-
workers_activity` (see Monitoring Activity) to generate a graphic showing the evolution of these values during
the time, for the different workers.

13.1.5 Bus-related Feedback

The bus speed measured by StarPU can be displayed by using the tool `starpu_machine_display`, for
instance:

StarPU has found:
3 CUDA devices
CUDA 0 (Tesla C2050 02:00.0)
CUDA 1 (Tesla C2050 03:00.0)
CUDA 2 (Tesla C2050 84:00.0)

from to RAM to CUDA 0 to CUDA 1 to CUDA 2
RAM 0.000000 5176.530428 5176.492994 5191.710722
CUDA 0 4523.732446 0.000000 2414.074751 2417.375119
CUDA 1 4523.718152 2414.078822 0.000000 2417.375119
CUDA 2 4534.229519 2417.069025 2417.060863 0.000000

Statistics about the data transfers which were performed and temporal average of bandwidth usage can be obtained
by setting the environment variable `STARPU_BUS_STATS` to 1; a summary will then be displayed at program
termination:

Data transfer stats:
RAM 0 -> CUDA 0 319.92 MB 213.10 MB/s (transfers : 91 - avg 3.52 MB)
CUDA 0 -> RAM 0 214.45 MB 142.85 MB/s (transfers : 61 - avg 3.52 MB)
RAM 0 -> CUDA 1 302.34 MB 201.39 MB/s (transfers : 86 - avg 3.52 MB)
CUDA 1 -> RAM 0 133.59 MB 88.99 MB/s (transfers : 38 - avg 3.52 MB)
CUDA 1 -> CUDA 0 144.14 MB 96.01 MB/s (transfers : 41 - avg 3.52 MB)
CUDA 1 -> CUDA 0 130.08 MB 86.64 MB/s (transfers : 37 - avg 3.52 MB)
RAM 0 -> CUDA 2 312.89 MB 208.42 MB/s (transfers : 89 - avg 3.52 MB)
CUDA 2 -> RAM 0 133.59 MB 88.99 MB/s (transfers : 38 - avg 3.52 MB)
CUDA 0 -> CUDA 2 151.17 MB 100.69 MB/s (transfers : 43 - avg 3.52 MB)
CUDA 2 -> CUDA 0 155.78 MB 117.09 MB/s (transfers : 50 - avg 3.52 MB)
CUDA 2 -> CUDA 1 203.91 MB 135.82 MB/s (transfers : 58 - avg 3.52 MB)
Total transfers: 2.27 GB
13.1.6 MPI-related Feedback

Statistics about the data transfers which were performed over MPI can be obtained by setting the environment variable \texttt{STARPU\_COMM\_STATS} to 1; a summary will then be displayed at program termination:

\begin{verbatim}
[starpu_comm_stats][1] TOTAL: 456.000000 B 0.000435 MB 0.000188 B/s 0.000000 MB/s
[starpu_comm_stats][1:0] 456.000000 B 0.000435 MB 0.000188 B/s 0.000000 MB/s
[starpu_comm_stats][0] TOTAL: 456.000000 B 0.000435 MB 0.000188 B/s 0.000000 MB/s
[starpu_comm_stats][0:1] 456.000000 B 0.000435 MB 0.000188 B/s 0.000000 MB/s
\end{verbatim}

These statistics can be plotted as heatmaps using StarPU tool \texttt{starpu_mpi_comm_matrix.py} (see Debugging MPI).

13.2 Task And Worker Profiling

A full example showing how to use the profiling API is available in the StarPU sources in the directory \texttt{examples/profiling/}.

```c
struct starpu_task *task = starpu_task_create();
task->cl = &cl;
task->synchronous = 1;
/* We will destroy the task structure by hand so that we can
 * query the profiling info before the task is destroyed. */
task->destroy = 0;

/* Submit and wait for completion (since synchronous was set to 1) */
starpu_task_submit(task);

/* The task is finished, get profiling information */
struct starpu_profiling_task_info *info = task->profiling_info;

/* How much time did it take before the task started ? */
double delay += starpu_timing_timespec_delay_us(&info->submit_time,
                 &info->start_time);

/* How long was the task execution ? */
double length += starpu_timing_timespec_delay_us(&info->start_time,
                 &info->end_time);

/* We no longer need the task structure */
starpu_task_destroy(task);

/* Display the occupancy of all workers during the test */
int worker;
for (worker = 0; worker < starpu_worker_get_count(); worker++)
{
    struct starpu_profiling_worker_info worker_info;
    int ret = starpu_profiling_worker_get_info(worker, &worker_info);
    STARPU_ASSERT(!ret);
    double total_time = starpu_timing_timespec_to_us(&worker_info.total_time);
    double executing_time = starpu_timing_timespec_to_us(&worker_info.executing_time);
    double sleeping_time = starpu_timing_timespec_to_us(&worker_info.sleeping_time);
    double overhead_time = total_time - executing_time - sleeping_time;
    float executing_ratio = 100.0*executing_time/total_time;
    float sleeping_ratio = 100.0*sleeping_time/total_time;
    float overhead_ratio = 100.0 - executing_ratio - sleeping_ratio;
    char workername[128];
    starpu_worker_get_name(worker, workername, 128);
    fprintf(stderr, "Worker %s:
", workername);
    fprintf(stderr, "total time: %.2lf ms
", total_time*1e-3);
    fprintf(stderr, "executing time: %.2lf ms (%.2f %%)
", executing_time*1e-3, executing_ratio);
    fprintf(stderr, "sleeping time: %.2lf ms (%.2f %%)
", sleeping_time*1e-3, sleeping_ratio);
    fprintf(stderr, "overhead time: %.2lf ms (%.2f %%)
", overhead_time*1e-3, overhead_ratio);
}
```

13.3 Performance Model Example

To achieve good scheduling, StarPU scheduling policies need to be able to estimate in advance the duration of a task. This is done by giving to codelets a performance model, by defining a structure \texttt{starpu_perfmodel} and providing
its address in the field starpu_codelet::model. The fields starpu_perfmodel::symbol and starpu_perfmodel::type are mandatory, to give a name to the model, and the type of the model, since there are several kinds of performance models. For compatibility, make sure to initialize the whole structure to zero, either by using explicit memset(), or by letting the compiler implicitly do it as exemplified below.

- Measured at runtime (model type STARPU_HISTORY_BASED). This assumes that for a given set of data input/output sizes, the performance will always be about the same. This is very true for regular kernels on GPUs for instance (<0.1% error), and just a bit less true on CPUs (~1% error). This also assumes that there are few different sets of data input/output sizes. StarPU will then keep record of the average time of previous executions on the various processing units, and use it as an estimation. History is done per task size, by using a hash of the input and output sizes as an index. It will also save it in $STARPU_HOME/.starpu/sampling/codelets for further executions, and can be observed by using the tool starpu_perfmodel_display, or drawn by using the tool starpu_perfmodel_plot (Performance Model Calibration). The models are indexed by machine name. To share the models between machines (e.g. for a homogeneous cluster), use export STARPU_HOSTNAME=some_global_name. Measurements are only done when using a task scheduler which makes use of it, such as dmda. Measurements can also be provided explicitly by the application, by using the function starpu_perfmodel_update_history().

The following is a small code example.

If e.g. the code is recompiled with other compilation options, or several variants of the code are used, the symbol string should be changed to reflect that, in order to recalibrate a new model from zero. The symbol string can even be constructed dynamically at execution time, as long as this is done before submitting any task using it.

```c
static struct starpu_perfmodel mult_perf_model =
{
  .type = STARPU_HISTORY_BASED,
  .symbol = "mult_perf_model"
};
struct starpu_codelet cl =
{
  .cpu_funcs = { cpu_mult },
  .cpu_funcs_name = { "cpu_mult" },
  .nbuffers = 3,
  .modes = { STARPU_R, STARPU_R, STARPU_W },
  .model = &mult_perf_model
};
```

- Measured at runtime and refined by regression (model types STARPU_REGRESSION_BASED and STARPU_NL_REGRESSION_BASED). This still assumes performance regularity, but works with various data input sizes, by applying regression over observed execution times. STARPU_REGRESSION_BASED uses an $a*n^b$ regression form, STARPU_NL_REGRESSION_BASED uses an $a*n^b+c$ (more precise than STARPU_REGRESSION_BASED, but costs a lot more to compute).

For instance, tests/perfmodels/regression_based.c uses a regression-based performance model for the function memset().

Of course, the application has to issue tasks with varying size so that the regression can be computed. StarPU will not trust the regression unless there is at least 10% difference between the minimum and maximum observed input size. It can be useful to set the environment variable STARPU_CALIBRATE to 1 and run the application on varying input sizes with STARPU_SCHED set to dmda scheduler, so as to feed the performance model for a variety of inputs. The application can also provide the measurements explicitly by using the function starpu_perfmodel_update_history(). The tools starpu_perfmodel_display and starpu_perfmodel_plot can be used to observe how much the performance model is calibrated (Performance Model Calibration); when their output look good, STARPU_CALIBRATE can be reset to 0 to let StarPU use the resulting performance model without recording new measures, and STARPU_SCHED can be set to dmda to benefit from the performance models. If the data input sizes vary a lot, it is really important to set STARPU_CALIBRATE to 0, otherwise StarPU will continue adding the measures, and result with a very big performance model, which will take time a lot of time to load and save.

For non-linear regression, since computing it is quite expensive, it is only done at termination of the application. This means that the first execution of the application will use only history-based performance model to perform scheduling, without using regression.
• Another type of model is \texttt{STARPU\_MULTIPLE\_REGRESSION\_BASED}, which is based on multiple linear regression. In this model, the user defines both the relevant parameters and the equation for computing the task duration.

\[ T_{\text{kernel}} = a + b(M^{\alpha_1} \times N^{\beta_1} \times K^{\gamma_1}) + c(M^{\alpha_2} \times N^{\beta_2} \times K^{\gamma_2}) + \ldots \]

\(M, N, K\) are the parameters of the task, added at the task creation. These need to be extracted by the \texttt{cl\_perf\_func} function, which should be defined by the user. \(\alpha, \beta, \gamma\) are the exponents defined by the user in \texttt{model\rightarrow combinations} table. Finally, coefficients \(a, b, c\) are computed automatically by the StarPU at the end of the execution, using least squares method of the \texttt{dgels\_LAPACK} function.

\texttt{examples/mlr/mlr.c} example provides more details on the usage of \texttt{STARPU\_MULTIPLE\_REGRESSION\_BASED} models.

Coefficients computation is done at the end of the execution, and the results are stored in standard codelet \texttt{permodel} files. Additional files containing the duration of task together with the value of each parameter are stored in \texttt{.starpu/sampling/codelets/tmp/} directory. These files are reused when \texttt{STARPU\_CALIBRATE} environment variable is set to 1, to recompute coefficients based on the current, but also on the previous executions. Additionally, when multiple linear regression models are disabled (using \texttt{--disable-mlr configure option}) or when the \texttt{model\rightarrow combinations} are not defined, StarPU will still write output files into \texttt{.starpu/sampling/codelets/tmp/} to allow performing an analysis. This analysis typically aims at finding the most appropriate equation for the codelet and \texttt{tools/starpu_mlr_analysis} script provides an example of how to perform such study.

• Provided as an estimation from the application itself (model type \texttt{STARPU\_COMMON} and field \texttt{starpu\_permodel:cost\_function}), see for instance \texttt{examples/common/blas\_model.c} and \texttt{examples/common/blas\_model.h}.

• Provided explicitly by the application (model type \texttt{STARPU\_PER\_ARCH}): either field \texttt{starpu\_permodel::arch\_cost\_function}, or the fields \texttt{.per\_arch[arch][nimpl].cost\_function} have to be filled with pointers to functions which return the expected duration of the task in micro-seconds, one per architecture, see for instance \texttt{tests/datawizard/locality.c}.

For \texttt{STARPU\_HISTORY\_BASED}, \texttt{STARPU\_REGRESSION\_BASED}, and \texttt{STARPU\_NL\_REGRESSION\_BASED}, the dimensions of task data (both input and output) are used as an index by default. \texttt{STARPU\_HISTORY\_BASED} uses a CRC hash of the dimensions as an index to distinguish histories, and \texttt{STARPU\_REGRESSION\_BASED} and \texttt{STARPU\_NL\_REGRESSION\_BASED} use the total size as an index for the regression.

The \texttt{starpu\_permodel: size\_base} and \texttt{starpu\_permodel: footprint} fields however permit the application to override that, when for instance some of the data do not matter for task cost (e.g. mere reference table), or when using sparse structures (in which case it is the number of non-zeros which matter), or when there is some hidden parameter such as the number of iterations, or when the application actually has a very good idea of the complexity of the algorithm, and just not the speed of the processor, etc. The example in the directory \texttt{examples/pi} uses this to include the number of iterations in the base size. \texttt{starpu\_permodel: size\_base} should be used when the variance of the actual performance is known (i.e. bigger return value is longer execution time), and thus particularly useful for \texttt{STARPU\_REGRESSION\_BASED} or \texttt{STARPU\_NL\_REGRESSION\_BASED}. \texttt{starpu\_permodel: footprint} can be used when the variance of the actual performance is unknown (irregular performance behavior, etc.), and thus only useful for \texttt{STARPU\_HISTORY\_BASED}. \texttt{starpu\_task\_data\_footprint()} can be used as a base and combined with other parameters through \texttt{starpu\_hash\_crc32c\_be()} for instance.

StarPU will automatically determine when the performance model is calibrated, or rather, it will assume the performance model is calibrated until the application submits a task for which the performance can not be predicted. For \texttt{STARPU\_HISTORY\_BASED}, StarPU will require 10 (\texttt{STARPU\_CALIBRATE\_MINIMUM}) measurements for a given size before estimating that an average can be taken as estimation for further executions with the same size. For \texttt{STARPU\_REGRESSION\_BASED} and \texttt{STARPU\_NL\_REGRESSION\_BASED}, StarPU will require 10 (\texttt{STARPU\_CALIBRATE\_MINIMUM}) measurements, and that the minimum measured data size is smaller than 90\% of the maximum measured data size (i.e. the measurement interval is large enough for a regression to have a meaning).

Calibration can also be forced by setting the \texttt{STARPU\_CALIBRATE} environment variable to 1, or even reset by setting it to 2.

How to use schedulers which can benefit from such performance model is explained in \texttt{Task\ Scheduling\ Policies}. The same can be done for task energy consumption estimation, by setting the field \texttt{starpu\_codelet:energy\_model} the same way as the field \texttt{starpu\_codelet::model}. Note: for now, the application has to give to the energy consumption performance model a name which is different from the execution time performance model.
The application can request time estimations from the StarPU performance models by filling a task structure as usual without actually submitting it. The data handles can be created by calling any of the functions `starpu_*_data_register` with a NULL pointer and -1 node and the desired data sizes, and need to be unregistered as usual. The functions `starpu_task_expected_length()` and `starpu_task_expected_energy()` can then be called to get an estimation of the task cost on a given arch. `starpu_task_footprint()` can also be used to get the footprint used for indexing history-based performance models. `starpu_task_destroy()` needs to be called to destroy the dummy task afterwards. See `tests/perfmodels/regression_based.c` for an example.

The application can also request an on-the-fly XML report of the performance model, by calling `starpu_perfmodel_dump_xml()` to print the report to a FILE*.

### 13.4 Data trace and tasks length

It is possible to get statistics about tasks length and data size by using:

```
$ starpu_fxt_data_trace filename [codelet1 codelet2 ... codeletn]
```

Where filename is the FxT trace file and codeletX the names of the codelets you want to profile (if no names are specified, `starpu_fxt_data_trace` will profile them all). This will create a file, `data_trace.gp` which can be executed to get a .eps image of these results. On the image, each point represents a task, and each color corresponds to a codelet.
Chapter 14

Offline Performance Tools

To get an idea of what is happening, a lot of performance feedback is available, detailed in this chapter. The various informations should be checked for.

- What does the Gantt diagram look like? (see Creating a Gantt Diagram)
  - If it's mostly green (tasks running in the initial context) or context specific color prevailing, then the machine is properly utilized, and perhaps the codelets are just slow. Check their performance, see Performance Of Codelets.
  - If it's mostly purple (FetchingInput), tasks keep waiting for data transfers, do you perhaps have far more communication than computation? Did you properly use CUDA streams to make sure communication can be overlapped? Did you use data-locality aware schedulers to avoid transfers as much as possible?
  - If it's mostly red (Blocked), tasks keep waiting for dependencies, do you have enough parallelism? It might be a good idea to check what the DAG looks like (see Creating a DAG With Graphviz).
  - If only some workers are completely red (Blocked), for some reason the scheduler didn't assign tasks to them. Perhaps the performance model is bogus, check it (see Performance Of Codelets). Do all your codelets have a performance model? When some of them don't, the schedulers switches to a greedy algorithm which thus performs badly.

You can also use the Temanejo task debugger (see Using The Temanejo Task Debugger) to visualize the task graph more easily.

14.1 Off-line Performance Feedback

14.1.1 Generating Traces With FxT

StarPU can use the FxT library (see https://savannah.nongnu.org/projects/fkt/) to generate traces with a limited runtime overhead.

You can get a tarball from http://download.savannah.gnu.org/releases/fkt/

Compiling and installing the FxT library in the $FXTDIR path is done following the standard procedure:

```
$ ./configure --prefix=$FXTDIR
$ make
$ make install
```

In order to have StarPU to generate traces, StarPU should be configured with the option `--with-fxt`:

```
$ ./configure --with-fxt
```

Or you can simply point the `PKG_CONFIG_PATH` to `$FXTDIR/lib/pkgconfig` and pass `--with-fxt` to configure

When FxT is enabled, a trace is generated when StarPU is terminated by calling `starpu_shutdown()`. The trace is a binary file whose name has the form `prof_file_XXX_YYY` where XXX is the user name, and YYY is the pid of the process that used StarPU. This file is saved in the `/tmp/` directory by default, or by the directory specified by the environment variable `STARPU_FXT_PREFIX`. 
The additional configure option `--enable-fxt-lock` can be used to generate trace events which describes the locks behaviour during the execution. It is however very heavy and should not be used unless debugging StarPU’s internal locking.

The environment variable `STARPU_FXTTRACE` can be set to 0 to disable the generation of the `prof_file_<XXX>_YYY` file.

When the FxT trace file `prof_file_something` has been generated, it is possible to generate different trace formats by calling:

```bash
$ starpu_fxt_tool -i /tmp/prof_file_something
```

Or alternatively, setting the environment variable `STARPU_GENERATE_TRACE` to 1 before application execution will make StarPU do it automatically at application shutdown.

One can also set the environment variable `STARPU_GENERATE_TRACE_OPTIONS` to specify options, see `starpu_fxt_tool -help` for example:

```bash
$ export STARPU_GENERATE_TRACE=1
$ export STARPU_GENERATE_TRACE_OPTIONS="--no-acquire"
```

When running a MPI application, `STARPU_GENERATE_TRACE` will not work as expected (each node will try to generate trace files, thus mixing outputs...), you have to collect the trace files from the MPI nodes, and specify them all on the command `starpu_fxt_tool`, for instance:

```bash
$ starpu_fxt_tool -i /tmp/prof_file_something*
```

By default, the generated trace contains all informations. To reduce the trace size, various `--no-foo` options can be passed to `starpu_fxt_tool`, see `starpu_fxt_tool -help`.

### 14.1.1.1 Creating a Gantt Diagram

One of the generated files is a trace in the Paje format. The file, located in the current directory, is named `paje.trace`. It can be viewed with VITE (http://vite.gforge.inria.fr/) a trace visualizing open-source tool. To open the file `paje.trace` with VITE, use the following command:

```bash
$ vite paje.trace
```

Tasks can be assigned a name (instead of the default `unknown`) by filling the optional `starpu_codelet::name`, or assigning them a performance model. The name can also be set with the field `starpu_task::name` or by using `STARPU_NAME` when calling `starpu_task_insert()`. Tasks are assigned default colors based on the worker which executed them (green for CPUs, yellow/orange/red for CUDAs, blue for OpenCLs, red for MICs, ...). To use a different color for every type of task, one can specify the option `-c` to `starpu_fxt_tool` or in `STARPU_GENERATE_TRACE_OPTIONS`. Tasks can also be given a specific color by setting the field `starpu_codelet::color` or the `starpu_task::color`. Colors are expressed with the following format `0xRRGGBB` (e.g `0xFF0000` for red). See `basic_examples/task_insert_color` for examples on how to assign colors.

To identify tasks precisely, the application can also set the field `starpu_task::tag_id` or setting `STARPU_UNIQUE` when calling `starpu_task_insert()`. The value of the tag will then show up in the trace.

One can also introduce user-defined events in the diagram thanks to the `starpu_fxt_trace_user_event_string()` function.

One can also set the iteration number, by just calling `starpu_iteration_push()` at the beginning of submission loops and `starpu_iteration_pop()` at the end of submission loops. These iteration numbers will show up in traces for all tasks submitted from there.

Coordinates can also be given to data with the `starpu_data_set_coordinates()` or `starpu_data_set_coordinates_array()` function. In the trace, tasks will then be assigned the coordinates of the first data they write to.

Traces can also be inspected by hand by using the tool `fxt_print`, for instance:

```bash
$ fxt_print -o -f /tmp/prof_file_something
```

Timings are in nanoseconds (while timings as seen in VITE are in milliseconds).

### 14.1.1.2 Creating a DAG With Graphviz

Another generated trace file is a task graph described using the DOT language. The file, created in the current directory, is named `dag.dot` file in the current directory. It is possible to get a graphical output of the graph by using the `graphviz` library:

```bash
$ dot -Tpdf dag.dot -o output.pdf
```
14.1 Off-line Performance Feedback

14.1.1.3 Getting Task Details

Another generated trace file gives details on the executed tasks. The file, created in the current directory, is named tasks.rec. This file is in the recutils format, i.e. Field: value lines, and empty lines to separate each task. This can be used as a convenient input for various ad-hoc analysis tools. By default it only contains information about the actual execution. Performance models can be obtained by running `starpu_tasks_rec_complete` on it:

```
$ starpu_tasks_rec_complete tasks.rec tasks2.rec
```

which will add EstimatedTime lines which contain the performance model-estimated time (in µs) for each worker starting from 0. Since it needs the performance models, it needs to be run the same way as the application execution, or at least with STARPU_HOSTNAME set to the hostname of the machine used for execution, to get the performance models of that machine.

Another possibility is to obtain the performance models as an auxiliary perfmodel.rec file, by using the `starpu_perfmodel_recdump` utility:

```
$ starpu_perfmodel_recdump tasks.rec -o perfmodel.rec
```

14.1.1.4 Monitoring Activity

Another generated trace file is an activity trace. The file, created in the current directory, is named activity.data. A profile of the application showing the activity of StarPU during the execution of the program can be generated:

```
$ starpu_workers_activity activity.data
```

This will create a file named activity.eps in the current directory. This picture is composed of two parts. The first part shows the activity of the different workers. The green sections indicate which proportion of the time was spent executed kernels on the processing unit. The red sections indicate the proportion of time spent in StarPU: an important overhead may indicate that the granularity may be too low, and that bigger tasks may be appropriate to use the processing unit more efficiently. The black sections indicate that the processing unit was blocked because there was no task to process: this may indicate a lack of parallelism which may be alleviated by creating more tasks when it is possible.

The second part of the picture activity.eps is a graph showing the evolution of the number of tasks available in the system during the execution. Ready tasks are shown in black, and tasks that are submitted but not schedulable yet are shown in grey.

14.1.1.5 Getting Modular Scheduler Animation

When using modular schedulers (i.e. schedulers which use a modular architecture, and whose name start with "modular-"), the call to `starpu_fxt_tool` will also produce a trace.html file which can be viewed in a javascript-enabled web browser. It shows the flow of tasks between the components of the modular scheduler.

14.1.2 Limiting The Scope Of The Trace

For computing statistics, it is useful to limit the trace to a given portion of the time of the whole execution. This can be achieved by calling

```
starpu_fxt_autostart_profiling(0)
```

before calling `starpu_init()`, to prevent tracing from starting immediately. Then

```
starpu_fxt_start_profiling();
```

and

```
starpu_fxt_stop_profiling();
```

can be used around the portion of code to be traced. This will show up as marks in the trace, and states of workers will only show up for that portion.
14.2 Performance Of Codelets

The performance model of codelets (see Performance Model Example) can be examined by using the tool `starpu_perfmodel_display`:

```
$ starpu_perfmodel_display -l
file: <malloc_pinned.hannibal>
file: <starpu_slu_lu_model_21.hannibal>
file: <starpu_slu_lu_model_11.hannibal>
file: <starpu_slu_lu_model_22.hannibal>
file: <starpu_slu_lu_model_12.hannibal>
```

Here, the codelets of the example `lu` are available. We can examine the performance of the kernel `22` (in microseconds), which is history-based:

```
$ starpu_perfmodel_display -s starpu_slu_lu_model_22
```

<table>
<thead>
<tr>
<th>footprint</th>
<th>size</th>
<th>mean</th>
<th>dev</th>
<th>n</th>
</tr>
</thead>
<tbody>
<tr>
<td>57618ab0</td>
<td>196080</td>
<td>2.851969e+05</td>
<td>1.829369e+04</td>
<td>109</td>
</tr>
</tbody>
</table>

Performance model for cpu

<table>
<thead>
<tr>
<th>footprint</th>
<th>size</th>
<th>mean</th>
<th>dev</th>
<th>n</th>
</tr>
</thead>
<tbody>
<tr>
<td>57618ab0</td>
<td>196080</td>
<td>1.164144e+04</td>
<td>1.556094e+01</td>
<td>315</td>
</tr>
</tbody>
</table>

Performance model for cuda_0

<table>
<thead>
<tr>
<th>footprint</th>
<th>size</th>
<th>mean</th>
<th>dev</th>
<th>n</th>
</tr>
</thead>
<tbody>
<tr>
<td>57618ab0</td>
<td>196080</td>
<td>1.164271e+04</td>
<td>1.330628e+01</td>
<td>360</td>
</tr>
</tbody>
</table>

Performance model for cuda_1

<table>
<thead>
<tr>
<th>footprint</th>
<th>size</th>
<th>mean</th>
<th>dev</th>
<th>n</th>
</tr>
</thead>
<tbody>
<tr>
<td>57618ab0</td>
<td>196080</td>
<td>1.166730e+04</td>
<td>3.390395e+02</td>
<td>456</td>
</tr>
</tbody>
</table>

Performance model for cuda_2

We can see that for the given size, over a sample of a few hundreds of execution, the GPUs are about 20 times faster than the CPUs (numbers are in us). The standard deviation is extremely low for the GPUs, and less than 10% for CPUs.

This tool can also be used for regression-based performance models. It will then display the regression formula, and in the case of non-linear regression, the same performance log as for history-based performance models:

```
$ starpu_perfmodel_display -s non_linear_memset_regression_based
```

Regression : #sample = 1400
Linear: y = alpha size ^ beta
alpha = 1.335973e-03
beta = 8.024020e-01
Non-Linear: y = a size ^b + c
a = 5.429195e-04
b = 8.654899e-01
c = 9.009313e-01

We can see that for the given size, over a sample of a few hundreds of execution, the GPUs are about 20 times faster than the CPUs (numbers are in us). The standard deviation is extremely low for the GPUs, and less than 10% for CPUs.

This tool can also be used for regression-based performance models. It will then display the regression formula, and in the case of non-linear regression, the same performance log as for history-based performance models:

```
$ starpu_perfmodel_display -s non_linear_memset_regression_based
```

Regression : #sample = 1400
Linear: y = alpha size ^ beta
alpha = 1.335973e-03
beta = 8.024020e-01
Non-Linear: y = a size ^b + c
a = 5.429195e-04
b = 8.654899e-01
c = 9.009313e-01

The same can also be achieved by using StarPU’s library API, see Performance Model and notably the function `starpu_perfmodel_load_symbol()`. The source code of the tool `starpu_perfmodel_display` can be a useful example.

An XML output can also be printed by using the `-x` option:

```
tools/starpu_perfmodel_display -x -s non_linear_memset_regression_based
<xml version="1.0" encoding="UTF-8">
<DOCTYPE StarPUPerfmodel SYSTEM "starpu-perfmodel.dtd">
<symbol non_linear_memset_regression_based -->
</symbol>
</xml>
```
The tool `starpu_perfmodel_plot` can be used to draw performance models. It writes a `.gp` file in the current directory, to be run with the tool gnuplot, which shows the corresponding curve.

When the field `starpu_task::flops` is set (or `STARPU_FLOPS` is passed to `starpu_task_insert()`), `starpu_perfmodel_plot` can directly draw a GFlops curve, by simply adding the `-f` option:

```
$ starpu_perfmodel_plot -f -s chol_model_11
```

This will however disable displaying the regression model, for which we can not compute GFlops.
When the FxT trace file `prof_file_something` has been generated, it is possible to get a profiling of each codelet by calling:

```bash
$ starpu_fxt_tool -i /tmp/prof_file_something
$ starpu_codelet_profile distrib.data codelet_name
```

This will create profiling data files, and a `distrib.data.gp` file in the current directory, which draws the distribution of codelet time over the application execution, according to data input size.
This is also available in the tool `starpu_perfmodel_plot`, by passing it the fxt trace:

```bash
$ starpu_perfmodel_plot -s non_linear_memset_regression_based -i /tmp/prof_file_foo_0
```

It will produce a `.gp` file which contains both the performance model curves, and the profiling measurements.
If you have the statistical tool \texttt{R} installed, you can additionally use

\begin{verbatim}
$ starpu_codelet_histo_profile distrib.data
\end{verbatim}

Which will create one .pdf file per codelet and per input size, showing a histogram of the codelet execution time distribution.

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{histogram.png}
\caption{Histogram of $val[\text{val} > \text{quantile(val, 0.01)} \& \text{val} < \text{quantile(val, 0.99)}]$}
\end{figure}

14.3 Trace Statistics

More than just codelet performance, it is interesting to get statistics over all kinds of StarPU states (allocations, data transfers, etc.). This is particularly useful to check what may have gone wrong in the accuracy of the simgrid simulation.

This requires the \texttt{R} statistical tool, with the \texttt{plyr}, \texttt{ggplot2} and \texttt{data.table} packages. If your system distribution does not have packages for these, one can fetch them from CRAN:

\begin{verbatim}
$ R
> install.packages("plyr")
> install.packages("ggplot2")
> install.packages("data.table")
> install.packages("knitr")
\end{verbatim}
The **pj_dump** tool from pajeng is also needed (see [https://github.com/schnorr/pajeng](https://github.com/schnorr/pajeng)). One can then get textual or `.csv` statistics over the trace states:

```bash
$ starpu_paje_state_stats -v native.trace simgrid.trace
"Value" "Events_native.csv" "Duration_native.csv" "Events_simgrid.csv" "Duration_simgrid.csv"
"Callback" 220 0.075978 220 0
"chol_model_11" 10 565.176 10 572.8695
"chol_model_21" 45 9184.828 45 9170.719
"chol_model_22" 165 64712.07 165 64299.203
$ starpu_paje_state_stats native.trace simgrid.trace
```

An other way to get statistics of StarPU states (without installing R and **pj_dump**) is to use the `starpu_trace_state_stats.py` script which parses the generated `trace.rec` file instead of the `paje.trace` file. The output is similar to the previous script but it doesn't need any dependencies.

The different prefixes used in `trace.rec` are:

- **E**: Event type
- **N**: Event name
- **C**: Event category
- **W**: Worker ID
- **T**: Thread ID
- **S**: Start time

Here's an example on how to use it:

```bash
$ python starpu_trace_state_stats.py trace.rec | column -t -s "," "Name" "Count" "Type" "Duration"
"Callback" 220 Runtime 0.075978
"chol_model_11" 10 Task 565.176
"chol_model_21" 45 Task 9184.828
"chol_model_22" 165 Task 64712.07
```

`starpu_trace_state_stats.py` can also be used to compute the different efficiencies. Refer to the usage description to show some examples. And one can plot histograms of execution times, of several states for instance:

```bash
$ starpu_paje_draw_histogram -n chol_model_11,chol_model_21,chol_model_22 native.trace simgrid.trace
```

and see the resulting pdf file.
A quick statistical report can be generated by using:

```
$ starpu_paje_summary native.trace simgrid.trace
```

it includes gantt charts, execution summaries, as well as state duration charts and time distribution histograms. Other external Paje analysis tools can be used on these traces, one just needs to sort the traces by timestamp order (which not guaranteed to make recording more efficient):

```
$ starpu_paje_sort paje.trace
```

### 14.4 Theoretical Lower Bound On Execution Time

StarPU can record a trace of what tasks are needed to complete the application, and then, by using a linear system, provide a theoretical lower bound of the execution time (i.e. with an ideal scheduling). The computed bound is not really correct when not taking into account dependencies, but for an application which have enough parallelism, it is very near to the bound computed with dependencies enabled (which takes a huge lot more time to compute), and thus provides a good-enough estimation of the ideal execution time. Theoretical Lower Bound On Execution Time Example provides an example on how to use this.
14.5 Theoretical Lower Bound On Execution Time Example

For kernels with history-based performance models (and provided that they are completely calibrated), StarPU can very easily provide a theoretical lower bound for the execution time of a whole set of tasks. See for instance examples/lu/lu_example.c: before submitting tasks, call the function starpu_bound_start(), and after complete execution, call starpu_bound_stop(). starpu_bound_print_lp() or starpu_bound_print_mps() can then be used to output a Linear Programming problem corresponding to the schedule of your tasks. Run it through lp_solve or any other linear programming solver, and that will give you a lower bound for the total execution time of your tasks. If StarPU was compiled with the library glpk installed, starpu_bound_compute() can be used to solve it immediately and get the optimized minimum, in ms. Its parameter integer allows to decide whether integer resolution should be computed and returned.

The deps parameter tells StarPU whether to take tasks, implicit data, and tag dependencies into account. Tags released in a callback or similar are not taken into account, only tags associated with a task are. It must be understood that the linear programming problem size is quadratic with the number of tasks and thus the time to solve it will be very long, it could be minutes for just a few dozen tasks. You should probably use lp_solve -timeout 1 test.pl -wmps test.mps to convert the problem to MPS format and then use a better solver, glpsol might be better than lp_solve for instance (the -pcost option may be useful), but sometimes doesn't manage to converge. cbc might look slower, but it is parallel. For lp_solve, be sure to try at least all the -B options. For instance, we often just use lp_solve -cc -B1 -Bb -Bg -Bp -Bf -Br -BG -Bd -Bs -BB -Bo -Bc -Bi, and the -gr option can also be quite useful. The resulting schedule can be observed by using the tool starpu_lp2paje, which converts it into the Paje format.

Data transfer time can only be taken into account when deps is set. Only data transfers inferred from implicit data dependencies between tasks are taken into account. Other data transfers are assumed to be completely overlapped.

Setting deps to 0 will only take into account the actual computations on processing units. It however still properly takes into account the varying performances of kernels and processing units, which is quite more accurate than just comparing StarPU performances with the fastest of the kernels being used.

The prio parameter tells StarPU whether to simulate taking into account the priorities as the StarPU scheduler would, i.e. schedule prioritized tasks before less prioritized tasks, to check to which extend this results to a less optimal solution. This increases even more computation time.

14.6 Memory Feedback

It is possible to enable memory statistics. To do so, you need to pass the option --enable-memory-stats when running configure. It is then possible to call the function starpu_data_display_memory_stats() to display statistics about the current data handles registered within StarPU.

Moreover, statistics will be displayed at the end of the execution on data handles which have not been cleared out. This can be disabled by setting the environment variable STARPU_MEMORY_STATS to 0.

For example, if you do not unregister data at the end of the complex example, you will get something similar to:

```bash
$ STARPU_MEMORY_STATS=0 .examples/interface/complex
Complex[0] = 45.00 + 12.00 i
Complex[0] = 78.00 + 78.00 i
Complex[0] = 45.00 + 12.00 i
Complex[0] = 45.00 + 12.00 i

$ STARPU_MEMORY_STATS=1 .examples/interface/complex
Complex[0] = 45.00 + 12.00 i
Complex[0] = 78.00 + 78.00 i
Complex[0] = 45.00 + 12.00 i
Complex[0] = 45.00 + 12.00 i

#---------------------
Memory stats:
#-------
Data on Node #3
#------
Data : 0x553ff40
Size : 16

#--
Data access stats
//\ Work Underway
```
### 14.7 Data Statistics

Different data statistics can be displayed at the end of the execution of the application. To enable them, you need to define the environment variable `STARPU_ENABLE_STATS`. When calling `starpu_shutdown()` various statistics will be displayed, execution, MSI cache statistics, allocation cache statistics, and data transfer statistics. The display can be disabled by setting the environment variable `STARPU_STATS` to 0.

```
$ ./examples/cholesky/cholesky_tag
Computation took (in ms) 518.16
Synthetic GFlops : 44.21
#---------------------
MSI cache stats :
TOTAL MSI stats hit 1622 (66.23 %) miss 827 (33.77 %)
...
```

```
$ STARPU_STATS=0 ./examples/cholesky/cholesky_tag
Computation took (in ms) 518.16
Synthetic GFlops : 44.21
```
Chapter 15

Frequently Asked Questions

15.1 How To Initialize A Computation Library Once For Each Worker?

Some libraries need to be initialized once for each concurrent instance that may run on the machine. For instance, a C++ computation class which is not thread-safe by itself, but for which several instanciated objects of that class can be used concurrently. This can be used in StarPU by initializing one such object per worker. For instance, the libstarpufft example does the following to be able to use FFTW on CPUs.

Some global array stores the instanciated objects:

```cpp
fftw_plan plan_cpu[STARPU_NMAXWORKERS];
```

At initialisation time of libstarpu, the objects are initialized:

```cpp
int workerid;
for (workerid = 0; workerid < starpu_worker_get_count(); workerid++)
{
    switch (starpu_worker_get_type(workerid))
    {
        case STARPU_CPU_WORKER:
            plan_cpu[workerid] = fftw_plan(...);
            break;
    }
}
```

And in the codelet body, they are used:

```cpp
static void fft(void *descr[], void *args)
{
    int workerid = starpu_worker_get_id();
    fftw_plan plan = plan_cpu[workerid];
    ...
    fftw_execute(plan, ...);
}
```

This however is not sufficient for FFT on CUDA: initialization has to be done from the workers themselves. This can be done thanks to `starpu_execute_on_each_worker()`. For instance libstarpufft does the following.

```cpp
static void fft_plan_gpu(void *args)
{
    plan plan = args;
    int n2 = plan->n2[0];
    int workerid = starpu_worker_get_id();
    cufftPlan1d(&plan->plans[workerid].plan_cuda, n, _CUFFT_C2C, 1);
    cufftSetStream(plan->plans[workerid].plan_cuda, starpu_cuda_get_local_stream());
}
```

```cpp
void starpufft_plan(void)
{
    starpu_execute_on_each_worker(fft_plan_gpu, plan, STARPU_CUDA);
}
```

15.2 Using The Driver API

Running Drivers
To add a new kind of device to the structure `starpu_driver`, one needs to:

1. Add a member to the union `starpu_driver::id`
2. Modify the internal function `_starpu_launch_drivers()` to make sure the driver is not always launched.
3. Modify the function `starpu_driver_run()` so that it can handle another kind of architecture.
4. Write the new function `_starpu_run_foobar()` in the corresponding driver.

### 15.3 On-GPU Rendering

Graphical-oriented applications need to draw the result of their computations, typically on the very GPU where these happened. Technologies such as OpenGL/CUDA interoperability permit to let CUDA directly work on the OpenGL buffers, making them thus immediately ready for drawing, by mapping OpenGL buffer, textures or renderbuffer objects into CUDA. CUDA however imposes some technical constraints: peer memcpy has to be disabled, and the thread that runs OpenGL has to be the one that runs CUDA computations for that GPU.

To achieve this with StarPU, pass the option `--disable-cuda-memcpy-peer` to `configure`. OpenGL/GLUT has to be initialized first, and the interoperability mode has to be enabled by using the field `starpu_conf::cuda_opengl_interoperability`, and the driver loop has to be run by the application, by using the field `starpu_conf::not_launched_drivers` to prevent StarPU from running it in a separate thread, and by using `starpu_driver_run()` to run the loop. The examples `gl_interop` and `gl_interop_idle` show how it articulates in a simple case, where rendering is done in task callbacks. The former uses `glutMainLoopEvent` to make GLUT progress from the StarPU driver loop, while the latter uses `glutIdleFunc` to make StarPU progress from the GLUT main loop.

Then, to use an OpenGL buffer as a CUDA data, StarPU simply needs to be given the CUDA pointer at registration, for instance:

```c
/* Get the CUDA worker id */
for (workerid = 0; workerid < starpu_worker_get_count(); workerid++)
    if (starpu_worker_get_type(workerid) == STARPU_CUDA_WORKER)
        break;

/* Build a CUDA pointer pointing at the OpenGL buffer */
cudaGraphicsResourceGetMappedPointer((void**)&output, &num_bytes, resource);
/* And register it to StarPU */
starpu_vector_data_register(&handle, starpu_worker_get_memory_node
    (workerid), output, num_bytes / sizeof(float4), sizeof(float4));
/* The handle can now be used as usual */
starpu_task_insert(&cl, STARPU_RW, handle, 0);
/* ... */
/* This gets back data into the OpenGL buffer */
starpu_data_unregister(handle);
```

and display it e.g. in the callback function.
15.4 Using StarPU With MKL 11 (Intel Composer XE 2013)

Some users had issues with MKL 11 and StarPU (versions 1.1rc1 and 1.0.5) on Linux with MKL, using 1 thread for MKL and doing all the parallelism using StarPU (no multithreaded tasks), setting the environment variable MKL_NUM_THREADS to 1, and using the threaded MKL library, with iomp5. Using this configuration, StarPU only uses 1 core, no matter the value of STARPU_NCPU. The problem is actually a thread pinning issue with MKL.


15.5 Thread Binding on NetBSD

When using StarPU on a NetBSD machine, if the topology discovery library hwloc is used, thread binding will fail. To prevent the problem, you should at least use the version 1.7 of hwloc, and also issue the following call:

```bash
$ sysctl -w security.models.extensions.user_set_cpu_affinity=1
```

Or add the following line in the file /etc/sysctl.conf

```
security.models.extensions.user_set_cpu_affinity=1
```

15.6 StarPU permanently eats 100% of all CPUs

Yes, this is on purpose.

By default, StarPU uses active polling on task queues, so as to minimize wake-up latency for better overall performance.

If eating CPU time is a problem (e.g. application running on a desktop), pass option --enable-blocking-drivers to configure. This will add some overhead when putting CPU workers to sleep or waking them, but avoid eating 100% CPU permanently.

15.7 Interleaving StarPU and non-StarPU code

If your application only partially uses StarPU, and you do not want to call starpu_init() / starpu_shutdown() at the beginning/end of each section, StarPU workers will poll for work between the sections. To avoid this behavior, you can "pause" StarPU with the starpu_pause() function. This will prevent the StarPU workers from accepting new work (tasks that are already in progress will not be frozen), and stop them from polling for more work.

Note that this does not prevent you from submitting new tasks, but they won’t execute until starpu_resume() is called. Also note that StarPU must not be paused when you call starpu_shutdown(), and that this function pair works in a push/pull manner, i.e you need to match the number of calls to these functions to clear their effect.

One way to use these functions could be:

```c
starpu_init(NULL);
starpu_pause();  // To submit all the tasks without a single one executing
submit_some_tasks();
starpu_resume();  // The tasks start executing

starpu_task_wait_for_all();
starpu_pause();  // Stop the workers from polling

starpu_resume();

starpu_shutdown();
```

15.8 When running with CUDA or OpenCL devices, I am seeing less CPU cores

Yes, this is on purpose.

Since GPU devices are way faster than CPUs, StarPU needs to react quickly when a task is finished, to feed the GPU with another task (StarPU actually submits a couple of tasks in advance so as to pipeline this, but filling the
pipeline still has to be happening often enough), and thus it has to dedicate threads for this, and this is a very CPU-consuming duty. StarPU thus dedicates one CPU core for driving each GPU by default. Such dedication is also useful when a codelet is hybrid, i.e. while kernels are running on the GPU, the codelet can run some computation, which thus be run by the CPU core instead of driving the GPU. One can choose to dedicate only one thread for all the CUDA devices by setting the \texttt{STARPU\_CUDA\_THREAD\_PER\_DEV} environment variable to 1. The application however should use \texttt{STARPU\_CUDA\_ASYNC} on its CUDA codelets (asynchronous execution), otherwise the execution of a synchronous CUDA codelet will monopolize the thread, and other CUDA devices will thus starve while it is executing.

15.9 StarPU does not see my CUDA device

First make sure that CUDA is properly running outside StarPU: build and run the following program with \texttt{-lcudart}:

```c
#include <stdio.h>
#include <cuda.h>
#include <cuda_runtime.h>

int main(void)
{
    int n, i, version;
    cudaError_t err;
    err = cudaGetDeviceCount(&n);
    if (err)
    {
        fprintf(stderr,"cuda error %d\n", err);
        exit(1);
    }
    cudaDriverGetVersion(&version);
    printf("driver version %d\n", version);
    cudaRuntimeGetVersion(&version);
    printf("runtime version %d\n", version);
    printf("\n");
    for (i = 0; i < n; i++)
    {
        struct cudaDeviceProp props;
        printf("CUDA%d\n", i);
        err = cudaGetDeviceProperties(&props, i);
        if (err)
        {
            fprintf(stderr,"cuda error %d\n", err);
            continue;
        }
        printf("%s\n", props.name);
        printf("%0.3f GB\n", (float) props.totalGlobalMem / (1<<30));
        printf("%u MP\n", props.multiProcessorCount);
        printf("\n");
    }
    return 0;
}
```

If that program does not find your device, the problem is not at the StarPU level, but the CUDA drivers, check the documentation of your CUDA setup.

15.10 StarPU does not see my OpenCL device

First make sure that OpenCL is properly running outside StarPU: build and run the following program with \texttt{-lOpenCL}:

```c
#include <CL/cl.h>
#include <stdio.h>
#include <assert.h>

int main(void)
{
    cl_device_id did[16];
    cl_int err;
    cl_platform_id pid, pids[16];
    cl_uint nplats, nb;
    char buf[128];
    size_t size;
    int i, j;
```
15.11 I keep getting a "Incorrect performance model file" error

The performance model file, used by StarPU to record the performance of codelets, seem to have been corrupted. Perhaps a previous run of StarPU stopped abruptly, and thus could not save it properly. You can have a look at the file if you can fix it, but the simplest way is to just remove the file and run again, StarPU will just have to re-perform calibration for the corresponding codelet.
Part IV

StarPU Extensions
Chapter 16
Out Of Core

16.1 Introduction

When using StarPU, one may need to store more data than what the main memory (RAM) can store. This part describes the method to add a new memory node on a disk and to use it. Similarly to what happens with GPUs (it's actually exactly the same code), when available main memory becomes scarce, StarPU will evict unused data to the disk, thus leaving room for new allocations. Whenever some evicted data is needed again for a task, StarPU will automatically fetch it back from the disk. The principle is that one first registers a disk location, seen by StarPU as a `void*`, which can be for instance a Unix path for the stdio, unistd or unistd_o_direct backends, or a leveldb database for the leveldb backend, an HDF5 file path for the HDF5 backend, etc. The disk backend opens this place with the plug() method. StarPU can then start using it to allocate room and store data there with the disk write method, without user intervention. The user can also use `starpu_disk_open()` to explicitly open an object within the disk, e.g. a file name in the stdio or unistd cases, or a database key in the leveldb case, and then use `starpu_*_register` functions to turn it into a StarPU data handle. StarPU will then use this file as external source of data, and automatically read and write data as appropriate.

In any case, the user also needs to set `STARPU_LIMIT_CPU_MEM` to the amount of data that StarPU will be allowed to afford. By default StarPU will use the machine memory size, but part of it is taken by the kernel, the system, daemons, and the application's own allocated data, whose size can not be predicted. That is why the user needs to specify what StarPU can afford.

Some Out-of-core tests are worth giving a read, see tests/disk/*.*.c

16.2 Use a new disk memory

To use a disk memory node, you have to register it with this function:

```c
int new_dd = starpu_disk_register(starpu_disk_unistd_ops, (void*)"/tmp/", 1024*1024*200);
```

Here, we use the unistd library to realize the read/write operations, i.e. fread/fwrite. This structure must have a path where to store files, as well as the maximum size the software can afford storing on the disk. Don't forget to check if the result is correct! This can also be achieved by just setting environment variables STARPU_DISK_SWAP, STARPU_DISK_SWAP_BACKEND and STARPU_DISK_SWAP_SIZE:

```bash
export STARPU_DISK_SWAP=/tmp
export STARPU_DISK_SWAP_BACKEND=unistd
export STARPU_DISK_SWAP_SIZE=200
```

The backend can be set to stdio (some caching is done by libc and the kernel), unistd (only caching in the kernel), unistd_o_direct (no caching), leveldb, or hdf5.

It is important to understand that when the backend is not set to unistd_o_direct, some caching will occur at the kernel level (the page cache), which will also consume memory... STARPU_LIMIT_CPU_MEM might need to be set to less that half of the machine memory just to leave room for the kernel's page cache, otherwise the kernel
will struggle to get memory. Using `unistd_o_direct` avoids this caching, thus allowing to set `STARPU_LIM←IT_CPU_MEM` to the machine memory size (minus some memory for normal kernel operations, system daemons, and application data).

When the register call is made, StarPU will benchmark the disk. This can take some time.

**Warning:** the size thus has to be at least `STARPU_DISK_SIZE_MIN` bytes!

StarPU will then automatically try to evict unused data to this new disk. One can also use the standard StarPU memory node API to prefetch data etc., see the Standard Memory Library and the Data Interfaces. The disk is unregistered during the `starpu_shutdown()`.

### 16.3 Data Registration

StarPU will only be able to achieve Out-Of-Core eviction if it controls memory allocation. For instance, if the application does the following:

```c
p = malloc(1024*1024*sizeof(float));
fill_with_data(p);
starpu_matrix_data_register(4h, STARPU_MAIN_RAM, (uintptr_t) p, 1024, 1024, 1024, sizeof(float));
```

StarPU will not be able to release the corresponding memory since it's the application which allocated it, and StarPU can not know how, and thus how to release it. One thus have to use the following instead:

```c
starpu_matrix_data_register(4h, -1, NULL, 1024, 1024, 1024, sizeof(float));
starpu_task_insert(cl_fill_with_data, STARPU_W, h, 0);
```

Which makes StarPU automatically do the allocation when the task running `cl-fill_with_data` gets executed. And then if its needs to, it will be able to release it after having pushed the data to the disk. Since no initial buffer is provided to `starpu_matrix_data_register()`, the handle does not have any initial value right after this call, and thus the very first task using the handle needs to use the `STARPU_W` mode like above, `STARPU_R` or `STARPU_RW` would not make sense.

By default, StarPU will try to push any data handle to the disk. To specify whether a given handle should be pushed to the disk, `starpu_data_set_ooc_flag()` should be used.

### 16.4 Using Wont Use

By default, StarPU uses a Least-Recently-Used (LRU) algorithm to determine which data should be evicted to the disk. This algorithm can be hinted by telling which data will no be used in the coming future thanks to `starpu←data_wont_use()`, for instance:

```c
starpu_task_insert(cl_work, STARPU_RW, h, 0);
starpu_data_wont_use(h);
```

StarPU will mark the data as "inactive" and tend to evict to the disk that data rather than others.

### 16.5 Examples: disk_copy

```c
/* Try to write into disk memory
 * Use mechanism to push datas from main ram to disk ram
 */
#include <starpu.h>
#include <stdlib.h>
#include <stdio.h>
#include <math.h>
/* size of one vector */
#define NX (30*1000000/sizeof(double))
#define FPRINTF(ofile, fmt, ...) do { if (!getenv("STARPU_SSILENT")) {fprintf(ofile, fmt, ## __VA_ARGS__); } } while(0)

int main(int argc, char **argv)
{
    / * limit main ram to force to push in disk */
```
setenv("STARPU_LIMIT_CPU_MEM", "160", 1);

/* Initialize StarPU with default configuration */
int ret = starpu_init(NULL);

if (ret == -ENODEV) goto enodev;

/* register a disk */
int new_dd = starpu_disk_register("/tmp/*", (void **) /* */ , 1024*1024*200);
/* can’t write on /tmp/ */
if (new_dd == -ENOENT) goto enoent;

/* allocate two memory spaces */
starpu_malloc_flags((void **) &A, NX*sizeof(double), STARPU_MALLOC_COUNT);
starpu_malloc_flags((void **) &F, NX*sizeof(double), STARPU_MALLOC_COUNT);

fprintf(stderr, "TEST DISK MEMORY \
\n");

unsigned int j;
/* initialization with bad values */
for (j = 0; j < NX; ++j)
{
    A[j] = j;
    F[j] = -j;
}

starpu_data_handle_t vector_handleA, vector_handleB, vector_handleC,
vector_handleD, vector_handleE, vector_handleF;

/* register vector in starpu */
starpu_vector_data_register(&vector_handleA, STARPU_MAIN_RAM,
 summer_t A, NX, sizeof(double));
starpu_vector_data_register(&vector_handleB, NULL, NULL, NX,
 sizeof(double));
starpu_vector_data_register(&vector_handleC, NULL, NULL, NX,
 sizeof(double));
starpu_vector_data_register(&vector_handleD, NULL, NULL, NX,
 sizeof(double));
starpu_vector_data_register(&vector_handleE, NULL, NULL, NX,
 sizeof(double));
starpu_vector_data_register(&vector_handleF, STARPU_MAIN_RAM,
 summer_t F, NX, sizeof(double));

/* copy vector A->B, B->C, C->D, D->E, E->F */
starpu_data_cpy(vector_handleB, vector_handleA, 0, NULL, NULL);
starpu_data_cpy(vector_handleC, vector_handleB, 0, NULL, NULL);
starpu_data_cpy(vector_handleD, vector_handleC, 0, NULL, NULL);
starpu_data_cpy(vector_handleE, vector_handleD, 0, NULL, NULL);
starpu_data_cpy(vector_handleF, vector_handleE, 0, NULL, NULL);

/* StarPU does not need to manipulate the array anymore so we can stop
* monitoring it */

/* free them */
starpu_data_unregister(vector_handleA);
starpu_data_unregister(vector_handleB);
starpu_data_unregister(vector_handleC);
starpu_data_unregister(vector_handleD);
starpu_data_unregister(vector_handleE);
starpu_data_unregister(vector_handleF);

/* check if computation is correct */
int try = 1;
for (j = 0; j < NX; ++j)
    if (A[j] != F[j])
        { printf("Fail A \%f != F \%f \n", A[j], F[j]);
            try = 0;
        }

/* free last vectors */
starpu_free_flags(A, NX*sizeof(double), STARPU_MALLOC_COUNT);
starpu_free_flags(F, NX*sizeof(double), STARPU_MALLOC_COUNT);

/* terminate StarPU, no task can be submitted after */
starpu_shutdown();

if (try)
    fprintf(stderr, "TEST SUCCESS\n");
else
    fprintf(stderr, "TEST FAIL\n");
return (try ? EXIT_SUCCESS : EXIT_FAILURE);

enodev:
return 77;

enoent:
  return 77;
}

16.6 Examples: disk_compute

/* Try to write into disk memory
 * Use mechanism to push datas from main ram to disk ram */

#include <starpu.h>
#include <stdlib.h>
#include <stdio.h>
#include <sys/types.h>
#include <unistd.h>
#include <math.h>

#define NX (1024)

int main(int argc, char **argv)
{
  /* Initialize StarPU with default configuration */
  int ret = starpu_init(NULL);
  if (ret == -ENODEV) goto enodev;

  /* Initialize path and name */
  char pid_str[16];
  int pid = getpid();
  snprintf(pid_str, sizeof(pid_str), "%d", pid);
  const char *name_file_start = "STARPU_DISK_COMPUTE_DATA_";
  const char *name_file_end = "STARPU_DISK_COMPUTE_DATA_RESULT_";
  char *path_file_start = malloc(strlen(base) + 1 + strlen(name_file_start) + 1);
  strcpy(path_file_start, base);
  strcat(path_file_start, "/
  strcat(path_file_start, name_file_start);
  char *path_file_end = malloc(strlen(base) + 1 + strlen(name_file_end) + 1);
  strcpy(path_file_end, base);
  strcat(path_file_end, "/
  strcat(path_file_end, name_file_end);

  /* register a disk */
  int new_dd = starpu_disk_register(&starpu_disk_unistd_ops
    , (void *) base, 1024*1024*1);
  if (new_dd == -ENOENT) goto enoent;
  unsigned dd = (unsigned) new_dd;

  printf("TEST DISK MEMORY
  
  /* Imagine, you want to compute datas */
  int *A;
  int *C;

  starpu_malloc_flags((void **)&A, NX*sizeof(int), STARPU_MALLOC_COUNT
    );
  starpu_malloc_flags((void **)&C, NX*sizeof(int), STARPU_MALLOC_COUNT
    );

  unsigned int j;

  for(j = 0; j < NX; ++j)
    A[j] = j;
  C[j] = 0;

  /* you create a file to store the vector ON the disk */
  FILE *f = fopen(path_file_start, "wb");
  if (f == NULL)
    goto enoent2;

  /* store it in the file */
  fwrite(A, sizeof(int), NX, f);
  /* close the file */
  fclose(f);
/* create a file to store result */
f = fopen(path_file_end, "wb+");
if (f == NULL)
    goto enoent2;

/* replace all datas by 0 */
fwrite(C, sizeof(int), NX, f);
/* close the file */close(f);

/* And now, you want to use your datas in StarPU */
void * data = starpu_disk_open(dd, (void *) name_file_start, NX*sizeof(int));
void * data_result = starpu_disk_open(dd, (void *) name_file_end, NX*sizeof(int));
starpu_data_handle_t vector_handleA, vector_handleC;
/* register vector in starpu */
starpu_vector_data_register(&vector_handleA, dd, (uintptr_t) data, NX, sizeof(int));
/* and do what you want with it, here we copy it into an other vector */
starpu_vector_data_register(&vector_handleC, dd, (uintptr_t) data_result, NX, sizeof(int));
starpu_data_cpy(vector_handleC, vector_handleA, 0, NULL, NULL);
/* free them */
starpu_data_unregister(vector_handleA);
starpu_data_unregister(vector_handleC);
/* close them in StarPU */
starpu_disk_close(dd, data, NX*sizeof(int));
starpu_disk_close(dd, data_result, NX*sizeof(int));
/* check results */
f = fopen(path_file_end, "rb+");
if (f == NULL)
    goto enoent;
/* take datas */
int size = fread(C, sizeof(int), NX, f);
/* close the file */close(f);

int try = 1;
for (j = 0; j < NX; ++j)
    if (A[j] != C[j])
        {
            printf("Fail A %d != C %d\n", A[j], C[j]);
            try = 0;
        }

starpu_free_flags(A, NX*sizeof(int), STARPU_MALLOC_COUNT);
starpu_free_flags(C, NX*sizeof(int), STARPU_MALLOC_COUNT);
unlink(path_file_start);
unlink(path_file_end);
free(path_file_start);
free(path_file_end);
/* terminate StarPU, no task can be submitted after */
starpu_shutdown();
if(try)
    printf("TEST SUCCESS\n");
else
    printf("TEST FAIL\n");
return (try ? EXIT_SUCCESS : EXIT_FAILURE);

enoenv:
    return 77;
enoent2:
    starpu_free_flags(A, NX*sizeof(int), STARPU_MALLOC_COUNT);
    starpu_free_flags(C, NX*sizeof(int), STARPU_MALLOC_COUNT);
    enoent:
    unlink(path_file_start);
    unlink(path_file_end);
    free(path_file_start);
    free(path_file_end);
    starpu_shutdown();
    return 77;
16.7 Performances

Scheduling heuristics for Out-of-core are still relatively experimental. The tricky part is that you usually have to find a compromise between privileging locality (which avoids back and forth with the disk) and privileging the critical path, i.e. taking into account priorities to avoid lack of parallelism at the end of the task graph.

It is notably better to avoid defining different priorities to tasks with low priority, since that will make the scheduler want to schedule them by levels of priority, at the expense of locality.

The scheduling algorithms worth trying are thus dmdar and lws, which privilege data locality over priorities. There will be work on this area in the coming future.

16.8 Feedback Figures

Beyond pure performance feedback, some figures are interesting to have a look at.

Using export STARPU_BUS_STATS=1 gives an overview of the data transfers which were needed. The values can also be obtained at runtime by using starpu_bus_get_profiling_info(). An example can be read in src/profiling/profiling_helpers.c.

```
#---------------------
Data transfer speed for /tmp/sthibault-disk-DJzhA\{node 1\}:
 0 -> 1: 99 MB/s
 1 -> 0: 99 MB/s
 0 -> 1: 23858 µs
 1 -> 0: 23858 µs

#---------------------
TEST DISK MEMORY
#---------------------
Data transfer stats:
Disk 0 -> NUMA 0 0.0000 GB 0.0000 MB/s (transfers : 0 - avg -nan MB)
NUMA 0 -> Disk 0 0.0625 GB 63.6816 MB/s (transfers : 2 - avg 32.0000 MB)
Total transfers: 0.0625 GB
#---------------------

Using export STARPU_ENABLE_STATS=1 gives information for each memory node on data miss/hit and allocation miss/hit.

#---------------------
MSI cache stats :
memory node NUMA 0
hit : 32 (66.67 %)
miss : 16 (33.33 %)
memory node Disk 0
hit : 0 (0.00 %)
miss : 0 (0.00 %)
#---------------------

#---------------------
Allocation cache stats:
memory node NUMA 0
total alloc : 16
cached alloc: 0 (0.00 %)
memory node Disk 0
total alloc : 8
cached alloc: 0 (0.00 %)
#---------------------
```

16.9 Disk functions

There are various ways to operate a disk memory node, described by the structure starpu_disk_ops. For instance, the variable starpu_disk_unistd_ops uses read/write functions.

All structures are in Out Of Core.
Chapter 17

MPI Support

The integration of MPI transfers within task parallelism is done in a very natural way by the means of asynchronous interactions between the application and StarPU. This is implemented in a separate libstarpumpi library which basically provides "StarPU" equivalents of MPI_* functions, where void * buffers are replaced with starpu_* data_handle_t, and all GPU-RAM-NIC transfers are handled efficiently by StarPU-MPI. The user has to use the usual mpirun command of the MPI implementation to start StarPU on the different MPI nodes.

An MPI Insert Task function provides an even more seamless transition to a distributed application, by automatically issuing all required data transfers according to the task graph and an application-provided distribution.

17.1 Example Used In This Documentation

The example below will be used as the base for this documentation. It initializes a token on node 0, and the token is passed from node to node, incremented by one on each step. The code is not using StarPU yet.

```c
for (loop = 0; loop < nloops; loop++)
{
    int tag = loop*size + rank;
    if (loop == 0 && rank == 0)
    {
        token = 0;
        fprintf(stdout, "Start with token value %d\n", token);
    } else
    {
        MPI_Recv(&token, 1, MPI_INT, (rank+size-1)%size, tag, MPI_COMM_WORLD);
    }
    token++;
    if (loop == last_loop && rank == last_rank)
    {
        fprintf(stdout, "Finished: token value %d\n", token);
    } else
    {
        MPI_Send(&token, 1, MPI_INT, (rank+1)%size, tag+1, MPI_COMM_WORLD);
    }
}
```

17.2 About Not Using The MPI Support

Although StarPU provides MPI support, the application programmer may want to keep his MPI communications as they are for a start, and only delegate task execution to StarPU. This is possible by just using starpu_data_acquire(), for instance:

```c
for (loop = 0; loop < nloops; loop++)
{
    int tag = loop*size + rank;

    /* Acquire the data to be able to write to it */
    starpu_data_acquire(token_handle, STARPU_W);
    if (loop == 0 && rank == 0)
    {
        token = 0;
    }
```
In that case, libstarpumpi is not needed. One can also use MPI_Isend() and MPI_Irecv(), by calling starpu_data_release() after MPI_Wait() or MPI_Test() have notified completion. It is however better to use libstarpumpi, to save the application from having to synchronize with starpu_data_acquire(), and instead just submit all tasks and communications asynchronously, and wait for the overall completion.

### 17.3 Simple Example

The flags required to compile or link against the MPI layer are accessible with the following commands:

```
$ pkg-config --cflags starpumpi-1.3 # options for the compiler
$ pkg-config --libs starpumpi-1.3 # options for the linker
```

```c
void increment_token(void)
{
    struct starpu_task *task = starpu_task_create();
    task->cl = &increment_cl;
    task->handles[0] = token_handle;
    starpu_task_submit(task);
}
```

```c
int main(int argc, char **argv)
{
    int rank, size;
    starpu_mpi_init_conf(&argc, &argv, 1, MPI_COMM_WORLD, NULL);
    starpu_mpi_comm_rank(MPI_COMM_WORLD, &rank);
    starpu_mpi_comm_size(MPI_COMM_WORLD, &size);
    starpu_vector_data_register(&token_handle, STARPU_MAIN_RAM, (uintptr_t)&token, 1, sizeof(unsigned));
    unsigned nloops = NITER;
    unsigned loop;
    unsigned last_loop = nloops - 1;
    unsigned last_rank = size - 1;
    for (loop = 0; loop < nloops; loop++)
    {
        int tag = loop*size + rank;
        if (loop == 0 && rank == 0)
        {
            starpu_data_acquire(token_handle, STARPU_W);
            token = 0;
            fprintf(stdout, "Start with token value %d\n", token);
            starpu_data_release(token_handle);
        } else
        {
            starpu_mpi_irecv_detached(token_handle, (rank+size-1)%size, tag, MPI_COMM_WORLD, NULL, NULL);
        }
    } 
    // Task delegation to StarPU to increment the token. The execution might be performed on a CPU, a GPU, etc. */
    increment_token();
    // Acquire the update data to be able to read from it */
    starpu_data_acquire(token_handle, STARPU_R);
    if (loop == last_loop && rank == last_rank)
    {
        fprintf(stdout, "Finished: token value %d\n", token);
    } else
    {
        MPI_Send(&token, 1, MPI_INT, (rank+1)%size, tag+1, MPI_COMM_WORLD);
    }
    starpu_data_release(token_handle);
    return 0;
}
```

Generated by Doxygen
```c
increment_token();

if (loop == last_loop && rank == last_rank)
{
    starpu_data_acquire(token_handle, STARPU_R);
    fprintf(stdout, "Finished: token value %d\n", token);
    starpu_data_release(token_handle);
}
else
{
    starpu_mpi_isend_detached(token_handle, (rank+1)%size, tag+1,
                          MPI_COMM_WORLD, NULL, NULL);
}
}

starpu_task_wait_for_all();

starpu_mpi_shutdown();

if (rank == last_rank)
{
    fprintf(stderr, \[%d\] token = %d == %d * %d ?\n",
        rank, token, nloops, size);
    STARPU_ASSERT(token == nloops*size);
}
```

We have here replaced `MPI_Recv()` and `MPI_Send()` with `starpu_mpi_irecv_detached()` and `starpu_mpi_isend_detached()`, which just submit the communication to be performed. The implicit sequential consistency dependencies provide synchronization between mpi reception and emission and the corresponding tasks. The only remaining synchronization with `starpu_data_acquire()` is at the beginning and the end.

### 17.4 How to Initialize StarPU-MPI

As seen in the previous example, one has to call `starpu_mpi_init_conf()` to initialize StarPU-MPI. The third parameter of the function indicates if MPI should be initialized by StarPU or if the application did it itself. If the application initializes MPI itself, it must call `MPI_Init_thread()` with `MPI_THREAD_SERIALIZED` or `MPI_THREAD_MULTIPLE`, since StarPU-MPI uses a separate thread to perform the communications. `MPI_THREAD_MULTIPLE` is necessary if the application also performs some MPI communications.

### 17.5 Point To Point Communication

The standard point to point communications of MPI have been implemented. The semantic is similar to the MPI one, but adapted to the DSM provided by StarPU. A MPI request will only be submitted when the data is available in the main memory of the node submitting the request.

There are two types of asynchronous communications: the classic asynchronous communications and the detached communications. The classic asynchronous communications (`starpu_mpi_isend()` and `starpu_mpi_irecv()`) need to be followed by a call to `starpu_mpi_wait()` or to `starpu_mpi_test()` to wait for or to test the completion of the communication. Waiting for or testing the completion of detached communications is not possible, this is done internally by StarPU-MPI, on completion, the resources are automatically released. This mechanism is similar to the pthread detach state attribute which determines whether a thread will be created in a joinable or a detached state.

For send communications, data is acquired with the mode `STARPU_R`. When using the configure option `-enable-mpi-pedantic-isend`, the mode `STARPU_RW` is used to make sure there is no more than 1 concurrent `MPI_Isend()` call accessing a data.

Internally, all communication are divided in 2 communications, a first message is used to exchange an envelope describing the data (i.e its tag and its size), the data itself is sent in a second message. All MPI communications submitted by StarPU uses a unique tag which has a default value, and can be accessed with the functions `starpu_mpi_get_communication_tag()` and `starpu_mpi_set_communication_tag()`. The matching of tags with corresponding requests is done within StarPU-MPI.

For any userland communication, the call of the corresponding function (e.g `starpu_mpi_isend()` will result in the creation of a StarPU-MPI request, the function `starpu_data_acquire_cb()` is then called to asynchronously request StarPU to fetch the data in main memory; when the data is ready and the corresponding buffer has already been received by MPI, it will be copied in the memory of the data, otherwise the request is stored in the `early requests list`. Sending requests are stored in the `ready requests list`. While requests need to be processed, the StarPU-MPI progression thread does the following:
1. It polls the **ready requests list**. For all the ready requests, the appropriate function is called to post the corresponding MPI call. For example, an initial call to `starpu_mpi_isend()` will result in a call to `MPI_Isend()`. If the request is marked as detached, the request will then be added in the **detached requests list**.

2. It posts a `MPI_Irecv()` to retrieve a data envelope.

3. It polls the **detached requests list**. For all the detached requests, it tests its completion of the MPI request by calling `MPI_Test()`. On completion, the data handle is released, and if a callback was defined, it is called.

4. Finally, it checks if a data envelope has been received. If so, if the data envelope matches a request in the **early requests list** (i.e. the request has already been posted by the application), the corresponding MPI call is posted (similarly to the first step above).

If the data envelope does not match any application request, a temporary handle is created to receive the data, a StarPU-MPI request is created and added into the **ready requests list**, and thus will be processed in the first step of the next loop.

**MPIPtpCommunication** gives the list of all the point to point communications defined in StarPU-MPI.

### 17.6 Exchanging User Defined Data Interface

New data interfaces defined as explained in **Defining A New Data Interface** can also be used within StarPU-MPI and exchanged between nodes. Two functions needs to be defined through the type `starpu_data_interface_ops`. The function `starpu_data_interface_ops::pack_data` takes a handle and returns a contiguous memory buffer allocated with `starpu_malloc_flags(ptr, size, 0)` along with its size where data to be conveyed to another node should be copied. The reversed operation is implemented in the function `starpu_data_interface_ops::unpack_data` which takes a contiguous memory buffer and recreates the data handle.

```c
static int complex_pack_data(starpu_data_handle_t handle, unsigned node, void **ptr, ssize_t *count)
{
    STARPU_ASSERT(starpu_data_test_if_allocated_on_node(handle, node));
    struct starpu_complex_interface *complex_interface = (struct starpu_complex_interface *)
        starpu_data_get_interface_on_node(handle, node);
    *count = complex_get_size(handle);
    starpu_malloc_flags(ptr, *count, 0);
    memcpy(ptr, complex_interface->real, complex_interface->nx*sizeof(double));
    memcpy(ptr+complex_interface->nx*sizeof(double), complex_interface->imaginary, complex_interface->nx*
                                 sizeof(double));
    return 0;
}

static int complex_unpack_data(starpu_data_handle_t handle, unsigned node, void *ptr,
                                size_t count)
{
    STARPU_ASSERT(starpu_data_test_if_allocated_on_node(handle, node));
    struct starpu_complex_interface *complex_interface = (struct starpu_complex_interface *)
        starpu_data_get_interface_on_node(handle, node);
    memcpy(complex_interface->real, ptr, complex_interface->nx*sizeof(double));
    memcpy(complex_interface->imaginary, ptr+complex_interface->nx*sizeof(double), complex_interface->nx*
                                sizeof(double));
    return 0;
}

static struct starpu_data_interface_ops interface_complex_ops =
{
    ... .pack_data = complex_pack_data,
    .unpack_data = complex_unpack_data
};
```

Instead of defining pack and unpack operations, users may want to attach a MPI type to their user defined data interface. The function `starpu_mpi_datatype_register()` allows to do so. This function takes 3 parameters: the data
handle for which the MPI datatype is going to be defined, a function’s pointer that will create the MPI datatype, and a function’s pointer that will free the MPI datatype.

```c
starpu_data_interface handle;
starpu_complex_data_register(handle, STARPU_MAIN_RAM, real, imaginary, 2);
starpu_mpi_datatype_register(handle, starpu_complex_interface_datatype_allocate , starpu_complex_interface_datatype_free);
```

The functions to create and free the MPI datatype are defined as follows.

```c
void starpu_complex_interface_datatype_allocate(starpu_data_handle_t handle,
      MPI_Datatype *mpi_datatype)
{
    int ret;
    int blocklengths[2];
    MPI_Aint displacements[2];
    MPI_Datatype types[2] = {MPI_DOUBLE, MPI_DOUBLE};
    struct starpu_complex_interface *complex_interface = (struct starpu_complex_interface *)
starpu_data_get_interface_on_node(handle, STARPU_MAIN_RAM);
    MPI_Get_address(complex_interface, displacements);
    MPI_Get_address(&complex_interface->imaginary, displacements+1);
    displacements[1] -= displacements[0];
    displacements[0] = 0;
    blocklengths[0] = complex_interface->nx;
    blocklengths[1] = complex_interface->nx;
    ret = MPI_Type_create_struct(2, blocklengths, displacements, types, mpi_datatype);
    STARPU_ASSERT_MSG(ret == MPI_SUCCESS, "MPI_Type_contiguous failed");
    ret = MPI_Type_commit(mpi_datatype);
    STARPU_ASSERT_MSG(ret == MPI_SUCCESS, "MPI_Type_commit failed");
}

void starpu_complex_interface_datatype_free(MPI_Datatype *mpi_datatype)
{
    MPI_Type_free(mpi_datatype);
}
```

Note that it is important to make sure no communication is going to occur before the function `starpu_mpi_datatype_register()` is called. This would produce an undefined result as the data may be received before the function is called, and so the MPI datatype would not be known by the StarPU-MPI communication engine, and the data would be processed with the pack and unpack operations.

```c
starpu_data_interface handle;
starpu_complex_data_register(handle, STARPU_MAIN_RAM, real, imaginary, 2);
starpu_mpi_datatype_register(handle, starpu_complex_interface_datatype_allocate , starpu_complex_interface_datatype_free);
starpu_mpi_barrier(MPI_COMM_WORLD);
```

### 17.7 MPI Insert Task Utility

To save the programmer from having to explicit all communications, StarPU provides an “MPI Insert Task Utility”. The principle is that the application decides a distribution of the data over the MPI nodes by allocating it and notifying StarPU of this decision, i.e. tell StarPU which MPI node “owns” which data. It also decides, for each handle, an MPI tag which will be used to exchange the content of the handle. All MPI nodes then process the whole task graph, and StarPU automatically determines which node actually execute which task, and trigger the required MPI transfers. The list of functions is described in MPIInsertTask.

Here an stencil example showing how to use `starpu_mpi_task_insert()`. One first needs to define a distribution function which specifies the locality of the data. Note that the data needs to be registered to MPI by calling `starpu_mpi_data_register()`. This function allows to set the distribution information and the MPI tag which should be used when communicating the data. It also allows to automatically clear the MPI communication cache when unregistering the data.

```c
/* Returns the MPI node number where data is */
int my_distrib(int x, int y, int nb_nodes)
{
    // Block distrib /
    return ((int)((x / sqrt(nb_nodes)) + (y / sqrt(nb_nodes))) * sqrt(nb_nodes)) % nb_nodes;
    // Other examples useful for other kinds of computations */
```
Now the data can be registered within StarPU. Data which are not owned but will be needed for computations can be registered through the lazy allocation mechanism, i.e. with a `home_node` set to -1. StarPU will automatically allocate the memory when it is used for the first time.

One can note an optimization here (the `else if` test): we only register data which will be needed by the tasks that we will execute.

```c
unsigned matrix[X][Y];
starpu_data_handle_t data_handles[X][Y];
for (x = 0; x < X; x++)
{
    for (y = 0; y < Y; y++)
    {
        int mpi_rank = my_distrib(x, y, size);
        if (mpi_rank == my_rank)
            /* Owning data */
            starpu_variable_data_register(&data_handles[x][y], STARPU_MAIN_RAM,
                                         (uintptr_t)&(matrix[x][y]), sizeof(unsigned));
        else if (my_rank == my_distrib(x+1, y, size) || my_rank == my_distrib(x-1, y, size)
                  || my_rank == my_distrib(x, y+1, size) || my_rank == my_distrib(x, y-1, size))
            /* I don't own this index, but will need it for my computations */
            starpu_variable_data_register(data_handles[x][y], -1, (uintptr_t)NULL,
                                         sizeof(unsigned));
        else
            /* I know it's useless to allocate anything for this */
            data_handles[x][y] = NULL;
    }
    if (data_handles[x][y])
        starpu_mpi_data_register(data_handles[x][y], x*Y+y, mpi_rank);
}
```

Now `starpu_mpi_task_insert()` can be called for the different steps of the application.

```c
for (loop=0; loop<niter; loop++)

    for (x = 1; x < X-1; x++)
        for (y = 1; y < Y-1; y++)

            starpu_mpi_task_insert(MPI_COMM_WORLD, &stencil5_cl,
                                  STARPU_RW, data_handles[x][y],
                                  STARPU_R, data_handles[x-1][y],
                                  STARPU_R, data_handles[x+1][y],
                                  STARPU_R, data_handles[x][y-1],
                                  STARPU_R, data_handles[x][y+1],
                                  0);

    starpu_task_wait_for_all();
```

I.e. all MPI nodes process the whole task graph, but as mentioned above, for each task, only the MPI node which owns the data being written to (here, `data_handles[x][y]`) will actually run the task. The other MPI nodes will automatically send the required data.

To tune the placement of tasks among MPI nodes, one can use `STARPU_EXECUTE_ON_NODE` or `STARPU←EXECUTE_ON_DATA` to specify an explicit node, or the node of a given data (e.g. one of the parameters), or use `starpu_mpi_node_selection_register_policy()` and `STARPU_NODE_SELECTION_POLICY` to provide a dynamic policy.

A function `starpu_mpi_task_build()` is also provided with the aim to only construct the task structure. All MPI nodes need to call the function, which posts the required send/recv on the various nodes which have to. Only the node which is to execute the task will then return a valid task structure, others will return NULL. This node must submit the task. All nodes then need to call the function `starpu_mpi_task_post_build()` — with the same list of arguments as `starpu_mpi_task_build()` — to post all the necessary data communications meant to happen after the task execution.

```c
struct starpu_task *task;

    task = starpu_mpi_task_build(MPI_COMM_WORLD, &cl,
                                 STARPU_RW, data_handles[0],
                                 STARPU_R, data_handles[1],
                                 0);
    if (task) starpu_task_submit(task);

    task = starpu_mpi_task_post_build(MPI_COMM_WORLD, &cl,
                                       STARPU_RW, data_handles[0],
                                       STARPU_R, data_handles[1],
                                       0);
```
17.8 Pruning MPI Task Insertion

Making all MPI nodes process the whole graph can be a concern with a growing number of nodes. To avoid this, the application can prune the task for loops according to the data distribution, so as to only submit tasks on nodes which have to care about them (either to execute them, or to send the required data).

A way to do some of this quite easily can be to just add an `if` like this:

```c
for(loop=0 ; loop<niter; loop++)
    for (x = 1; x < X-1; x++)
        for (y = 1; y < Y-1; y++)
            if (my_distrib(x,y,size) == my_rank
                 || my_distrib(x-1,y,size) == my_rank
                 || my_distrib(x+1,y,size) == my_rank
                 || my_distrib(x,y-1,size) == my_rank
                 || my_distrib(x,y+1,size) == my_rank)
                starpu_mpi_task_insert(MPI_COMM_WORLD, &stencil5_cl,
                                        STARPU_RW, data_handles[x][y],
                                        STARPU_R, data_handles[x-1][y],
                                        STARPU_R, data_handles[x+1][y],
                                        STARPU_R, data_handles[x][y-1],
                                        STARPU_R, data_handles[x][y+1],
                                        0);
starpu_task_wait_for_all();
```

This permits to drop the cost of function call argument passing and parsing.

If the `my_distrib` function can be inlined by the compiler, the latter can improve the test.

If the `size` can be made a compile-time constant, the compiler can considerably improve the test further.

If the distribution function is not too complex and the compiler is very good, the latter can even optimize the for loops, thus dramatically reducing the cost of task submission.

To estimate quickly how long task submission takes, and notably how much pruning saves, a quick and easy way is to measure the submission time of just one of the MPI nodes. This can be achieved by running the application on just one MPI node with the following environment variables:

```bash
export STARPU_DISABLE_KERNELS=1
export STARPU_MPI_FAKE_RANK=2
export STARPU_MPI_FAKE_SIZE=1024
```

Here we have disabled the kernel function call to skip the actual computation time and only keep submission time, and we have asked StarPU to fake running on MPI node 2 out of 1024 nodes.

17.9 Temporary Data

To be able to use `starpu_mpi_task_insert()`, one has to call `starpu_mpi_data_register()`, so that StarPU-MPI can know what it needs to do for each data. Parameters of `starpu_mpi_data_register()` are normally the same on all nodes for a given data, so that all nodes agree on which node owns the data, and which tag is used to transfer its value.

It can however be useful to register e.g. some temporary data on just one node, without having to register a dumb handle on all nodes, while only one node will actually need to know about it. In this case, nodes which do not need the data can just pass NULL to `starpu_mpi_task_insert()`:

```c
starpu_data_handle_t data0 = NULL;
if (rank == 0)
    [ 
        starpu_variable_data_register(&data0, STARPU_MAIN_RAM, 
                                    (uintptr_t) &val0, sizeof(val0));
        starpu_mpi_data_register(data0, 0, rank);
    ]
starpu_mpi_task_insert(MPI_COMM_WORLD, &cl, STARPU_W, data0, 0); /* Executes on node 0 */
```

Here, nodes whose rank is not 0 will simply not take care of the data, and consider it to be on another node. This can be mixed various way, for instance here node 1 determines that it does not have to care about `data0`, but knows that it should send the value of its `data1` to node 0, which owns data and thus will need the value of `data1` to execute the task:

```c
starpu_data_handle_t data0 = NULL, data1, data;
if (rank == 0)
    [ 
        starpu_variable_data_register(&data0, STARPU_MAIN_RAM, 
                                    (uintptr_t) &val0, sizeof(val0));
        starpu_mpi_data_register(data0, -1, rank);
    ]
```
17.10 Per-node Data

Further than temporary data on just one node, one may want per-node data, to e.g. replicate some computation because that is less expensive than communicating the value over MPI:

```c
starpu_data_handle pernode, data0, data1;
starpu_variable_data_register(&pernode, -1, 0, sizeof(val));
starpu_mpi_data_register(pernode, -1, STARPU_MPI_PER_NODE);
/* Normal data: one on node0, one on node1 */
if (rank == 0)
    { 
        starpu_variable_data_register(&data0, STARPU_MAIN_RAM, (uintptr_t) &val0, sizeof(val0));
        starpu_variable_data_register(&data1, -1, 0, sizeof(val1));
    }
else if (rank == 1)
    { 
        starpu_variable_data_register(&data0, -1, 0, sizeof(val1));
        starpu_variable_data_register(&data1, STARPU_MAIN_RAM, (uintptr_t) &val1, sizeof(val1));
    }
starpu_mpi_data_register(data0, 42, 0);
starpu_mpi_data_register(data1, 43, 1);
starpu_mpi_task_insert(MPI_COMM_WORLD, &cl, STARPU_W, pernode, 0); /* Will be replicated on all nodes */
starpu_mpi_task_insert(MPI_COMM_WORLD, &cl2, STARPU_RW, data0, STARPU_R, pernode); /* Will execute on node 0, using its own pernode */
starpu_mpi_task_insert(MPI_COMM_WORLD, &cl2, STARPU_RW, data1, STARPU_R, pernode); /* Will execute on node 1, using its own pernode */
```

One can turn a normal data into pernode data, by first broadcasting it to all nodes:

```c
starpu_data_handle data;
starpu_variable_data_register(&data, -1, 0, sizeof(val));
starpu_mpi_data_register(data, 42, 0);
/* Compute some value */
starpu_mpi_task_insert(MPI_COMM_WORLD, &cl, STARPU_W, data, 0); /* Node 0 computes it */
/* Get it on all nodes */
starpu_mpi_get_data_on_all_nodes_detached(MPI_COMM_WORLD, data);
/* And turn it per-node */
starpu_mpi_data_set_rank(data, STARPU_MPI_PER_NODE);
```

The data can then be used just like pernode above.

17.11 Priorities

All send functions have a _prio variant which takes an additional priority parameter, which allows to make StarPU-MPI change the order of MPI requests before submitting them to MPI. The default priority is 0. When using the starpu_mpi_task_insert() helper, STARPU_PRIORITY defines both the task priority and the MPI requests priority.

To test how much MPI priorities have a good effect on performance, you can set the environment variable STARPU_MPI_PRIORITIES to 0 to disable the use of priorities in StarPU-MPI.
17.12 MPI Cache Support

StarPU-MPI automatically optimizes duplicate data transmissions: if an MPI node \( B \) needs a piece of data \( D \) from MPI node \( A \), for several tasks, only one transmission of \( D \) will take place from \( A \) to \( B \), and the value of \( D \) will be kept on \( B \) as long as no task modifies \( D \).

If a task modifies \( D \), \( B \) will wait for all tasks which need the previous value of \( D \), before invalidating the value of \( D \). As a consequence, it releases the memory occupied by \( D \). Whenever a task running on \( B \) needs the new value of \( D \), allocation will take place again to receive it.

Since tasks can be submitted dynamically, StarPU-MPI can not know whether the current value of data \( D \) will again be used by a newly-submitted task before being modified by another newly-submitted task, so until a task is submitted to modify the current value, it can not decide by itself whether to flush the cache or not. The application can however explicitly tell StarPU-MPI to flush the cache by calling `starpu_mpi_cache_flush()` or `starpu_mpi_cache←flush_all_data()`, for instance in case the data will not be used at all any more (see for instance the cholesky example in mpi/examples/matrix_decomposition), or at least not in the close future. If a newly-submitted task actually needs the value again, another transmission of \( D \) will be initiated from \( A \) to \( B \). A mere `starpu_mpi_cache←flush_all_data()` calls during the algorithm; the effect for the data deallocation will be the same, but it will additionally release some pressure from the StarPU-MPI cache hash table during task submission.

One can determine whether a piece of is cached with `starpu_mpi_cached_receive()` and `starpu_mpi_cached←send()`.

The whole caching behavior can be disabled thanks to the `STARPU_MPI_CACHE` environment variable. The variable `STARPU_MPI_CACHE_STATS` can be set to 1 to enable the runtime to display messages when data are added or removed from the cache holding the received data.

17.13 MPI Data Migration

The application can dynamically change its mind about the data distribution, to balance the load over MPI nodes for instance. This can be done very simply by requesting an explicit move and then change the registered rank.

For instance, we here switch to a new distribution function `my_distrib2`: we first register any data which wasn’t registered already and will be needed, then migrate the data, and register the new location.

```c
for(x = 0; x < X; x++)
{
    for (y = 0; y < Y; y++)
    {
        int mpi_rank = my_distrib2(x, y, size);
        if (data_handles[x][y] && mpi_rank == my_rank || mpi_rank == my_distrib(x+1, y, size) || mpi_rank == my_distrib(x-1, y, size) || mpi_rank == my_distrib(x, y+1, size) || mpi_rank == my_distrib(x, y-1, size))
            /* Register newly-needed data */
            starpu_variable_data_register(&data_handles[x][y], -1, (uintptr_t)NULL, sizeof(unsigned));
        if (data_handles[x][y])
            /* Migrate the data */
            starpu_mpi_data_migrate(MPI_COMM_WORLD, data_handles[x][y], mpi_rank);
    }
}
```

From then on, further tasks submissions will use the new data distribution, which will thus change both MPI communications and task assignments.

Very importantly, since all nodes have to agree on which node owns which data so as to determine MPI communications and task assignments the same way, all nodes have to perform the same data migration, and at the same point among task submissions. It thus does not require a strict synchronization, just a clear separation of task submissions before and after the data redistribution.

Before data unregistration, it has to be migrated back to its original home node (the value, at least), since that is where the user-provided buffer resides. Otherwise the unregistration will complain that it does not have the latest value on the original home node.

```c
for(x = 0; x < X; x++)
{
    for (y = 0; y < Y; y++)
    {
        if (data_handles[x][y])
        {
            /* Migrate the data */
            starpu_mpi_data_migrate(MPI_COMM_WORLD, dataHandles[x][y], mpi_rank);
        }
    }
}
```
17.14 MPI Collective Operations

The functions are described in MPICollectiveOperations.

```c
if (rank == root)
{
    /* Allocate the vector */
    vector = malloc(nblocks * sizeof(float *));
    for(x=0 ; x<nblocks ; x++)
    {
        starpu_malloc((void **)&vector[x], block_size*sizeof(float));
    }
    /* Allocate data handles and register data to StarPU */
    data_handles = malloc(nblocks*sizeof(starpu_data_handle_t *));
    for(x = 0; x < nblocks ; x++)
    {
        int mpi_rank = my_distrib(x, nodes);
        if (rank == root)
        {
            starpu_vector_data_register(&data_handles[x], STARPU_MAIN_RAM,
                (uintptr_t)vector[x], block_size, sizeof(float));
        }
        else if ((mpi_rank == rank) || ((rank == mpi_rank+1 || rank == mpi_rank-1)))
        {
            /* I own this index, or i will need it for my computations */
            starpu_vector_data_register(&data_handles[x], STARPU_MAIN_RAM,
                (uintptr_t)NULL, block_size, sizeof(float));
        }
        else
        {
            /* I know it's useless to allocate anything for this */
            data_handles[x] = NULL;
        }
    }
    /* Scatter the matrix among the nodes */
    starpu_mpi_scatter_detached(data_handles, nblocks, root, MPI_COMM_WORLD, NULL, NULL, NULL, NULL);
    /* Calculation */
    for(x = 0; x < nblocks ; x++)
    {
        if (data_handles[x])
        {
            int owner = starpu_data_get_rank(data_handles[x]);
            if (owner == rank)
            {
                starpu_task_insert(&cl, STARPU_RW, data_handles[x], 0);
            }
        }
    }
    /* Gather the matrix on main node */
    starpu_mpi_gather_detached(data_handles, nblocks, 0, MPI_COMM_WORLD, NULL, NULL, NULL, NULL);
}
```

Other collective operations would be easy to define, just ask starpu-devel for them!

17.15 Make StarPU-MPI Progression Thread Execute Tasks

The default behaviour of StarPU-MPI is to spawn an MPI thread to take care only of MPI communications in an active fashion (i.e the StarPU-MPI thread sleeps only when there is no active request submitted by the application),
with the goal of being as reactive as possible to communications. Knowing that, users usually leave one free core for the MPI thread when starting a distributed execution with StarPU-MPI. However, this could result in a loss of performance for applications that do not require an extreme reactivity to MPI communications.

The `starpu_mpi_init_conf()` routine allows the user to give the `starpu_conf` configuration structure of StarPU (usually given to the `starpu_init()` routine) to StarPU-MPI, so that StarPU-MPI reserves for its own use one of the CPU drivers of the current computing node, or one of the CPU cores, and then calls `starpu_init()` internally. This allows the MPI communication thread to call a StarPU CPU driver to run tasks when there is no active requests to take care of, and thus recover the computational power of the “lost” core. Since there is a trade-off between executing tasks and polling MPI requests, which is how much the application wants to lose in reactivity to MPI communications to get back the computing power of the core dedicated to the StarPU-MPI thread, there are two environment variables to pilot the behaviour of the MPI thread so that users can tune this trade-off depending of the behaviour of the application.

The `STARPU_MPI_DRIVER_CALL_FREQUENCY` environment variable sets how many times the MPI progression thread goes through the MPI_Test() loop on each active communication request (and thus try to make communications progress by going into the MPI layer) before executing tasks. The default value for this environment variable is 0, which means that the support for interleaving task execution and communication polling is deactivated, thus returning the MPI progression thread to its original behaviour.

The `STARPU_MPI_DRIVER_TASK_FREQUENCY` environment variable sets how many tasks are executed by the MPI communication thread before checking all active requests again. While this environment variable allows a better use of the core dedicated to StarPU-MPI for computations, it also decreases the reactivity of the MPI communication thread as much.

### 17.16 Debugging MPI

Communication trace will be enabled when the environment variable `STARPU_MPI_COMM` is set to 1, and StarPU has been configured with the option `--enable-verbose`.

Statistics will be enabled for the communication cache when the environment variable `STARPU_MPI_CACHE_STATS` is set to 1. It prints messages on the standard output when data are added or removed from the received communication cache.

When the environment variable `STARPU_COMM_STATS` is set to 1, StarPU will display at the end of the execution for each node the volume and the bandwidth of data sent to all the other nodes. Here an example of such a trace.

```plaintext
[starpu_comm_stats][3] TOTAL: 476.000000 B 0.000454 MB 0.000098 B/s 0.000000 MB/s
[starpu_comm_stats][3:0] 248.000000 B 0.000237 MB 0.000051 B/s 0.000000 MB/s
[starpu_comm_stats][3:2] 50.000000 B 0.000022 MB 0.000004 B/s 0.000000 MB/s
[starpu_comm_stats][2] TOTAL: 288.000000 B 0.000275 MB 0.000059 B/s 0.000000 MB/s
[starpu_comm_stats][2:1] 128.000000 B 0.000103 MB 0.000022 B/s 0.000000 MB/s
[starpu_comm_stats][2:3] 160.000000 B 0.000172 MB 0.000037 B/s 0.000000 MB/s
[starpu_comm_stats][1] TOTAL: 80.000000 B 0.000080 MB 0.000017 B/s 0.000000 MB/s
[starpu_comm_stats][1:0] 40.000000 B 0.000064 MB 0.000013 B/s 0.000000 MB/s
[starpu_comm_stats][1:2] 40.000000 B 0.000017 MB 0.000004 B/s 0.000000 MB/s
[starpu_comm_stats][0] TOTAL: 64.000000 B 0.000056 MB 0.000011 B/s 0.000000 MB/s
[starpu_comm_stats][0:1] 32.000000 B 0.000038 MB 0.000008 B/s 0.000000 MB/s
[starpu_comm_stats][0:3] 32.000000 B 0.000019 MB 0.000004 B/s 0.000000 MB/s
```

These statistics can be plotted as heatmaps using StarPU tool `starpu_mpi_comm_matrix.py`, this will produce 2 PDF files, one plot for the bandwidth, and one plot for the data volume.
17.17 More MPI examples

MPI examples are available in the StarPU source code in mpi/examples:

- **comm** shows how to use communicators with StarPU-MPI
- **complex** is a simple example using a user-define data interface over MPI (complex numbers),
- **stencil5** is a simple stencil example using `starpu_mpi_task_insert()`,
- **matrix_decomposition** is a cholesky decomposition example using `starpu_mpi_task_insert()`. The non-distributed version can check for algorithm correctness in 1-node configuration, the distributed version uses exactly the same source code, to be used over MPI,
- **mpi_lu** is an LU decomposition example, provided in three versions: `plu_example` uses explicit MPI data transfers, `plu_implicit_example` uses implicit MPI data transfers, `plu_outofcore_example` uses implicit MPI data transfers and supports data matrices which do not fit in memory (out-of-core).

17.18 Notes about the Implementation

StarPU-MPI is implemented directly on top of MPI. Since the release 1.3.0, an implementation on top of NewMadeleine, an optimizing communication library for high-performance networks, is also provided. To use it, one needs to install NewMadeleine (see [http://pm2.gforge.inria.fr/newmadeleine/](http://pm2.gforge.inria.fr/newmadeleine/)) and enable the configure option `--enable-nmad`. Both implementations provide the same public API.
17.19 MPI Master Slave Support

StarPU provides an other way to execute applications across many nodes. The Master Slave support permits to use remote cores without thinking about data distribution. This support can be activated with the `configure` option `--enable-mpi-master-slave`. However, you should not activate both MPI support and MPI Master-Slave support.

The existing kernels for CPU devices can be used as such. They only have to be exposed through the name of the function in the `starpu_codelet::cpu funcs name` field. Functions have to be globally-visible (i.e. not static) for StarPU to be able to look them up, and `-rdynamic` must be passed to gcc (or `-export-dynamic` to ld) so that symbols of the main program are visible. Optionally, you can choose the use of another function on slaves thanks to the field `starpu_codelet::mpi ms funcs`.

By default, one core is dedicated on the master node to manage the entire set of slaves. If the implementation of MPI you are using has a good multiple threads support, you can use the `configure` option `--with-mpi-master-slave-multiple-thread` to dedicate one core per slave.

Choosing the number of cores on each slave device is done by setting the environment variable `STARPU_NMPI=MSTHREADS=<number>` with `<number>` being the requested number of cores. By default all the slave's cores are used.

Setting the number of slaves nodes is done by changing the `-n` parameter when executing the application with `mpirun` or `mpiexec`.

The master node is by default the node with the MPI rank equal to 0. To select another node, use the environment variable `STARPU_MPI_MASTER_NODE=<number>` with `<number>` being the requested MPI rank node.
Chapter 18

FFT Support

StarPU provides libstarpufft, a library whose design is very similar to both fftw and cufft, the difference being that it takes benefit from both CPUs and GPUs. It should however be noted that GPUs do not have the same precision as CPUs, so the results may differ by a negligible amount.

Different precisions are available, namely float, double and long double precisions, with the following fftw naming conventions:

- double precision structures and functions are named e.g. starpufft_execute()
- float precision structures and functions are named e.g. starpufftf_execute()
- long double precision structures and functions are named e.g. starpufftl_execute()

The documentation below is given with names for double precision, replace starpufft_ with starpufftf_ or starpufftl_ as appropriate.

Only complex numbers are supported at the moment.

The application has to call starpu_init() before calling starpufft functions.

Either main memory pointers or data handles can be provided.

- To provide main memory pointers, use starpuff_start() or starpufft_execute(). Only one FFT can be performed at a time, because StarPU will have to register the data on the fly. In the starpufft_start() case, starpufft←cleanup() needs to be called to unregister the data.
- To provide data handles (which is preferable), use starpuff_start_handle() (preferred) or starpufft_execute←_handle(). Several FFTs tasks can be submitted for a given plan, which permits e.g. to start a series of FFT with just one plan. starpufft_start_handle() is preferable since it does not wait for the task completion, and thus permits to enqueue a series of tasks.

All functions are defined in FFT Support.

18.1 Compilation

The flags required to compile or link against the FFT library are accessible with the following commands:

```
$ pkg-config --cflags starpufft-1.3  # options for the compiler
$ pkg-config --libs starpufft-1.3    # options for the linker
```

Also pass the option -static if the application is to be linked statically.
MIC Xeon Phi Support

19.1 Compilation

MIC Xeon Phi support actually needs two compilations of StarPU, one for the host and one for the device. The PATH environment variable has to include the path to the cross-compilation toolchain, for instance /usr/linux-k1om-4.7/bin. The SINK_PKG_CONFIG_PATH environment variable should include the path to the cross-compiled hwloc.pc. The script mic-configure can then be used to achieve the two compilations: it basically calls configure as appropriate from two new directories: build_mic and build_.make and make install can then be used as usual and will recurse into both directories. If different configure options are needed for the host and for the mic, one can use --with-host-param=--with-fxt for instance to specify the --with-fxt option for the host only, or --with-mic-param=--with-fxt for the mic only.

One can also run StarPU just natively on the Xeon Phi, i.e. it will only run directly on the Phi without any exchange with the host CPU. The binaries in build_mic can be run that way.

For MPI support, you will probably have to specify different MPI compiler path or option for the host and the device builds, for instance:

```bash
./mic-configure --with-mic-param=--with-mpicc="/.../mpiicc -mmic" \
  --with-host-param=--with-mpicc="/.../mpiicc
```

In case you have troubles with the coi or scif libraries (the Intel paths are really not standard, it seems...), you can still make a build in native mode only, by using mic-configure --enable-native-mic (and notably without --enable-mic since in that case we don't need mic offloading support).

19.2 Porting Applications To MIC Xeon Phi

The simplest way to port an application to MIC Xeon Phi is to set the field starpu_codelet::cpu_funcs_name, to provide StarPU with the function name of the CPU implementation, so for instance:

```c
struct starpu_codelet cl =
{
  .cpu_funcs = {myfunc},
  .cpu_funcs_name = {"myfunc"},
  .nbuffers = 1,
}
```

StarPU will thus simply use the existing CPU implementation (cross-built in the MIC Xeon Phi case). The functions have to be globally-visible (i.e. not static) for StarPU to be able to look them up, and -rdynamic must be passed to gcc (or --export-dynamic to ld) so that symbols of the main program are visible.

If you have used the starpu_codelet::where field, you additionally need to add in it STARPU_MIC for the Xeon Phi. For non-native MIC Xeon Phi execution, the ‘main’ function of the application, on the sink, should call starpu_init() immediately upon start-up; the starpu_init() function never returns. On the host, the ‘main’ function may freely perform application related initialization calls as usual, before calling starpu_init().

For MIC Xeon Phi, the application may programmatically detect whether executing on the sink or on the host, by checking whether the STARPU_SINK environment variable is defined (on the sink) or not (on the host).
19.3 Launching Programs

MIC programs are started from the host. StarPU automatically starts the same program on MIC devices. It however needs to get the MIC-cross-built binary. It will look for the file given by the environment variable `STARPU_MIC_SINK_PROGRAM_NAME` or in the directory given by the environment variable `STARPU_MIC_SINK_PROGRAM_M_PATH`, or in the field `starpu_conf::mic_sink_program_path`. It will also look in the current directory for the same binary name plus the suffix `-mic` or `_mic`.

The testsuite can be started by simply running `make check` from the top directory. It will recurse into both `build_host` to run tests with only the host, and into `build_mic` to run tests with both the host and the MIC devices. Single tests with the host and the MIC can be run by starting `./loader-cross.sh ./the_test` from `build_mic/tests`.
Chapter 20

Native Fortran Support

StarPU provides the necessary routines and support to natively access most of its functionalities from Fortran 2008+ codes.

All symbols (functions, constants) are defined in fstarpu_mod.f90. Every symbol of the Native Fortran support API is prefixed by fstarpu_.

Note: Mixing uses of fstarpu_ and starpu_ symbols in the same Fortran code has unspecified behaviour. See Valid API Mixes and Language Mixes for a discussion about valid and unspecified combinations.

20.1 Implementation Details and Specificities

20.1.1 Prerequisites

The Native Fortran support relies on Fortran 2008 specific constructs, as well as on the support of interoperability of assumed-shape arrays introduced as part of Fortran’s Technical Specification ISO/IEC TS 29113:2012, for which no equivalent are available in previous versions of the standard. It has currently been tested successfully with GNU GFortran 4.9, GFortran 5.x, GFortran 6.x and the Intel Fortran Compiler >= 2016. It is known not to work with GNU GFortran < 4.9, Intel Fortran Compiler < 2016.

See Section Using StarPU with Older Fortran Compilers on information on how to write StarPU Fortran code with older compilers.

20.1.2 Configuration

The Native Fortran API is enabled and its companion fstarpu_mod.f90 Fortran module source file is installed by default when a Fortran compiler is found, unless the detected Fortran compiler is known not to support the requirements for the Native Fortran API. The support can be disabled through the configure option --disable-fortran. Conditional compiled source codes may check for the availability of the Native Fortran Support by testing whether the preprocessor macro STARPU_HAVE_FC is defined or not.

20.1.3 Examples

Several examples using the Native Fortran API are provided in StarPU’s examples/native_fortran/ examples directory, to showcase the Fortran flavor of various basic and more advanced StarPU features.

20.1.4 Compiling a Native Fortran Application

The Fortran module fstarpu_mod.f90 installed in StarPU’s include/ directory provides all the necessary API definitions. It must be compiled with the same compiler (same vendor, same version) as the application itself, and the resulting fstarpu_mod.o object file must linked with the application executable.

Each example provided in StarPU’s examples/native_fortran/ examples directory comes with its own dedicated Makefile for out-of-tree build. Such example Makefiles may be used as starting points for building application codes with StarPU.
20.2 Fortran Translation for Common StarPU API Idioms

All these examples assume that the standard Fortran module `iso_c_binding` is in use.

- **Specifying a NULL pointer**

  ```fortran
  type(c_ptr) :: my_ptr ! variable to store the pointer
  ! [...] my_ptr = c_null_ptr ! assign standard constant for null ptr
  ```

- **Obtaining a pointer to some object**

  ```fortran
  real(8), dimension(:), allocatable, target :: va
type(c_ptr) :: p_va ! variable to store a pointer to array va
  ! [...] p_va = c_loc(va)
  ```

- **Obtaining a pointer to some subroutine**

  ```fortran
  ! pointed routine definition
recursive subroutine myfunc () bind(C)
  ! [...] type(c_funptr) :: p_fun ! variable to store the routine pointer
  ! [...] p_fun = c_funloc(my_func)
  ```

- **Obtaining the size of some object**

  ```fortran
  real(8) :: a
integer(c_size_t) :: sz_a ! variable to store the size of a
  ! [...] sz_a = c_sizeof(a)
  ```

- **Obtaining the length of an array dimension**

  ```fortran
  real(8), dimension(:,,:), allocatable, target :: vb
  integer(c_int) :: ln_vb_1 ! variable to store the length of vb’s dimension 1
  integer(c_int) :: ln_vb_2 ! variable to store the length of vb’s dimension 2
  ! [...] ln_vb_1 = 1+ubound(vb,1)-lbound(vb,1) ! get length of dimension 1 of vb
  ln_vb_2 = 1+ubound(vb,2)-lbound(vb,2) ! get length of dimension 2 of vb
  ```

- **Specifying a string constant**

  ```fortran
  type(c_ptr) :: my_cl ! a StarPU codelet
  ! [...] call fstarpu_codelet_set_name(my_cl, c_char_"my_codelet"//c_null_char)
  ```

  ```fortran
  ! note: using the C_CHAR prefix and the //C_NULL_CHAR concatenation at the end ensures
  ! that the string constant is properly ‘\0’ terminated, and compatible with StarPU’s
  ! internal C routines
  ! note: plain Fortran string constants are not ‘\0’ terminated, and as such, must not be
  ! passed to starpu routines.
  ```

- **Combining multiple flag constants with a bitwise ‘or’**

  ```fortran
  type(c_ptr) :: my_cl ! a pointer for the codelet structure
  ! [...] call fstarpu_codelet_add_buffer(my_cl, fstarpu_rw.ior.fstarpu_locality)
  ```
20.3 Uses, Initialization and Shutdown

The snippet below show an example of minimal StarPU code using the Native Fortran support. The program should use the standard module iso_c_binding as well as StarPU's fstarpu_mod. The StarPU runtime engine is initialized with a call to function fstarpu_init, which returns an integer status of 0 if successful or non-0 otherwise. Eventually, a call to fstarpu_shutdown ends the runtime engine and frees all internal StarPU data structures.

```fortran
program nf_initexit
    use iso_c_binding ! C interfacing module
    use fstarpu_mod ! StarPU interfacing module
    implicit none ! Fortran recommended best practice
    integer(c_int) :: err ! return status for fstarpu_init

    ! initialize StarPU with default settings
    err = fstarpu_init(c_null_ptr)
    if (err /= 0) then
        stop 1 ! StarPU initialization failure
    end if

    ! - add StarPU Native Fortran API calls here

    ! shut StarPU down
    call fstarpu_shutdown()
end program nf_initexit
```

20.4 Fortran Flavor of StarPU's Variadic Insert_task

Fortran does not have a construction similar to C variadic functions on which starpu_insert_task() relies at the time of this writing. However, Fortran's variable length arrays of c_ptr elements enable to emulate much of the convenience of C's variadic functions. This is the approach retained for implementing fstarpu_insert_task.

The general syntax for using fstarpu_insert_task is as follows:

```fortran
    call fstarpu_insert_task((/ <codelet ptr> &
                  [, <access mode flags>, <data handle>]* &
                  [, <argument type constant>, <argument>]*, &
                  , c_null_ptr /))
```

There is thus a unique array argument (/* ... */ ) passed to fstarpu_insert_task which itself contains the task settings. Each element of the array must be of type type(c_ptr). The last element of the array must be C_NULL_PTR.

Example extracted from nf_vector.f90:

```fortran
    call fstarpu_insert_task((/ cl_vec, & ! codelet
                  fstarpu_r, dh_va, & ! a first data handle
                  fstarpu_rw.ior.fstarpu_locality, dh_vb, & ! a second data handle
                  c_null_ptr /)) ! no more args
```

20.5 Functions and Subroutines Expecting Data Structures Arguments

Several StarPU structures that are expected to be passed to the C API, are replaced by function/subroutine wrapper sets to allocate, set fields and free such structure. This strategy has been prefered over defining native Fortran equivalent of such structures using Fortran's derived types, to avoid potential layout mismatch between C and Fortran StarPU data structures. Examples of such data structures wrappers include fstarpu_conf_allocate and alike, fstarpu_codelet_allocate and alike, fstarpu_data_filter_allocate and alike.

Here is an example of allocating, filling and deallocating a codelet structure:

```fortran
    ! a pointer for the codelet structure
    type(c_ptr) :: cl_vec

    ! allocate an empty codelet structure
    cl_vec = fstarpu_codelet_allocate()

    ! add a CPU implementation function to the codelet
    call fstarpu_codelet_add_cpu_func(cl_vec, c_funloc(cl_cpu_func_vec))

    ! set the codelet name
    call fstarpu_codelet_set_name(cl_vec, c_char_"my_vec_codelet"//c_null_char)

    ! add a Read-only mode data buffer to the codelet
    call fstarpu_codelet_add_buffer(cl_vec, fstarpu_r)

    ! add a Read-Write mode data buffer to the codelet
    call fstarpu_codelet_add_buffer(cl_vec, fstarpu_rw.ior.fstarpu_locality)

    ! free codelet structure
    call fstarpu_codelet_free(cl_vec)
```
20.6 Additional Notes about the Native Fortran Support

20.6.1 Using StarPU with Older Fortran Compilers

When using older compilers, Fortran applications may still interoperate with StarPU using C marshalling functions as exemplified in StarPU's examples/fortran/ and examples/fortran90/ example directories, though the process will be less convenient.

Basically, the main FORTRAN code calls some C wrapper functions to submit tasks to StarPU. Then, when StarPU starts a task, another C wrapper function calls the FORTRAN routine for the task.

Note that this marshalled FORTRAN support remains available even when specifying configure option --disable-fortran (which only disables StarPU's native Fortran layer).

20.6.2 Valid API Mixes and Language Mixes

Mixing uses of fstarpu_ and starpu_ symbols in the same Fortran code has unspecified behaviour. Using fstarpu_ symbols in C code has unspecified behaviour.

For multi-language applications using both C and Fortran source files:

- C source files must use starpu_ symbols exclusively
- Fortran sources must uniformly use either fstarpu_ symbols exclusively, or starpu_ symbols exclusively. Every other combination has unspecified behaviour.
Chapter 21

SOCL OpenCL Extensions

SOCL is an OpenCL implementation based on StarPU. It gives a unified access to every available OpenCL device: applications can now share entities such as Events, Contexts or Command Queues between several OpenCL implementations.

In addition, command queues that are created without specifying a device provide automatic scheduling of the submitted commands on OpenCL devices contained in the context to which the command queue is attached. Setting the `CL_QUEUE_OUT_OF_ORDER_EXEC_MODE_ENABLE` flag on a command queue also allows StarPU to reorder kernels queued on the queue, otherwise they would be serialized and several command queues would be necessary to see kernels dispatched on the various OpenCL devices.

Note: this is still an area under development and subject to change.

When compiling StarPU, SOCL will be enabled if a valid OpenCL implementation is found on your system. To be able to run the SOCL test suite, the environment variable `SOCL_OCL_LIB_OPENCL` needs to be defined to the location of the file `libOpenCL.so` of the OCL ICD implementation. You should for example add the following line in your file `.bashrc`:

```bash
export SOCL_OCL_LIB_OPENCL=/usr/lib/x86_64-linux-gnu/libOpenCL.so
```

You can then run the test suite in the directory `socl/examples`.

```
$ make check
... 
PASS: basic/basic
PASS: testmap/testmap
PASS: clinfo/clinfo
PASS: matmul/matmul
PASS: mansched/mansched
===================
All 5 tests passed
===================
```

The environment variable `OCL_ICD_VENDORS` has to point to the directory where the socl.icd ICD file is installed. When compiling StarPU, the files are in the directory `socl/vendors`. With an installed version of StarPU, the files are installed in the directory `$prefix/share/starpu/opencl/vendors`. 
To run the tests by hand, you have to call for example,

```
$ LD_PRELOAD=$SOCL_OCL_LIB_OPENCL OCL_ICD_VENDORS=socl/vendors/ socl/examples/clinfo/clinfo
```

```
Number of platforms: 2
Platform Profile: FULL_PROFILE
Platform Version: OpenCL 1.1 CUDA 4.2.1
Platform Name: NVIDIA CUDA
Platform Vendor: NVIDIA Corporation
Platform Extensions: cl_khr_byte_addressable_store cl_khr_icd cl_khr_gl_sharing cl_nv_compiler_options cl_nv_ipc_interop

Platform Profile: FULL_PROFILE
Platform Version: OpenCL 1.0 SOCL Edition (0.1.0)
Platform Name: SOCL Platform
Platform Vendor: Inria
Platform Extensions: cl_khr_icd
```

```
To enable the use of CPU cores via OpenCL, one can set the `STARPU_OPENCL_ON_CPUS` environment variable to 1 and `STARPU_NCPUS` to 0 (to avoid using CPUs both via the OpenCL driver and the normal CPU driver).
```
Chapter 22

SimGrid Support

StarPU can use Simgrid in order to simulate execution on an arbitrary platform. This was tested with simgrid from 3.11 to 3.16, and 3.18 to 3.22. Other versions may have compatibility issues. 3.17 notably does not build at all. MPI simulation does not work with version 3.22.

22.1 Preparing Your Application For Simulation

There are a few technical details which need to be handled for an application to be simulated through Simgrid. If the application uses gettimeofday to make its performance measurements, the real time will be used, which will be bogus. To get the simulated time, it has to use starpu_timing_now() which returns the virtual timestamp in us.

For some technical reason, the application’s .c file which contains main() has to be recompiled with starpu←_simgrid_wrap.h, which in the simgrid case will # define main() into starpu_main(), and it is libstarpu which will provide the real main() and will call the application’s main(). To be able to test with crazy data sizes, one may want to only allocate application data if the macro STARPU_SIMGRID is not defined. Passing a NULL pointer to starpu_data_register functions is fine, data will never be read/written to by StarPU in Simgrid mode anyway.

To be able to run the application with e.g. CUDA simulation on a system which does not have CUDA installed, one can fill the starpu_codelet::cuda_funcs with (void *)1, to express that there is a CUDA implementation, even if one does not actually provide it. StarPU will not actually run it in Simgrid mode anyway by default (unless the STARP←U_CODELET_SIMGRID_EXECUTE or STARP←U_CODELET_SIMGRID_EXECUTE_AND_INJECT flags are set in the codelet)

```c
static struct starpu_codelet cl11 =
{
    .cpu_funcs = {chol_cpu_codelet_update_u11},
    .cpu_funcs_name = "{chol_cpu_codelet_update_u11}"
#ifdef STARPU_USE_CUDA
    .cuda_funcs = {chol_cublas_codelet_update_u11},
#else defined(STARPU_SIMGRID)
    .cuda_funcs = {[void*]1},
#endif
    .nbuffers = 1,
    .modes = {STARPU_RW},
    .model = &chol_model_11
};
```

22.2 Calibration

The idea is to first compile StarPU normally, and run the application, so as to automatically benchmark the bus and the codelets.

```
$ ./configure && make
$ STARPU_SCHED=dmda ./examples/matvecmult/matvecmult
[starpu][_starpu_load_history_based_model] Warning: model matvecmult is not calibrated, forcing calibration for this run. Use the STARPU_CALIBRATE environment variable to control this.
$ ...
$ STARPU_SCHED=dmda ./examples/matvecmult/matvecmult
TEST PASSED
```
Note that we force to use the scheduler `dmda` to generate performance models for the application. The application may need to be run several times before the model is calibrated.

### 22.3 Simulation

Then, recompile StarPU, passing `--enable-simgrid` to configure. Make sure to keep all other configure options the same, and notably options such as `--enable-maxcudadev`.

```
$ ./configure --enable-simgrid
```

To specify the location of SimGrid, you can either set the environment variables `SIMGRID_CFLAGS` and `SIMGDIR_LIBS`, or use the configure options `--with-simgrid-dir`, `--with-simgrid-include-dir` and `--with-simgrid-lib-dir`, for example

```
$ ./configure --with-simgrid-dir=/opt/local/simgrid
```

You can then re-run the application.

```
$ make
$ STARPU_SCHED=dmda ./examples/matvecmult/matvecmult
```

It is normal that the test fails: since the computation are not actually done (that is the whole point of SimGrid), the result is wrong, of course.

If the performance model is not calibrated enough, the following error message will be displayed

```
$ STARPU_SCHED=dmda ./examples/matvecmult/matvecmult
[starpu][_starpu_load_history_based_model] Warning: model matvecmult is not calibrated, forcing calibration for this run. Use the STARPU_CALIBRATE environment variable to control this.
[starpu][_starpu_simgrid_execute_job][assert failure] Codelet matvecmult does not have a perfmodel, or is not calibrated enough
```

The number of devices can be chosen as usual with `STARPU_NCPU`, `STARPU_NCUDA`, and `STARPU_NOPECL`, and the amount of GPU memory with `STARPU_LIMIT_CUDA_MEM`, `STARPU_LIMIT_CUDA_devid_MEM`, `STARPU_LIMIT_OPENCL_MEM`, and `STARPU_LIMIT_OPENCL_devid_MEM`.

### 22.4 Simulation On Another Machine

The SimGrid support even permits to perform simulations on another machine, your desktop, typically. To achieve this, one still needs to perform the Calibration step on the actual machine to be simulated, then copy them to your desktop machine (the `$STARPU_HOME`/`.starpu` directory). One can then perform the Simulation step on the desktop machine, by setting the environment variable `STARPU_HOSTNAME` to the name of the actual machine, to make StarPU use the performance models of the simulated machine even on the desktop machine.

If the desktop machine does not have CUDA or OpenCL, StarPU is still able to use SimGrid to simulate execution with CUDA/OpenCL devices, but the application source code will probably disable the CUDA and OpenCL codelets in that case. Since during SimGrid execution, the functions of the codelet are actually not called by default, one can use dummy functions such as the following to still permit CUDA or OpenCL execution.

### 22.5 Simulation Examples

StarPU ships a few performance models for a couple of systems: `attila`, `mirage`, `idgraf`, and `sirocco`. See Section `Simulated benchmarks` for the details.

### 22.6 Simulations On Fake Machines

It is possible to build fake machines which do not exist, by modifying the platform file in `$STARPU_HOME`/`.starpu/sampling/bus/machine.platform.xml` by hand: one can add more CPUs, add GPUs (but the performance model file has to be extended as well), change the available GPU memory size, PCI memory bandwidth, etc.
22.7 Tweaking Simulation

The simulation can be tweaked, to be able to tune it between a very accurate simulation and a very simple simulation (which is thus close to scheduling theory results), see the `STARPU_SIMGRID_TRANSFER_COST`, `STARPU_SIMGRID_CUDA_MALLOC_COST`, `STARPU_SIMGRID_CUDA_QUEUE_COST`, `STARPU_SIMGRID_TASK_SUBMIT_COST`, `STARPU_SIMGRID_FETCHING_INPUT_COST` and `STARPU_SIMGRID_SCHED_COST` environment variables.

22.8 MPI Applications

StarPU-MPI applications can also be run in SimGrid mode. It needs to be compiled with `smpicc`, and run using the `starpu_smpirun` script, for instance:

```bash
$ STARPU_SCHED=dmda starpu_smpirun -platform cluster.xml -hostfile hostfile ./mpi/tests/pingpong
```

Where `cluster.xml` is a SimGrid-MPI platform description, and `hostfile` the list of MPI nodes to be used. StarPU currently only supports homogeneous MPI clusters: for each MPI node it will just replicate the architecture referred by `STARPU_HOSTNAME`.

22.9 Debugging Applications

By default, SimGrid uses its own implementation of threads, which prevents `gdb` from being able to inspect stacks of all threads. To be able to fully debug an application running with SimGrid, pass the `-cfg=contexts/factory:thread` option to the application, to make SimGrid use system threads, which `gdb` will be able to manipulate as usual.

It is also worth noting SimGrid 3.21’s new parameter `-cfg=simix/breakpoint` which allows to put a breakpoint at a precise (deterministic!) timing of the execution. If for instance in an execution trace we see that something odd is happening at time 19000ms, we can use `-cfg=simix/breakpoint:19.000` and `SIGTRAP` will be raised at that point, which will thus interrupt execution within `gdb`, allowing to inspect e.g. scheduler state, etc.

22.10 Memory Usage

Since kernels are not actually run and data transfers are not actually performed, the data memory does not actually need to be allocated. This allows for instance to simulate the execution of applications processing very big data on a small laptop.

The application can for instance pass 1 (or whatever bogus pointer) to starpu data registration functions, instead of allocating data. This will however require the application to take care of not trying to access the data, and will not work in MPI mode, which performs transfers.

Another way is to pass the `STARPU_MALLOC_SIMULATION_FOLDED` flag to the `starpu_malloc_flags()` function. This will make it allocate a memory area which one can read/write, but optimized so that this does not actually consume memory. Of course, the values read from such area will be bogus, but this allows the application to keep e.g. data load, store, initialization as it is, and also work in MPI mode.

Note however that notably Linux kernels refuse obvious memory overcommitting by default, so a single allocation can typically not be bigger than the amount of physical memory, see [https://www.kernel.org/doc/Documentation/vm/overcommit-accounting](https://www.kernel.org/doc/Documentation/vm/overcommit-accounting). This prevents for instance from allocating a single huge matrix. Allocating a huge matrix in several tiles is not a problem, however. `sysctl vm.overcommit_memory=1` can also be used to allow such overcommit.

Note however that this folding is done by remapping the same file several times, and Linux kernels will also refuse to create too many memory areas. `sysctl vm.max_map_count` can be used to check and change the default (65535). By default, StarPU uses a 1MiB file, so it hopefully fits in the CPU cache. This however limits the amount of such folded memory to a bit below 64GiB. The `STARPU_MALLOC_SIMULATION_FOLD` environment variable can be used to increase the size of the file.
Chapter 23

The StarPU OpenMP Runtime Support (SORS)

StarPU provides the necessary routines and support to implement an OpenMP (http://www.openmp.org/) runtime compliant with the revision 3.1 of the language specification, and compliant with the task-related data dependency functionalities introduced in the revision 4.0 of the language. This StarPU OpenMP Runtime Support (SORS) has been designed to be targeted by OpenMP compilers such as the Klang-OMP compiler. Most supported OpenMP directives can both be implemented inline or as outlined functions. All functions are defined in OpenMP Runtime Support.

23.1 Implementation Details and Specificities

23.1.1 Main Thread

When using the SORS, the main thread gets involved in executing OpenMP tasks just like every other threads, in order to be compliant with the specification execution model. This contrasts with StarPU's usual execution model where the main thread submit tasks but does not take part in executing them.

23.1.2 Extended Task Semantics

The semantics of tasks generated by the SORS are extended with respect to regular StarPU tasks in that SORS' tasks may block and be preempted by SORS call, whereas regular StarPU tasks cannot. SORS tasks may coexist with regular StarPU tasks. However, only the tasks created using SORS API functions inherit from extended semantics.

23.2 Configuration

The SORS can be compiled into libstarpu through the configure option `--enable-openmp`. Conditional compiled source codes may check for the availability of the OpenMP Runtime Support by testing whether the C preprocessor macro `STARPU_OPENMP` is defined or not.

23.3 Uses, Initialization and Shutdown

The SORS needs to be executed/terminated by the `starpu_omp_init()` / `starpu_omp_shutdown()` instead of `starpu_omp_init() / starpu_shutdown()`. This requirement is necessary to make sure that the main thread gets the proper execution environment to run OpenMP tasks. These calls will usually be performed by a compiler runtime. Thus, they can be executed from a constructor/destructor such as this:

```c
//attribute__((constructor))
static void omp Constructor(void)
{
    int ret = starpu_omp_init();
    STARPU_CHECK_RETURN_VALUE(ret, "starpu_omp_init");
}

//attribute__((destructor))
static void omp Destructor(void)
{
```

```c
```
The StarPU OpenMP Runtime Support (SORS)

starpu_omp_shutdown();

See also

starpu_omp_init()
starpu_omp_shutdown()

23.4 Parallel Regions and Worksharing

The SORS provides functions to create OpenMP parallel regions as well as mapping work on participating workers. The current implementation does not provide nested active parallel regions: Parallel regions may be created recursively, however only the first level parallel region may have more than one worker. From an internal point-of-view, the SORS’ parallel regions are implemented as a set of implicit, extended semantics StarPU tasks, following the execution model of the OpenMP specification. Thus the SORS’ parallel region tasks may block and be preempted, by SORS calls, enabling constructs such as barriers.

23.4.1 Parallel Regions

Parallel regions can be created with the function starpu_omp_parallel_region() which accepts a set of attributes as parameter. The execution of the calling task is suspended until the parallel region completes. The field starpu←_omp_parallel_region_attr::cl is a regular StarPU codelet. However only CPU codelets are supported for parallel regions. Here is an example of use:

```c
void parallel_region_f(void *buffers[], void *args)
{
    (void) buffers;
    (void) args;
    pthread_t tid = pthread_self();
    int worker_id = starpu_worker_get_id();
    printf("[tid %p] task thread = %d\n", (void *)tid, worker_id);
}
void f(void)
{
    struct starpu_omp_parallel_region_attr attr;
    memset(&attr, 0, sizeof(attr));
    attr.cl.cpu_funcs[0] = parallel_region_f;
    attr.cl.where = STARPU_CPU;
    attr.if_clause = 1;
    starpu_omp_parallel_region(&attr);
    return 0;
}
```

See also

struct starpu_omp_parallel_region_attr
starpu_omp_parallel_region()

23.4.2 Parallel For

OpenMP for loops are provided by the starpu_omp_for() group of functions. Variants are available for inline or outlined implementations. The SORS supports static, dynamic, and guided loop scheduling clauses. The auto scheduling clause is implemented as static. The runtime scheduling clause honors the scheduling mode selected through the environment variable OMP_SCHEDULE or the starpu_omp_set_schedule() function. For loops with the ordered clause are also supported. An implicit barrier can be enforced or skipped at the end of the worksharing construct, according to the value of the nowait parameter.

The canonical family of starpu_omp_for() functions provide each instance with the first iteration number and the number of iterations (possibly zero) to perform. The alternate family of starpu_omp_for_alt() functions provide each instance with the (possibly empty) range of iterations to perform, including the first and excluding the last. The family of starpu_omp_ordered() functions enable to implement OpenMP's ordered construct, a region with a parallel for loop that is guaranteed to be executed in the sequential order of the loop iterations.

```c
void for_g(unsigned long long i, unsigned long long nb_i, void *arg)
{
    (void) arg;
}
for (; nb_i > 0; i++, nb_i--) {
    array[i] = 1;
}
}

void parallel_region_f(void *buffers[], void *args) {
    (void) buffers;
    (void) args;
    starpu_omp_for(for_g, NULL, NB_ITERS, CHUNK, starpu_omp_sched_static, 0, 0);
}

See also
starpu_omp_for()
starpu_omp_for_inline_first()
starpu_omp_for_inline_next()
starpu_omp_for_alt()
starpu_omp_for_inline_first_alt()
starpu_omp_for_inline_next_alt()
starpu_omp_ordered()
starpu_omp_ordered_inline_begin()
starpu_omp_ordered_inline_end()

23.4.3 Sections

OpenMP sections worksharing constructs are supported using the set of starpu_omp_sections() variants. The general principle is either to provide an array of per-section functions or a single function that will redirect to execution to the suitable per-section functions. An implicit barrier can be enforced or skipped at the end of the worksharing construct, according to the value of the nowait parameter.

void parallel_region_f(void *buffers[], void *args) {
    (void) buffers;
    (void) args;
    section_funcs[0] = f;
    section_funcs[1] = g;
    section_funcs[2] = h;
    section_funcs[3] = i;
    section_args[0] = arg_f;
    section_args[1] = arg_g;
    section_args[2] = arg_h;
    section_args[3] = arg_i;
    starpu_omp_sections(4, section_f, section_args, 0);
}

See also
starpu_omp_sections()
starpu_omp_sections_combined()

23.4.4 Single

OpenMP single worksharing constructs are supported using the set of starpu_omp_single() variants. An implicit barrier can be enforced or skipped at the end of the worksharing construct, according to the value of the nowait parameter.

void single_f(void *arg) {
    (void) arg;
    pthread_t tid = pthread_self();
    int worker_id = starpu_worker_get_id();
    printf("[tid %p] task thread = %d -- single\n", (void *)tid, worker_id);
}

void parallel_region_f(void *buffers[], void *args) {
    (void) buffers;

Generated by Doxygen
The SORS also provides dedicated support for single sections with copyprivate clauses through the `starpu_omp_single_copyprivate()` function variants. The OpenMP master directive is supported as well using the `starpu_omp_master()` function variants.

See also

```
starpu_omp_master()
starpu_omp_master_inline()
starpu_omp_single()
starpu_omp_single_inline()
starpu_omp_single_copyprivate()
starpu_omp_single_copyprivate_inline_begin()
starpu_omp_single_copyprivate_inline_end()
```

23.5 Tasks

The SORS implements the necessary support of OpenMP 3.1 and OpenMP 4.0's so-called explicit tasks, together with OpenMP 4.0's data dependency management.

23.5.1 Explicit Tasks

Explicit OpenMP tasks are created with the SORS using the `starpu_omp_task_region()` function. The implementation supports if, final, untied and mergeable clauses as defined in the OpenMP specification. Unless specified otherwise by the appropriate clause(s), the created task may be executed by any participating worker of the current parallel region.

The current SORS implementation requires explicit tasks to be created within the context of an active parallel region. In particular, an explicit task cannot be created by the main thread outside of a parallel region. Explicit OpenMP tasks created using `starpu_omp_task_region()` are implemented as StarPU tasks with extended semantics, and may as such be blocked and preempted by SORS routines.

The current SORS implementation supports recursive explicit tasks creation, to ensure compliance with the OpenMP specification. However, it should be noted that StarPU is not designed nor optimized for efficiently scheduling of recursive task applications.

The code below shows how to create 4 explicit tasks within a parallel region.

```c
void task_region_g(void *buffers[], void *args)
{
    (void) buffers;
    (void) args;
    pthread tid = pthread_self();
    int worker_id = starpu_worker_get_id();
    printf("[tid %p] task thread = %d: explicit task\n", (void *)tid, worker_id);
}

void parallel_region_f(void *buffers[], void *args)
{
    (void) buffers;
    (void) args;
    struct starpu_omp_task_region_attr attr;
    memset(&attr, 0, sizeof(attr));
    attr.cl.cpu_func[0] = task_region_g;
    attr.cl.where = STARPU_CPU;
    attr.if_clause = 1;
    attr.final_clause = 0;
    attr.untied_clause = 1;
    attr.mergeable_clause = 0;
    starpu_omp_task_region(&attr);
    starpu_omp_task_region(&attr);
    starpu_omp_task_region(&attr);
    starpu_omp_task_region(&attr);
}
```

See also

```
struct starpu_omp_task_region_attr
starpu_omp_task_region()
```
23.5 Tasks

23.5.2 Data Dependencies

The SORS implements inter-tasks data dependencies as specified in OpenMP 4.0. Data dependencies are expressed using regular StarPU data handles (*starpu_data_handle_t*) plugged into the task's `attr.cl` codelet. The family of `starpu_vector_data_register()`-like functions and the `starpu_data_lookup()` function may be used to register a memory area and to retrieve the current data handle associated with a pointer respectively. The testcase `./tests/openmp/task_02.c` gives a detailed example of using OpenMP 4.0 tasks dependencies with the SORS implementation.

Note: the OpenMP 4.0 specification only supports data dependencies between sibling tasks, that is tasks created by the same implicit or explicit parent task. The current SORS implementation also only supports data dependencies between sibling tasks. Consequently the behaviour is unspecified if dependencies are expressed between tasks that have not been created by the same parent task.

23.5.3 TaskWait and TaskGroup

The SORS implements both the `taskwait` and `taskgroup` OpenMP task synchronization constructs specified in OpenMP 4.0, with the `starpu_omp_taskwait()` and `starpu_omp_taskgroup()` functions respectively.

An example of `starpu_omp_taskwait()` use, creating two explicit tasks and waiting for their completion:

```c
void task_region_g(void *buffers[], void *args)
{
    (void) buffers;
    (void) args;
    printf("Hello, World!\n");
}

void parallel_region_f(void *buffers[], void *args)
{
    (void) buffers;
    (void) args;
    struct starpu_omp_task_region_attr attr;
    memset(&attr, 0, sizeof(attr));
    attr.cl.cpu_funcs[0] = task_region_g;
    attr.cl.where = STARPU_CPU;
    attr.if_clause = 1;
    attr.final_clause = 0;
    attr.untied_clause = 1;
    attr.mergeable_clause = 0;
    starpu_omp_task_region(&attr);
    starpu_omp_task_region(&attr);
    starpu_omp_taskwait();
}
```

An example of `starpu_omp_taskgroup()` use, creating a task group of two explicit tasks:

```c
void task_region_g(void *buffers[], void *args)
{
    (void) buffers;
    (void) args;
    printf("Hello, World!\n");
}

void taskgroup_f(void *arg)
{
    (void) arg;
    struct starpu_omp_task_region_attr attr;
    memset(&attr, 0, sizeof(attr));
    attr.cl.cpu_funcs[0] = task_region_g;
    attr.cl.where = STARPU_CPU;
    attr.if_clause = 1;
    attr.final_clause = 0;
    attr.untied_clause = 1;
    attr.mergeable_clause = 0;
    starpu_omp_task_region(&attr);
    starpu_omp_task_region(&attr);
}

void parallel_region_f(void *buffers[], void *args)
{
    (void) buffers;
    (void) args;
    starpu_omp_taskgroup(taskgroup_f, (void *)NULL);
}
```
23.6 Synchronization Support

The SORS implements objects and method to build common OpenMP synchronization constructs.

23.6.1 Simple Locks

The SORS Simple Locks are opaque starpu_omp_lock_t objects enabling multiple tasks to synchronize with each others, following the Simple Lock constructs defined by the OpenMP specification. In accordance with such specification, simple locks may not by acquired multiple times by the same task, without being released in-between; otherwise, deadlocks may result. Codes requiring the possibility to lock multiple times recursively should use Nestable Locks (Nestable Locks). Codes NOT requiring the possibility to lock multiple times recursively should use Simple Locks as they incur less processing overhead than Nestable Locks.

See also

- starpu_omp_lock_t
- starpu_omp_init_lock()
- starpu_omp_destroy_lock()
- starpu_omp_set_lock()
- starpu_omp_unset_lock()
- starpu_omp_test_lock()

23.6.2 Nestable Locks

The SORS Nestable Locks are opaque starpu_omp_nest_lock_t objects enabling multiple tasks to synchronize with each others, following the Nestable Lock constructs defined by the OpenMP specification. In accordance with such specification, nestable locks may by acquired multiple times recursively by the same task without deadlocking. Nested locking and unlocking operations must be well parenthesized at any time, otherwise deadlock and/or undefined behaviour may occur. Codes requiring the possibility to lock multiple times recursively should use Nestable Locks. Codes NOT requiring the possibility to lock multiple times recursively should use Simple Locks (Simple Locks) instead, as they incur less processing overhead than Nestable Locks.

See also

- starpu_omp_nest_lock_t
- starpu_omp_init_nest_lock()
- starpu_omp_destroy_nest_lock()
- starpu_omp_set_nest_lock()
- starpu_omp_unset_nest_lock()
- starpu_omp_test_nest_lock()

23.6.3 Critical Sections

The SORS implements support for OpenMP critical sections through the family of starpu_omp_critical functions. Critical sections may optionally be named. There is a single, common anonymous critical section. Mutual exclusion only occur within the scope of single critical section, either a named one or the anonymous one.

See also

- starpu_omp_critical()
- starpu_omp_critical_inline_begin()
- starpu_omp_critical_inline_end()
23.6.4 Barriers

The SORS provides the `starpu_omp_barrier()` function to implement barriers over parallel region teams. In accordance with the OpenMP specification, the `starpu_omp_barrier()` function waits for every implicit task of the parallel region to reach the barrier and every explicit task launched by the parallel region to complete, before returning.

See also

- `starpu_omp_barrier()`
Chapter 24

Clustering a Machine

24.1 General Ideas

Clusters are a concept introduced in this paper. The granularity problem is tackled by using resource aggregation: instead of dynamically splitting tasks, resources are aggregated to process coarse grain tasks in a parallel fashion. This is built on top of scheduling contexts to be able to handle any type of parallel tasks.

This comes from a basic idea, making use of two levels of parallelism in a DAG. We keep the DAG parallelism but consider on top of it that a task can contain internal parallelism. A good example is if each task in the DAG is OpenMP enabled.

The particularity of such tasks is that we will combine the power of two runtime systems: StarPU will manage the DAG parallelism and another runtime (e.g. OpenMP) will manage the internal parallelism. The challenge is in creating an interface between the two runtime systems so that StarPU can regroup cores inside a machine (creating what we call a cluster) on top of which the parallel tasks (e.g. OpenMP tasks) will be run in a contained fashion.

The aim of the cluster API is to facilitate this process in an automatic fashion. For this purpose, we depend on the hwloc tool to detect the machine configuration and then partition it into usable clusters.

An example of code running on clusters is available in examples/sched_ctx/parallel_tasks_with_cluster_api.c.

Let's first look at how to create a cluster.

To enable clusters in StarPU, one needs to set the configure option --enable-cluster.

24.2 Creating Clusters

Partitioning a machine into clusters with the cluster API is fairly straightforward. The simplest way is to state under which machine topology level we wish to regroup all resources. This level is an hwloc object, of the type hwloc_obj_type_t. More information can be found in the hwloc documentation.

Once a cluster is created, the full machine is represented with an opaque structure starpu_cluster_machine. This can be printed to show the current machine state.

```c
struct starpu_cluster_machine *clusters;
clusters = starpu_cluster_machine(HWLOC_OBJ_SOCKET, 0);
starpu_cluster_print(clusters);
/* submit some tasks with OpenMP computations */
starpu_uncluster_machine(clusters);
/* we are back in the default StarPU state */
```

The following graphic is an example of what a particular machine can look like once clusterized. The main difference is that we have less worker queues and tasks which will be executed on several resources at once. The execution of these tasks will be left to the internal runtime system, represented with a dashed box around the resources.
Creating clusters as shown in the example above will create workers able to execute OpenMP code by default. The cluster creation function \texttt{starpu\_cluster\_machine()} takes optional parameters after the \texttt{hwloc} object (always terminated by the value 0) which allow to parametrize the cluster creation. These parameters can help creating clusters of a type different from OpenMP, or create a more precise partition of the machine. This is explained in Section Creating Custom Clusters.

### 24.3 Example Of Constraining OpenMP

Clusters require being able to constrain the runtime managing the internal task parallelism (internal runtime) to the resources set by StarPU. The purpose of this is to express how StarPU must communicate with the internal runtime to achieve the required cooperation. In the case of OpenMP, StarPU will provide an awake thread from the cluster to execute this liaison. It will then provide on demand the process ids of the other resources supposed to be in the region. Finally, thanks to an OpenMP region we can create the required number of threads and bind each of them on the correct region. These will then be reused each time we encounter a \#pragma omp parallel in the following computations of our program.

The following graphic is an example of what an OpenMP-type cluster looks like and how it represented in StarPU. We can see that one StarPU (black) thread is awake, and we need to create on the other resources the OpenMP threads (in pink).

Finally, the following code shows how to force OpenMP to cooperate with StarPU and create the aforementioned OpenMP threads constrained in the cluster's resources set:

```c
void starpu_openmp_prologue(void * sched_ctx_id) {
    int sched_ctx = *((int*)sched_ctx_id);
    int *cpuids = NULL;
    int ncpuids = 0;
    int workerid = starpu_worker_get_id();
```
24.4 Creating Custom Clusters

Clusters can be created either with the predefined types provided within StarPU, or with user-defined functions to
bind another runtime inside StarPU.

The predefined cluster types provided by StarPU are STARPU_CLUSTER_OPENMP, STARPU_CLUSTER_INTEL_OPENMP_MKL and
STARPU_CLUSTER_GNU_OPENMP_MKL. The last one is only provided if StarPU is compiled with the MKL library. It uses MKL
functions to set the number of threads which is more reliable when using an OpenMP implementation different from the
Intel one.

The cluster type is set when calling the function starpu_cluster_machine() with the parameter ::STARPU_CLUSTERTYPE as in
the example below, which is creating a MKL cluster.

```
struct starpu_cluster_machine *clusters;
clusters = starpu_cluster_machine(HWLOC_OBJ_SOCKET,
                                  STARPU_CLUSTER_TYPE, STARPU_CLUSTER_GNU_OPENMP_MKL,
                                  0);
```

Using the default type STARPU_CLUSTER_OPENMP is similar to calling starpu_cluster_machine() without any extra parameter.

Users can also define their own function.

```
void foo_func(void* foo_arg);
```

```
int foo_arg = 0;
struct starpu_cluster_machine *clusters;
clusters = starpu_cluster_machine(HWLOC_OBJ_SOCKET,
                                  STARPU_CLUSTER_CREATE_FUNC, &foo_func,
                                  STARPU_CLUSTER_CREATE_FUNC_ARG, &foo_arg,
                                  0);
```

Parameters that can be given to starpu_cluster_machine() are ::STARPU_CLUSTER_MIN_NB, ::STARPU_CLUSTERMAX_NB, ::STARPU_CLUSTERNB, ::STARPU_CLUSTER_POLICY_NAME, ::STARPU_CLUSTER_POLICY_STRUCT, ::STARPU_CLUSTER_KEEP_HOMOGENEOUS, ::STARPU_CLUSTER_PREFERE_MIN, ::STARPU_CLUSTER_TYPE, ::STARPU_CLUSTER_AWAKE_WORKERS, ::STARPU_CLUSTER_PARTITION_ONE, ::STARPU_CLUSTER_NEW and ::STARPU_CLUSTER_NCORES.

24.5 Clusters With Scheduling

As previously mentioned, the cluster API is implemented on top of Scheduling Contexts. Its main addition is to ease
the creation of a machine CPU partition with no overlapping by using hwloc, whereas scheduling contexts can use any
number of any type of resources.

It is therefore possible, but not recommended, to create clusters using the scheduling contexts API. This can be useful
mostly in the most complex machine configurations where users have to dimension precisely clusters by hand using their
own algorithm.
```c
/* the list of resources the context will manage */
int workerids[3] = {1, 3, 10};

/* indicate the list of workers assigned to it, the number of workers,
the name of the context and the scheduling policy to be used within
the context */
int id_ctx = starpu_sched_ctx_create(workerids, 3, "my_ctx", 0);

/* let StarPU know that the following tasks will be submitted to this context */
starpu_sched_ctx_set_task_context(id);

task->prologue_callback_pop_func=runtime_interface_function_here;

/* submit the task to StarPU */
starpu_task_submit(task);
```

As this example illustrates, creating a context without scheduling policy will create a cluster. The interface function between StarPU and the other runtime must be specified through the field starpu_task::prologue_callback_pop_func. Such a function can be similar to the OpenMP thread team creation one (see above).

Note that the OpenMP mode is the default mode both for clusters and contexts. The result of a cluster creation is a woken-up master worker and sleeping "slaves" which allow the master to run tasks on their resources.

To create a cluster with woken-up workers, the flag STARPU_SCHED_CTX_AWAKE_WORKERS must be set when using the scheduling context API function starpu_sched_ctx_create(), or the flag ::STARPU_CLUSTER_AWAKE_WORKERS must be set when using the cluster API function starpu_cluster_machine().
Chapter 25

Interoperability Support

In situations where multiple parallel software elements have to coexist within the same application, uncoordinated accesses to computing units may lead such parallel software elements to collide and interfere. The purpose of the Interoperability routines of StarPU, implemented along the definition of the Resource Management APIs of Project H2020 INTERTWinE, is to enable StarPU to coexist with other parallel software elements without resulting in computing core oversubscription or undersubscription. These routines allow the programmer to dynamically control the computing resources allocated to StarPU, to add or remove processor cores and/or accelerator devices from the pool of resources used by StarPU's workers to execute tasks. They also allow multiple libraries and applicative codes using StarPU simultaneously to select distinct sets of resources independently. Internally, the Interoperability Support is built on top of Scheduling Contexts (see Scheduling Contexts).

25.1 StarPU Resource Management

The starpurm module is a library built on top of the starpu library. It exposes a series of routines prefixed with starpurm_ defining the resource management API. All functions are defined in Interoperability Support.

25.1.1 Linking a program with the starpurm module

The starpurm module must be linked explicitly with the applicative executable using it. Example Makefiles in the starpurm/dev/ subdirectories show how to do so. If the pkg-config command is available and the PKG_CONFIG_PATH environment variable is properly positioned, the proper settings may be obtained with the following Makefile snippet:

CFLAGS += $(shell pkg-config --cflags starpurm-1.3)
LDFLAGS += $(shell pkg-config --libs-only-L starpurm-1.3)
LDLIBS += $(shell pkg-config --libs-only-l starpurm-1.3)

25.1.2 Uses, Initialization and Shutdown

The starpurm module is initialized with a call to starpurm_initialize() and must be finalized with a call to starpurm_shutdown(). The starpurm module supports CPU cores as well as devices. An integer ID is assigned to each supported device type. The ID assigned to a given device type can be queried with the starpurm_get_device_type_id() routine, which currently expects one of the following strings as argument and returns the corresponding ID:

- "cpu"
- "opencl"
- "cuda"
- "mic"

The cpu pseudo device type is defined for convenience and designates CPU cores. The number of units of each type available for computation can be obtained with a call to starpu_get_nb_devices_by_type().
Each CPU core unit available for computation is designated by its rank among the StarPU CPU worker threads and by its own CPUSET bit. Each non-CPU device unit can be designated both by its rank number in the type, and by the CPUSET bit corresponding to its StarPU device worker thread. The CPUSET of a computing unit or its associated worker can be obtained from its type ID and rank with `starpurm_get_device_worker_cpuset()`, which returns the corresponding HWLOC CPUSET.

### 25.1.3 Default Context

The `starpurm` module assumes a default, global context, manipulated through a series of routines allowing to assign and withdrawing computing units from the main StarPU context. Assigning CPU cores can be done with `starpurm_assign_cpu_to_starpu()` and `starpurm_assign_cpu_mask_to_starpu()`, and assigning device units can be done with `starpurm_assign_device_to_starpu()` and `starpurm_assign_device_mask_to_starpu()`. Conversely, withdrawing CPU cores can be done with `starpurm_withdraw_cpu_from_starpu()` and `starpurm_withdraw_cpu_mask_from_starpu()`, and withdrawing device units can be done with `starpurm_withdraw_device_from_starpu()` and `starpurm_withdraw_device_mask_from_starpu()`. These routine should typically be used to control resource usage for the main applicative code.

### 25.1.4 Temporary Contexts

Besides the default, global context, `starpurm` can create temporary contexts and launch the computation of kernels confined to these temporary contexts. The routine `starpurm_spawn_kernel_on_cpus()` can be used to do so: it allocates a temporary context and spawns a kernel within this context. The temporary context is subsequently freed upon completion of the kernel. The temporary context is set as the default context for the kernel throughout its lifespan. This routine should typically be used to control resource usage for a parallel kernel handled by an external library built on StarPU. Internally, it relies on the use of `starpu_sched_ctx_set_context()` to set the temporary context as default context for the parallel kernel, and then restore the main context upon completion. Note: the maximum number of temporary contexts allocated concurrently at any time should not exceed `STARPU_NMAX_SCHED_CTXS-2`, otherwise, the call to `starpurm_spawn_kernel_on_cpus()` may block until a temporary context becomes available. The routine `starpurm_spawn_kernel_on_cpus()` returns upon the completion of the parallel kernel. An asynchronous variant is available with the routine `starpurm_spawn_kernel_on_cpus_callback()`. This variant returns immediately, however it accepts a callback function, which is subsequently called to notify the calling code about the completion of the parallel kernel.
Part V

StarPU Reference API
Chapter 26

Execution Configuration Through Environment Variables

The behavior of the StarPU library and tools may be tuned thanks to the following environment variables.

26.1 Configuring Workers

**STARPU_NCPU** Specify the number of CPU workers (thus not including workers dedicated to control accelerators). Note that by default, StarPU will not allocate more CPU workers than there are physical CPUs, and that some CPUs are used to control the accelerators.

**STARPU_RESERVE_NCPU** Specify the number of CPU cores that should not be used by StarPU, so the application can use `starpu_get_next_bindid()` and `starpu_bind_thread_on()` to bind its own threads. This option is ignored if `STARPU_NCPU` or `starpu_conf::ncpus` is set.

**STARPU_NCPUS** This variable is deprecated. You should use `STARPU_NCPU`.

**STARPU_NCUDA** Specify the number of CUDA devices that StarPU can use. If `STARPU_NCUDA` is lower than the number of physical devices, it is possible to select which CUDA devices should be used by the means of the environment variable `STARPU_WORKERS_CUDAID`. By default, StarPU will create as many CUDA workers as there are CUDA devices.

**STARPU_NWORKER_PER_CUDA** Specify the number of workers per CUDA device, and thus the number of kernels which will be concurrently running on the devices. The default value is 1.

**STARPU_CUDA_THREAD_PER_WORKER** Specify whether the cuda driver should use one thread per stream (1) or to use a single thread to drive all the streams of the device or all devices (0), and `STARPU_CUDA_THREAD_PER_DEV` determines whether is it one thread per device or one thread for all devices. The default value is 0. Setting it to 1 is contradictory with setting `STARPU_CUDA_THREAD_PER_DEV`.

**STARPU_CUDA_THREAD_PER_DEV** Specify whether the cuda driver should use one thread per device (1) or to use a single thread to drive all the devices (0). The default value is 1. It does not make sense to set this variable if `STARPU_CUDA_THREAD_PER_WORKER` is set to 1 (since `STARPU_CUDA_THREAD_PER_DEV` is then meaningless).

**STARPU_CUDA_PIPELINE** Specify how many asynchronous tasks are submitted in advance on CUDA devices. This for instance permits to overlap task management with the execution of previous tasks, but it also allows concurrent execution on Fermi cards, which otherwise bring spurious synchronizations. The default is 2. Setting the value to 0 forces a synchronous execution of all tasks.

**STARPU_NOPENCL** OpenCL equivalent of the environment variable `STARPU_NCUDA`.

**STARPU_OPENCL_PIPELINE** Specify how many asynchronous tasks are submitted in advance on OpenCL devices. This for instance permits to overlap task management with the execution of previous tasks, but it also allows concurrent execution on Fermi cards, which otherwise bring spurious synchronizations. The default is 2. Setting the value to 0 forces a synchronous execution of all tasks.
STARPU_OPENCL_ON_CPUS  By default, the OpenCL driver only enables GPU and accelerator devices. By setting the environment variable STARPU_OPENCL_ON_CPUS to 1, the OpenCL driver will also enable CPU devices.

STARPU_OPENCL_ONLY_ON_CPUS  By default, the OpenCL driver enables GPU and accelerator devices. By setting the environment variable STARPU_OPENCL_ONLY_ON_CPUS to 1, the OpenCL driver will only enable CPU devices.

STARPU_NMIC  MIC equivalent of the environment variable STARPU_NCUDA, i.e. the number of MIC devices to use.

STARPU_NMICTHREADS  Number of threads to use on the MIC devices.

STARPU_NMPI_MS  MPI Master Slave equivalent of the environment variable STARPU_NCUDA, i.e. the number of MPI Master Slave devices to use.

STARPU_NMPIMSTHREADS  Number of threads to use on the MPI Slave devices.

STARPU_MPI_MASTER_NODE  This variable allows to choose which MPI node (with the MPI ID) will be the master.

STARPU_WORKERS_NOBIND  Setting it to non-zero will prevent StarPU from binding its threads to CPUs. This is for instance useful when running the testsuite in parallel.

STARPU_WORKERS_CPUID  Passing an array of integers in STARPU_WORKERS_CPUID specifies on which logical CPU the different workers should be bound. For instance, if STARPU_WORKERS_CPUID = "0 1 4 5", the first worker will be bound to logical CPU #0, the second CPU worker will be bound to logical CPU #1 and so on. Note that the logical ordering of the CPUs is either determined by the OS, or provided by the library hwloc in case it is available. Ranges can be provided: for instance, STARPU_WORKERS_CPUID = "1-3 5" will bind the first three workers on logical CPUs #1, #2, and #3, and the fourth worker on logical CPU #5. Unbound ranges can also be provided: STARPU_WORKERS_CPUID = "1-" will bind the workers starting from logical CPU #1 up to last CPU.

Note that the first workers correspond to the CUDA workers, then come the OpenCL workers, and finally the CPU workers. For example if we have STARPU_NCUDA=1, STARPU_NOPENCL=1, STARPU_NCPU=2 and STARPU_WORKERS_CPUID = "0 2 1 3", the CUDA device will be controlled by logical CPU #0, the OpenCL device will be controlled by logical CPU #2, and the logical CPUs #1 and #3 will be used by the CPU workers.

If the number of workers is larger than the array given in STARPU_WORKERS_CPUID, the workers are bound to the logical CPUs in a round-robin fashion: if STARPU_WORKERS_CPUID = "0 1", the first and the third (resp. second and fourth) workers will be put on CPU #0 (resp. CPU #1).

This variable is ignored if the field starpu_conf::use_explicit_workers_bindid passed to starpu_init() is set.

STARPU_MAIN_THREAD_BIND  When defined, this make StarPU bind the thread that calls starpu_initialize() to a reserved CPU, subtracted from the CPU workers.

STARPU_MAIN_THREAD_CPUID  When defined, this make StarPU bind the thread that calls starpu_initialize() to the given CPU ID.

STARPU_MPI_THREAD_CPUID  When defined, this make StarPU bind its MPI thread to the given CPU ID. Setting it to -1 (the default value) will use a reserved CPU, subtracted from the CPU workers.

STARPU_WORKERS_CUDAID  Similarly to the STARPU_WORKERS_CPUID environment variable, it is possible to select which CUDA devices should be used by StarPU. On a machine equipped with 4 GPUs, setting STARPU_WORKERS_CUDAID = "1 3" and STARPU_NCUDA=2 specifies that 2 CUDA workers should be created, and that they should use CUDA devices #1 and #3 (the logical ordering of the devices is the one reported by CUDA).

This variable is ignored if the field starpu_conf::use_explicit_workers_cuda_gpuid passed to starpu_init() is set.

STARPU_WORKERS_OPENCLID  OpenCL equivalent of the STARPU_WORKERS_CUDAID environment variable.

This variable is ignored if the field starpu_conf::use_explicit_workers_opencl_gpuid passed to starpu_init() is set.
STARPU_WORKERS_MICID  
MIC equivalent of the STARPU_WORKERS_CUDAID environment variable. This variable is ignored if the field starpu_conf::use_explicit_workers_mic_deviceid passed to starpu_init() is set.

STARPU_WORKER_TREE  Define to 1 to enable the tree iterator in schedulers.

STARPU_SINGLE_COMBINED_WORKER  If set, StarPU will create several workers which won’t be able to work concurrently. It will by default create combined workers which size goes from 1 to the total number of CPU workers in the system. STARPU_MIN_WORKERSIZE and STARPU_MAX_WORKERSIZE can be used to change this default.

STARPU_MIN_WORKERSIZE  STARPU_MIN_WORKERSIZE permits to specify the minimum size of the combined workers (instead of the default 2).

STARPU_MAX_WORKERSIZE  STARPU_MAX_WORKERSIZE permits to specify the minimum size of the combined workers (instead of the number of CPU workers in the system).

STARPU_SYNTHESIZE_ARITY_COMBINED_WORKER  Let the user decide how many elements are allowed between combined workers created from hwloc information. For instance, in the case of sockets with 6 cores without shared L2 caches, if STARPU_SYNTHESIZE_ARITY_COMBINED_WORKER is set to 6, no combined worker will be synthesized beyond one for the socket and one per core. If it is set to 3, 3 intermediate combined workers will be synthesized, to divide the socket cores into 3 chunks of 2 cores. If it set to 2, 2 intermediate combined workers will be synthesized, to divide the the socket cores into 2 chunks of 3 cores, and then 3 additional combined workers will be synthesized, to divide the former synthesized workers into a bunch of 2 cores, and the remaining core (for which no combined worker is synthesized since there is already a normal worker for it).

The default, 2, thus makes StarPU tend to building a binary trees of combined workers.

STARPU_DISABLEASYNCHRONOUS_COPY  Disable asynchronous copies between CPU and GPU devices. The AMD implementation of OpenCL is known to fail when copying data asynchronously. When using this implementation, it is therefore necessary to disable asynchronous data transfers.

STARPU_DISABLEASYNCHRONOUS_CUDA_COPY  Disable asynchronous copies between CPU and CUDA devices.

STARPU_DISABLEASYNCHRONOUS_OPENCL_COPY  Disable asynchronous copies between CPU and OpenCL devices. The AMD implementation of OpenCL is known to fail when copying data asynchronously. When using this implementation, it is therefore necessary to disable asynchronous data transfers.

STARPU_DISABLEASYNCHRONOUS_MIC_COPY  Disable asynchronous copies between CPU and MIC devices.

STARPU_DISABLEASYNCHRONOUS_MPI_MS_COPY  Disable asynchronous copies between CPU and MPI Slave devices.

STARPU_ENABLECUDA_GPU_GPU_DIRECT  Enable (1) or Disable (0) direct CUDA transfers from GPU to GPU, without copying through RAM. The default is Enabled. This permits to test the performance effect of GPU-Direct.

STARPU_DISABLEPINNING  Disable (1) or Enable (0) pinning host memory allocated through starpu_malloc, starpu_memory_pin and friends. The default is Enabled. This permits to test the performance effect of memory pinning.

STARPU_MIC_SINK_PROGRAM_NAME  todo

STARPU_MIC_SINK_PROGRAM_PATH  todo

STARPU_MIC_PROGRAM_PATH  todo
26.2 Configuring The Scheduling Engine

**STARPU_SCHED** Choose between the different scheduling policies proposed by StarPU: work random, stealing, greedy, with performance models, etc.

Use `STARPU_SCHED=help` to get the list of available schedulers.

**STARPU_MIN_PRIO** Set the minimum priority used by priorities-aware schedulers.

**STARPU_MAX_PRIO** Set the maximum priority used by priorities-aware schedulers.

**STARPU_CALIBRATE** If this variable is set to 1, the performance models are calibrated during the execution. If it is set to 2, the previous values are dropped to restart calibration from scratch. Setting this variable to 0 disable calibration, this is the default behaviour.

Note: this currently only applies to dm and dmda scheduling policies.

**STARPU_CALIBRATE_MINIMUM** Define the minimum number of calibration measurements that will be made before considering that the performance model is calibrated. The default value is 10.

**STARPU_BUS_CALIBRATE** If this variable is set to 1, the bus is recalibrated during initialization.

**STARPU_PREFETCH** Indicate whether data prefetching should be enabled (0 means that it is disabled). If prefetching is enabled, when a task is scheduled to be executed e.g. on a GPU, StarPU will request an asynchronous transfer in advance, so that data is already present on the GPU when the task starts. As a result, computation and data transfers are overlapped. Note that prefetching is enabled by default in StarPU.

**STARPU_SCHED_ALPHA** To estimate the cost of a task StarPU takes into account the estimated computation time (obtained thanks to performance models). The alpha factor is the coefficient to be applied to it before adding it to the communication part.

**STARPU_SCHED_BETA** To estimate the cost of a task StarPU takes into account the estimated data transfer time (obtained thanks to performance models). The beta factor is the coefficient to be applied to it before adding it to the computation part.

**STARPU_SCHED_GAMMA** Define the execution time penalty of a joule (Energy-based Scheduling).

**STARPU_IDLE_POWER** Define the idle power of the machine (Energy-based Scheduling).

**STARPU_PROFILING** Enable on-line performance monitoring (Enabling On-line Performance Monitoring).

26.3 Extensions

**SOCL_OCL_LIB_OPENCL** THE SOCL test suite is only run when the environment variable `SOCL_OCL_LIB_OCL` is defined. It should contain the location of the file `libOpenCL.so` of the OCL ICD implementation.

**OCL_ICD_VENDORS** When using SOCL with OpenCL ICD (https://forge.imag.fr/projects/ocl-icd/), this variable may be used to point to the directory where ICD files are installed. The default directory is `/etc/OpenCL/vendors`. StarPU installs ICD files in the directory `$prefix/share/starpu/opencl/vendors`.

**STARPU_COMM_STATS** Communication statistics for starpumpi (Debugging MPI) will be enabled when the environment variable `STARPU_COMM_STATS` is defined to an value other than 0.

**STARPU_MPI_CACHE** Communication cache for starpumpi (MPI Support) will be disabled when the environment variable `STARPU_MPI_CACHE` is set to 0. It is enabled by default or for any other values of the variable `STARPU_MPI_CACHE`.

**STARPU_MPI_COMM** Communication trace for starpumpi (MPI Support) will be enabled when the environment variable `STARPU_MPI_COMM` is set to 1, and StarPU has been configured with the option `--enable-verbose`.

**STARPU_MPI_CACHE_STATS** When set to 1, statistics are enabled for the communication cache (MPI Support). For now, it prints messages on the standard output when data are added or removed from the received communication cache.
26.4 Miscellaneous And Debug

**STARPU_MPI_PRIORITIES** When set to 0, the use of priorities to order MPI communications is disabled (MPI Support).

**STARPU_MPI_FAKE_SIZE** Setting to a number makes StarPU believe that there are as many MPI nodes, even if it was run on only one MPI node. This allows e.g. to simulate the execution of one of the nodes of a big cluster without actually running the rest. It of course does not provide computation results and timing.

**STARPU_MPI_FAKE_RANK** Setting to a number makes StarPU believe that it runs the given MPI node, even if it was run on only one MPI node. This allows e.g. to simulate the execution of one of the nodes of a big cluster without actually running the rest. It of course does not provide computation results and timing.

**STARPU_MPI_DRIVER_CALL_FREQUENCY** When set to a positive value, activates the interleaving of the execution of tasks with the progression of MPI communications (MPI Support). The `starpu_mpi_init_conf()` function must have been called by the application for that environment variable to be used. When set to 0, the MPI progression thread does not use at all the driver given by the user, and only focuses on making MPI communications progress.

**STARPU_MPI_DRIVER_TASK_FREQUENCY** When set to a positive value, the interleaving of the execution of tasks with the progression of MPI communications mechanism to execute several tasks before checking communication requests again (MPI Support). The `starpu_mpi_init_conf()` function must have been called by the application for that environment variable to be used, and the `STARPU_MPI_DRIVER_CALL_FREQUENCY` environment variable set to a positive value.

**STARPU_SIMGRID_TRANSFER_COST** When set to 1 (which is the default), data transfers (over PCI bus, typically) are taken into account in simgrid mode.

**STARPU_SIMGRID_CUDA_MALLOC_COST** When set to 1 (which is the default), CUDA malloc costs are taken into account in simgrid mode.

**STARPU_SIMGRID_CUDA_QUEUE_COST** When set to 1 (which is the default), CUDA task and transfer queueing costs are taken into account in simgrid mode.

**STARPU_PCI_FLAT** When unset or set to 0, the platform file created for simgrid will contain PCI bandwidths and routes.

**STARPU_SIMGRID_QUEUE_MALLOC_COST** When unset or set to 1, simulate within simgrid the GPU transfer queueing.

**STARPU_MALLOC_SIMULATION_FOLD** Define the size of the file used for folding virtual allocation, in MiB. The default is 1, thus allowing 64GiB virtual memory when Linux’s `sysctl vm.max_map_count` value is the default 65535.

**STARPU_SIMGRID_TASK_SUBMIT_COST** When set to 1 (which is the default), task submission costs are taken into account in simgrid mode. This provides more accurate simgrid predictions, especially for the beginning of the execution.

**STARPU_SIMGRID_FETCHING_INPUT_COST** When set to 1 (which is the default), fetching input costs are taken into account in simgrid mode. This provides more accurate simgrid predictions, especially regarding data transfers.

**STARPU_SIMGRID_SCHED_COST** When set to 1 (0 is the default), scheduling costs are taken into account in simgrid mode. This provides more accurate simgrid predictions, and allows studying scheduling overhead of the runtime system. However, it also makes simulation non-deterministic.

26.4 Miscellaneous And Debug

**STARPU_HOME** Specify the main directory in which StarPU stores its configuration files. The default is `$HOME` on Unix environments, and `$USERPROFILE` on Windows environments.

**STARPU_PATH** Only used on Windows environments. Specify the main directory in which StarPU is installed (Running a Basic StarPU Application on Microsoft Visual C)

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Generated by Doxygen
STARPU_PERF_MODEL_DIR Specify the main directory in which StarPU stores its performance model files. The default is $STARPU_HOME/.starpu/sampling.

STARPU_PERF_MODEL_HOMOGENEOUS_CPU When this is set to 0, StarPU will assume that CPU devices do not have the same performance, and thus use different performance models for them, thus making kernel calibration much longer, since measurements have to be made for each CPU core.

STARPU_PERF_MODEL_HOMOGENEOUS_CUDA When this is set to 1, StarPU will assume that all CUDA devices have the same performance, and thus share performance models for them, thus allowing kernel calibration to be much faster, since measurements only have to be once for all CUDA GPUs.

STARPU_PERF_MODEL_HOMOGENEOUS_OPENCL When this is set to 1, StarPU will assume that all OPENCL devices have the same performance, and thus share performance models for them, thus allowing kernel calibration to be much faster, since measurements only have to be once for all OPENCL GPUs.

STARPU_PERF_MODEL_HOMOGENEOUS_MIC When this is set to 1, StarPU will assume that all MIC devices have the same performance, and thus share performance models for them, thus allowing kernel calibration to be much faster, since measurements only have to be once for all MIC GPUs.

STARPU_PERF_MODEL_HOMOGENEOUS_MPI_MS When this is set to 1, StarPU will assume that all MPI Slave devices have the same performance, and thus share performance models for them, thus allowing kernel calibration to be much faster, since measurements only have to be once for all MPI Slaves.

STARPU_HOSTNAME When set, force the hostname to be used when dealing performance model files. Models are indexed by machine name. When running for example on a homogenous cluster, it is possible to share the models between machines by setting export STARPU_HOSTNAME=some_global_name.

STARPU_OPENCL_PROGRAM_DIR Specify the directory where the OpenCL codelet source files are located. The function starpu_opencl_load_program_source() looks for the codelet in the current directory, in the directory specified by the environment variable STARPU_OPENCL_PROGRAM_DIR, in the directory share/starpu/opencl of the installation directory of StarPU, and finally in the source directory of StarPU.

STARPU_SILENT Allow to disable verbose mode at runtime when StarPU has been configured with the option --enable-verbose. Also disable the display of StarPU information and warning messages.

STARPU_LOGFILENAME Specify in which file the debugging output should be saved to.

STARPU_FXT_PREFIX Specify in which directory to save the trace generated if FxT is enabled. It needs to have a trailing '/ character.

STARPU_FXT_TRACE Specify whether to generate (1) or not (0) the FxT trace in /tmp/prof_file_XXX_YYY . The default is 1 (generate it)

STARPU_LIMIT_CUDA_devid_MEM Specify the maximum number of megabytes that should be available to the application on the CUDA device with the identifier devid. This variable is intended to be used for experimental purposes as it emulates devices that have a limited amount of memory. When defined, the variable overwrites the value of the variable STARPU_LIMIT_CUDA_MEM.

STARPU_LIMIT_CUDA_MEM Specify the maximum number of megabytes that should be available to the application on each CUDA device. This variable is intended to be used for experimental purposes as it emulates devices that have a limited amount of memory.

STARPU_LIMIT_OPENCL_devid_MEM Specify the maximum number of megabytes that should be available to the application on the OpenCL device with the identifier devid. This variable is intended to be used for experimental purposes as it emulates devices that have a limited amount of memory. When defined, the variable overwrites the value of the variable STARPU_LIMIT_OPENCL_MEM.

STARPU_LIMIT_OPENCL_MEM Specify the maximum number of megabytes that should be available to the application on each OpenCL device. This variable is intended to be used for experimental purposes as it emulates devices that have a limited amount of memory.

STARPU_LIMIT_CPU_MEM Specify the maximum number of megabytes that should be available to the application in the main CPU memory. Setting it enables allocation cache in main memory. Setting it to zero lets StarPU overflow memory.
STARPU_LIMIT_CPU_NUMA_devid_MEM Specify the maximum number of megabytes that should be available to the application on the NUMA node with the OS identifier devid.

STARPU_MINIMUM_AVAILABLE_MEM Specify the minimum percentage of memory that should be available in GPUs (or in main memory, when using out of core), below which a reclaiming pass is performed. The default is 0%.

STARPU_TARGET_AVAILABLE_MEM Specify the target percentage of memory that should be reached in GPUs (or in main memory, when using out of core), when performing a periodic reclaiming pass. The default is 0%.

STARPU_MINIMUM_CLEAN_BUFFERS Specify the minimum percentage of number of buffers that should be clean in GPUs (or in main memory, when using out of core), below which asynchronous writebacks will be issued. The default is 5%.

STARPU_TARGET_CLEAN_BUFFERS Specify the target percentage of number of buffers that should be reached in GPUs (or in main memory, when using out of core), when performing an asynchronous writeback pass. The default is 10%.

STARPU_DIDUSE_BARRIER When set to 1, StarPU will never evict a piece of data if it has not been used by at least one task. This avoids odd behaviors under high memory pressure, but can lead to deadlocks, so is to be considered experimental only.

STARPU_DISK_SWAP Specify a path where StarPU can push data when the main memory is getting full.

STARPU_DISK_SWAP_BACKEND Specify the backend to be used by StarPU to push data when the main memory is getting full. The default is unistd (i.e. using read/write functions), other values are stdio (i.e. using fread/write), unistd_o_direct (i.e. using read/write with O_DIRECT), leveldb (i.e. using a leveldb database), and hdf5 (i.e. using HDF5 library).

STARPU_DISK_SWAP_SIZE Specify the maximum size in MiB to be used by StarPU to push data when the main memory is getting full. The default is unlimited.

STARPU_LIMIT_MAX_SUBMITTED_TASKS Allow users to control the task submission flow by specifying to StarPU a maximum number of submitted tasks allowed at a given time, i.e. when this limit is reached task submission becomes blocking until enough tasks have completed, specified by STARPU_LIMIT_MIN_SUBMITTED_TASKS. Setting it enables allocation cache buffer reuse in main memory.

STARPU_LIMIT_MIN_SUBMITTED_TASKS Allow users to control the task submission flow by specifying to StarPU a submitted task threshold to wait before unblocking task submission. This variable has to be used in conjunction with STARPU_LIMIT_MAX_SUBMITTED_TASKS which puts the task submission thread to sleep. Setting it enables allocation cache buffer reuse in main memory.

STARPU_TRACE_BUFFER_SIZE Set the buffer size for recording trace events in MiB. Setting it to a big size allows to avoid pauses in the trace while it is recorded on the disk. This however also consumes memory, of course. The default value is 64.

STARPU_GENERATE_TRACE When set to 1, indicate that StarPU should automatically generate a Paje trace when starpu_shutdown() is called.

STARPU_GENERATE_TRACE_OPTIONS When the variable STARPU_GENERATE_TRACE is set to 1 to generate a Paje trace, this variable can be set to specify options (see starpu_fxt_tool -help).

STARPU_ENABLE_STATS When defined, enable gathering various data statistics (Data Statistics).

STARPU_MEMORY_STATS When set to 0, disable the display of memory statistics on data which have not been unregistered at the end of the execution (Memory Feedback).

STARPU_MAX_MEMORY_USE When set to 1, display at the end of the execution the maximum memory used by StarPU for internal data structures during execution.

STARPU_BUS_STATS When defined, statistics about data transfers will be displayed when calling starpu_shutdown() (Profiling).
STARPU_WORKER_STATS When defined, statistics about the workers will be displayed when calling starpu←shutdown() (Profiling). When combined with the environment variable STARPU_PROFILING, it displays the energy consumption (Energy-based Scheduling).

STARPU_STATS When set to 0, data statistics will not be displayed at the end of the execution of an application (Data Statistics).

STARPU_WATCHDOG_TIMEOUT When set to a value other than 0, allows to make StarPU print an error message whenever StarPU does not terminate any task for the given time (in µs), but lets the application continue normally. Should be used in combination with STARPU_WATCHDOG_CRASH (see Detecting Stuck Conditions).

STARPU_WATCHDOG_CRASH When set to a value other than 0, trigger a crash when the watch dog is reached, thus allowing to catch the situation in gdb, etc (see Detecting Stuck Conditions)

STARPU_WATCHDOG_DELAY Delay the activation of the watchdog by the given time (in µs). This can be convenient for letting the application initialize data etc. before starting to look for idle time.

STARPU_TASK_BREAK_ON_PUSH When this variable contains a job id, StarPU will raise SIGTRAP when the task with that job id is being pushed to the scheduler, which will be nicely catched by debuggers (see Debugging Scheduling)

STARPU_TASK_BREAK_ON_SCHED When this variable contains a job id, StarPU will raise SIGTRAP when the task with that job id is being scheduled by the scheduler (at a scheduler-specific point), which will be nicely catched by debuggers. This only works for schedulers which have such a scheduling point defined (see Debugging Scheduling)

STARPU_TASK_BREAK_ON_POP When this variable contains a job id, StarPU will raise SIGTRAP when the task with that job id is being popped from the scheduler, which will be nicely catched by debuggers (see Debugging Scheduling)

STARPU_TASK_BREAK_ON_EXEC When this variable contains a job id, StarPU will raise SIGTRAP when the task with that job id is being executed, which will be nicely catched by debuggers (see Debugging Scheduling)

STARPU_DISABLE_KERNELS When set to a value other than 1, it disables actually calling the kernel functions, thus allowing to quickly check that the task scheme is working properly, without performing the actual application-provided computation.

STARPU_HISTORY_MAX_ERROR History-based performance models will drop measurements which are really far from the measured average. This specifies the allowed variation. The default is 50 (%), i.e. the measurement is allowed to be x1.5 faster or /1.5 slower than the average.

STARPU_RAND_SEED The random scheduler and some examples use random numbers for their own working. Depending on the examples, the seed is by default just always 0 or the current time() (unless simgrid mode is enabled, in which case it is always 0). STARPU_RAND_SEED allows to set the seed to a specific value.

STARPU_IDLE_TIME When set to a value being a valid filename, a corresponding file will be created when shutting down StarPU. The file will contain the sum of all the workers’ idle time.

STARPU_GLOBAL_ARBITER When set to a positive value, StarPU will create a arbiter, which implements an advanced but centralized management of concurrent data accesses (see Concurrent Data Accesses).

STARPU_USE_NUMA When defined, NUMA nodes are taking into account by StarPU. Otherwise, memory is considered as only one node. This is experimental for now.

When enabled, STARPU_MAIN_MEMORY is a pointer to the NUMA node associated to the first CPU worker if it exists, the NUMA node associated to the first GPU discovered otherwise. If StarPU doesn’t find any NUMA node after these step, STARPU_MAIN_MEMORY is the first NUMA node discovered by StarPU.

STARPU_IDLE_FILE If the environment variable STARPU_IDLE_FILE is defined, a file named after its contents will be created at the end of the execution. The file will contain the sum of the idle times of all the workers.

STARPU_HWLOC_INPUT If the environment variable STARPU_HWLOC_INPUT is defined to the path of an XML file, hwloc will be made to use it as input instead of detecting the current platform topology, which can save significant initialization time.

To produce this XML file, use lstopo file.xml

Generated by Doxygen
STARPU_CATCH_SIGNALS  By default, StarPU catch signals SIGINT, SIGSEGV and SIGTRAP to perform final actions such as dumping FxT trace files even though the application has crashed. Setting this variable to a value other than 1 will disable this behaviour. This should be done on JVM systems which may use these signals for their own needs. The flag can also be set through the field starpu_conf::catch_signals.

26.5 Configuring The Hypervisor

SC_HYPERVISOR_POLICY  Choose between the different resizing policies proposed by StarPU for the hypervisor: idle, app_driven, feast_lp, teft_lp; ispeed_lp, throughput_lp etc. Use SC_HYPERVISOR_POLICY=help to get the list of available policies for the hypervisor.

SC_HYPERVISOR_TRIGGER_RESIZE  Choose how should the hypervisor be triggered: speed if the resizing algorithm should be called whenever the speed of the context does not correspond to an optimal precomputed value, idle if the resizing algorithm should be called whenever the workers are idle for a period longer than the value indicated when configuring the hypervisor.

SC_HYPERVISOR_START_RESIZE  Indicate the moment when the resizing should be available. The value correspond to the percentage of the total time of execution of the application. The default value is the resizing frame.

SC_HYPERVISOR_MAX_SPEED_GAP  Indicate the ratio of speed difference between contexts that should trigger the hypervisor. This situation may occur only when a theoretical speed could not be computed and the hypervisor has no value to compare the speed to. Otherwise the resizing of a context is not influenced by the speed of the other contexts, but only by the the value that a context should have.

SC_HYPERVISOR_STOP_PRINT  By default the values of the speed of the workers is printed during the execution of the application. If the value 1 is given to this environment variable this printing is not done.

SC_HYPERVISOR.LAZY_RESIZE  By default the hypervisor resizes the contexts in a lazy way, that is workers are firstly added to a new context before removing them from the previous one. Once this workers are clearly taken into account into the new context (a task was poped there) we remove them from the previous one. However if the application would like that the change in the distribution of workers should change right away this variable should be set to 0.

SC_HYPERVISOR_SAMPLE_CRITERIA  By default the hypervisor uses a sample of flops when computing the speed of the contexts and of the workers. If this variable is set to time the hypervisor uses a sample of time (10% of an aproximation of the total execution time of the application).
Chapter 27

Compilation Configuration

The behavior of the StarPU library and tools may be tuned thanks to the following configure options.

27.1 Common Configuration

--enable-debug   Enable debugging messages.

--enable-spinlock-check   Enable checking that spinlocks are taken and released properly.

--enable-fast   Disable assertion checks, which saves computation time.

--enable-verbose   Increase the verbosity of the debugging messages. This can be disabled at runtime by setting the environment variable STARPU_SILENT to any value. --enable-verbose=extra increase even more the verbosity.

$ STARPU_SILENT=1 ./vector_scal

--enable-coverage   Enable flags for the coverage tool gcov.

--enable-quick-check   Specify tests and examples should be run on a smaller data set, i.e allowing a faster execution time

--enable-long-check   Enable some exhaustive checks which take a really long time.

--enable-new-check   Enable new testcases which are known to fail.

--with-hwloc   Specify hwloc should be used by StarPU. hwloc should be found by the means of the tool pkg-config.

--with-hwloc=prefix   Specify hwloc should be used by StarPU. hwloc should be found in the directory specified by prefix.

--without-hwloc   Specify hwloc should not be used by StarPU.

--disable-build-doc   Disable the creation of the documentation. This should be done on a machine which does not have the tools doxygen and latex (plus the packages latex-xcolor and texlive-latex-extra).

--disable-icc   Disable the usage of the ICC compiler. When found, some specific ICC examples are compiled.

Additionally, the script configure recognize many variables, which can be listed by typing ./configure --help. For example, ./configure NVCCFLAGS="-arch sm_20" adds a flag for the compilation of CUDA kernels, and NVCC_CC=gcc-5 allows to change the C++ compiler used by nvcc.
27.2 Configuring Workers

- **--enable-blocking-drivers**  By default, StarPU keeps CPU workers awake permanently, for better reactivity. This option makes StarPU put CPU workers to real sleep when there are not enough tasks to compute.

- **--enable-worker-callbacks**  If blocking drivers are enabled, enable callbacks to notify an external resource manager about workers going to sleep and waking up.

- **--enable-maxcpus=count**  Use at most count CPU cores. This information is then available as the macro STARPU_MAXCPUS.

- **--enable-maxnumanodes=count**  Use at most count NUMA nodes. This information is then available as the macro STARPU_MAXNUMANODES.

- **--disable-cpu**  Disable the use of CPUs of the machine. Only GPUs etc. will be used.

- **--enable-maxcudadev=count**  Use at most count CUDA devices. This information is then available as the macro STARPU_MAXCUDADEVS.

- **--disable-cuda**  Disable the use of CUDA, even if a valid CUDA installation was detected.

- **--with-cuda-dir=prefix**  Search for CUDA under prefix, which should notably contain the file include/cuda.h.

- **--with-cuda-include-dir=dir**  Search for CUDA headers under dir, which should notably contain the file cuda.h. This defaults to /include appended to the value given to --with-cuda-dir.

- **--with-cuda-lib-dir=dir**  Search for CUDA libraries under dir, which should notably contain the CUDA shared libraries—e.g., libcuda.so. This defaults to /lib appended to the value given to --with-cuda-dir.

- **--disable-cuda-memcpy-peer**  Explicitly disable peer transfers when using CUDA 4.0.

- **--enable-maxopencldev=count**  Use at most count OpenCL devices. This information is then available as the macro STARPU_MAXOPENCLDEVS.

- **--disable-opencl**  Disable the use of OpenCL, even if the SDK is detected.

- **--with-opencl-dir=prefix**  Search for an OpenCL implementation under prefix, which should notably contain include/CL/cl.h (or include/OpenCL/cl.h on Mac OS).

- **--with-opencl-include-dir=dir**  Search for OpenCL headers under dir, which should notably contain CL/cl.h (or OpenCL/cl.h on Mac OS). This defaults to /include appended to the value given to --with-opencl-dir.

- **--with-opencl-lib-dir=dir**  Search for an OpenCL library under dir, which should notably contain the OpenCL shared libraries—e.g., libOpenCL.so. This defaults to /lib appended to the value given to --with-opencl-dir.

- **--enable-opencl-simulator**  Enable considering the provided OpenCL implementation as a simulator, i.e. use the kernel duration returned by OpenCL profiling information as wallclock time instead of the actual measured real time. This requires simgrid support.

- **--enable-maximplementations=count**  Allow for at most count codelet implementations for the same target device. This information is then available as the macro STARPU_MAXIMPLEMENTATIONS macro.

- **--enable-max-sched-ctxs=count**  Allow for at most count scheduling contexts. This information is then available as the macro STARPU_NMAX_SCHED_CTXS.

- **--disable-asynchronous-copy**  Disable asynchronous copies between CPU and GPU devices. The AMD implementation of OpenCL is known to fail when copying data asynchronously. When using this implementation, it is therefore necessary to disable asynchronous data transfers.

- **--disable-asynchronous-cuda-copy**  Disable asynchronous copies between CPU and CUDA devices.

- **--disable-asynchronous-opencl-copy**  Disable asynchronous copies between CPU and OpenCL devices. The AMD implementation of OpenCL is known to fail when copying data asynchronously. When using this implementation, it is therefore necessary to disable asynchronous data transfers.
--enable-maxmicthreads Specify the maximum number of MIC threads

--disable-asynchronous-mic-copy Disable asynchronous copies between CPU and MIC devices.

--disable-asynchronous-mpi-master-slave-copy Disable asynchronous copies between CPU and MPI Slave devices.

--enable-maxnodes=count Use at most count memory nodes. This information is then available as the macro STARPU_MAXNODES. Reducing it allows to considerably reduce memory used by StarPU data structures.

27.3 Extension Configuration

--disable-mpi Disable the build of libstarpumpi. By default, it is enabled when MPI is found.

--with-mpicc=path Use the compiler mpicc at path, for StarPU-MPI. (MPI Support).

--enable-mpi-pedantic-isend Before performing any MPI communication, StarPU-MPI waits for the data to be available in the main memory of the node submitting the request. For send communications, data is acquired with the mode STARPU_R. When enabling the pedantic mode, data are instead acquired with the STARP ← U_RW which thus ensures that there is not more than 1 concurrent MPI_Isend calls accessing the data.

--enable-mpi-master-slave Enable the MPI Master-Slave support. By default, it is disabled.

--with-mpi-master-slave-multiple-thread Create one thread per MPI Slave on the MPI master to manage communications.

--enable-mpi-verbose Increase the verbosity of the MPI debugging messages. This can be disabled at runtime by setting the environment variable STARPU_SILENT to any value. -enable-mpi-verbose=extra increase even more the verbosity.

$ STARPU_SILENT=1 mpirun -np 2 ./insert_task

--enable-nmad Enable the NewMadeleine implementation for StarPU-MPI.

--disable-fortran Disable the fortran extension. By default, it is enabled when a fortran compiler is found.

--disable-socl Disable the SOCL extension (SOCL OpenCL Extensions). By default, it is enabled when an OpenCL implementation is found.

--with-coi-dir Specify the directory to the COI library for MIC support. The default value is /opt/intel/mic/coi

--mic-host Specify the precise MIC architecture host identifier. The default value is x86_64-k1om-linux

--enable-openmp Enable OpenMP Support (The StarPU OpenMP Runtime Support (SORS))

--enable-cluster Enable cluster Support (Clustering A Machine)

27.4 Advanced Configuration

--enable-perf-debug Enable performance debugging through gprof.

--enable-model-debug Enable performance model debugging.

--enable-fxt-lock Enable additional trace events which describes locks behaviour. This is however extremely heavy and should only be enabled when debugging inside StarPU.

--enable-maxbuffers Define the maximum number of buffers that tasks will be able to take as parameters, then available as the macro STARPU_NMAXBUFS.

--enable-allocation-cache Enable the use of a data allocation cache to avoid the cost of it with CUDA. Still experimental.

--enable-opengl-render Enable the use of OpenGL for the rendering of some examples.

Generated by Doxygen
–enable-blas-lib=prefix Specify the blas library to be used by some of the examples. Libraries available:

• none [default]: no BLAS library is used
• atlas: use ATLAS library
• goto: use GotoBLAS library
• openblas: use OpenBLAS library
• mkl: use MKL library (you may need to set specific CFLAGS and LDFLAGS with –with-mkl-cflags and –with-mkl-ldflags)

–enable-leveldb Enable linking with LevelDB if available

–disable-hdf5 Disable building HDF5 support.

–with-hdf5-include-dir=path Specify the directory where is stored the header hdf5.h.

–with-hdf5-lib-dir=path Specify the directory where is stored the hdf5 library.

–disable-starpufft Disable the build of libstarpufft, even if \texttt{fftw} or \texttt{cuFFT} is available.

–enable-starpufft-examples Enable the compilation and the execution of the libstarpufft examples. By default, they are neither compiled nor checked.

–with-fxt=prefix Search for FxT under \texttt{prefix}. FxT (\url{http://savannah.nongnu.org/projects/fkt}) is used to generate traces of scheduling events, which can then be rendered them using ViTE (Off-line Performance Feedback). \texttt{prefix} should notably contain \texttt{include/fxt/fxt.h}.

–with-perf-model-dir=dir Store performance models under \texttt{dir}, instead of the current user’s home.

–with-goto-dir=prefix Search for GotoBLAS under \texttt{prefix}, which should notably contain \texttt{libgoto.so} or \texttt{libgoto2.so}.

–with-atlas-dir=prefix Search for ATLAS under \texttt{prefix}, which should notably contain \texttt{include/cblas.h}.

–with-mkl-cflags=cflags Use \texttt{cflags} to compile code that uses the MKL library.

–with-mkl-ldflags=ldflags Use \texttt{ldflags} when linking code that uses the MKL library. Note that the MKL website (\url{http://software.intel.com/en-us/articles/intel-mkl-link-line-advisor/}) provides a script to determine the linking flags.

–disable-glpk Disable the use of libglpk for computing area bounds.

–disable-build-tests Disable the build of tests.

–disable-build-examples Disable the build of examples.

–disable-build-tests Disable the build of tests.

–enable-sc-hypervisor Enable the Scheduling Context Hypervisor plugin (Scheduling Context Hypervisor). By default, it is disabled.

–enable-memory-stats Enable memory statistics (Memory Feedback).

–enable-simgrid Enable simulation of execution in simgrid, to allow easy experimentation with various numbers of cores and GPUs, or amount of memory, etc. Experimental.

The path to simgrid can be specified through the SIMGRID\_CFLAGS and SIMGRID\_LIBS environment variables, for instance:

\begin{verbatim}
export SIMGRID\_CFLAGS="-I/usr/local/simgrid/include"
export SIMGRID\_LIBS="-L/usr/local/simgrid/lib -lsimgrid"
\end{verbatim}

–with-simgrid-dir Similar to the option –enable-simgrid but also allows to specify the location to the SimGrid library.
–with-simgrid-include-dir Similar to the option --enable-simgrid but also allows to specify the location to the SimGrid include directory.

–with-simgrid-lib-dir Similar to the option --enable-simgrid but also allows to specify the location to the SimGrid lib directory.

–with-smpirun=path Use the smpirun at path

–enable-simgrid-mc Enable the Model Checker in simulation of execution in simgrid, to allow exploring various execution paths.

–enable-calibration-heuristic Allows to set the maximum authorized percentage of deviation for the history-based calibrator of StarPU. A correct value of this parameter must be in [0..100]. The default value of this parameter is 10. Experimental.
Chapter 28

Module Index

28.1 Modules

Here is a list of all modules:

- FFT Support ........................................... 358
- Threads .................................................. 195
- Versioning ............................................. 181
- Bitmap .................................................. 205
- Theoretical Lower Bound on Execution Time .......... 319
- Clustering Machine ................................... 433
- CUDA Extensions ...................................... 320
- Data Partition ......................................... 260
- Data Management ..................................... 216
- Data Interfaces ....................................... 226
- Out Of Core ........................................... 270
- Running Drivers ....................................... 381
- Expert Mode .......................................... 382
- FxT Support ........................................... 356
- Initialization and Termination ......................... 182
- Miscellaneous Helpers ................................ 354
- MIC Extensions ...................................... 353
- OpenCL Extensions .................................... 323
- OpenMP Runtime Support ............................. 329
- Performance Model ................................... 306
- Profiling ............................................... 315
- Random Functions .................................... ??
- Modularized Scheduler Interface ....................... 418
- Scheduling Contexts .................................. 383
- Scheduling Policy ..................................... 390
- Sink ..................................................... ??
- Standard Memory Library ............................ 189
- Task Bundles ......................................... 376
- Codelet And Tasks ..................................... 274
- Explicit Dependencies ................................ 302
- Task Lists .............................................. 377
- Task Insert Utility .................................... 296
- Tree ..................................................... 399
- Toolbox ............................................... 193
- Workers' Properties .................................. 207
- Parallel Tasks ........................................ 379
- MPI Support .......................................... 360
- Scheduling Context Hypervisor - Regular usage ........ 409
- Scheduling Context Hypervisor - Linear Programming .... 415
- Scheduling Context Hypervisor - Building a new resizing policy .. 399
| Interoperability Support | 434 |
Chapter 29

Deprecated List

**Global starpu_codelet::cpu_func**
Optional field which has been made deprecated. One should use instead the field `starpu_codelet::cpu_funcs`.

**Global starpu_codelet::cuda_func**
Optional field which has been made deprecated. One should use instead the `starpu_codelet::cuda_funcs` field.

**Global starpu_codelet::opencl_func**
Optional field which has been made deprecated. One should use instead the `starpu_codelet::opencl_funcs` field.

**Global starpu_data_free_pinned_if_possible**
Equivalent to `starpu_free()`. This macro is provided to avoid breaking old codes.

**Global starpu_data_interface_ops::handle_to_pointer(starpu_data_handle_t handle, unsigned node)**
Use `starpu_data_interface_ops::to_pointer` instead. Return the current pointer (if any) for the handle on the given node.

**Global starpu_data_malloc_pinned_if_possible**
Equivalent to `starpu_malloc()`. This macro is provided to avoid breaking old codes.

**Global starpu_mpi_initialize (void)**
This function has been made deprecated. One should use instead the function `starpu_mpi_init()`. This function does not call `MPI_Init()`, it should be called beforehand.

**Global starpu_mpi_initialize_extended (int *rank, int *world_size)**
This function has been made deprecated. One should use instead the function `starpu_mpi_init()`. MPI will be initialized by `starpumpi` by calling `MPI_Init_Thread(argc, argv, MPI_THREAD_SERIALIZED, ...).

**Global STARPU_MULTIPLE_CPU_IMPLEMENTATIONS**
Setting the field `starpu_codelet::cpu_func` with this macro indicates the codelet will have several implementations. The use of this macro is deprecated. One should always only define the field `starpu_codelet::cpu_funcs`.

**Global STARPU_MULTIPLE_CUDA_IMPLEMENTATIONS**
Setting the field `starpu_codelet::cuda_func` with this macro indicates the codelet will have several implementations. The use of this macro is deprecated. One should always only define the field `starpu_codelet::cuda_funcs`.

**Global STARPU_MULTIPLE_OPENCL_IMPLEMENTATIONS**
Setting the field `starpu_codelet::opencl_func` with this macro indicates the codelet will have several implementations. The use of this macro is deprecated. One should always only define the field `starpu_codelet::opencl_funcs`.
Chapter 30

Module Documentation a.k.a StarPU’s API

30.1 Versioning

Macros

- 
  #define STARPU_MAJOR_VERSION
- 
  #define STARPU_MINOR_VERSION
- 
  #define STARPU_RELEASE_VERSION

Functions

- 
  void starpu_get_version (int *major, int *minor, int *release)

30.1.1 Detailed Description

30.1.2 Macro Definition Documentation

30.1.2.1 STARPU_MAJOR_VERSION

#define STARPU_MAJOR_VERSION

Define the major version of StarPU. This is the version used when compiling the application.

30.1.2.2 STARPU_MINOR_VERSION

#define STARPU_MINOR_VERSION

Define the minor version of StarPU. This is the version used when compiling the application.

30.1.2.3 STARPU_RELEASE_VERSION

#define STARPU_RELEASE_VERSION

Define the release version of StarPU. This is the version used when compiling the application.

30.1.3 Function Documentation

30.1.3.1 starpu_get_version()

void starpu_get_version (  
    int * major,  
    int * minor,  
    int * release )

Return as 3 integers the version of StarPU used when running the application.
30.2 Initialization and Termination

Data Structures

- struct starpu_conf

Macros

- #define STARPU_THREAD_ACTIVE

Functions

- int starpu_conf_init (struct starpu_conf *conf)
- int starpu_init (struct starpu_conf *conf) STARPU_WARN_UNUSED_RESULT
- int starpu_initialize (struct starpu_conf *user_conf, int *argc, char ***argv)
- int starpu_is_initialized (void)
- void starpu_wait_initialized (void)
- void starpu_shutdown (void)
- void starpu_pause (void)
- void starpu_resume (void)
- unsigned starpu_get_next_bindid (unsigned flags, unsigned *preferred, unsigned npreferred)
- int starpu_bind_thread_on (int cpuid, unsigned flags, const char *name)
- void starpu_topology_print (FILE *f)
- int starpu_asynchronous_copy_disabled (void)
- int starpu_asynchronous_cuda_copy_disabled (void)
- int starpu_asynchronous_opencl_copy_disabled (void)
- int starpu_asynchronous_mic_copy_disabled (void)
- int starpu_asynchronous_mpi_ms_copy_disabled (void)
- void starpu_display_stats (void)

30.2.1 Detailed Description

30.2.2 Data Structure Documentation

30.2.2.1 struct starpu_conf

Structure passed to the starpu_init() function to configure StarPU. It has to be initialized with starpu_conf_init(). When the default value is used, StarPU automatically selects the number of processing units and takes the default scheduling policy. The environment variables overwrite the equivalent parameters.

Data Fields

- const char * sched_policy_name
- struct starpu_sched_policy * sched_policy
- void(* sched_policy_init *) (unsigned)
- int ncpus
- int reserve_ncpus
- int ncuda
- int nopencl
- int nmic
- int nmpi_ms
- unsigned use_explicit_workers_bindid
- unsigned workers_bindid [STARPU_NMAXWORKERS]
- unsigned use_explicit_workers_cuda_gpuid
- unsigned workers_cuda_gpuid [STARPU_NMAXWORKERS]
- unsigned use_explicit_workers_opencl_gpuid
- unsigned workers_opencl_gpuid [STARPU_NMAXWORKERS]
30.2 Initialization and Termination

- unsigned use_explicit_workers_mic_deviceid
- unsigned workers_mic_deviceid [STARPU_NMAXWORKERS]
- unsigned use_explicit_workers_mpi_ms_deviceid
- unsigned workers_mpi_ms_deviceid [STARPU_NMAXWORKERS]
- int bus_calibrate
- int calibrate
- int single_combined_worker
- char * mic_sink_program_path
- int disable_asynchronous_copy
- int disable_asynchronous_cuda_copy
- int disable_asynchronous_opencl_copy
- int disable_asynchronous_mic_copy
- int disable_asynchronous_mpi_ms_copy
- unsigned * cuda_opengl_interoperability
- unsigned n_cuda_opengl_interoperability
- struct starpu_driver * not_launched_drivers
- unsigned n_not_launched_drivers
- unsigned trace_buffer_size
- int global_sched_ctx_min_priority
- int global_sched_ctx_max_priority
- void(* callback_worker_going_to_sleep)(unsigned workerid)
- void(* callback_worker_waking_up)(unsigned workerid)
- int catch_signals

Private Attributes

- int magic

30.2.2.1.1 Field Documentation

30.2.2.1.1.1 magic

int starpu_conf::magic [private]
Will be initialized by starpu_conf_init(). Should not be set by hand.

30.2.2.1.1.2 sched_policy_name

const char* starpu_conf::sched_policy_name
Name of the scheduling policy. This can also be specified with the environment variable STARPU_SCHED. (default = NULL).

30.2.2.1.1.3 sched_policy

struct starpu_sched_policy* starpu_conf::sched_policy
Definition of the scheduling policy. This field is ignored if starpu_conf::sched_policy_name is set. (default = NULL)

30.2.2.1.1.4 ncpus

int starpu_conf::ncpus
Number of CPU cores that StarPU can use. This can also be specified with the environment variable STARPU_NCPU. (default = -1)

30.2.2.1.1.5 reserve_ncpus

int starpu_conf::reserve_ncpus
Number of CPU cores to that StarPU should leave aside. They can then be used by application threads, by calling starpu_get_next_bindid() to get their ID, and starpu_bind_thread_on() to bind the current thread to them.

30.2.2.1.1.6 ncuda

int starpu_conf::ncuda
Number of CUDA devices that StarPU can use. This can also be specified with the environment variable STARPU_U_NCUDA. (default = -1)
30.2.2.1.1.7 nopencl

int starpu_conf::nopencl

Number of OpenCL devices that StarPU can use. This can also be specified with the environment variable $\text{STARPU\_NOPENCL}$. (default = -1)

30.2.2.1.1.8 nmic

int starpu_conf::nmic

Number of MIC devices that StarPU can use. This can also be specified with the environment variable $\text{STARPU\_NMIC}$. (default = -1)

30.2.2.1.1.9 nmpi_ms

int starpu_conf::nmpi_ms

Number of MPI Master Slave devices that StarPU can use. This can also be specified with the environment variable $\text{STARPU\_NMPI\_MS}$. (default = -1)

30.2.2.1.1.10 use_explicit_workers_bindid

unsigned starpu_conf::use_explicit_workers_bindid

If this flag is set, the starpu_conf::workers_bindid array indicates where the different workers are bound, otherwise StarPU automatically selects where to bind the different workers. This can also be specified with the environment variable $\text{STARPU\_WORKERS\_CPUID}$. (default = 0)

30.2.2.1.1.11 workers_bindid

unsigned starpu_conf::workers_bindid[STARPU_NMAXWORKERS]

If the starpu_conf::use_explicit_workers_bindid flag is set, this array indicates where to bind the different workers. The i-th entry of the starpu_conf::workers_bindid indicates the logical identifier of the processor which should execute the i-th worker. Note that the logical ordering of the CPUs is either determined by the OS, or provided by the hwloc library in case it is available.

30.2.2.1.1.12 use_explicit_workers_cuda_gpuid

unsigned starpu_conf::use_explicit_workers_cuda_gpuid

If this flag is set, the CUDA workers will be attached to the CUDA devices specified in the starpu_conf::workers_cuda_gpuid array. Otherwise, StarPU affects the CUDA devices in a round-robin fashion. This can also be specified with the environment variable $\text{STARPU\_WORKERS\_CUDAID}$. (default = 0)

30.2.2.1.1.13 workers_cuda_gpuid

unsigned starpu_conf::workers_cuda_gpuid[STARPU_NMAXWORKERS]

If the starpu_conf::use_explicit_workers_cuda_gpuid flag is set, this array contains the logical identifiers of the CUDA devices (as used by $\text{cudaGetDevice()}$).

30.2.2.1.1.14 use_explicit_workers_opencl_gpuid

unsigned starpu_conf::use_explicit_workers_opencl_gpuid

If this flag is set, the OpenCL workers will be attached to the OpenCL devices specified in the starpu_conf::workers_opencl_gpuid array. Otherwise, StarPU affects the OpenCL devices in a round-robin fashion. This can also be specified with the environment variable $\text{STARPU\_WORKERS\_OPENCLID}$. (default = 0)

30.2.2.1.1.15 workers_opencl_gpuid

unsigned starpu_conf::workers_opencl_gpuid[STARPU_NMAXWORKERS]

If the starpu_conf::use_explicit_workers_opencl_gpuid flag is set, this array contains the logical identifiers of the OpenCL devices to be used.

30.2.2.1.1.16 use_explicit_workers_mic_deviceid

unsigned starpu_conf::use_explicit_workers_mic_deviceid

If this flag is set, the MIC workers will be attached to the MIC devices specified in the array starpu_conf::workers_mic_deviceid. Otherwise, StarPU affects the MIC devices in a round-robin fashion. This can also be specified with the environment variable $\text{STARPU\_WORKERS\_MICID}$. (default = 0)

30.2.2.1.1.17 workers_mic_deviceid

unsigned starpu_conf::workers_mic_deviceid[STARPU_NMAXWORKERS]

If the flag starpu_conf::use_explicit_workers_mic_deviceid is set, the array contains the logical identifiers of the MIC devices to be used.
30.2.1.1.18 use_explicit_workers_mpi_ms_deviceid

**unsigned starpu_conf::use_explicit_workers_mpi_ms_deviceid**

If this flag is set, the MPI Master Slave workers will be attached to the MPI Master Slave devices specified in the array starpu_conf::workers_mpi_ms_deviceid. Otherwise, StarPU affects the MPI Master Slave devices in a round-robin fashion. (default = 0)

30.2.1.1.19 workers_mpi_ms_deviceid

**unsigned starpu_conf::workers_mpi_ms_deviceid[STARPU_NMAXWORKERS]**

If the flag starpu_conf::use_explicit_workers_mpi_ms_deviceid is set, the array contains the logical identifiers of the MPI Master Slave devices to be used.

30.2.1.1.20 bus_calibrate

**int starpu_conf::bus_calibrate**

If this flag is set, StarPU will recalibrate the bus. If this value is equal to -1, the default value is used. This can also be specified with the environment variable STARPU_BUS_CALIBRATE. (default = 0)

30.2.1.1.21 calibrate

**int starpu_conf::calibrate**

If this flag is set, StarPU will calibrate the performance models when executing tasks. If this value is equal to -1, the default value is used. If the value is equal to 1, it will force continuing calibration. If the value is equal to 2, the existing performance models will be overwritten. This can also be specified with the environment variable STARPU_CALIBRATE. (default = 0)

30.2.1.1.22 single_combined_worker

**int starpu_conf::single_combined_worker**

By default, StarPU executes parallel tasks concurrently. Some parallel libraries (e.g. most OpenMP implementations) however do not support concurrent calls to parallel code. In such case, setting this flag makes StarPU only start one parallel task at a time (but other CPU and GPU tasks are not affected and can be run concurrently). The parallel task scheduler will however still try varying combined worker sizes to look for the most efficient ones. This can also be specified with the environment variable STARPU_SINGLE_COMBINED_WORKER. (default = 0)

30.2.1.1.23 mic_sink_program_path

**char *starpu_conf::mic_sink_program_path**

Path to the kernel to execute on the MIC device, compiled for MIC architecture. When set to NULL, StarPU automatically looks next to the host program location. (default = NULL)

30.2.1.1.24 disable_asynchronous_copy

**int starpu_conf::disable_asynchronous_copy**

This flag should be set to 1 to disable asynchronous copies between CPUs and all accelerators. The AMD implementation of OpenCL is known to fail when copying data asynchronously. When using this implementation, it is therefore necessary to disable asynchronous data transfers. This can also be specified with the environment variable STARPU_DISABLEASYNCHRONOUS_COPY. This can also be specified at compilation time by giving to the configure script the option --disable-asynchronous-copy. (default = 0)

30.2.1.1.25 disable_asynchronous_c CUDA copy

**int starpu_conf::disable_asynchronous_c CUDA copy**

This flag should be set to 1 to disable asynchronous copies between CPUs and CUDA accelerators. This can also be specified with the environment variable STARPU_DISABLEASYNCHRONOUS_CUDA_COPY. This can also be specified at compilation time by giving to the configure script the option --disable-asynchronous-cuda-copy. (default = 0)

30.2.1.1.26 disable_asynchronous_opencl copy

**int starpu_conf::disable_asynchronous_opencl copy**

This flag should be set to 1 to disable asynchronous copies between CPUs and OpenCL accelerators. The AMD implementation of OpenCL is known to fail when copying data asynchronously. When using this implementation, it is therefore necessary to disable asynchronous data transfers. This can also be specified with the environment variable STARPU_DISABLEASYNCHRONOUS_OPENCL_COPY. This can also be specified at compilation time by giving to the configure script the option --disable-asynchronous-opencl-copy. (default = 0)
disable_asynchronous_mic_copy

int starpu_conf::disable_asynchronous_mic_copy

This flag should be set to 1 to disable asynchronous copies between CPUs and MIC accelerators. This can also be specified with the environment variable STARPU_DISABLE_ASYNCHRONOUS_MIC_COPY. This can also be specified at compilation time by giving to the configure script the option --disable-asynchronous-mic-copy. (default = 0).

disable_asynchronous_mpi_ms_copy

int starpu_conf::disable_asynchronous_mpi_ms_copy

This flag should be set to 1 to disable asynchronous copies between CPUs and MPI Master Slave devices. This can also be specified with the environment variable STARPU_DISABLE_ASYNCHRONOUS_MPI_MS_COPY. This can also be specified at compilation time by giving to the configure script the option --disable-asynchronous-mpi-master-slave-copy. (default = 0).

cuda_opengl_interoperability

unsigned* starpu_conf::cuda_opengl_interoperability

Enable CUDA/OpenGL interoperation on these CUDA devices. This can be set to an array of CUDA device identifiers for which cudaGLSetGLDevice() should be called instead of cudaSetDevice(). Its size is specified by the starpu_conf::n_cuda_opengl_interoperability field below (default = NULL).

n_cuda_opengl_interoperability

unsigned starpu_conf::n_cuda_opengl_interoperability

Size of the array starpu_conf::cuda_opengl_interoperability

not_launched_drivers

struct starpu_driver* starpu_conf::not_launched_drivers

Array of drivers that should not be launched by StarPU. The application will run in one of its own threads. (default = NULL)

n_not_launched_drivers

unsigned starpu_conf::n_not_launched_drivers

The number of StarPU drivers that should not be launched by StarPU, i.e number of elements of the array starpu_conf::not_launched_drivers. (default = 0)

trace_buffer_size

unsigned starpu_conf::trace_buffer_size

Specify the buffer size used for FxT tracing. Starting from FxT version 0.2.12, the buffer will automatically be flushed when it fills in, but it may still be interesting to specify a bigger value to avoid any flushing (which would disturb the trace).

catch_signals

int starpu_conf::catch_signals

Specify if StarPU should catch SIGINT, SIGSEGV and SIGTRAP signals to make sure final actions (e.g dumping FxT trace files) are done even though the application has crashed. By default (value = 1), signals are caught. It should be disabled on systems which already catch these signals for their own needs (e.g JVM) This can also be specified with the environment variable STARPU_CATCH_SIGNALS

Macro Definition Documentation

STARPU_THREAD_ACTIVE

#define STARPU_THREAD_ACTIVE

Value to be passed to starpu_get_next_bindid() and starpu_bind_thread_on() when binding a thread which will significantly eat CPU time, and should thus have its own dedicated CPU.

Function Documentation
30.2.4.1 starpu_conf_init()

```c
int starpu_conf_init (  
    struct starpu_conf * conf )
```

Initialize the `conf` structure with the default values. In case some configuration parameters are already specified through environment variables, `starpu_conf_init()` initializes the fields of `conf` according to the environment variables. For instance if `STARPU_CALIBRATE` is set, its value is put in the field `starpu_conf::calibrate` of `conf`. Upon successful completion, this function returns 0. Otherwise, `-EINVAL` indicates that the argument was `NULL`.

30.2.4.2 starpu_init()

```c
int starpu_init (  
    struct starpu_conf * conf )
```

StarPU initialization method, must be called prior to any other StarPU call. It is possible to specify StarPU's configuration (e.g. scheduling policy, number of cores, ...) by passing a non-NULL `conf`. Default configuration is used if `conf` is `NULL`. Upon successful completion, this function returns 0. Otherwise, `-ENODEV` indicates that no worker was available (and thus StarPU was not initialized).

30.2.4.3 starpu_initialize()

```c
int starpu_initialize (  
    struct starpu_conf * user_conf,  
    int * argc,  
    char *** argv )
```

Similar to `starpu_init()`, but also take the `argc` and `argv` as defined by the application. Do not call `starpu_init()` and `starpu_initialize()` in the same program.

30.2.4.4 starpu_is_initialized()

```c
int starpu_is_initialized (    
    void )
```

Return 1 if StarPU is already initialized.

30.2.4.5 starpu_wait_initialized()

```c
void starpu_wait_initialized (    
    void )
```

Wait for `starpu_init()` call to finish.

30.2.4.6 starpu_shutdown()

```c
void starpu_shutdown (    
    void )
```

StarPU termination method, must be called at the end of the application: statistics and other post-mortem debugging information are not guaranteed to be available until this method has been called.

30.2.4.7 starpu_pause()

```c
void starpu_pause (    
    void )
```

Suspend the processing of new tasks by workers. It can be used in a program where StarPU is used during only a part of the execution. Without this call, the workers continue to poll for new tasks in a tight loop, wasting CPU time. The symmetric call to `starpu_resume()` should be used to unfreeze the workers.

30.2.4.8 starpu_resume()

```c
void starpu_resume (    
    void )
```

Symmetrical call to `starpu_pause()`, used to resume the workers polling for new tasks.
30.2.4.9 starpu_get_next_bindid()

```c
unsigned starpu_get_next_bindid (  
    unsigned flags,  
    unsigned * preferred,  
    unsigned npref  
)
```

Return a PU binding ID which can be used to bind threads with `starpu_bind_thread_on()`. `flags` can be set to `STARPU_THREAD_ACTIVE` or 0. When `npref` is set to non-zero, `preferred` is an array of size `npref` in which a preference of PU binding IDs can be set. By default StarPU will return the first PU available for binding.

30.2.4.10 starpu_bind_thread_on()

```c
int starpu_bind_thread_on (  
    int cpuid,  
    unsigned flags,  
    const char * name  
)
```

Bind the calling thread on the given `cpuid` (which should have been obtained with `starpu_get_next_bindid()`). Return -1 if a thread was already bound to this PU (but binding will still have been done, and a warning will have been printed), so the caller can tell the user how to avoid the issue.

`name` should be set to a unique string so that different calls with the same name for the same `cpuid` does not produce a warning.

30.2.4.11 starpu_topology_print()

```c
void starpu_topology_print (  
    FILE * f  
)
```

Print a description of the topology on `f`.

30.2.4.12 starpu_asynchronous_copy_disabled()

```c
int starpu_asynchronous_copy_disabled (  
    void  
)
```

Return 1 if asynchronous data transfers between CPU and accelerators are disabled.

30.2.4.13 starpu_asynchronous_cuda_copy_disabled()

```c
int starpu_asynchronous_cuda_copy_disabled (  
    void  
)
```

Return 1 if asynchronous data transfers between CPU and CUDA accelerators are disabled.

30.2.4.14 starpu_asynchronous_opencl_copy_disabled()

```c
int starpu_asynchronous_opencl_copy_disabled (  
    void  
)
```

Return 1 if asynchronous data transfers between CPU and OpenCL accelerators are disabled.

30.2.4.15 starpu_asynchronous_mic_copy_disabled()

```c
int starpu_asynchronous_mic_copy_disabled (  
    void  
)
```

Return 1 if asynchronous data transfers between CPU and MIC devices are disabled.

30.2.4.16 starpu_asynchronous_mpi_ms_copy_disabled()

```c
int starpu_asynchronous_mpi_ms_copy_disabled (  
    void  
)
```

Return 1 if asynchronous data transfers between CPU and MPI Slave devices are disabled.
30.3 Standard Memory Library

Macros

- `#define STARPU_MALLOC_PINNED`
- `#define STARPU_MALLOC_COUNT`
- `#define STARPU_MALLOC_NORECLAIM`
- `#define STARPU_MEMORY_WAIT`
- `#define STARPU_MEMORY_OVERFLOW`
- `#define STARPU_MALLOC_SIMULATION_FOLDED`
- `#define starpu_data_malloc_pinned_if_possible`
- `#define starpu_data_free_pinned_if_possible`

Typedefs

- `typedef int(* starpu_malloc_hook)(unsigned dst_node, void **A, size_t dim, int flags)`
- `typedef int(* starpu_free_hook)(unsigned dst_node, void *A, size_t dim, int flags)`

Functions

- `void starpu_malloc_set_align(size_t align)`
- `int starpu_malloc(void **A, size_t dim)`
- `int starpu_free(void *A)`
- `int starpu_malloc_flags(void **A, size_t dim, int flags)`
- `int starpu_free_flags(void *A, size_t dim, int flags)`
- `void starpu_malloc_set_hooks(starpu_malloc_hook malloc_hook, starpu_free_hook free_hook)`
- `int starpu_memory_pin(void *addr, size_t size)`
- `int starpu_memory_unpin(void *addr, size_t size)`
- `starpu_ssize_t starpu_memory_get_total(unsigned node)`
- `starpu_ssize_t starpu_memory_get_available(unsigned node)`
- `starpu_ssize_t starpu_memory_get_total_all_nodes(void)`
- `starpu_ssize_t starpu_memory_get_available_all_nodes(void)`
- `int starpu_memory_allocate(unsigned node, size_t size, int flags)`
- `void starpu_memory_deallocate(unsigned node, size_t size)`
- `void starpu_memory_wait_available(unsigned node, size_t size)`
- `void starpu_usleep(float nb_micro_sec)`

30.3.1 Detailed Description

30.3.2 Macro Definition Documentation

30.3.2.1 STARPU_MALLOC_PINNED

`#define STARPU_MALLOC_PINNED`

Value passed to the function `starpu_malloc_flags()` to indicate the memory allocation should be pinned.

30.3.2.2 STARPU_MALLOC_COUNT

`#define STARPU_MALLOC_COUNT`

Value passed to the function `starpu_malloc_flags()` to indicate the memory allocation should be in the limit defined by the environment variables `STARPU_LIMIT_CUDA_devid_MEM`, `STARPU_LIMIT_CUDA_MEM`, `STARPU_LIMIT_OPENCL_devid_MEM`, `STARPU_LIMIT_OPENCL_MEM` and `STARPU_LIMIT_CPU_MEM` (see Section How to Limit Memory Used By StarPU And Cache Buffer Allocations). If no memory is available, it tries to reclaim memory from StarPU. Memory allocated this way needs to be freed by calling the function `starpu_free_flags()` with the same flag.
### 30.3.2.3 STARPU_MALLOC_NORECLAIM

```c
#define STARPU_MALLOC_NORECLAIM
```

Value passed to the function `starpu_malloc_flags()` along `STARPU_MALLOC_COUNT` to indicate that while the memory allocation should be kept in the limits defined for `STARPU_MALLOC_COUNT`, no reclaiming should be performed by `starpu_malloc_flags()` itself, thus potentially overflowing the memory node a bit. StarPU will reclaim memory after next task termination, according to the `STARPU_MINIMUM_AVAILABLE_MEM`, `STARPU_TARGET_AVAILABLE_MEM`, `STARPU_MINIMUM_CLEAN_BUFFERS`, and `STARPU_TARGET_CLEAN_BUFFERS` environment variables. If `STARPU_MEMORY_WAIT` is set, no overflowing will happen, `starpu_malloc_flags()` will wait for other eviction mechanisms to release enough memory.

### 30.3.2.4 STARPU_MEMORY_WAIT

```c
#define STARPU_MEMORY_WAIT
```

Value passed to `starpu_memory_allocate()` to specify that the function should wait for the requested amount of memory to become available, and atomically allocate it.

### 30.3.2.5 STARPU_MEMORY_OVERFLOW

```c
#define STARPU_MEMORY_OVERFLOW
```

Value passed to `starpu_memory_allocate()` to specify that the function should allocate the amount of memory, even if that means overflowing the total size of the memory node.

### 30.3.2.6 STARPU_MALLOC_SIMULATION_FOLDED

```c
#define STARPU_MALLOC_SIMULATION_FOLDED
```

Value passed to the function `starpu_malloc_flags()` to indicate that when StarPU is using simgrid, the allocation can be "folded", i.e. a memory area is allocated, but its content is actually a replicate of the same memory area, to avoid having to actually allocate that much memory. This thus allows to have a memory area that does not actually consumes memory, to which one can read from and write to normally, but get bogus values.

### 30.3.2.7 starpu_data_malloc_pinned_if_possible

```c
#define starpu_data_malloc_pinned_if_possible
```

**Deprecated** Equivalent to `starpu_malloc()`. This macro is provided to avoid breaking old codes.

### 30.3.2.8 starpu_data_free_pinned_if_possible

```c
#define starpu_data_free_pinned_if_possible
```

**Deprecated** Equivalent to `starpu_free()`. This macro is provided to avoid breaking old codes.

### 30.3.3 Function Documentation

#### 30.3.3.1 starpu_malloc_set_align()

```c
void starpu_malloc_set_align ( size_t align )
```

Set an alignment constraints for `starpu_malloc()` allocations. `align` must be a power of two. This is for instance called automatically by the OpenCL driver to specify its own alignment constraints.
30.3.3.2 starpu_malloc()

```c
int starpu_malloc ( void ** A, size_t dim )
```

Allocate data of the given size `dim` in main memory, and return the pointer to the allocated data through `A`. It will also try to pin it in CUDA or OpenCL, so that data transfers from this buffer can be asynchronous, and thus permit data transfer and computation overlapping. The allocated buffer must be freed thanks to the `starpu_free()` function.

30.3.3.3 starpu_free()

```c
int starpu_free ( void * A )
```

Free memory which has previously been allocated with `starpu_malloc()`.

30.3.3.4 starpu_malloc_flags()

```c
int starpu_malloc_flags ( void ** A, size_t dim, int flags )
```

Perform a memory allocation based on the constraints defined by the given flag.

30.3.3.5 starpu_free_flags()

```c
int starpu_free_flags ( void * A, size_t dim, int flags )
```

Free memory by specifying its size. The given flags should be consistent with the ones given to `starpu_malloc_flags()` when allocating the memory.

30.3.3.6 starpu_malloc_set_hooks()

```c
void starpu_malloc_set_hooks ( starpu_malloc_hook malloc_hook, starpu_free_hook free_hook )
```

Set allocation functions to be used by StarPU. By default, StarPU will use `malloc()` (or `cudaHostAlloc()` if CUDA GPUs are used) for all its data handle allocations. The application can specify another allocation primitive by calling this. The `malloc_hook` should pass the allocated pointer through the `A` parameter, and return 0 on success. On allocation failure, it should return -ENOMEM. The `flags` parameter contains STARPU_MALLOC_PINNED if the memory should be pinned by the hook for GPU transfer efficiency. The hook can use `starpu_memory_pin()` to achieve this. The `dst_node` parameter is the starpu memory node, one can convert it to an hwloc logical id with `starpu_memory_nodes_numa_id_to_hwloclogid()` or to an OS NUMA number with `starpu_memory_nodes_devid_to_id()`.

30.3.3.7 starpu_memory_pin()

```c
int starpu_memory_pin ( void * addr, size_t size )
```

Pin the given memory area, so that CPU-GPU transfers can be done asynchronously with DMAs. The memory must be unpinned with `starpu_memory_unpin()` before being freed. Return 0 on success, -1 on error.

30.3.3.8 starpu_memory_unpin()

```c
int starpu_memory_unpin ( void * addr, size_t size )
```
Unpin the given memory area previously pinned with `starpu_memory_pin()`. Return 0 on success, -1 on error.

### 30.3.3.9 starpu_memory_get_total()

```c
starpu_ssize_t starpu_memory_get_total (
    unsigned node
)
```

If a memory limit is defined on the given node (see Section How to Limit Memory Used By StarPU And Cache Buffer Allocations), return the amount of total memory on the node. Otherwise return -1.

### 30.3.3.10 starpu_memory_get_available()

```c
starpu_ssize_t starpu_memory_get_available ( 
    unsigned node
)
```

If a memory limit is defined on the given node (see Section How to Limit Memory Used By StarPU And Cache Buffer Allocations), return the amount of available memory on the node. Otherwise return -1.

### 30.3.3.11 starpu_memory_get_total_all_nodes()

```c
starpu_ssize_t starpu_memory_get_total_all_nodes ( 
    void
)
```

Return the amount of total memory on all memory nodes for whose a memory limit is defined (see Section How to Limit Memory Used By StarPU And Cache Buffer Allocations).

### 30.3.3.12 starpu_memory_get_available_all_nodes()

```c
starpu_ssize_t starpu_memory_get_available_all_nodes ( 
    void
)
```

Return the amount of available memory on all memory nodes for whose a memory limit is defined (see Section How to Limit Memory Used By StarPU And Cache Buffer Allocations).

### 30.3.3.13 starpu_memory_allocate()

```c
int starpu_memory_allocate ( 
    unsigned node, 
    size_t size, 
    int flags
)
```

If a memory limit is defined on the given node (see Section How to Limit Memory Used By StarPU And Cache Buffer Allocations), try to allocate some of it. This does not actually allocate memory, but only accounts for it. This can be useful when the application allocates data another way, but want StarPU to be aware of the allocation size e.g. for memory reclaiming. By default, return -ENOMEM if there is not enough room on the given node. flags can be either STARPU_MEMORY_WAIT or STARPU_MEMORY_OVERFLOW to change this.

### 30.3.3.14 starpu_memory_deallocate()

```c
void starpu_memory_deallocate ( 
    unsigned node, 
    size_t size
)
```

If a memory limit is defined on the given node (see Section How to Limit Memory Used By StarPU And Cache Buffer Allocations), free some of it. This does not actually free memory, but only accounts for it, like `starpu_memory_allocate()`. The amount does not have to be exactly the same as what was passed to `starpu_memory_allocate()`, only the eventual amount needs to be the same, i.e. one call to `starpu_memoryAllocate()` can be followed by several calls to `starpu_memory_deallocate()` to declare the deallocation piece by piece.

### 30.3.3.15 starpu_memory_wait_available()

```c
void starpu_memory_wait_available ( 
    unsigned node, 
    size_t size
)
If a memory limit is defined on the given node (see Section How to Limit Memory Used By StarPU And Cache Buffer Allocations), this will wait for size bytes to become available on node. Of course, since another thread may be allocating memory concurrently, this does not necessarily mean that this amount will be actually available, just that it was reached. To atomically wait for some amount of memory and reserve it, starpu_memoryAllocate() should be used with the STARPU_MEMORY_WAIT flag.

### 30.4 Toolbox

The following macros allow to make GCC extensions portable, and to have a code which can be compiled with any C compiler.

#### Macros

- `#define STARPU_GNUC_PREREQ(maj, min)`
- `#define STARPU_UNLIKELY(expr)`
- `#define STARPU_LIKELY(expr)`
- `#define STARPU_ATTRIBUTE_UNUSED`
- `#define STARPU_ATTRIBUTE_NORETURN`
- `#define STARPU_ATTRIBUTE_INTERNAL`
- `#define STARPU_ATTRIBUTE_MALLOC`
- `#define STARPU_ATTRIBUTE_WARN_UNUSED_RESULT`
- `#define STARPU_ATTRIBUTEPURE`
- `#define STARPU_ATTRIBUTE_ALIGNED(size)`
- `#define STARPU_ATTRIBUTE_FORMAT(type, string, first)`
- `#define STARPU_INLINE`  
- `#define STARPU_ATTRIBUTE_MALLOC_SIZE(num, size)`
- `#define STARPU_ATTRIBUTE_ALLOC_SIZE(size)`
- `#define STARPU_WARN_UNUSED_RESULT`  
- `#define STARPU_BACKTRACE_LENGTH`  
- `#define STARPU_DUMP_BACKTRACE()`  
- `#define STARPU_SIMGRID_ASSERT(x)`  
- `#define STARPU_ASSERT(x)`  
- `#define STARPU_ASSERT_ACCESSIBLE(ptr)`  
- `#define STARPU_ASSERT_MSG(x, msg, ...)`  
- `#define _starpu_abort()`  
- `#define STARPU_ABORT()`  
- `#define STARPU_ABORT_MSG(msg, ...)`  
- `#define STARPU_CHECK_RETURN_VALUE(err, message, ...)`  
- `#define STARPU_CHECK_RETURN_VALUE_IS(err, value, message, ...)`  
- `#define STARPU_ATOMIC_SOMETHING(name, expr)`  
- `#define STARPU_ATOMIC_SOMETHINGL(name, expr)`  
- `#define STARPU_RMB()`  
- `#define STARPU_WMB()`

#### 30.4.1 Detailed Description

The following macros allow to make GCC extensions portable, and to have a code which can be compiled with any C compiler.

#### 30.4.2 Macro Definition Documentation
30.4.2.1 STARPU_GNUC_PREREQ
#define STARPU_GNUC_PREREQ( 
  maj, 
  min )
Return true (non-zero) if GCC version maj.min or later is being used (macro taken from glibc.)

30.4.2.2 STARPU_UNLIKELY
#define STARPU_UNLIKELY( 
  expr )
When building with a GNU C Compiler, allow programmers to mark an expression as unlikely.

30.4.2.3 STARPU_LIKELY
#define STARPU_LIKELY( 
  expr )
When building with a GNU C Compiler, allow programmers to mark an expression as likely.

30.4.2.4 STARPU_ATTRIBUTE_UNUSED
#define STARPU_ATTRIBUTE_UNUSED
When building with a GNU C Compiler, defined to __attribute__((unused))

30.4.2.5 STARPU_ATTRIBUTE_NORETURN
#define STARPU_ATTRIBUTE_NORETURN
When building with a GNU C Compiler, defined to __attribute__((noreturn))

30.4.2.6 STARPU_ATTRIBUTE_INTERNAL
#define STARPU_ATTRIBUTE_INTERNAL
When building with a GNU C Compiler, defined to __attribute__((visibility("internal")))

30.4.2.7 STARPU_ATTRIBUTE_MALLOC
#define STARPU_ATTRIBUTE_MALLOC
When building with a GNU C Compiler, defined to __attribute__((malloc))

30.4.2.8 STARPU_ATTRIBUTE_WARN_UNUSED_RESULT
#define STARPU_ATTRIBUTE_WARN_UNUSED_RESULT
When building with a GNU C Compiler, defined to __attribute__((warn_unused_result))

30.4.2.9 STARPU_ATTRIBUTE_PURE
#define STARPU_ATTRIBUTE_PURE
When building with a GNU C Compiler, defined to __attribute__((pure))

30.4.2.10 STARPU_ATTRIBUTEAligned
#define STARPU_ATTRIBUTEAligned( 
  size )
When building with a GNU C Compiler, defined to __attribute__((aligned(size)))

30.4.2.11 STARPU_ASSERT
#define STARPU_ASSERT( 
  x )
Unless StarPU has been configured with the option --enable-fast, this macro will abort if the expression x is false.
30.4.2.12 STARPU_ASSERT_MSG

#define STARPU_ASSERT_MSG(
  x,
  msg,
  ...
)

Unless StarPU has been configured with the option --enable-fast, this macro will abort if the expression \( x \) is false. The string \( msg \) will be displayed.

30.4.2.13 STARPU_ABORT

#define STARPU_ABORT( )

Abort the program.

30.4.2.14 STARPU_ABORT_MSG

#define STARPU_ABORT_MSG(
  msg,
  ...
)

Print the string '[starpu][abort][name of the calling function:name of the file:line in the file]' followed by the given string \( msg \) and abort the program.

30.4.2.15 STARPU_CHECK_RETURN_VALUE

#define STARPU_CHECK_RETURN_VALUE(
  err,
  message,
  ...
)

Abort the program (after displaying \( message \)) if \( err \) has a value which is not 0.

30.4.2.16 STARPU_CHECK_RETURN_VALUE_IS

#define STARPU_CHECK_RETURN_VALUE_IS(
  err,
  value,
  message,
  ...
)

Abort the program (after displaying \( message \)) if \( err \) is different from \( value \).

30.4.2.17 STARPU_RMB

#define STARPU_RMB( )

This macro can be used to do a synchronization.

30.4.2.18 STARPU_WMB

#define STARPU_WMB( )

This macro can be used to do a synchronization.

30.5 Threads

This section describes the thread facilities provided by StarPU. The thread function are either implemented on top of the pthread library or the Simgrid library when the simulated performance mode is enabled (SimGrid Support).

Macros

- #define STARPU_PTHREAD_CREATE_ON(name, thread, attr, routine, arg, where)
- #define STARPU_PTHREAD_CREATE(thread, attr, routine, arg)
- #define STARPU_PTHREAD_MUTEX_INIT(mutex, attr)
#define STARPU_PTHREAD_MUTEX_DESTROY(mutex)
#define STARPU_PTHREAD_MUTEX_LOCK(mutex)
#define STARPU_PTHREAD_MUTEX_UNLOCK(mutex)
#define STARPU_PTHREAD_KEY_CREATE(key, destr)
#define STARPU_PTHREAD_KEY_DELETE(key)
#define STARPU_PTHREAD_SETSPECIFIC(key, ptr)
#define STARPU_PTHREAD_GETSPECIFIC(key)
#define STARPU_PTHREAD_RWLOCK_INIT(rwlock, attr)
#define STARPU_PTHREAD_RWLOCK_RDCALL(rwlock)
#define STARPU_PTHREAD_RWLOCK_WRDCALL(rwlock)
#define STARPU_PTHREAD_RWLOCK_UNLOCK(rwlock)
#define STARPU_PTHREAD_RWLOCK_DESTROY(rwlock)
#define STARPU_PTHREAD_COND_INIT(cond, attr)
#define STARPU_PTHREAD_COND_DESTROY(cond)
#define STARPU_PTHREAD_COND_SIGNAL(cond)
#define STARPU_PTHREAD_COND_BROADCAST(cond)
#define STARPU_PTHREAD_COND_WAIT(cond, mutex)
#define STARPU_PTHREAD_BARRIER_INIT(barrier, attr, count)
#define STARPU_PTHREAD_BARRIER_DESTROY(barrier)
#define STARPU_PTHREAD_BARRIER_WAIT(barrier)
#define STARPU_PTHREAD_MUTEX_INITIALIZER
#define STARPU_PTHREAD_COND_INITIALIZER

Functions

- int starpu_pthread_create (starpu_pthread_t *thread, const starpu_pthread_attr_t *attr, void *(*start_routine)(void *), void *arg)
- int starpu_pthread_join (starpu_pthread_t thread, void **retval)
- int starpu_pthread_exit (void *retval) STARPU_ATTRIBUTE_NORETURN
- int starpu_pthread_attr_init (starpu_pthread_attr_t *attr)
- int starpu_pthread_attr_destroy (starpu_pthread_attr_t *attr)
- int starpu_pthread_attr_setdetachstate (starpu_pthread_attr_t *attr, int detachstate)
- int starpu_pthread_mutex_init (starpu_pthread_mutex_t *mutex, const starpu_pthread_mutexattr_t *mutexattr)
- int starpu_pthread_mutex_destroy (starpu_pthread_mutex_t *mutex)
- int starpu_pthread_mutex_lock (starpu_pthread_mutex_t *mutex)
- int starpu_pthread_mutex_unlock (starpu_pthread_mutex_t *mutex)
- int starpu_pthread_mutex_trylock (starpu_pthread_mutex_t *mutex)
- int starpu_pthread_mutexattr_gettype (const starpu_pthread_mutexattr_t *attr, int *type)
- int starpu_pthread_mutexattr_settype (starpu_pthread_mutexattr_t *attr, int type)
- int starpu_pthread_mutexattr_destroy (starpu_pthread_mutexattr_t *attr)
- int starpu_pthread_mutexattr_init (starpu_pthread_mutexattr_t *attr)
- int starpu_pthread_key_create (starpu_pthread_key_t *key, void (**destr_function)(void *))
- int starpu_pthread_key_delete (starpu_pthread_key_t *key)
- int starpu_pthread_setspecific (starpu_pthread_key_t *key, const void *pointer)
- void *starpu_pthread_getspecific (starpu_pthread_key_t *key)
- int starpu_pthread_cond_init (starpu_pthread_cond_t *cond, starpu_pthread_condattr_t *condattr)
- int starpu_pthread_cond_signal (starpu_pthread_cond_t *cond)
- int starpu_pthread_cond_broadcast (starpu_pthread_cond_t *cond)
- int starpu_pthread_cond_wait (starpu_pthread_cond_t *cond, starpu_pthread_mutex_t *mutex)
- int starpu_pthread_cond_timedwait (starpu_pthread_cond_t *cond, starpu_pthread_mutex_t *mutex, const struct timespec *abstime)
- int starpu_pthread_cond_destroy (starpu_pthread_cond_t *cond)
- int starpu_pthread_rwlock_init (starpu_pthread_rwlock_t *rwlock, const starpu_pthread_rwlockattr_t *attr)
- int starpu_pthread_rwlock_destroy (starpu_pthread_rwlock_t *rwlock)
30.5 Threads

- int starpu_pthread_rwlock_rdlock (starpu_pthread_rwlock_t *rwlock)
- int starpu_pthread_rwlock_tryrdlock (starpu_pthread_rwlock_t *rwlock)
- int starpu_pthread_rwlock_wrlock (starpu_pthread_rwlock_t *rwlock)
- int starpu_pthread_rwlock_trywrlock (starpu_pthread_rwlock_t *rwlock)
- int starpu_pthread_rwlock_unlock (starpu_pthread_rwlock_t *rwlock)
- int starpu_pthread_barrier_init (starpu_pthread_barrier_t *barrier, const starpu_pthread_barrierattr_t *attr, unsigned count)
- int starpu_pthread_barrier_destroy (starpu_pthread_barrier_t *barrier)
- int starpu_pthread_barrier_wait (starpu_pthread_barrier_t *barrier)
- int starpu_pthread_spin_init (starpu_pthread_spinlock_t *lock, int pshared)
- int starpu_pthread_spin_destroy (starpu_pthread_spinlock_t *lock)
- int starpu_pthread_spin_lock (starpu_pthread_spinlock_t *lock)
- int starpu_pthread_spin_trylock (starpu_pthread_spinlock_t *lock)
- int starpu_pthread_spin_unlock (starpu_pthread_spinlock_t *lock)
- void starpu_sleep (float nb_sec)

### 30.5.1 Detailed Description

This section describes the thread facilities provided by StarPU. The thread function are either implemented on top of the pthread library or the Simgrid library when the simulated performance mode is enabled (SimGrid Support).

### 30.5.2 Macro Definition Documentation

#### 30.5.2.1 STARPU_PTHREAD_CREATE_ON

```c
#define STARPU_PTHREAD_CREATE_ON(
    name,
    thread,
    attr,
    routine,
    arg,
    where )
```

Call starpu_pthread_create_on() and abort on error.

#### 30.5.2.2 STARPU_PTHREAD_CREATE

```c
#define STARPU_PTHREAD_CREATE(
    thread,
    attr,
    routine,
    arg )
```

Call starpu_pthread_create() and abort on error.

#### 30.5.2.3 STARPU_PTHREAD_MUTEX_INIT

```c
#define STARPU_PTHREAD_MUTEX_INIT(
    mutex,
    attr )
```

Call starpu_pthread_mutex_init() and abort on error.

#### 30.5.2.4 STARPU_PTHREAD_MUTEX_DESTROY

```c
#define STARPU_PTHREAD_MUTEX_DESTROY(
    mutex )
```

Call starpu_pthread_mutex_destroy() and abort on error.
30.5.2.5 STARPU_PTHREAD_MUTEX_LOCK

#define STARPU_PTHREAD_MUTEX_LOCK(mutex)
Call starpu_pthread_mutex_lock() and abort on error.

30.5.2.6 STARPU_PTHREAD_MUTEX_UNLOCK

#define STARPU_PTHREAD_MUTEX_UNLOCK(mutex)
Call starpu_pthread_mutex_unlock() and abort on error.

30.5.2.7 STARPU_PTHREAD_KEY_CREATE

#define STARPU_PTHREAD_KEY_CREATE(key, destr)
Call starpu_pthread_key_create() and abort on error.

30.5.2.8 STARPU_PTHREAD_KEY_DELETE

#define STARPU_PTHREAD_KEY_DELETE(key)
Call starpu_pthread_key_delete() and abort on error.

30.5.2.9 STARPU_PTHREAD_SETSPECIFIC

#define STARPU_PTHREAD_SETSPECIFIC(key, ptr)
Call starpu_pthread_setspecific() and abort on error.

30.5.2.10 STARPU_PTHREAD_GETSPECIFIC

#define STARPU_PTHREAD_GETSPECIFIC(key)
Call starpu_pthread_getspecific() and abort on error.

30.5.2.11 STARPU_PTHREAD_RWLOCK_INIT

#define STARPU_PTHREAD_RWLOCK_INIT(rwlock, attr)
Call starpu_pthread_rwlock_init() and abort on error.

30.5.2.12 STARPU_PTHREAD_RWLOCK_RDLOCK

#define STARPU_PTHREAD_RWLOCK_RDLOCK(rwlock)
Call starpu_pthread_rwlock_rdlock() and abort on error.

30.5.2.13 STARPU_PTHREAD_RWLOCK_WRLOCK

#define STARPU_PTHREAD_RWLOCK_WRLOCK(rwlock)
Call starpu_pthread_rwlock_wrlock() and abort on error.
30.5.2.14 STARPU_PTHREAD_RWLOCK_UNLOCK

#define STARPU_PTHREAD_RWLOCK_UNLOCK(rwlock)
Call starpu_pthread_rwlock_unlock() and abort on error.

30.5.2.15 STARPU_PTHREAD_RWLOCK_DESTROY

#define STARPU_PTHREAD_RWLOCK_DESTROY(rwlock)
Call starpu_pthread_rwlock_destroy() and abort on error.

30.5.2.16 STARPU_PTHREAD_COND_INIT

#define STARPU_PTHREAD_COND_INIT(cond, attr)
Call starpu_pthread_cond_init() and abort on error.

30.5.2.17 STARPU_PTHREAD_COND_DESTROY

#define STARPU_PTHREAD_COND_DESTROY(cond)
Call starpu_pthread_cond_destroy() and abort on error.

30.5.2.18 STARPU_PTHREAD_COND_SIGNAL

#define STARPU_PTHREAD_COND_SIGNAL(cond)
Call starpu_pthread_cond_signal() and abort on error.

30.5.2.19 STARPU_PTHREAD_COND_BROADCAST

#define STARPU_PTHREAD_COND_BROADCAST(cond)
Call starpu_pthread_cond_broadcast() and abort on error.

30.5.2.20 STARPU_PTHREAD_COND_WAIT

#define STARPU_PTHREAD_COND_WAIT(cond, mutex)
Call starpu_pthread_cond_wait() and abort on error.

30.5.2.21 STARPU_PTHREAD_BARRIER_INIT

#define STARPU_PTHREAD_BARRIER_INIT(barrier, attr, count)
Call starpu_pthread_barrier_init() and abort on error.

30.5.2.22 STARPU_PTHREAD_BARRIER_DESTROY

#define STARPU_PTHREAD_BARRIER_DESTROY(barrier)
Call starpu_pthread_barrier_destroy() and abort on error.
30.5.2.23 STARPU_PTHREAD_BARRIER_WAIT

#define STARPU_PTHREAD_BARRIER_WAIT(barrier)
Call starpu_pthread_barrier_wait() and abort on error.

30.5.2.24 STARPU_PTHREAD_MUTEX_INITIALIZER

STARPU_PTHREAD_MUTEX_INITIALIZER
Initialize the mutex given in parameter.

30.5.2.25 STARPU_PTHREAD_COND_INITIALIZER

STARPU_PTHREAD_COND_INITIALIZER
Initialize the condition variable given in parameter.

30.5.3 Function Documentation

30.5.3.1 starpu_pthread_create()

int starpu_pthread_create (  
    starpu_pthread_t * thread,  
    const starpu_pthread_attr_t * attr,  
    void *(*)(void *) start_routine,  
    void * arg )
Start a new thread in the calling process. The new thread starts execution by invoking start_routine; arg is passed as the sole argument of start_routine.

30.5.3.2 starpu_pthread_join()

int starpu_pthread_join (  
    starpu_pthread_t thread,  
    void ** retval )
Wait for the thread specified by thread to terminate. If that thread has already terminated, then the function returns immediately. The thread specified by thread must be joinable.

30.5.3.3 starpu_pthread_exit()

int starpu_pthread_exit (  
    void * retval )
Terminate the calling thread and return a value via retval that (if the thread is joinable) is available to another thread in the same process that calls starpu_pthread_join().

30.5.3.4 starpu_pthread_attr_init()

int starpu_pthread_attr_init (  
    starpu_pthread_attr_t * attr )
Initialize the thread attributes object pointed to by attr with default attribute values. Do not do anything when the simulated performance mode is enabled (SimGrid Support).

30.5.3.5 starpu_pthread_attr_destroy()

int starpu_pthread_attr_destroy (  
    starpu_pthread_attr_t * attr )
Destroy a thread attributes object which is no longer required. Destroying a thread attributes object has no effect on threads that were created using that object. Do not do anything when the simulated performance mode is enabled (SimGrid Support).
30.5.3.6 starpu_pthread_attr_setdetachstate()

int starpu_pthread_attr_setdetachstate (  
    starpu_pthread_attr_t * attr,  
    int detachstate )

Set the detach state attribute of the thread attributes object referred to by attr to the value specified in detachstate. The detach state attribute determines whether a thread created using the thread attributes object attr will be created in a joinable or a detached state.

Do not do anything when the simulated performance mode is enabled (SimGrid Support).

30.5.3.7 starpu_pthread_mutex_init()

int starpu_pthread_mutex_init (  
    starpu_pthread_mutex_t * mutex,  
    const starpu_pthread_mutexattr_t * mutexattr )

Initialize the mutex object pointed to by mutex according to the mutex attributes specified in mutexattr. If mutexattr is NULL, default attributes are used instead.

30.5.3.8 starpu_pthread_mutex_destroy()

int starpu_pthread_mutex_destroy (  
    starpu_pthread_mutex_t * mutex )

Destroy a mutex object, and free the resources it might hold. The mutex must be unlocked on entrance.

30.5.3.9 starpu_pthread_mutex_lock()

int starpu_pthread_mutex_lock (  
    starpu_pthread_mutex_t * mutex )

Lock the given mutex. If mutex is currently unlocked, it becomes locked and owned by the calling thread, and the function returns immediately. If mutex is already locked by another thread, the function suspends the calling thread until mutex is unlocked.

This function also produces trace when the configure option --enable-fxt-lock is enabled.

30.5.3.10 starpu_pthread_mutex_unlock()

int starpu_pthread_mutex_unlock (  
    starpu_pthread_mutex_t * mutex )

Unlock the given mutex. The mutex is assumed to be locked and owned by the calling thread on entrance to starpu_pthread_mutex_unlock().

This function also produces trace when the configure option --enable-fxt-lock is enabled.

30.5.3.11 starpu_pthread_mutex_trylock()

int starpu_pthread_mutex_trylock (  
    starpu_pthread_mutex_t * mutex )

Behave identically to starpu_pthread_mutex_lock(), except that it does not block the calling thread if the mutex is already locked by another thread (or by the calling thread in the case of a “fast” mutex). Instead, the function returns immediately with the error code EBUSY.

This function also produces trace when the configure option --enable-fxt-lock is enabled.

30.5.3.12 starpu_pthread_mutexattr_gettype()

int starpu_pthread_mutexattr_gettype (  
    const starpu_pthread_mutexattr_t * attr,  
    int * type )

todo
30.5.3.13  starpu_pthread_mutexattr_settype()

int starpu_pthread_mutexattr_settype (  
    starpu_pthread_mutexattr_t * attr,  
    int type )

todo

30.5.3.14  starpu_pthread_mutexattr_destroy()

int starpu_pthread_mutexattr_destroy (  
    starpu_pthread_mutexattr_t * attr )

todo

30.5.3.15  starpu_pthread_mutexattr_init()

int starpu_pthread_mutexattr_init (  
    starpu_pthread_mutexattr_t * attr )

todo

30.5.3.16  starpu_pthread_key_create()

int starpu_pthread_key_create (  
    starpu_pthread_key_t * key,  
    void(*)(void *) destr_function )

Allocate a new TSD key. The key is stored in the location pointed to by key.

30.5.3.17  starpu_pthread_key_delete()

int starpu_pthread_key_delete (  
    starpu_pthread_key_t key )

Deallocate a TSD key. Do not check whether non-NULL values are associated with that key in the currently executing threads, nor call the destructor function associated with the key.

30.5.3.18  starpu_pthread_setspecific()

int starpu_pthread_setspecific (  
    starpu_pthread_key_t key,  
    const void * pointer )

Change the value associated with key in the calling thread, storing the given pointer instead.

30.5.3.19  starpu_pthread_getspecific()

void * starpu_pthread_getspecific (  
    starpu_pthread_key_t key )

Return the value associated with key on success, and NULL on error.

30.5.3.20  starpu_pthread_cond_init()

int starpu_pthread_cond_init (  
    starpu_pthread_cond_t * cond,  
    starpu_pthread_condattr_t * cond_attr )

Initialize the condition variable cond, using the condition attributes specified in cond_attr, or default attributes if cond_attr is NULL.

30.5.3.21  starpu_pthread_cond_signal()

int starpu_pthread_cond_signal (  
    starpu_pthread_cond_t * cond )

Restart one of the threads that are waiting on the condition variable cond. If no threads are waiting on cond, nothing happens. If several threads are waiting on cond, exactly one is restarted, but it is not specified which.
30.5.3.22 `starpu_pthread_cond_broadcast()`

```c
int starpu_pthread_cond_broadcast (const starpu_pthread_cond_t * cond )
```

Restart all the threads that are waiting on the condition variable `cond`. Nothing happens if no threads are waiting on `cond`.

30.5.3.23 `starpu_pthread_cond_wait()`

```c
int starpu_pthread_cond_wait (const starpu_pthread_cond_t * cond,
const starpu_pthread_mutex_t * mutex )
```

Atomically unlock `mutex` (as per `starpu_pthread_mutex_unlock()`) and wait for the condition variable `cond` to be signaled. The thread execution is suspended and does not consume any CPU time until the condition variable is signaled. The mutex must be locked by the calling thread on entrance to `starpu_pthread_cond_wait()`. Before returning to the calling thread, the function re-acquires mutex (as per `starpu_pthread_mutex_lock()`). This function also produces trace when the configure option `--enable-fxt-lock` is enabled.

30.5.3.24 `starpu_pthread_cond_timedwait()`

```c
int starpu_pthread_cond_timedwait (const starpu_pthread_cond_t * cond,
const starpu_pthread_mutex_t * mutex,
const struct timespec * abstime )
```

Atomically unlocks `mutex` and wait on `cond`, as `starpu_pthread_cond_wait()` does, but also bound the duration of the wait with `abstime`.

30.5.3.25 `starpu_pthread_cond_destroy()`

```c
int starpu_pthread_cond_destroy (const starpu_pthread_cond_t * cond )
```

Destroy a condition variable, freeing the resources it might hold. No threads must be waiting on the condition variable on entrance to the function.

30.5.3.26 `starpu_pthread_rwlock_init()`

```c
int starpu_pthread_rwlock_init (const starpu_pthread_rwlock_t * rwlock,
const starpu_pthread_rwlockattr_t * attr )
```

Similar to `starpu_pthread_mutex_init()`.

30.5.3.27 `starpu_pthread_rwlock_destroy()`

```c
int starpu_pthread_rwlock_destroy (const starpu_pthread_rwlock_t * rwlock )
```

Similar to `starpu_pthread_mutex_destroy()`.

30.5.3.28 `starpu_pthread_rwlock_rdlock()`

```c
int starpu_pthread_rwlock_rdlock (const starpu_pthread_rwlock_t * rwlock )
```

Similar to `starpu_pthread_mutex_lock()`.

30.5.3.29 `starpu_pthread_rwlock_tryrdlock()`

```c
int starpu_pthread_rwlock_tryrdlock (const starpu_pthread_rwlock_t * rwlock )
```

todo
30.5.30 starpu_pthread_rwlock_wrlock()

```c
int starpu_pthread_rwlock_wrlock (
    starpu_pthread_rwlock_t * rwlock )
```

Similar to `starpu_pthread_mutex_lock()`.

30.5.31 starpu_pthread_rwlock_trywrlock()

```c
int starpu_pthread_rwlock_trywrlock (
    starpu_pthread_rwlock_t * rwlock )
```

todo

30.5.32 starpu_pthread_rwlock_unlock()

```c
int starpu_pthread_rwlock_unlock ( 
    starpu_pthread_rwlock_t * rwlock )
```

Similar to `starpu_pthread_mutex_unlock()`.

30.5.33 starpu_pthread_barrier_init()

```c
int starpu_pthread_barrier_init ( 
    starpu_pthread_barrier_t * barrier,
    const starpu_pthread_barrierattr_t * attr,
    unsigned count)
```

todo

30.5.34 starpu_pthread_barrier_destroy()

```c
int starpu_pthread_barrier_destroy ( 
    starpu_pthread_barrier_t * barrier )
```

todo

30.5.35 starpu_pthread_barrier_wait()

```c
int starpu_pthread_barrier_wait ( 
    starpu_pthread_barrier_t * barrier )
```

todo

30.5.36 starpu_pthread_spin_init()

```c
int starpu_pthread_spin_init ( 
    starpu_pthread_spinlock_t * lock,
    int pshared )
```

todo

30.5.37 starpu_pthread_spin_destroy()

```c
int starpu_pthread_spin_destroy ( 
    starpu_pthread_spinlock_t * lock )
```

todo

30.5.38 starpu_pthread_spin_lock()

```c
int starpu_pthread_spin_lock ( 
    starpu_pthread_spinlock_t * lock )
```

todo
30.5.3.39 starpu_pthread_spin_trylock()

```c
int starpu_pthread_spin_trylock (  
    starpu_pthread_spinlock_t * lock )
```
todo

30.5.3.40 starpu_pthread_spin_unlock()

```c
int starpu_pthread_spin_unlock (  
    starpu_pthread_spinlock_t * lock )
```
todo

30.5.3.41 starpu_sleep()

```c
void starpu_sleep (  
    float nb_sec )
```
Similar to calling Unix' `sleep` function, except that it takes a float to allow sub-second sleeping, and when StarPU is compiled in simgrid mode it does not really sleep but just makes simgrid record that the thread has taken some time to sleep.

30.6 Bitmap

This is the interface for the bitmap utilities provided by StarPU.

Functions

- struct starpu_bitmap * starpu_bitmap_create (void) STARPU_ATTRIBUTE_MALLOC
- void starpu_bitmap_destroy (struct starpu_bitmap *b)
- void starpu_bitmap_set (struct starpu_bitmap *b, int e)
- void starpu_bitmap_unset (struct starpu_bitmap *b, int e)
- void starpu_bitmap_unset_all (struct starpu_bitmap *b)
- int starpu_bitmap_get (struct starpu_bitmap *b, int e)
- void starpu_bitmap_unset_and (struct starpu_bitmap *a, struct starpu_bitmap *b, struct starpu_bitmap *c)
- void starpu_bitmap_or (struct starpu_bitmap *a, struct starpu_bitmap *b)
- int starpu_bitmap_and_get (struct starpu_bitmap *b1, struct starpu_bitmap *b2, int e)
- int starpu_bitmap_cardinal (struct starpu_bitmap *b)
- int starpu_bitmap_first (struct starpu_bitmap *b)
- int starpu_bitmap_last (struct starpu_bitmap *b)
- int starpu_bitmap_next (struct starpu_bitmap *b, int e)
- int starpu_bitmap_has_next (struct starpu_bitmap *b, int e)

30.6.1 Detailed Description

This is the interface for the bitmap utilities provided by StarPU.

30.6.2 Function Documentation

30.6.2.1 starpu_bitmap_create()

```c
struct starpu_bitmap* starpu_bitmap_create (  
    void )
```
create a empty starpu_bitmap
30.6.2.2 starpu_bitmap_destroy()

```c
void starpu_bitmap_destroy ( 
    struct starpu_bitmap * b ) 
free b
```

30.6.2.3 starpu_bitmap_set()

```c
void starpu_bitmap_set ( 
    struct starpu_bitmap * b, 
    int e ) 
set bit e in b
```

30.6.2.4 starpu_bitmap_unset()

```c
void starpu_bitmap_unset ( 
    struct starpu_bitmap * b, 
    int e ) 
unset bit e in b
```

30.6.2.5 starpu_bitmap_unset_all()

```c
void starpu_bitmap_unset_all ( 
    struct starpu_bitmap * b ) 
unset all bits in b
```

30.6.2.6 starpu_bitmap_get()

```c
int starpu_bitmap_get ( 
    struct starpu_bitmap * b, 
    int e ) 
return true iff bit e is set in b
```

30.6.2.7 starpu_bitmap_unset_and()

```c
void starpu_bitmap_unset_and ( 
    struct starpu_bitmap * a, 
    struct starpu_bitmap * b, 
    struct starpu_bitmap * c ) 
Basically compute starpu_bitmap_unset_all(a); a = b & c;
```

30.6.2.8 starpu_bitmap_or()

```c
void starpu_bitmap_or ( 
    struct starpu_bitmap * a, 
    struct starpu_bitmap * b ) 
Basically compute a | b
```

30.6.2.9 starpu_bitmap_and_get()

```c
int starpu_bitmap_and_get ( 
    struct starpu_bitmap * b1, 
    struct starpu_bitmap * b2, 
    int e ) 
return 1 iff e is set in b1 AND e is set in b2
```

30.6.2.10 starpu_bitmap_cardinal()

```c
int starpu_bitmap_cardinal ( 
    struct starpu_bitmap * b )
```
return the number of set bits in b

30.6.2.11 starpu_bitmap_first()

int starpu_bitmap_first ( struct starpu_bitmap * b )
return the index of the first set bit of b, -1 if none

30.6.2.12 starpu_bitmap_last()

int starpu_bitmap_last ( struct starpu_bitmap * b )
return the position of the last set bit of b, -1 if none

30.6.2.13 starpu_bitmap_next()

int starpu_bitmap_next ( struct starpu_bitmap * b, int e )
return the position of set bit right after e in b, -1 if none

30.6.2.14 starpu_bitmap_has_next()

int starpu_bitmap_has_next ( struct starpu_bitmap * b, int e )
todo

30.7 Workers’ Properties

Data Structures

• struct starpu_sched_ctx_iterator
• struct starpu_worker_collection

Macros

• #define starpu_worker_get_id_check()
• #define STARPU_NMAXWORKERS
• #define STARPU_MAXCPUS
• #define STARPU_MAXNUMANODES
• #define STARPU_MAXNODES

Enumerations

• enum starpu_node_kind {
  STARPU_UNUSED, STARPU_CPU_RAM, STARPU_CUDA_RAM, STARPU_OPENCL_RAM,
  STARPU_DISK_RAM, STARPU_MIC_RAM, STARPU(MPI_MS_RAM)
• enum starpu_worker_archtype {
  STARPU_CPU_WORKER, STARPU_CUDA_WORKER, STARPU_OPENCL_WORKER, STARPU_MIC_WORKER,
  STARPU(MPI_MS_WORKER, STARPU_ANY_WORKER)
• enum starpu_worker_collection_type { STARPU_WORKER_TREE, STARPU_WORKER_LIST }
Functions

- `unsigned starpu_worker_get_count (void)`
- `unsigned starpu_cpu_worker_get_count (void)`
- `unsigned starpu_cuda_worker_get_count (void)`
- `unsigned starpu_opencl_worker_get_count (void)`
- `unsigned starpu_mic_worker_get_count (void)`
- `unsigned starpu_mpi_ms_worker_get_count (void)`
- `unsigned starpu_mic_device_get_count (void)`
- `int starpu_worker_get_id (void)`
- `unsigned _starpu_worker_get_id_check (const char *f, int l)`
- `int starpu_worker_get_bindid (int workerid)`
- `void starpu_sched_find_all_worker_combinations (void)`
- `enum starpu_worker_archtype starpu_worker_get_type (int id)`
- `int starpu_worker_get_count_by_type (enum starpu_worker_archtype type)`
- `unsigned starpu_worker_get_ids_by_type (enum starpu_worker_archtype type, int *workerids, unsigned maxsize)`
- `int starpu_worker_get_by_type (enum starpu_worker_archtype type, int num)`
- `int starpu_worker_get_devid (int id)`
- `int starpu_worker_get_mp_nodeid (int id)`
- `struct starpu_tree *starpu_workers_get_tree (void)`
- `unsigned starpu_worker_get_sched_ctx_list (int worker, unsigned **sched_ctx)`
- `unsigned starpu_worker_is_blocked_in_parallel (int workerid)`
- `unsigned starpu_worker_is_slave_somewhere (int workerid)`
- `char *starpu_worker_get_type_as_string (enum starpu_worker_archtype type)`
- `int starpu_bindid_get_workerids (int bindid, int **workerids)`
- `int starpu_worker_get_devids (enum starpu_worker_archtype type, int **devids, int num)`
- `int starpu_worker_get_stream_workerids (unsigned devid, int **workerids, enum starpu_worker_archtype type)`
- `unsigned starpu_worker_get_sched_ctx_id_stream (unsigned stream_workerid)`
- `hwloc_cpuset_t starpu_worker_get_hwloc_cpuset (int workerid)`
- `hwloc_obj_t starpu_worker_get_hwloc_obj (int workerid)`
- `int starpu_memory_node_get_devid (unsigned node)`
- `unsigned starpu_worker_get_local_memory_node (void)`
- `unsigned starpu_worker_get_memory_node (unsigned workerid)`
- `unsigned starpu_memory_nodes_get_count (void)`
- `int starpu_memory_node_get_name (unsigned node, char *name, size_t size)`
- `int starpu_memory_nodes_get_numa_count (void)`
- `int starpu_memory_nodes_numa_id_to_devid (int osid)`
- `int starpu_memory_nodes_numa_devid_to_id (unsigned id)`
- `enum starpu_node_kind starpu_node_get_kind (unsigned node)`

Variables

- `struct starpu_worker_collection worker_list`
- `struct starpu_worker_collection worker_tree`
30.7 Workers’ Properties

Scheduling operations

- int starpu_worker_sched_op_pending (void)
- void starpu_worker_relax_on (void)
- void starpu_worker_relax_off (void)
- int starpu_worker_get_relax_state (void)
- void starpu_worker_lock (int workerid)
- int starpu_worker_trylock (int workerid)
- void starpu_worker_unlock (int workerid)
- void starpu_worker_lock_self (void)
- void starpu_worker_unlock_self (void)
- void starpu_worker_set_going_to_sleep_callback (void(∗callback)(unsigned workerid))
- void starpu_worker_set_waking_up_callback (void(∗callback)(unsigned workerid))

30.7.1 Detailed Description

30.7.2 Data Structure Documentation

30.7.2.1 struct starpu_sched_ctx_iterator

Structure needed to iterate on the collection

Data Fields

<table>
<thead>
<tr>
<th>Data Type</th>
<th>Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>cursor</td>
<td>The index of the current worker in the collection, needed when iterating on the collection.</td>
</tr>
<tr>
<td>void ∗</td>
<td>value</td>
<td></td>
</tr>
<tr>
<td>void ∗</td>
<td>possible_value</td>
<td></td>
</tr>
<tr>
<td>char</td>
<td>visited[STARPU_NMAXWORKERS]</td>
<td></td>
</tr>
<tr>
<td>int</td>
<td>possibly_parallel</td>
<td></td>
</tr>
</tbody>
</table>

30.7.2.2 struct starpu_worker_collection

A scheduling context manages a collection of workers that can be memorized using different data structures. Thus, a generic structure is available in order to simplify the choice of its type. Only the list data structure is available but further data structures (like tree) implementations are foreseen.

Data Fields

- int ∗ workerids
- void ∗ collection_private
- unsigned nworkers
- void ∗ unblocked_workers
- unsigned nunblocked_workers
- void ∗ masters
- unsigned nmasters
- char present[STARPU_NMAXWORKERS]
- char is_unblocked[STARPU_NMAXWORKERS]
- char is_master[STARPU_NMAXWORKERS]
- enum starpu_worker_collection_type type
- unsigned(∗) has_next (struct starpu_worker_collection ∗workers, struct starpu_sched_ctx_iterator ∗it)
- int(∗) get_next (struct starpu_worker_collection ∗workers, struct starpu_sched_ctx_iterator ∗it)
- int(∗) add (struct starpu_worker_collection ∗workers, int worker)
- int(∗) remove (struct starpu_worker_collection ∗workers, int worker)
- void(∗) init (struct starpu_worker_collection ∗workers)
- void(∗) deinit (struct starpu_worker_collection ∗workers)
• void(* init_iterator )(struct starpu_worker_collection *workers, struct starpu_sched_ctx_iterator *it)
• void(* init_iterator_for_parallel_tasks )(struct starpu_worker_collection *workers, struct starpu_sched_ctx_iterator *it, struct starpu_task *task)

30.7.2.1 Field Documentation

30.7.2.2.1 workerids
int* starpu_worker_collection::workerids
The workerids managed by the collection

30.7.2.2.1.2 nworkers
unsigned starpu_worker_collection::nworkers
The number of workers in the collection

30.7.2.2.1.3 type
enum starpu_worker_collection_type starpu_worker_collection::type
The type of structure

30.7.2.2.1.4 has_next
unsigned(* starpu_worker_collection::has_next) (struct starpu_worker_collection *workers, struct starpu_sched_ctx_iterator *it)
Check if there is another element in collection

30.7.2.2.1.5 get_next
int(* starpu_worker_collection::get_next) (struct starpu_worker_collection *workers, struct starpu_sched_ctx_iterator *it)
Return the next element in the collection

30.7.2.2.1.6 add
int(* starpu_worker_collection::add) (struct starpu_worker_collection *workers, int worker)
Add a new element in the collection

30.7.2.2.1.7 remove
int(* starpu_worker_collection::remove) (struct starpu_worker_collection *workers, int worker)
Remove an element from the collection

30.7.2.2.1.8 init
void(* starpu_worker_collection::init) (struct starpu_worker_collection *workers)
Initialize the collection

30.7.2.2.1.9 deinit
void(* starpu_worker_collection::deinit) (struct starpu_worker_collection *workers)
Deinitialize the collection

30.7.2.2.1.10 init_iterator
void(* starpu_worker_collection::init_iterator) (struct starpu_worker_collection *workers, struct starpu_sched_ctx_iterator *it)
Initialize the cursor if there is one

30.7.3 Macro Definition Documentation

30.7.3.1 starpu_worker_get_id_check
unsigned starpu_worker_get_id_check{
    void
}
Similar to starpu_worker_get_id(), but abort when called from outside a worker (i.e. when starpu_worker_get_id() would return -1).
30.7 Workers’ Properties

30.7.3.2 STARPU_NMAXWORKERS
#define STARPU_NMAXWORKERS
Define the maximum number of workers managed by StarPU.

30.7.3.3 STARPU_MAXCPUS
#define STARPU_MAXCPUS
Define the maximum number of CPU workers managed by StarPU. The default value can be modified at configure by using the option --enable-maxcpus.

30.7.3.4 STARPU_MAXNUMANODES
#define STARPU_MAXNUMANODES
Define the maximum number of NUMA nodes managed by StarPU. The default value can be modified at configure by using the option --enable-maxnumanodes.

30.7.3.5 STARPU_MAXNODES
#define STARPU_MAXNODES
Define the maximum number of memory nodes managed by StarPU. The default value can be modified at configure by using the option --enable-maxnodes. Reducing it allows to considerably reduce memory used by StarPU data structures.

30.7.4 Enumeration Type Documentation

30.7.4.1 starpu_worker_archtype
enum starpu_worker_archtype
Worker Architecture Type
The value 4 which was used by the driver SCC is no longer used as renumbering workers would make unusable old performance model files.

<table>
<thead>
<tr>
<th>Enumerator</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>STARPU_CPU_WORKER</td>
<td>CPU core</td>
</tr>
<tr>
<td>STARPU_CUDA_WORKER</td>
<td>NVIDIA CUDA device</td>
</tr>
<tr>
<td>STARPU_OPENCL_WORKER</td>
<td>OpenCL device</td>
</tr>
<tr>
<td>STARPU_MIC_WORKER</td>
<td>Intel MIC device</td>
</tr>
<tr>
<td>STARPU_MPI_MS_WORKER</td>
<td>MPI Slave device</td>
</tr>
<tr>
<td>STARPU_ANY_WORKER</td>
<td>any worker, used in the hypervisor</td>
</tr>
</tbody>
</table>

30.7.4.2 starpu_worker_collection_type
enum starpu_worker_collection_type
Types of structures the worker collection can implement

<table>
<thead>
<tr>
<th>Enumerator</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>STARPU_WORKER_TREE</td>
<td>The collection is a tree</td>
</tr>
<tr>
<td>STARPU_WORKER_LIST</td>
<td>The collection is an array</td>
</tr>
</tbody>
</table>
30.7.5 Function Documentation

30.7.5.1 starpu_worker_get_count()

unsigned starpu_worker_get_count ( void )

Return the number of workers (i.e. processing units executing StarPU tasks). The return value should be at most \texttt{STARPU\_NMAXWORKERS}.

30.7.5.2 starpu_cpu_worker_get_count()

unsigned starpu_cpu_worker_get_count ( void )

Return the number of CPUs controlled by StarPU. The return value should be at most \texttt{STARPU\_MAXCPUS}.

30.7.5.3 starpu_cuda_worker_get_count()

unsigned starpu_cuda_worker_get_count ( void )

Return the number of CUDA devices controlled by StarPU. The return value should be at most \texttt{STARPU\_MAXCU\_UDADEVS}.

30.7.5.4 starpu_opencl_worker_get_count()

unsigned starpu_opencl_worker_get_count ( void )

Return the number of OpenCL devices controlled by StarPU. The return value should be at most \texttt{STARPU\_MAXCU\_OPENCLDEVS}.

30.7.5.5 starpu_mic_worker_get_count()

unsigned starpu_mic_worker_get_count ( void )

Return the number of MIC workers controlled by StarPU.

30.7.5.6 starpu_mpi_ms_worker_get_count()

unsigned starpu_mpi_ms_worker_get_count ( void )

Return the number of MPI Master Slave workers controlled by StarPU.

30.7.5.7 starpu_mic_device_get_count()

unsigned starpu_mic_device_get_count ( void )

Return the number of MIC devices controlled by StarPU. The return value should be at most \texttt{STARPU\_MAXMIC\_DEVS}.

30.7.5.8 starpu_worker_get_id()

int starpu_worker_get_id ( void )

Return the identifier of the current worker, i.e the one associated to the calling thread. The return value is either \(-1\) if the current context is not a StarPU worker (i.e. when called from the application outside a task or a callback), or an integer between 0 and \texttt{starpu_worker_get_count()} - 1.
30.7.5.9  starpu_worker_get_type()

enum starpu_worker_archtype starpu_worker_get_type (int id)

Return the type of processing unit associated to the worker id. The worker identifier is a value returned by the function starpu_worker_get_id(). The return value indicates the architecture of the worker: STARPU_CPU_WORKER for a CPU core, STARPU_CUDA_WORKER for a CUDA device, and STARPU_OPENCL_WORKER for an OpenCL device. The return value for an invalid identifier is unspecified.

30.7.5.10  starpu_worker_get_count_by_type()

int starpu_worker_get_count_by_type (enum starpu_worker_archtype type)

Return the number of workers of type. A positive (or NULL) value is returned in case of success, -EINVAL indicates that type is not valid otherwise.

30.7.5.11  starpu_worker_get_ids_by_type()

unsigned starpu_worker_get_ids_by_type (enum starpu_worker_archtype type, int * workerids, unsigned maxsize)

Get the list of identifiers of workers of type. Fill the array workerids with the identifiers of the workers. The argument maxsize indicates the size of the array workerids. The return value gives the number of identifiers that were put in the array. -ERANGE is returned if maxsize is lower than the number of workers with the appropriate type: in that case, the array is filled with the maxsize first elements. To avoid such overflows, the value of maxsize can be chosen by the means of the function starpu_worker_get_count_by_type(), or by passing a value greater or equal to STARPU_NMAXWORKERS.

30.7.5.12  starpu_worker_get_by_type()

int starpu_worker_get_by_type (enum starpu_worker_archtype type, int num)

Return the identifier of the num-th worker that has the specified type. If there is no such worker, -1 is returned.

30.7.5.13  starpu_worker_get_by_devid()

int starpu_worker_get_by_devid (enum starpu_worker_archtype type, int devid)

Return the identifier of the worker that has the specified type and device id devid (which may not be the n-th, if some devices are skipped for instance). If there is no such worker, -1 is returned.

30.7.5.14  starpu_worker_get_name()

void starpu_worker_get_name (int id, char * dst, size_t maxlen)

Get the name of the worker id. StarPU associates a unique human readable string to each processing unit. This function copies at most the maxlen first bytes of the unique string associated to the worker id into the dst buffer. The caller is responsible for ensuring that dst is a valid pointer to a buffer of maxlen bytes at least. Calling this function on an invalid identifier results in an unspecified behaviour.

30.7.5.15  starpu_worker_display_names()

void starpu_worker_display_names (FILE * output, enum starpu_worker_archtype type)
Display on output the list (if any) of all the workers of the given type.

30.7.16 starpu_worker_get_devid()

int starpu_worker_get_devid (int id)

Return the device id of the worker id. The worker should be identified with the value returned by the starpu_worker_get_id() function. In the case of a CUDA worker, this device identifier is the logical device identifier exposed by CUDA (used by the function cudaGetDevice() for instance). The device identifier of a CPU worker is the logical identifier of the core on which the worker was bound; this identifier is either provided by the OS or by the library hwloc in case it is available.

30.7.17 starpu_worker_get_type_as_string()

char* starpu_worker_get_type_as_string (enum starpu_worker_archtype type)

Return worker type as a string.

30.7.18 starpu_worker_get_hwloc_cpuset()

hwloc_cpuset_t starpu_worker_get_hwloc_cpuset (int workerid)

If StarPU was compiled with hwloc support, return a duplicate of the hwloc cpuset associated with the worker workerid. The returned cpuset is obtained from a hwloc_bitmap_dup() function call. It must be freed by the caller using hwloc_bitmap_free().

30.7.19 starpu_worker_get_hwloc_obj()

hwloc_obj_t starpu_worker_get_hwloc_obj (int workerid)

If StarPU was compiled with hwloc support, return the hwloc object corresponding to the worker workerid.

30.7.20 starpu_worker_get_local_memory_node()

unsigned starpu_worker_get_local_memory_node (void)

Return the memory node associated to the current worker.

30.7.21 starpu_worker_get_memory_node()

unsigned starpu_worker_get_memory_node (unsigned workerid)

Return the identifier of the memory node associated to the worker identified by workerid.

30.7.22 starpu_memory_nodes_numa_id_to_devid()

int starpu_memory_nodes_numa_id_to_devid (int osid)

Return the identifier of the memory node associated to the NUMA node identified by osid by the Operating System.

30.7.23 starpu_memory_nodes_numa_devid_to_id()

int starpu_memory_nodes_numa_devid_to_id (unsigned id)

Return the Operating System identifier of the memory node whose StarPU identifier is id.
30.7.5.24 starpu_node_get_kind()

```c
enum starpu_node_kind starpu_node_get_kind (unsigned node)
```

Return the type of `node` as defined by `::starpu_node_kind`. For example, when defining a new data interface, this function should be used in the allocation function to determine on which device the memory needs to be allocated.

30.7.5.25 starpu_worker_sched_op_pending()

```c
int starpu_worker_sched_op_pending (void)
```

Return `!0` if current worker has a scheduling operation in progress, and `0` otherwise.

30.7.5.26 starpu_worker_relax_on()

```c
void starpu_worker_relax_on (void)
```

Allow other threads and workers to temporarily observe the current worker state, even though it is performing a scheduling operation. Must be called by a worker before performing a potentially blocking call such as acquiring a mutex other than its own sched_mutex. This function increases `state_relax_refcnt` from the current worker. No more than `UINT_MAX-1` nested `starpu_worker_relax_on()` calls should performed on the same worker. This function is automatically called by `starpu_worker_lock()` to relax the caller worker state while attempting to lock the target worker.

30.7.5.27 starpu_worker_relax_off()

```c
void starpu_worker_relax_off (void)
```

Must be called after a potentially blocking call is complete, to restore the relax state in place before the corresponding `starpu_worker_relax_on()`. Decreases `state_relax_refcnt`. Calls to `starpu_worker_relax_on()` and `starpu_worker_relax_off()` must be properly paired. This function is automatically called by `starpu_worker_unlock()` after the target worker has been unlocked.

30.7.5.28 starpu_worker_get_relax_state()

```c
int starpu_worker_get_relax_state (void)
```

Return `!0` if the current worker `state_relax_refcnt`!`=0` and `0` otherwise.

30.7.5.29 starpu_worker_lock()

```c
void starpu_worker_lock (int workerid)
```

Acquire the sched mutex of `workerid`. If the caller is a worker, distinct from `workerid`, the caller worker automatically enters a relax state while acquiring the target worker lock.

30.7.5.30 starpu_worker_trylock()

```c
int starpu_worker_trylock (int workerid)
```

Attempt to acquire the sched mutex of `workerid`. Returns `0` if successful, `!0` if `workerid` sched mutex is held or the corresponding worker is not in a relax state. If the caller is a worker, distinct from `workerid`, the caller worker automatically enters relax state if successfully acquiring the target worker lock.

30.7.5.31 starpu_worker_unlock()

```c
void starpu_worker_unlock (int workerid)
```
Release the previously acquired sched mutex of \texttt{workerid}. Restore the relax state of the caller worker if needed.

30.7.5.32 \texttt{starpu\_worker\_lock\_self()}

```c
void starpu_worker_lock_self()
```

Acquire the current worker sched mutex.

30.7.5.33 \texttt{starpu\_worker\_unlock\_self()}

```c
void starpu_worker_unlock_self()
```

Release the current worker sched mutex.

30.7.5.34 \texttt{starpu\_worker\_set\_going\_to\_sleep\_callback()}

```c
void starpu_worker_set_going_to_sleep_callback(unsigned workerid) callback )
```

If StarPU was compiled with blocking drivers support and worker callbacks support enabled, allow to specify an external resource manager callback to be notified about workers going to sleep.

30.7.5.35 \texttt{starpu\_worker\_set\_waking\_up\_callback()}

```c
void starpu_worker_set_waking_up_callback(unsigned workerid) callback )
```

If StarPU was compiled with blocking drivers support and worker callbacks support enabled, allow to specify an external resource manager callback to be notified about workers waking-up.

30.8 Data Management

Data management facilities provided by StarPU. We show how to use existing data interfaces in \texttt{Data Interfaces}, but developers can design their own data interfaces if required.

\textbf{Typedefs}

- typedef struct \_starpu\_data\_state * \texttt{starpu\_data\_handle\_t}
- typedef struct starpu\_arbiter * \texttt{starpu\_arbiter\_t}

\textbf{Enumerations}

- enum \texttt{starpu\_data\_access\_mode} { \texttt{STARPU\_NONE, STARPU\_R, STARPU\_W, STARPU\_RW, STARPU\_SCRATCH, STARPU\_REDUX, STARPU\_COMMUTE, STARPU\_SSEND, STARPU\_LOCALITY, STARPU\_ACCESS\_MODE\_MAX} }

\textbf{Functions}

- void \texttt{starpu\_data\_set\_name(starpu\_data\_handle\_t handle, const char *name)}
- void \texttt{starpu\_data\_set\_coordinates\_array(starpu\_data\_handle\_t handle, int dimensions, int dims[])}
- void \texttt{starpu\_data\_set\_coordinates(starpu\_data\_handle\_t handle, unsigned dimensions,...)}
- void \texttt{starpu\_data\_unregister(starpu\_data\_handle\_t handle)}
- void \texttt{starpu\_data\_unregister\_no\_coherency(starpu\_data\_handle\_t handle)}
- void \texttt{starpu\_data\_unregister\_submit(starpu\_data\_handle\_t handle)}
- void \texttt{starpu\_data\_invalidate(starpu\_data\_handle\_t handle)}
- void \texttt{starpu\_data\_invalidate\_submit(starpu\_data\_handle\_t handle)}
- void \texttt{starpu\_data\_advise\_as\_important(starpu\_data\_handle\_t handle, unsigned is\_important)}
30.8 Data Management

- `starpu_arbiter_t` `starpu_arbiter_create (void)` `{STARPU_ATTRIBUTE_MALLOC}
- `void starpu_data_assign_arbiter (starpu_data_handle_t handle, starpu_arbiter_t arbiter)`
- `void starpu_arbiter_destroy (starpu_arbiter_t arbiter)`
- `int starpu_data_request_allocation (starpu_data_handle_t handle, unsigned node)`
- `int starpu_data_fetch_on_node (starpu_data_handle_t handle, unsigned node, unsigned async)`
- `int starpu_data_prefetch_on_node (starpu_data_handle_t handle, unsigned node, unsigned async)`
- `int starpu_data_prefetch_on_node_prio (starpu_data_handle_t handle, unsigned node, unsigned async, int prio)`
- `int starpu_data_idle_prefetch_on_node (starpu_data_handle_t handle, unsigned node, unsigned async)`
- `int starpu_data_idle_prefetch_on_node_prio (starpu_data_handle_t handle, unsigned node, unsigned async, int prio)`
- `unsigned starpu_data_is_on_node (starpu_data_handle_t handle, unsigned node)`
- `void starpu_data_wont_use (starpu_data_handle_t handle)`
- `void starpu_data_set_wt_mask (starpu_data_handle_t handle, uint32_t wt_mask)`
- `void starpu_data_set_ooc_flag (starpu_data_handle_t handle, unsigned flag)`
- `unsigned starpu_data_get_ooc_flag (starpu_data_handle_t handle)`
- `void starpu_data_query_status (starpu_data_handle_t handle, int memory_node, int *is_allocated, int *is_valid, int *is_requested)`
- `void starpu_data_set_reduction_methods (starpu_data_handle_t handle, struct starpu_codelet *redux_cl, struct starpu_codelet *init_cl)`
- `struct starpu_data_interface_ops *starpu_data_get_interface_ops (starpu_data_handle_t handle)`
- `unsigned starpu_data_test_if_allocated_on_node (starpu_data_handle_t handle, unsigned memory_node)`
- `void starpu_memchunk_tidy (unsigned memory_node)`
- `void starpu_data_set_user_data (starpu_data_handle_t handle, void *user_data)`
- `void *starpu_data_get_user_data (starpu_data_handle_t handle)`

Access registered data from the application

- `int starpu_data_acquire (starpu_data_handle_t handle, enum starpu_data_access_mode mode)`
- `int starpu_data_acquire_on_node (starpu_data_handle_t handle, int node, enum starpu_data_access_mode mode)`
- `int starpu_data_acquire_cb (starpu_data_handle_t handle, enum starpu_data_access_mode mode, void(*)(void *), void *arg)`
- `int starpu_data_acquire_on_node_cb (starpu_data_handle_t handle, int node, enum starpu_data_access_mode mode, void(*)(void *), void *arg)`
- `int starpu_data_acquire_cb_sequential_consistency (starpu_data_handle_t handle, enum starpu_data_access_mode mode, void(*)(void *), void *arg, int sequential_consistency)`
- `int starpu_data_acquire_on_node_cb_sequential_consistency (starpu_data_handle_t handle, int node, enum starpu_data_access_mode mode, void(*)(void *), void *arg, int sequential_consistency)`
- `int starpu_data_acquire_on_node_cb_sequential_consistency_quick (starpu_data_handle_t handle, int node, enum starpu_data_access_mode mode, void(*)(void *), void *arg, int sequential_consistency, int quick)`
- `int starpu_data_acquire_on_node_cb_sequential_consistency_sync_jobids (starpu_data_handle_t handle, int node, enum starpu_data_access_mode mode, void(*)(void *), void *arg, int sequential_consistency, int quick, long *pre_sync_jobid, long *post_sync_jobid)`
- `int starpu_data_acquire_try (starpu_data_handle_t handle, enum starpu_data_access_mode mode)`
- `int starpu_data_acquire_on_node_try (starpu_data_handle_t handle, int node, enum starpu_data_access_mode mode)`
- `void starpu_data_release (starpu_data_handle_t handle)`
- `void starpu_data_release_on_node (starpu_data_handle_t handle, int node)`

#define STARPU_ACQUIRE_NO_NODE
#define STARPU_ACQUIRE_NO_NODE_LOCK_ALL
#define STARPU_DATA_ACQUIRE_CB(handle, mode, code)
Implicit Data Dependencies

In this section, we describe how StarPU makes it possible to insert implicit task dependencies in order to enforce sequential data consistency. When this data consistency is enabled on a specific data handle, any data access will appear as sequentially consistent from the application. For instance, if the application submits two tasks that access the same piece of data in read-only mode, and then a third task that access it in write mode, dependencies will be added between the two first tasks and the third one. Implicit data dependencies are also inserted in the case of data accesses from the application.

- void starpu_data_set_sequential_consistency_flag (starpu_data_handle_t handle, unsigned flag)
- unsigned starpu_data_get_sequential_consistency_flag (starpu_data_handle_t handle)
- unsigned starpu_data_get_default_sequential_consistency_flag (void)
- void starpu_data_set_default_sequential_consistency_flag (unsigned flag)

30.8.1 Detailed Description

Data management facilities provided by StarPU. We show how to use existing data interfaces in Data Interfaces, but developers can design their own data interfaces if required.

30.8.2 Macro Definition Documentation

30.8.2.1 STARPU_ACQUIRE_NO_NODE

#define STARPU_ACQUIRE_NO_NODE
This macro can be used to acquire data, but not require it to be available on a given node, only enforce R/W dependencies. This can for instance be used to wait for tasks which produce the data, but without requesting a fetch to the main memory.

30.8.2.2 STARPU_ACQUIRE_NO_NODE_LOCK_ALL

#define STARPU_ACQUIRE_NO_NODE_LOCK_ALL
Similar to STARPU_ACQUIRE_NO_NODE, but will lock the data on all nodes, preventing them from being evicted for instance. This is mostly useful inside StarPU only.

30.8.2.3 STARPU_DATA_ACQUIRE_CB

#define STARPU_DATA_ACQUIRE_CB(
  handle,
  mode,
  code )
STARPU_DATA_ACQUIRE_CB() is the same as starpu_data_acquire_cb(), except that the code to be executed in a callback is directly provided as a macro parameter, and the data handle is automatically released after it. This permits to easily execute code which depends on the value of some registered data. This is non-blocking too and may be called from task callbacks.

30.8.3 Typedef Documentation

30.8.3.1 starpu_data_handle_t

typedef struct _starpu_data_state* starpu_data_handle_t
StarPU uses starpu_data_handle_t as an opaque handle to manage a piece of data. Once a piece of data has been registered to StarPU, it is associated to a starpu_data_handle_t which keeps track of the state of the piece of data over the entire machine, so that we can maintain data consistency and locate data replicates for instance.
30.8 Data Management

30.8.3.2 starpu_arbiter_t

typedef struct starpu_arbiter* starpu_arbiter_t

This is an arbiter, which implements an advanced but centralized management of concurrent data accesses, see Concurrent Data Accesses for the details.

30.8.4 Enumeration Type Documentation

30.8.4.1 starpu_data_access_mode

defined as :

```
enum starpu_data_access_mode
```

Describe a StarPU data access mode

Note: when adding a flag here, update _starpu_detect_implicit_data_deps_with_handle

Note: other STARPU_* values in include/starpu_task_util.h

<table>
<thead>
<tr>
<th>Enumerator</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>STARPU_NONE</td>
<td>todo</td>
</tr>
<tr>
<td>STARPU_R</td>
<td>read-only mode</td>
</tr>
<tr>
<td>STARPU_W</td>
<td>write-only mode</td>
</tr>
<tr>
<td>STARPU_RW</td>
<td>read-write mode. Equivalent to STARPU_R</td>
</tr>
<tr>
<td>STARPU_SCRATCH</td>
<td>A temporary buffer is allocated for the task, but StarPU does not enforce data consistency—i.e. each device has its own buffer, independently from each other (even for CPUs), and no data transfer is ever performed. This is useful for temporary variables to avoid allocating/freeing buffers inside each task. Currently, no behavior is defined concerning the relation with the STARPU_R and STARPU_W modes and the value provided at registration — i.e., the value of the scratch buffer is undefined at entry of the codelet function. It is being considered for future extensions at least to define the initial value. For now, data to be used in STARPU_SCRATCH mode should be registered with node -1 and a NULL pointer, since the value of the provided buffer is simply ignored for now.</td>
</tr>
<tr>
<td>STARPU_REDUX</td>
<td>todo</td>
</tr>
<tr>
<td>STARPU_COMMUTE</td>
<td>STARPU_COMMUTE can be passed along STARPU_W or STARPU_RW to express that StarPU can let tasks commute, which is useful e.g. when bringing a contribution into some data, which can be done in any order (but still require sequential consistency against reads or non-commutative writes).</td>
</tr>
<tr>
<td>STARPU_SSEND</td>
<td>used in starpu_mpi_insert_task() to specify the data has to be sent using a synchronous and non-blocking mode (see starpu_mpi_isend())</td>
</tr>
<tr>
<td>STARPU_LOCALITY</td>
<td>used to tell the scheduler which data is the most important for the task, and should thus be used to try to group tasks on the same core or cache, etc. For now only the ws and lws schedulers take this flag into account, and only when rebuild with USE_LOCALITY flag defined in the src/sched_policies/work_stealing_policy.c source code.</td>
</tr>
<tr>
<td>STARPU_ACCESS_MODE_MAX</td>
<td>todo</td>
</tr>
</tbody>
</table>

30.8.5 Function Documentation
30.8.5.1 starpu_data_set_name()

```c
void starpu_data_set_name(
    starpu_data_handle_t handle,
    const char * name)
```

Set the name of the data, to be shown in various profiling tools.

30.8.5.2 starpu_data_set_coordinates_array()

```c
void starpu_data_set_coordinates_array(
    starpu_data_handle_t handle,
    int dimensions,
    int dims[])
```

Set the coordinates of the data, to be shown in various profiling tools. `dimensions` is the size of the `dims` array. This can be for instance the tile coordinates within a big matrix.

30.8.5.3 starpu_data_set_coordinates()

```c
void starpu_data_set_coordinates(
    starpu_data_handle_t handle,
    unsigned dimensions,
    ...)
```

Set the coordinates of the data, to be shown in various profiling tools. `dimensions` is the number of subsequent `int` parameters. This can be for instance the tile coordinates within a big matrix.

30.8.5.4 starpu_data_unregister()

```c
void starpu_data_unregister(
    starpu_data_handle_t handle)
```

Unregister a data handle from StarPU. If the data was automatically allocated by StarPU because the home node was -1, all automatically allocated buffers are freed. Otherwise, a valid copy of the data is put back into the home node in the buffer that was initially registered. Using a data handle that has been unregistered from StarPU results in an undefined behaviour. In case we do not need to update the value of the data in the home node, we can use the function `starpu_data_unregister_no_coherency()` instead.

30.8.5.5 starpu_data_unregister_no_coherency()

```c
void starpu_data_unregister_no_coherency(
    starpu_data_handle_t handle)
```

Similar to `starpu_data_unregister()`, except that StarPU does not put back a valid copy into the home node, in the buffer that was initially registered.

30.8.5.6 starpu_data_unregister_submit()

```c
void starpu_data_unregister_submit(
    starpu_data_handle_t handle)
```

Destroy the data handle once it is no longer needed by any submitted task. No coherency is assumed.

30.8.5.7 starpu_data_invalidate()

```c
void starpu_data_invalidate(
    starpu_data_handle_t handle)
```

Destroy all replicates of the data handle immediately. After data invalidation, the first access to handle must be performed in STARPU_W mode. Accessing an invalidated data in STARPU_R mode results in undefined behaviour.

30.8.5.8 starpu_data_invalidate_submit()

```c
void starpu_data_invalidate_submit(
    starpu_data_handle_t handle)
```
Submit invalidation of the data handle after completion of previously submitted tasks.

30.8.5.9 starpu_data_advise_as_important()

```c
void starpu_data_advise_as_important (  
    starpu_data_handle_t handle,  
    unsigned is_important )
```

Specify that the data handle can be discarded without impacting the application.

30.8.5.10 starpu_data_acquire()

```c
int starpu_data_acquire (  
    starpu_data_handle_t handle,  
    enum starpu_data_access_mode mode )
```

The application must call this function prior to accessing registered data from main memory outside tasks. StarPU ensures that the application will get an up-to-date copy of handle in main memory located where the data was originally registered, and that all concurrent accesses (e.g. from tasks) will be consistent with the access mode specified with mode. starpu_data_release() must be called once the application no longer needs to access the piece of data. Note that implicit data dependencies are also enforced by starpu_data_acquire(), i.e. starpu_data_acquire() will wait for all tasks scheduled to work on the data, unless they have been disabled explicitly by calling starpu_data_set_default_sequential_consistency_flag() or starpu_data_set_sequential_consistency_flag(). starpu_data_acquire() is a blocking call, so that it cannot be called from tasks or from their callbacks (in that case, starpu_data_acquire() returns -EDEADLK). Upon successful completion, this function returns 0.

30.8.5.11 starpu_data_acquire_on_node()

```c
int starpu_data_acquire_on_node (  
    starpu_data_handle_t handle,  
    int node,  
    enum starpu_data_access_mode mode )
```

Similar to starpu_data_acquire(), except that the data will be available on the given memory node instead of main memory. STARPU_ACQUIRE_NO_NODE and STARPU_ACQUIRE_NO_NODE_LOCK_ALL can be used instead of an explicit node number.

30.8.5.12 starpu_data_acquire_cb()

```c
int starpu_data_acquire_cb (  
    starpu_data_handle_t handle,  
    enum starpu_data_access_mode mode,  
    void(void*) callback,  
    void * arg )
```

Asynchronous equivalent of starpu_data_acquire(). When the data specified in handle is available in the access mode, the callback function is executed. The application may access the requested data during the execution of callback. The callback function must call starpu_data_release() once the application no longer needs to access the piece of data. Note that implicit data dependencies are also enforced by starpu_data_acquire_cb() in case they are not disabled. Contrary to starpu_data_acquire(), this function is non-blocking and may be called from task callbacks. Upon successful completion, this function returns 0.

30.8.5.13 starpu_data_acquire_on_node_cb()

```c
int starpu_data_acquire_on_node_cb (  
    starpu_data_handle_t handle,  
    int node,  
    enum starpu_data_access_mode mode,  
    void(void*) callback,  
    void * arg )
```

Similar to starpu_data_acquire_cb(), except that the data will be available on the given memory node instead of main memory. STARPU_ACQUIRE_NO_NODE and STARPU_ACQUIRE_NO_NODE_LOCK_ALL can be used instead of an explicit node number.
30.8.5.14 starpu_data_acquire_cb_sequential_consistency()

```c
int starpu_data_acquire_cb_sequential_consistency(
    starpu_data_handle_t handle,
    enum starpu_data_access_mode mode,
    void(*)(void *) callback,
    void * arg,
    int sequential_consistency)
```

Similar to starpu_data_acquire_cb() with the possibility of enabling or disabling data dependencies. When the data specified in `handle` is available in the access `mode`, the `callback` function is executed. The application may access the requested data during the execution of this `callback`. The `callback` function must call `starpu_data_release()` once the application no longer needs to access the piece of data. Note that implicit data dependencies are also enforced by `starpu_data_acquire_cb_sequential_consistency()` in case they are not disabled specifically for the given `handle` or by the parameter `sequential_consistency`. Similarly to `starpu_data_acquire_cb()`, this function is non-blocking and may be called from task callbacks. Upon successful completion, this function returns 0.

30.8.5.15 starpu_data_acquire_on_node_cb_sequential_consistency()

```c
int starpu_data_acquire_on_node_cb_sequential_consistency(
    starpu_data_handle_t handle,
    int node,
    enum starpu_data_access_mode mode,
    void(*)(void *) callback,
    void * arg,
    int sequential_consistency)
```

Similar to `starpu_data_acquire_cb_sequential_consistency()`, except that the data will be available on the given memory node instead of main memory. `STARPU_ACQUIRE_NO_NODE` and `STARPU_ACQUIRE_NO_NODE_LOCK_ALL` can be used instead of an explicit node number.

30.8.5.16 starpu_data_acquire_on_node_cb_sequential_consistency_sync_jobids()

```c
int starpu_data_acquire_on_node_cb_sequential_consistency_sync_jobids(
    starpu_data_handle_t handle,
    int node,
    enum starpu_data_access_mode mode,
    void(*)(void *) callback,
    void * arg,
    int sequential_consistency,
    int quick,
    long * pre_sync_jobid,
    long * post_sync_jobid)
```

Similar to `starpu_data_acquire_on_node_cb_sequential_consistency()`, except that the `pre_sync_jobid` and `post_sync_jobid` parameters can be used to retrieve the jobid of the synchronization tasks. `pre_sync_jobid` happens just before the acquisition, and `post_sync_jobid` happens just after the release.

30.8.5.17 starpu_data_acquire_try()

```c
int starpu_data_acquire_try(
    starpu_data_handle_t handle,
    enum starpu_data_access_mode mode)
```

The application can call this function instead of `starpu_data_acquire()` so as to acquire the data like `starpu_data_acquire()`, but only if all previously-submitted tasks have completed, in which case `starpu_data_acquire_try()` returns 0. StarPU will have ensured that the application will get an up-to-date copy of `handle` in main memory located where the data was originally registered. `starpu_data_release()` must be called once the application no longer needs to access the piece of data.
30.8.5.18 starpu_data_acquire_on_node_try()

```c
int starpu_data_acquire_on_node_try (  
    starpu_data_handle_t handle,  
    int node,  
    enum starpu_data_access_mode mode )
```

Similar to `starpu_data_acquire_try()`, except that the data will be available on the given memory node instead of main memory. `STARPU_ACQUIRE_NO_NODE` and `STARPU_ACQUIRE_NO_NODE_LOCK_ALL` can be used instead of an explicit node number.

30.8.5.19 starpu_data_release()

```c
void starpu_data_release (  
    starpu_data_handle_t handle )
```

Release the piece of data acquired by the application either by `starpu_data_acquire()` or by `starpu_data_acquire←_cb()`.

30.8.5.20 starpu_data_release_on_node()

```c
void starpu_data_release_on_node (  
    starpu_data_handle_t handle,  
    int node )
```

Similar to `starpu_data_release()` except that the data will be available on the given memory node instead of main memory. The `node` parameter must be exactly the same as the corresponding `starpu_data_acquire_on←_node*` call.

30.8.5.21 starpu_arbiter_create()

```c
starpu_arbiter_t starpu_arbiter_create (  
    void )
```

Create a data access arbiter, see Concurrent Data Accesses for the details.

30.8.5.22 starpu_data_assign_arbiter()

```c
void starpu_data_assign_arbiter (  
    starpu_data_handle_t handle,  
    starpu_arbiter_t arbiter )
```

Make access to `handle` managed by `arbiter`.

30.8.5.23 starpu_arbiter_destroy()

```c
void starpu_arbiter_destroy (  
    starpu_arbiter_t arbiter )
```

Destroy the `arbiter`. This must only be called after all data assigned to it have been unregistered.

30.8.5.24 starpu_data_request_allocation()

```c
int starpu_data_request_allocation (  
    starpu_data_handle_t handle,  
    unsigned node )
```

Explicitly ask StarPU to allocate room for a piece of data on the specified memory `node`.

30.8.5.25 starpu_data_fetch_on_node()

```c
int starpu_data_fetch_on_node (  
    starpu_data_handle_t handle,  
    unsigned node,  
    unsigned async )
```

Issue a fetch request for the data `handle` to `node`, i.e., requests that the data be replicated to the given node as soon as possible, so that it is available there for tasks. If `async` is 0, the call will block until the transfer is
achieved, else the call will return immediately, after having just queued the request. In the latter case, the request will asynchronously wait for the completion of any task writing on the data.

30.8.5.26  

```c
int starpu_data_prefetch_on_node(
    starpu_data_handle_t handle,
    unsigned node,
    unsigned async)
```

Issue a prefetch request for the data handle to node, i.e. requests that the data be replicated to node when there is room for it, so that it is available there for tasks. If async is 0, the call will block until the transfer is achieved, else the call will return immediately, after having just queued the request. In the latter case, the request will asynchronously wait for the completion of any task writing on the data.

30.8.5.27  

```c
int starpu_data_idle_prefetch_on_node(
    starpu_data_handle_t handle,
    unsigned node,
    unsigned async)
```

Issue an idle prefetch request for the data handle to node, i.e. requests that the data be replicated to node, so that it is available there for tasks, but only when the bus is really idle. If async is 0, the call will block until the transfer is achieved, else the call will return immediately, after having just queued the request. In the latter case, the request will asynchronously wait for the completion of any task writing on the data.

30.8.5.28  

```c
unsigned starpu_data_is_on_node(
    starpu_data_handle_t handle,
    unsigned node)
```

Check whether a valid copy of handle is currently available on memory node node.

30.8.5.29  

```c
void starpu_data_wont_use(
    starpu_data_handle_t handle)
```

Advise StarPU that handle will not be used in the close future, and is thus a good candidate for eviction from GPUs. StarPU will thus write its value back to its home node when the bus is idle, and select this data in priority for eviction when memory gets low.

30.8.5.30  

```c
void starpu_data_set_wt_mask(
    starpu_data_handle_t handle,
    uint32_t wt_mask)
```

Set the write-through mask of the data handle (and its children), i.e. a bitmask of nodes where the data should be always replicated after modification. It also prevents the data from being evicted from these nodes when memory gets scarce. When the data is modified, it is automatically transferred into those memory nodes. For instance a $1 << 0$ write-through mask means that the CUDA workers will commit their changes in main memory (node 0).

30.8.5.31  

```c
void starpu_data_set_sequential_consistency_flag(
    starpu_data_handle_t handle,
    unsigned flag)
```

Set the data consistency mode associated to a data handle. The consistency mode set using this function has the priority over the default mode which can be set with starpu_data_set_default_sequential_consistency_flag().
30.8.5.32 starpu_data_get_sequential_consistency_flag()

unsigned starpu_data_get_sequential_consistency_flag (starpu_data_handle_t handle)

Get the data consistency mode associated to the data handle handle.

30.8.5.33 starpu_data_get_default_sequential_consistency_flag()

unsigned starpu_data_get_default_sequential_consistency_flag (void)

Return the default sequential consistency flag.

30.8.5.34 starpu_data_set_default_sequential_consistency_flag()

void starpu_data_set_default_sequential_consistency_flag (unsigned flag)

Set the default sequential consistency flag. If a non-zero value is passed, a sequential data consistency will be enforced for all handles registered after this function call, otherwise it is disabled. By default, StarPU enables sequential data consistency. It is also possible to select the data consistency mode of a specific data handle with the function starpu_data_set_sequential_consistency_flag().

30.8.5.35 starpu_data_set_ooc_flag()

void starpu_data_set_ooc_flag (starpu_data_handle_t handle, unsigned flag)

Set whether this data should be eligible to be evicted to disk storage (1) or not (0). The default is 1.

30.8.5.36 starpu_data_get_ooc_flag()

unsigned starpu_data_get_ooc_flag (starpu_data_handle_t handle)

Get whether this data was set to be eligible to be evicted to disk storage (1) or not (0).

30.8.5.37 starpu_data_query_status()

void starpu_data_query_status (starpu_data_handle_t handle, int memory_node, int *is_allocated, int *is_valid, int *is_requested)

Query the status of handle on the specified memory_node.

30.8.5.38 starpu_data_set_reduction_methods()

void starpu_data_set_reduction_methods (starpu_data_handle_t handle, struct starpu_codelet *redux_cl, struct starpu_codelet *init_cl)

Set the codelets to be used for handle when it is accessed in the mode STARPU_REDUX. Per-worker buffers will be initialized with the codelet init_cl, and reduction between per-worker buffers will be done with the codelet redux_cl.

30.8.5.39 starpu_data_set_user_data()

void starpu_data_set_user_data (starpu_data_handle_t handle, void *user_data)
Set the field `user_data` for the handle to `user_data`. It can then be retrieved with `starpu_data_get_user_data()`. `user_data` can be any application-defined value, for instance a pointer to an object-oriented container for the data.

30.8.5.40 starpu_data_get_user_data()

```c
void* starpu_data_get_user_data ( 
    starpu_data_handle_t handle 
)
```

Retrieve the field `user_data` previously set for the handle.

## 30.9 Data Interfaces

Data management is done at a high-level in StarPU: rather than accessing a mere list of contiguous buffers, the tasks may manipulate data that are described by a high-level construct which we call data interface.

### Data Structures

- struct `starpu_data_copy_methods`
- struct `starpu_data_interface_ops`
- struct `starpu_matrix_interface`
- struct `starpu_coo_interface`
- struct `starpu_block_interface`
- struct `starpu_vector_interface`
- struct `starpu_variable_interface`
- struct `starpu_csr_interface`
- struct `starpu_bcsr_interface`
- struct `starpu_multiformat_data_interface_ops`
- struct `starpu_multiformat_interface`

### Enumerations

- enum `starpu_data_interface_id` {
}

### Basic API

- void `starpu_data_register` (starpu_data_handle_t *handleptr, int home_node, void *data_interface, struct starpu_data_interface_ops *ops)
- void `starpu_data_ptr_register` (starpu_data_handle_t handle, unsigned node)
- void `starpu_data_register_same` (starpu_data_handle_t *handledst, starpu_data_handle_t handlesrc)
- void * `starpu_data_handle_to_pointer` (starpu_data_handle_t handle, unsigned node)
- int `starpu_data_pointer_is_inside` (starpu_data_handle_t handle, unsigned node, void *ptr)
- void * `starpu_data_get_local_ptr` (starpu_data_handle_t handle)
- void `starpu_data_get_interface_on_node` (starpu_data_handle_t handle, unsigned memory_node)
- enum `starpu_data_interface_id` starpu_data_get_interface_id (starpu_data_handle_t handle)
- int `starpu_data_pack` (starpu_data_handle_t handle, void **ptr, starpu_ssize_t *count)
- int `starpu_data_unpack` (starpu_data_handle_t handle, void *ptr, size_t count)
- size_t `starpu_data_get_size` (starpu_data_handle_t handle)
- size_t `starpu_data_get_alloc_size` (starpu_data_handle_t handle)
- starpu_data_handle_t `starpu_data_lookup` (const void *ptr)
- int `starpu_data_get_home_node` (starpu_data_handle_t handle)
• int starpu_data_interface_get_next_id (void)
• int starpu_interface_copy (uintptr_t src, size_t src_offset, unsigned src_node, uintptr_t dst, size_t dst_offset, unsigned dst_node, size_t size, void *async_data)
• void starpu_interface_start_driver_copy_async (unsigned src_node, unsigned dst_node, double *start)
• void starpu_interface_end_driver_copy_async (unsigned src_node, unsigned dst_node, double start)
• void starpu_interface_data_copy (unsigned src_node, unsigned dst_node, size_t size)
• uintptr_t starpu_malloc_on_node_flags (unsigned dst_node, size_t size, int flags)
• uintptr_t starpu_malloc_on_node (unsigned dst_node, size_t size)
• void starpu_free_on_node_flags (unsigned dst_node, uintptr_t addr, size_t size, int flags)
• void starpu_free_on_node (unsigned dst_node, uintptr_t addr, size_t size)
• void starpu_malloc_on_node_set_default_flags (unsigned node, int flags)

Accessing Matrix Data Interfaces

• struct starpu_data_interface_ops starpu_interface_matrix_ops
• void starpu_matrix_data_register (starpu_data_handle_t *handle, int home_node, uintptr_t ptr, uint32_t ld, uint32_t nx, uint32_t ny, size_t elemsize)
• void starpu_matrix_data_register_allocsize (starpu_data_handle_t *handle, int home_node, uintptr_t ptr, uint32_t ld, uint32_t nx, uint32_t ny, size_t elemsize, size_t allocsize)
• void starpu_matrix_ptr_register (starpu_data_handle_t handle, unsigned node, uintptr_t ptr, uintptr_t dev_handle, size_t offset, uint32_t ld)
• uint32_t starpu_matrix_get_nx (starpu_data_handle_t handle)
• uint32_t starpu_matrix_get_ny (starpu_data_handle_t handle)
• uint32_t starpu_matrix_get_local_ld (starpu_data_handle_t handle)
• uintptr_t starpu_matrix_get_local_ptr (starpu_data_handle_t handle)
• size_t starpu_matrix_get_elemsize (starpu_data_handle_t handle)
• size_t starpu_matrix_get_allocsize (starpu_data_handle_t handle)
• #define STARPU_MATRIX_GET_PTR(interface)
• #define STARPU_MATRIX_GET_DEV_HANDLE(interface)
• #define STARPU_MATRIX_GET_OFFSET(interface)
• #define STARPU_MATRIX_GET_NX(interface)
• #define STARPU_MATRIX_GET_NY(interface)
• #define STARPU_MATRIX_GET_LD(interface)
• #define STARPU_MATRIX_GET_ELEMSIZE(interface)
• #define STARPU_MATRIX_GET_ALLOCSIZE(interface)
• #define STARPU_MATRIX_SET_NX(interface, newnx)
• #define STARPU_MATRIX_SET_NY(interface, newny)
• #define STARPU_MATRIX_SET_LD(interface, newld)

Accessing COO Data Interfaces

• struct starpu_data_interface_ops starpu_interface_coo_ops
• void starpu_coo_data_register (starpu_data_handle_t *handleptr, int home_node, uint32_t nx, uint32_t ny, uint32_t n_values, uint32_t *columns, uint32_t *rows, uintptr_t values, size_t elemsize)
• #define STARPU_COO_GET_COLUMNS(interface)
• #define STARPU_COO_GET_COLUMNS_DEV_HANDLE(interface)
• #define STARPU_COO_GET_ROWS(interface)
• #define STARPU_COO_GET_ROWS_DEV_HANDLE(interface)
• #define STARPU_COO_GET_VALUES(interface)
• #define STARPU_COO_GET_OFFSET
• #define STARPU_COO_GET_NVALUES(interface)
• #define STARPU_COO_GET_NX(interface)
• #define STARPU_COO_GET_NY(interface)
• #define STARPU_COO_GET_ELEMSIZE(interface)
Block Data Interface

- struct starpu_data_interface_ops starpu_interface_block_ops
- void starpu_block_data_register (starpu_data_handle_t *handle, int home_node, uintptr_t ptr, uint32_t ldy, uint32_t ldz, uint32_t nx, uint32_t ny, uint32_t nz, size_t elemsize)
- void starpu_block_ptr_register (starpu_data_handle_t handle, unsigned node, uintptr_t ptr, uintptr_t dev_handle, size_t offset, uint32_t ldy, uint32_t ldz)
- uint32_t starpu_block_get_nx (starpu_data_handle_t handle)
- uint32_t starpu_block_get_ny (starpu_data_handle_t handle)
- uint32_t starpu_block_get_nz (starpu_data_handle_t handle)
- uint32_t starpu_block_get_local_ldy (starpu_data_handle_t handle)
- uint32_t starpu_block_get_local_ldz (starpu_data_handle_t handle)
- uintptr_t starpu_block_get_local_ptr (starpu_data_handle_t handle)
- size_t starpu_block_get elemsize (starpu_data_handle_t handle)
- #define STARPU_BLOCK_GET_PTR(interface)
- #define STARPU_BLOCK_GET_DEV_HANDLE(interface)
- #define STARPU_BLOCK_GET_OFFSET(interface)
- #define STARPU_BLOCK_GET_NX(interface)
- #define STARPU_BLOCK_GET_NY(interface)
- #define STARPU_BLOCK_GET_NZ(interface)
- #define STARPU_BLOCK_GET_LDY(interface)
- #define STARPU_BLOCK_GET_LDZ(interface)
- #define STARPU_BLOCK_GET_ELEMSIZE(interface)

Vector Data Interface

- struct starpu_data_interface_ops starpu_interface_vector_ops
- void starpu_vector_data_register (starpu_data_handle_t *handle, int home_node, uintptr_t ptr, uint32_t nx, size_t elemsize)
- void starpu_vector_data_register_allocsize (starpu_data_handle_t *handle, int home_node, uintptr_t ptr, uint32_t nx, size_t elemsize, size_t allocsize)
- void starpu_vector_ptr_register (starpu_data_handle_t handle, unsigned node, uintptr_t ptr, uintptr_t dev_handle, size_t offset)
- uint32_t starpu_vector_get_nx (starpu_data_handle_t handle)
- size_t starpu_vector_get_elemsize (starpu_data_handle_t handle)
- size_t starpu_vector_get_allocsize (starpu_data_handle_t handle)
- uintptr_t starpu_vector_get_local_ptr (starpu_data_handle_t handle)
- #define STARPU_VECTOR_GET_PTR(interface)
- #define STARPU_VECTOR_GET_DEV_HANDLE(interface)
- #define STARPU_VECTOR_GET_OFFSET(interface)
- #define STARPU_VECTOR_GET_NX(interface)
- #define STARPU_VECTOR_GET_ELEMSIZE(interface)
- #define STARPU_VECTOR_GET_ALLOCSIZE(interface)
- #define STARPU_VECTOR_GET_SLICE_BASE(interface)
- #define STARPU_VECTOR_SET_NX(interface, newnx)

Variable Data Interface

- struct starpu_data_interface_ops starpu_interface_variable_ops
- void starpu_variable_data_register (starpu_data_handle_t *handle, int home_node, uintptr_t ptr, size_t size)
- void starpu_variable_ptr_register (starpu_data_handle_t handle, unsigned node, uintptr_t ptr, uintptr_t dev_handle, size_t offset)
- size_t starpu_variable_get elemsize (starpu_data_handle_t handle)
- uintptr_t starpu_variable_get_local_ptr (starpu_data_handle_t handle)
- #define STARPU_VARIABLE_GET_PTR(interface)
- #define STARPU_VARIABLE_GET_OFFSET(interface)
- #define STARPU_VARIABLE_GET_ELEMSIZE(interface)
- #define STARPU_VARIABLE_GET_DEV_HANDLE(interface)
Void Data Interface

- struct starpu_data_interface_ops starpu_interface_void_ops
- void starpu_void_data_register (starpu_data_handle_t *handle)

CSR Data Interface

- struct starpu_data_interface_ops starpu_interface_csr_ops
- void starpu_csr_data_register (starpu_data_handle_t *handle, int home_node, uint32_t nnz, uint32_t nrow, 
  uintptr_t nzval, uint32_t *colind, uint32_t *rowptr, uint32_t *firstentry, size_t elemsize)
- uint32_t starpu_csr_get_nnz (starpu_data_handle_t handle)
- uint32_t starpu_csr_get_nrow (starpu_data_handle_t handle)
- uint32_t starpu_csr_get_firstentry (starpu_data_handle_t handle)
- uintptr_t starpu_csr_get_local_nzval (starpu_data_handle_t handle)
- uint32_t * starpu_csr_get_local_colind (starpu_data_handle_t handle)
- uint32_t * starpu_csr_get_local_rowptr (starpu_data_handle_t handle)
- size_t starpu_csr_get_elemsize (starpu_data_handle_t handle)
- #define STARPU_CSR_GET_NNZ(interface)
- #define STARPU_CSR_GET_NROW(interface)
- #define STARPU_CSR_GET_NZVAL(interface)
- #define STARPU_CSR_GET_NZVAL_DEV_HANDLE(interface)
- #define STARPU_CSR_GET_COLIND(interface)
- #define STARPU_CSR_GET_COLIND_DEV_HANDLE(interface)
- #define STARPU_CSR_GET_ROWPTR(interface)
- #define STARPU_CSR_GET_ROWPTR_DEV_HANDLE(interface)
- #define STARPU_CSR_GET_OFFSET
- #define STARPU_CSR_GET_ELEMSIZE(interface)

BCSR Data Interface

- struct starpu_data_interface_ops starpu_interface_bcsr_ops
- void starpu_bcsr_data_register (starpu_data_handle_t *handle, int home_node, uint32_t nnz, uint32_t nrow, 
  uintptr_t nzval, uint32_t *colind, uint32_t *rowptr, uint32_t firstentry, uint32_t r, uint32_t c, size_t elemsize)
- uint32_t starpu_bcsr_get_nnz (starpu_data_handle_t handle)
- uint32_t starpu_bcsr_get_nrow (starpu_data_handle_t handle)
- uint32_t starpu_bcsr_get_firstentry (starpu_data_handle_t handle)
- uintptr_t starpu_bcsr_get_local_nzval (starpu_data_handle_t handle)
- uint32_t * starpu_bcsr_get_local_colind (starpu_data_handle_t handle)
- uint32_t * starpu_bcsr_get_local_rowptr (starpu_data_handle_t handle)
- uint32_t starpu_bcsr_get_r (starpu_data_handle_t handle)
- uint32_t starpu_bcsr_get_c (starpu_data_handle_t handle)
- size_t starpu_bcsr_get_elemsize (starpu_data_handle_t handle)
- #define STARPU_BCSR_GET_NNZ(interface)
- #define STARPU_BCSR_GET_NZVAL(interface)
- #define STARPU_BCSR_GET_NZVAL_DEV_HANDLE(interface)
- #define STARPU_BCSR_GET_COLIND(interface)
- #define STARPU_BCSR_GET_COLIND_DEV_HANDLE(interface)
- #define STARPU_BCSR_GET_ROWPTR(interface)
- #define STARPU_BCSR_GET_ROWPTR_DEV_HANDLE(interface)
- #define STARPU_BCSR_GET_OFFSET
30.9.1 Detailed Description

Data management is done at a high-level in StarPU: rather than accessing a mere list of contiguous buffers, the tasks may manipulate data that are described by a high-level construct which we call data interface. An example of data interface is the "vector" interface which describes a contiguous data array on a specific memory node. This interface is a simple structure containing the number of elements in the array, the size of the elements, and the address of the array in the appropriate address space (this address may be invalid if there is no valid copy of the array in the memory node). More informations on the data interfaces provided by StarPU are given in Data Interfaces.

When a piece of data managed by StarPU is used by a task, the task implementation is given a pointer to an interface describing a valid copy of the data that is accessible from the current processing unit. Every worker is associated to a memory node which is a logical abstraction of the address space from which the processing unit gets its data. For instance, the memory node associated to the different CPU workers represents main memory (RAM), the memory node associated to a GPU is DRAM embedded on the device. Every memory node is identified by a logical index which is accessible from the function starpu_worker_get_memory_node(). When registering a piece of data to StarPU, the specified memory node indicates where the piece of data initially resides (we also call this memory node the home node of a piece of data).

In the case of NUMA systems, functions starpu_memory_nodes_numa_devid_to_id() and starpu_memory_nodes←_numa_id_to_devid() can be used to convert from NUMA node numbers as seen by the Operating System and NUMA node numbers as seen by StarPU.

There are several ways to register a memory region so that it can be managed by StarPU. StarPU provides data interfaces for vectors, 2D matrices, 3D matrices as well as BCSR and CSR sparse matrices.

30.9.2 Data Structure Documentation

30.9.2.1 struct starpu_data_copy_methods

Define the per-interface methods. If the starpu_data_copy_methods::any_to_any method is provided, it will be used by default if no specific method is provided. It can still be useful to provide more specific method in case of e.g. available particular CUDA or OpenCL support.

Data Fields

- int(∗ can_copy )(void ∗src_interface, unsigned src_node, void ∗dst_interface, unsigned dst_node, unsigned handling_node)
- int(∗ ram_to_ram )(void ∗src_interface, unsigned src_node, void ∗dst_interface, unsigned dst_node)
- int(∗ ram_to_cud a )(void ∗src_interface, unsigned src_node, void ∗dst_interface, unsigned dst_node)
- int(∗ ram_to_opencl )(void ∗src_interface, unsigned src_node, void ∗dst_interface, unsigned dst_node)
- int(∗ ram_to_mic )(void ∗src_interface, unsigned src_node, void ∗dst_interface, unsigned dst_node)
- int(∗ cuda_to_ram )(void ∗src_interface, unsigned src_node, void ∗dst_interface, unsigned dst_node)
- int(∗ cuda_to_cud a )(void ∗src_interface, unsigned src_node, void ∗dst_interface, unsigned dst_node)
- int(∗ cuda_to_opencl )(void ∗src_interface, unsigned src_node, void ∗dst_interface, unsigned dst_node)
30.9 Data Interfaces

- int(* opencl_to_ram ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
- int(* opencl_to_cuda ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
- int(* opencl_to_opencl ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
- int(* mic_to_ram ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
- int(* ram_to_mpi_ms ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
- int(* mpi_ms_to_ram ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
- int(* mpi_ms_to_mpi_ms ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
- int(* ram_to_cuda_async ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, starpu_cudaStream_t stream)
- int(* cuda_to_ram_async ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, starpu_cudaStream_t stream)
- int(* cuda_to_cuda_async ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, starpu_cudaStream_t stream)
- int(* ram_to_opencl_async ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, cl_event *event)
- int(* opencl_to_ram_async ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, cl_event *event)
- int(* opencl_to_opencl_async ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, cl_event *event)
- int(* ram_to_mpi_ms_async ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, void *event)
- int(* mpi_ms_to_ram_async ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, void *event)
- int(* mpi_ms_to_mpi_ms_async ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, void *event)
- int(* ram_to_mic_async ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
- int(* mic_to_ram_async ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
- int(* any_to_any ) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, void *async_data)

30.9.2.1.1 Field Documentation

30.9.2.1.1.1 can_copy

int(* starpu_data_copy_methods::can_copy) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, void *handling_node)

If defined, allow the interface to declare whether it supports transferring from src_interface on node src_node to dst_interface on node dst_node, run from node handling_node. If not defined, it is assumed that the interface supports all transfers.

30.9.2.1.2 ram_to_ram

int(* starpu_data_copy_methods::ram_to_ram) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)

Define how to copy data from the src_interface interface on the src_node CPU node to the dst_interface interface on the dst_node CPU node. Return 0 on success.

30.9.2.1.3 ram_to_cuda

int(* starpu_data_copy_methods::ram_to_cuda) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)

Define how to copy data from the src_interface interface on the src_node CPU node to the dst_interface interface on the dst_node CUDA node. Return 0 on success.

30.9.2.1.4 ram_to_opencl

int(* starpu_data_copy_methods::ram_to_opencl) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)

Define how to copy data from the src_interface interface on the src_node CPU node to the dst_interface interface on the dst_node OpenCL node. Return 0 on success.

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30.9.2.1.5 ram_to_mic

```c
int(* starpu_data_copy_methods::ram_to_mic)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
```

Define how to copy data from the src_interface interface on the src_node CPU node to the dst_node MIC node. Return 0 on success.

30.9.2.1.6 cuda_to_ram

```c
int(* starpu_data_copy_methods::cuda_to_ram)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
```

Define how to copy data from the src_interface interface on the src_node CUDA node to the dst_node CPU node. Return 0 on success.

30.9.2.1.7 cuda_to_cuda

```c
int(* starpu_data_copy_methods::cuda_to_cuda)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
```

Define how to copy data from the src_interface interface on the src_node CUDA node to the dst_node CUDA node. Return 0 on success.

30.9.2.1.8 cuda_to_opencl

```c
int(* starpu_data_copy_methods::cuda_to_opencl)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
```

Define how to copy data from the src_interface interface on the src_node CUDA node to the dst_node OpenCL node. Return 0 on success.

30.9.2.1.9 opencl_to_ram

```c
int(* starpu_data_copy_methods::opencl_to_ram)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
```

Define how to copy data from the src_interface interface on the src_node OpenCL node to the dst_node CPU node. Return 0 on success.

30.9.2.1.10 opencl_to_cuda

```c
int(* starpu_data_copy_methods::opencl_to_cuda)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
```

Define how to copy data from the src_interface interface on the src_node OpenCL node to the dst_node CUDA node. Return 0 on success.

30.9.2.1.11 opencl_to_opencl

```c
int(* starpu_data_copy_methods::opencl_to_opencl)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
```

Define how to copy data from the src_interface interface on the src_node OpenCL node to the dst_node OpenCL node. Return 0 on success.

30.9.2.1.12 mic_to_ram

```c
int(* starpu_data_copy_methods::mic_to_ram)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
```

Define how to copy data from the src_interface interface on the src_node MIC node to the dst_node CPU node. Return 0 on success.

30.9.2.1.13 ram_to mpi_ms

```c
int(* starpu_data_copy_methods::ram_to_mpi_ms)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
```

Define how to copy data from the src_interface interface on the src_node CPU node to the dst_node MPI Slave node. Return 0 on success.

30.9.2.1.14 mpi_ms_to_ram

```c
int(* starpu_data_copy_methods::mpi_ms_to_ram)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
```

Define how to copy data from the src_interface interface on the src_node MPI Slave node to the dst_node CPU node. Return 0 on success.
30.9 Data Interfaces

30.9.2.1.15 mpi_ms_to_mpi_ms

```c
int (* starpu_data_copy_methods::mpi_ms_to_mpi_ms) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
```

Define how to copy data from the src_interface interface on the src_node MPI Slave node to the dst_interface interface on the dst_node MPI Slave node. Return 0 on success.

30.9.2.1.16 ram_to_cuda_async

```c
int (* starpu_data_copy_methods::ram_to_cuda_async) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, starpu_cudaStream_t stream)
```

Define how to copy data from the src_interface interface on the src_node CPU node to the dst_interface interface on the dst_node CUDA node, using the given stream. Must return 0 if the transfer was actually completed completely synchronously, or -EAGAIN if at least some transfers are still ongoing and should be awaited for by the core.

30.9.2.1.17 cuda_to_ram_async

```c
int (* starpu_data_copy_methods::cuda_to_ram_async) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, starpu_cudaStream_t stream)
```

Define how to copy data from the src_interface interface on the src_node CUDA node to the dst_interface interface on the dst_node CPU node, using the given stream. Must return 0 if the transfer was actually completed completely synchronously, or -EAGAIN if at least some transfers are still ongoing and should be awaited for by the core.

30.9.2.1.18 cuda_to_cuda_async

```c
int (* starpu_data_copy_methods::cuda_to_cuda_async) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, starpu_cudaStream_t stream)
```

Define how to copy data from the src_interface interface on the src_node CUDA node to the dst_interface interface on the dst_node CUDA node, using the given stream. Must return 0 if the transfer was actually completed completely synchronously, or -EAGAIN if at least some transfers are still ongoing and should be awaited for by the core.

30.9.2.1.19 ram_to_opencl_async

```c
int (* starpu_data_copy_methods::ram_to_opencl_async) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, starpu_cudaStream_t stream)
```

Define how to copy data from the src_interface interface on the src_node CPU node to the dst_interface interface on the dst_node OpenCL node, by recording in event, a pointer to a cl_event, the event of the last submitted transfer. Must return 0 if the transfer was actually completed completely synchronously, or -EAGAIN if at least some transfers are still ongoing and should be awaited for by the core.

30.9.2.1.20 opencl_to_ram_async

```c
int (* starpu_data_copy_methods::opencl_to_ram_async) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, cl_event *event)
```

Define how to copy data from the src_interface interface on the src_node OpenCL node to the dst_interface interface on the dst_node CPU node, by recording in event, a pointer to a cl_event, the event of the last submitted transfer. Must return 0 if the transfer was actually completed completely synchronously, or -EAGAIN if at least some transfers are still ongoing and should be awaited for by the core.

30.9.2.1.21 opencl_to_opencl_async

```c
int (* starpu_data_copy_methods::opencl_to_opencl_async) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, cl_event *event)
```

Define how to copy data from the src_interface interface on the src_node OpenCL node to the dst_interface interface on the dst_node OpenCL node, by recording in event, a pointer to a cl_event, the event of the last submitted transfer. Must return 0 if the transfer was actually completed completely synchronously, or -EAGAIN if at least some transfers are still ongoing and should be awaited for by the core.

30.9.2.1.22 ram_to_mpi_ms_async

```c
int (* starpu_data_copy_methods::ram_to_mpi_ms_async) (void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, void *event)
```

Define how to copy data from the src_interface interface on the src_node CPU node to the dst_interface interface on the dst_node MPI Slave node, with the given even. Must return 0 if the transfer was...
actually completed completely synchronously, or \texttt{-EAGAIN} if at least some transfers are still ongoing and should be awaited for by the core.

\texttt{30.9.2.1.1.23 mpi\_ms\_to\_ram\_async}

\begin{verbatim}
int(* starpu_data_copy_methods::mpi_ms_to_ram_async)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, void *event)
\end{verbatim}

Define how to copy data from the \texttt{src\_interface} interface on the \texttt{src\_node} MPI Slave node to the \texttt{dst\_interface} interface on the \texttt{dst\_node} CPU node, with the given event. Must return 0 if the transfer was actually completed completely synchronously, or \texttt{-EAGAIN} if at least some transfers are still ongoing and should be awaited for by the core.

\texttt{30.9.2.1.1.24 mpi\_ms\_to\_mpi\_ms\_async}

\begin{verbatim}
int(* starpu_data_copy_methods::mpi_ms_to_mpi_ms_async)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, void *event)
\end{verbatim}

Define how to copy data from the \texttt{src\_interface} interface on the \texttt{src\_node} MPI Slave node to the \texttt{dst\_interface} interface on the \texttt{dst\_node} MPI Slave node, using the given stream. Must return 0 if the transfer was actually completed completely synchronously, or \texttt{-EAGAIN} if at least some transfers are still ongoing and should be awaited for by the core.

\texttt{30.9.2.1.1.25 ram\_to\_mic\_async}

\begin{verbatim}
int(* starpu_data_copy_methods::ram_to_mic_async)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
\end{verbatim}

Define how to copy data from the \texttt{src\_interface} interface on the \texttt{src\_node} CPU node to the \texttt{dst\_interface} interface on the \texttt{dst\_node} MIC node. Must return 0 if the transfer was actually completed completely synchronously, or \texttt{-EAGAIN} if at least some transfers are still ongoing and should be awaited for by the core.

\texttt{30.9.2.1.1.26 mic\_to\_ram\_async}

\begin{verbatim}
int(* starpu_data_copy_methods::mic_to_ram_async)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node)
\end{verbatim}

Define how to copy data from the \texttt{src\_interface} interface on the \texttt{src\_node} MIC node to the \texttt{dst\_interface} interface on the \texttt{dst\_node} CPU node. Must return 0 if the transfer was actually completed completely synchronously, or \texttt{-EAGAIN} if at least some transfers are still ongoing and should be awaited for by the core.

\texttt{30.9.2.1.1.27 any\_to\_any}

\begin{verbatim}
int(* starpu_data_copy_methods::any_to_any)(void *src_interface, unsigned src_node, void *dst_interface, unsigned dst_node, void *async_data)
\end{verbatim}

Define how to copy data from the \texttt{src\_interface} interface on the \texttt{src\_node} node to the \texttt{dst\_interface} interface on the \texttt{dst\_node} node. This is meant to be implemented through the \texttt{starpu\_interface\_copy()} helper, to which \texttt{async\_data} should be passed as such, and will be used to manage asynchronicity. This must return \texttt{-EAGAIN} if any of the \texttt{starpu\_interface\_copy()} calls has returned \texttt{-EAGAIN} (i.e. at least some transfer is still ongoing), and return 0 otherwise. This can only be implemented if the interface has ready-to-send data blocks. If the interface is more involved than this, i.e. it needs to collect pieces of data before transferring, \texttt{starpu\_data\_interface\_ops::pack\_data} and \texttt{starpu\_data\_interface\_ops::unpack\_data} should be implemented instead, and the core will just transfer the resulting data buffer.

\texttt{30.9.2.2 struct starpu\_data\_interface\_ops}

Per-interface data management methods.

Data Fields

\begin{itemize}
\item \texttt{void(* register\_data\_handle)(starpu\_data\_handle_t handle, unsigned home\_node, void *data\_interface)}
\item \texttt{starpu\_ssize\_t(* allocate\_data\_on\_node)(void *data\_interface, unsigned node)}
\item \texttt{void(* free\_data\_on\_node)(void *data\_interface, unsigned node)}
\item \texttt{void(* init)(void *data\_interface)}
\item \texttt{const struct starpu\_data\_copy\_methods * copy\_methods}
\end{itemize}
30.9 Data Interfaces

- `void (*)(starpu_data_handle_t handle, unsigned node)`
- `void (*)(void *data_interface, unsigned node)`
- `int (*)(void *data_interface, unsigned node, void *ptr)`
- `size_t (*)(starpu_data_handle_t handle)`
- `size_t (*)(starpu_data_handle_t handle)`
- `uint32_t (*)(starpu_data_handle_t handle)`
- `uint32_t (*)(starpu_data_handle_t handle)`
- `int (*)(void *data_interface_a, void *data_interface_b)`
- `int (*)(void *data_interface_a, void *data_interface_b)`
- `void (*)(starpu_data_handle_t handle, FILE *)`
- `starpu_ssize_t (*)(void *data_interface, char *buf, size_t size)`
- `enum starpu_data_interface_id interfaceid`
- `size_t interface_size`
- `char is_multiformat`
- `char dontcache`
- `struct starpu_multiformat_data_interface_ops *(*get_mf_ops)(void *data_interface)`
- `int (*)(starpu_data_handle_t handle, unsigned node, void **ptr, starpu_ssize_t *count)`
- `int (*)(starpu_data_handle_t handle, unsigned node, void *ptr, size_t count)`
- `char *name`

### 30.9.2.2.1 Field Documentation

#### 30.9.2.2.1.1 register_data_handle

```c
void(* starpu_data_interface_ops::register_data_handle) (starpu_data_handle_t handle, unsigned home_node, void *data_interface)
```

Register an existing interface into a data handle.

This iterates over all memory nodes to initialize all fields of the data interface on each of them. Since data is not allocated yet except on the home node, pointers should be left as NULL except on the `home_node`, for which the pointers should be copied from the given `data_interface`, which was filled with the application's pointers.

This method is mandatory.

#### 30.9.2.2.1.2 allocate_data_on_node

```c
starpu_ssize_t(* starpu_data_interface_ops::allocate_data_on_node) (void *data_interface, unsigned node)
```

Allocate data for the interface on a given node. This should use `starpu_malloc_on_node()` to perform the allocation(s), and fill the pointers in the data interface. It should return the size of the allocated memory, or -ENOMEM if memory could not be allocated.

Note that the memory node can be CPU memory, GPU memory, or even disk area. The result returned by `starpu_malloc_on_node()` should be just stored as uintptr_t without trying to interpret it since it may be a GPU pointer, a disk descriptor, etc.

This method is mandatory to be able to support memory nodes.

#### 30.9.2.2.1.3 free_data_on_node

```c
void(* starpu_data_interface_ops::free_data_on_node) (void *data_interface, unsigned node)
```

Free data of the interface on a given node.

This method is mandatory to be able to support memory nodes.

#### 30.9.2.2.1.4 init

```c
void(* starpu_data_interface_ops::init) (void *data_interface)
```

Initialize the interface. This method is optional. It is called when initializing the handler on all the memory nodes.

#### 30.9.2.2.1.5 copy_methods

```c
const struct starpu_data_copy_methods* starpu_data_interface_ops::copy_methods
```

Struct with pointer to functions for performing ram/cuda/opencl synchronous and asynchronous transfers.

This field is mandatory to be able to support memory nodes, except disk nodes which can be supported by just implementing `starpu_data_interface_ops::pack_data` and `starpu_data_interface_ops::unpack_data`.

---

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30.9.2.2.1.6 handle_to_pointer

```c
void(* starpu_data_interface_ops::handle_to_pointer)(starpu_data_handle_t handle, unsigned node)
```

**Deprecated** Use `starpu_data_interface_ops::to_pointer` instead. Return the current pointer (if any) for the handle on the given node.

This method is only required if `starpu_data_interface_ops::to_pointer` is not implemented.

30.9.2.2.1.7 to_pointer

```c
void(* starpu_data_interface_ops::to_pointer)(void *data_interface, unsigned node)
```

Return the current pointer (if any) for the given interface on the given node.

This method is only required for `starpu_data_handle_to_pointer()` and `starpu_data_get_local_ptr()`, and for disk support.

30.9.2.2.1.8 pointer_is_inside

```c
int(* starpu_data_interface_ops::pointer_is_inside)(void *data_interface, unsigned node, void *ptr)
```

Return whether the given `ptr` is within the data for the given interface on the given node. This method is optional, as it is only used for coherency checks.

30.9.2.2.1.9 get_size

```c
size_t(* starpu_data_interface_ops::get_size)(starpu_data_handle_t handle)
```

Return an estimation of the size of data, for performance models and tracing feedback.

30.9.2.2.1.10 get_alloc_size

```c
size_t(* starpu_data_interface_ops::get_alloc_size)(starpu_data_handle_t handle)
```

Return an estimation of the size of allocated data, for allocation management. If not specified, the `starpu_data_interface_ops::get_size` method is used instead.

30.9.2.2.1.11 footprint

```c
uint32_t(* starpu_data_interface_ops::footprint)(starpu_data_handle_t handle)
```

Return a 32bit footprint which characterizes the data size and layout (nx, ny, ld, elemsize, etc.), required for indexing performance models. `starpu_hash_crc32c_be()` and alike can be used to produce this 32bit value from various types of values.

30.9.2.2.1.12 alloc_footprint

```c
uint32_t(* starpu_data_interface_ops::alloc_footprint)(starpu_data_handle_t handle)
```

Return a 32bit footprint which characterizes the data allocation, to be used for indexing allocation cache. If not specified, the `starpu_data_interface_ops::footprint` method is used instead.

30.9.2.2.1.13 compare

```c
int(* starpu_data_interface_ops::compare)(void *data_interface_a, void *data_interface_b)
```

Compare the data size and layout of two interfaces (nx, ny, ld, elemsize, etc.), to be used for indexing performance models. It should return 1 if the two interfaces size and layout match computation-wise, and 0 otherwise.

30.9.2.2.1.14 alloc_compare

```c
int(* starpu_data_interface_ops::alloc_compare)(void *data_interface_a, void *data_interface_b)
```

Compare the data allocation of two interfaces etc.), to be used for indexing allocation cache. It should return 1 if the two interfaces are allocation-compatible, i.e. basically have the same alloc_size, and 0 otherwise. If not specified, the `starpu_data_interface_ops::compare` method is used instead.

30.9.2.2.1.15 display

```c
void(* starpu_data_interface_ops::display)(starpu_data_handle_t handle, FILE *f)
```

Dump the sizes of a handle to a file. This is required for performance models.

30.9.2.2.1.16 describe

```c
starpu_ssize_t(* starpu_data_interface_ops::describe)(void *data_interface, char *buf, size_t size)
```

Describe the data into a string in a brief way, such as one letter to describe the type of data, and the data dimensions.
This is required for tracing feedback.

30.9.2.2.1.17 interfaceid

enum starpu_data_interface_id starpu_data_interface_ops::interfaceid

An identifier that is unique to each interface.

30.9.2.2.1.18 interface_size

size_t starpu_data_interface_ops::interface_size

Size of the interface data descriptor.

30.9.2.2.1.19 dontcache

char starpu_data_interface_ops::dontcache

If set to non-zero, StarPU will never try to reuse an allocated buffer for a different handle. This can be notably useful for application-defined interfaces which have a dynamic size, and for which it thus does not make sense to reuse the buffer since will probably not have the proper size.

30.9.2.2.1.20 pack_data

int(* starpu_data_interface_ops::pack_data) (starpu_data_handle_t handle, unsigned node, void **ptr, size_t *count)

Pack the data handle into a contiguous buffer at the address allocated with starpu_malloc_flags(ptr, size, 0) (and thus returned in ptr) and set the size of the newly created buffer in count. If ptr is NULL, the function should not copy the data in the buffer but just set count to the size of the buffer which would have been allocated. The special value -1 indicates the size is yet unknown.

This method (and starpu_data_interface_ops::unpack_data) is required for disk support if the starpu_data_copy←_methods::any_to_any method is not implemented (because the in-memory data layout is too complex). This is also required for MPI support if there is no registered MPI data type.

30.9.2.2.1.21 unpack_data

int(* starpu_data_interface_ops::unpack_data) (starpu_data_handle_t handle, unsigned node, void *ptr, size_t count)

Unpack the data handle from the contiguous buffer at the address ptr of size count. The memory at the address ptr should be freed after the data unpacking operation.

30.9.2.2.1.22 name

char* starpu_data_interface_ops::name

Name of the interface

30.9.2.3 struct starpu_matrix_interface

Matrix interface for dense matrices

Data Fields

<table>
<thead>
<tr>
<th>enum starpu_data_interface_id</th>
<th>id</th>
<th>Identifier of the interface</th>
</tr>
</thead>
<tbody>
<tr>
<td>uintptr_t</td>
<td>ptr</td>
<td>local pointer of the matrix</td>
</tr>
<tr>
<td>uintptr_t</td>
<td>dev_handle</td>
<td>device handle of the matrix</td>
</tr>
<tr>
<td>size_t</td>
<td>offset</td>
<td>offset in the matrix</td>
</tr>
<tr>
<td>uint32_t</td>
<td>nx</td>
<td>number of elements on the x-axis of the matrix</td>
</tr>
<tr>
<td>uint32_t</td>
<td>ny</td>
<td>number of elements on the y-axis of the matrix</td>
</tr>
<tr>
<td>uint32_t</td>
<td>ld</td>
<td>number of elements between each row of the matrix. Maybe be equal to starpu_matrix_interface::nx when there is no padding.</td>
</tr>
<tr>
<td>size_t</td>
<td>elemsize</td>
<td>size of the elements of the matrix</td>
</tr>
<tr>
<td>size_t</td>
<td>allocsize</td>
<td>size actually currently allocated</td>
</tr>
</tbody>
</table>
### 30.9.2.4 struct starpu_coo_interface

**COO Matrices**

Data Fields

<table>
<thead>
<tr>
<th>Field Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>enum</td>
<td><code>starpu_data_interface_id</code></td>
<td>id</td>
</tr>
<tr>
<td><code>uint32_t*</code></td>
<td><code>columns</code></td>
<td>columns array of the matrix</td>
</tr>
<tr>
<td><code>uint32_t*</code></td>
<td><code>rows</code></td>
<td>row array of the matrix</td>
</tr>
<tr>
<td><code>uintptr_t</code></td>
<td><code>values</code></td>
<td>values of the matrix</td>
</tr>
<tr>
<td><code>uint32_t</code></td>
<td><code>nx</code></td>
<td>number of elements on the x-axis of the matrix</td>
</tr>
<tr>
<td><code>uint32_t</code></td>
<td><code>ny</code></td>
<td>number of elements on the y-axis of the matrix</td>
</tr>
<tr>
<td><code>uint32_t</code></td>
<td><code>n_values</code></td>
<td>number of values registered in the matrix</td>
</tr>
<tr>
<td><code>size_t</code></td>
<td><code>elemsize</code></td>
<td>size of the elements of the matrix</td>
</tr>
</tbody>
</table>

### 30.9.2.5 struct starpu_block_interface

**Block interface for 3D dense blocks**

Data Fields

<table>
<thead>
<tr>
<th>Field Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>enum</td>
<td><code>starpu_data_interface_id</code></td>
<td>id</td>
</tr>
<tr>
<td><code>uintptr_t</code></td>
<td><code>ptr</code></td>
<td>local pointer of the block</td>
</tr>
<tr>
<td><code>uintptr_t</code></td>
<td><code>dev_handle</code></td>
<td>device handle of the block</td>
</tr>
<tr>
<td><code>size_t</code></td>
<td><code>offset</code></td>
<td>offset in the block</td>
</tr>
<tr>
<td><code>uint32_t</code></td>
<td><code>nx</code></td>
<td>number of elements on the x-axis of the block</td>
</tr>
<tr>
<td><code>uint32_t</code></td>
<td><code>ny</code></td>
<td>number of elements on the y-axis of the block</td>
</tr>
<tr>
<td><code>uint32_t</code></td>
<td><code>nz</code></td>
<td>number of elements on the z-axis of the block</td>
</tr>
<tr>
<td><code>uint32_t</code></td>
<td><code>ldy</code></td>
<td>number of elements between two lines</td>
</tr>
<tr>
<td><code>uint32_t</code></td>
<td><code>ldz</code></td>
<td>number of elements between two planes</td>
</tr>
<tr>
<td><code>size_t</code></td>
<td><code>elemsize</code></td>
<td>size of the elements of the block</td>
</tr>
</tbody>
</table>

### 30.9.2.6 struct starpu_vector_interface

Data Fields

<table>
<thead>
<tr>
<th>Field Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>enum</td>
<td><code>starpu_data_interface_id</code></td>
<td>id</td>
</tr>
<tr>
<td><code>uintptr_t</code></td>
<td><code>ptr</code></td>
<td>local pointer of the vector</td>
</tr>
<tr>
<td><code>uintptr_t</code></td>
<td><code>dev_handle</code></td>
<td>device handle of the vector</td>
</tr>
<tr>
<td><code>size_t</code></td>
<td><code>offset</code></td>
<td>offset in the vector</td>
</tr>
<tr>
<td><code>uint32_t</code></td>
<td><code>nx</code></td>
<td>number of elements on the x-axis of the vector</td>
</tr>
<tr>
<td><code>size_t</code></td>
<td><code>elemsize</code></td>
<td>size of the elements of the vector</td>
</tr>
<tr>
<td><code>size_t</code></td>
<td><code>slice_base</code></td>
<td>vector slice base, used by the StarPU OpenMP runtime support</td>
</tr>
<tr>
<td><code>size_t</code></td>
<td><code>allocsize</code></td>
<td>size actually currently allocated</td>
</tr>
</tbody>
</table>

### 30.9.2.7 struct starpu_variable_interface

**Variable interface for a single data (not a vector, a matrix, a list, ...)**

Data Fields

<table>
<thead>
<tr>
<th>Field Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>enum</td>
<td><code>starpu_data_interface_id</code></td>
<td>id</td>
</tr>
</tbody>
</table>
Data Fields

| `uintptr_t` | `ptr` | local pointer of the variable |
| `uintptr_t` | `dev_handle` | device handle of the variable. |
| `size_t` | `offset` | offset in the variable |
| `size_t` | `elemsize` | size of the variable |

30.9.2.8 struct `starpu_csr_interface`

CSR interface for sparse matrices (compressed sparse row representation)

Data Fields

| `enum starpu_data_interface_id` | `id` | Identifier of the interface |
| `uint32_t` | `nnz` | number of non-zero entries |
| `uint32_t` | `nrow` | number of rows |
| `uintptr_t` | `nzval` | non-zero values |
| `uint32_t` | `colind` | position of non-zero entries on the row |
| `uint32_t` | `rowptr` | index (in nzval) of the first entry of the row |
| `uint32_t` | `firstentry` | k for k-based indexing (0 or 1 usually). Also useful when partitionning the matrix. |
| `size_t` | `elemsize` | size of the elements of the matrix |

30.9.2.9 struct `starpu_bcsr_interface`

BCSR interface for sparse matrices (blocked compressed sparse row representation)

Data Fields

| `enum starpu_data_interface_id` | `id` | Identifier of the interface |
| `uint32_t` | `nnz` | number of non-zero BLOCKS |
| `uint32_t` | `nrow` | number of rows (in terms of BLOCKS) |
| `uintptr_t` | `nzval` | non-zero values |
| `uint32_t` | `colind` | array of `nnz` elements, `colind[i]` is the block-column index for block `i` in `nzval` |
| `uint32_t` | `rowptr` | array of `nrow+1` elements, `rowptr[i]` is the block-index (in `nzval`) of the first block of row `i`. By convention, `rowptr[nrow]` is the number of blocks, this allows an easier access of the matrix's elements for the kernels. |
| `uint32_t` | `firstentry` | k for k-based indexing (0 or 1 usually). Also useful when partitionning the matrix. |
| `uint32_t` | `r` | height of the blocks |
| `uint32_t` | `c` | width of the blocks |
| `size_t` | `elemsize` | size of the elements of the matrix |

30.9.2.10 struct `starpu_multiformat_data_interface_ops`

Multiformat operations

Data Fields

| `size_t` | `cpu elemsize` | size of each element on CPUs |

Generated by Doxygen
### Data Fields

<table>
<thead>
<tr>
<th>size_t</th>
<th>opencl_elemsize</th>
<th>size of each element on OpenCL devices</th>
</tr>
</thead>
<tbody>
<tr>
<td>struct starpu_codelet *</td>
<td>cpu_to_opencl_cl</td>
<td>pointer to a codelet which converts from CPU to OpenCL</td>
</tr>
<tr>
<td>struct starpu_codelet *</td>
<td>opencl_to_cpu_cl</td>
<td>pointer to a codelet which converts from OpenCL to CPU</td>
</tr>
<tr>
<td>size_t</td>
<td>cuda_elemsize</td>
<td>size of each element on CUDA devices</td>
</tr>
<tr>
<td>struct starpu_codelet *</td>
<td>cpu_to_cuda_cl</td>
<td>pointer to a codelet which converts from CPU to CUDA</td>
</tr>
<tr>
<td>struct starpu_codelet *</td>
<td>cuda_to_cpu_cl</td>
<td>pointer to a codelet which converts from CUDA to CPU</td>
</tr>
<tr>
<td>size_t</td>
<td>mic_elemsize</td>
<td>size of each element on MIC devices</td>
</tr>
<tr>
<td>struct starpu_codelet *</td>
<td>cpu_to_mic_cl</td>
<td>pointer to a codelet which converts from CPU to MIC</td>
</tr>
<tr>
<td>struct starpu_codelet *</td>
<td>mic_to_cpu_cl</td>
<td>pointer to a codelet which converts from MIC to CPU</td>
</tr>
</tbody>
</table>

#### 30.9.2.11 struct starpu_multiformat_interface

### Data Fields

<table>
<thead>
<tr>
<th>enum starpu_data_interface_id</th>
<th>id</th>
</tr>
</thead>
<tbody>
<tr>
<td>void *</td>
<td>cpu_ptr</td>
</tr>
<tr>
<td>void *</td>
<td>cuda_ptr</td>
</tr>
<tr>
<td>void *</td>
<td>opencl_ptr</td>
</tr>
<tr>
<td>void *</td>
<td>mic_ptr</td>
</tr>
<tr>
<td>uint32_t</td>
<td>nx</td>
</tr>
</tbody>
</table>

| struct starpu_multiformat_data_interface_ops * | ops |

### 30.9.3 Macro Definition Documentation

#### 30.9.3.1 STARPU_MATRIX_GET_PTR

```c
#define STARPU_MATRIX_GET_PTR( interface )
```

Return a pointer to the matrix designated by `interface`, valid on CPUs and CUDA devices only. For OpenCL devices, the device handle and offset need to be used instead.

#### 30.9.3.2 STARPU_MATRIX_GET_DEV_HANDLE

```c
#define STARPU_MATRIX_GET_DEV_HANDLE( interface )
```

Return a device handle for the matrix designated by `interface`, to be used with OpenCL. The offset returned by `STARPU_MATRIX_GET_OFFSET` has to be used in addition to this.

#### 30.9.3.3 STARPU_MATRIX_GET_OFFSET

```c
#define STARPU_MATRIX_GET_OFFSET( interface )
```

Return the offset in the matrix designated by `interface`, to be used with the device handle.

#### 30.9.3.4 STARPU_MATRIX_GET_NX

```c
#define STARPU_MATRIX_GET_NX( interface )
```

Return the number of elements on the x-axis of the matrix designated by `interface`. 

---

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30.9.3.5 STARPU_MATRIX_GET_NY

#define STARPU_MATRIX_GET_NY(interface)  

Return the number of elements on the y-axis of the matrix designated by interface.

30.9.3.6 STARPU_MATRIX_GET_LD

#define STARPU_MATRIX_GET_LD(interface)  

Return the number of elements between each row of the matrix designated by interface. May be equal to nx when there is no padding.

30.9.3.7 STARPU_MATRIX_GET_ELEMSIZE

#define STARPU_MATRIX_GET_ELEMSIZE(interface)  

Return the size of the elements registered into the matrix designated by interface.

30.9.3.8 STARPU_MATRIX_GET_ALLOCSIZE

#define STARPU_MATRIX GET_ALLOCSIZE(interface)  

Return the allocated size of the matrix designated by interface.

30.9.3.9 STARPU_MATRIX_SET_NX

#define STARPU_MATRIX_SET_NX(interface, newnx)  

Set the number of elements on the x-axis of the matrix designated by interface.

30.9.3.10 STARPU_MATRIX_SET_NY

#define STARPU_MATRIX_SET_NY(interface, newny)  

Set the number of elements on the y-axis of the matrix designated by interface.

30.9.3.11 STARPU_MATRIX_SET_LD

#define STARPU_MATRIX_SET_LD(interface, newld)  

Set the number of elements between each row of the matrix designated by interface. May be set to the same value as nx when there is no padding.

30.9.3.12 STARPU_COO_GET_COLUMNS

#define STARPU_COO_GET_COLUMNS(interface)  

Return a pointer to the column array of the matrix designated by interface.

30.9.3.13 STARPU_COO_GET_COLUMNS_DEV_HANDLE

#define STARPU_COO_GET_COLUMNS_DEV_HANDLE(interface)  

Return a device handle for the column array of the matrix designated by interface, to be used with OpenCL. The offset returned by STARPU_COO_GET_OFFSET has to be used in addition to this.
30.9.3.14 STARPU_COO_GET_ROWS

#define STARPU_COO_GET_ROWS(
    interface
)  
Return a pointer to the rows array of the matrix designated by interface.

30.9.3.15 STARPU_COO_GET_ROWS_DEV_HANDLE

#define STARPU_COO_GET_ROWS_DEV_HANDLE(
    interface
)  
Return a device handle for the row array of the matrix designated by interface, to be used on OpenCL. The offset returned by STARPU_COO_GET_OFFSET has to be used in addition to this.

30.9.3.16 STARPU_COO_GET_VALUES

#define STARPU_COO_GET_VALUES(
    interface
)  
Return a pointer to the values array of the matrix designated by interface.

30.9.3.17 STARPU_COO_GET_VALUES_DEV_HANDLE

#define STARPU_COO_GET_VALUES_DEV_HANDLE(
    interface
)  
Return a device handle for the value array of the matrix designated by interface, to be used on OpenCL. The offset returned by STARPU_COO_GET_OFFSET has to be used in addition to this.

30.9.3.18 STARPU_COO_GET_OFFSET

#define STARPU_COO_GET_OFFSET  
Return the offset in the arrays of the COO matrix designated by interface.

30.9.3.19 STARPU_COO_GET_NX

#define STARPU_COO_GET_NX(
    interface
)  
Return the number of elements on the x-axis of the matrix designated by interface.

30.9.3.20 STARPU_COO_GET_NY

#define STARPU_COO_GET_NY(
    interface
)  
Return the number of elements on the y-axis of the matrix designated by interface.

30.9.3.21 STARPU_COO_GET_NVALUES

#define STARPU_COO_GET_NVALUES(
    interface
)  
Return the number of values registered in the matrix designated by interface.

30.9.3.22 STARPU_COO_GET_ELEMSIZE

#define STARPU_COO_GET_ELEMSIZE(
    interface
)  
Return the size of the elements registered into the matrix designated by interface.

30.9.3.23 STARPU_BLOCK_GET_PTR

#define STARPU_BLOCK_GET_PTR(
    interface
)  
Return a pointer to the block designated by interface.
### 30.9.3.24 STARPU_BLOCK_GET_DEV_HANDLE

#define STARPU_BLOCK_GET_DEV_HANDLE(interface)  
Return a device handle for the block designated by interface, to be used on OpenCL. The offset returned by STARPU_BLOCK_GET_OFFSET has to be used in addition to this.

### 30.9.3.25 STARPU_BLOCK_GET_OFFSET

#define STARPU_BLOCK_GET_OFFSET(interface)  
Return the offset in the block designated by interface, to be used with the device handle.

### 30.9.3.26 STARPU_BLOCK_GET_NX

#define STARPU_BLOCK_GET_NX(interface)  
Return the number of elements on the x-axis of the block designated by interface.

### 30.9.3.27 STARPU_BLOCK_GET_NY

#define STARPU_BLOCK_GET_NY(interface)  
Return the number of elements on the y-axis of the block designated by interface.

### 30.9.3.28 STARPU_BLOCK_GET_NZ

#define STARPU_BLOCK_GET_NZ(interface)  
Return the number of elements on the z-axis of the block designated by interface.

### 30.9.3.29 STARPU_BLOCK_GET_LDY

#define STARPU_BLOCK_GET_LDY(interface)  
Return the number of elements between each row of the block designated by interface. May be equal to nx when there is no padding.

### 30.9.3.30 STARPU_BLOCK_GET_LDZ

#define STARPU_BLOCK_GET_LDZ(interface)  
Return the number of elements between each z plane of the block designated by interface. May be equal to nx*ny when there is no padding.

### 30.9.3.31 STARPU_BLOCK_GET_ELEMSIZE

#define STARPU_BLOCK_GET_ELEMSIZE(interface)  
Return the size of the elements of the block designated by interface.

### 30.9.3.32 STARPU_VECTOR_GET_PTR

#define STARPU_VECTOR_GET_PTR(interface)  
Return a pointer to the array designated by interface, valid on CPUs and CUDA only. For OpenCL, the device handle and offset need to be used instead.
30.9.3.33  STARPU_VECTOR_GET_DEV_HANDLE

#define STARPU_VECTOR_GET_DEV_HANDLE(interface)

Return a device handle for the array designated by interface, to be used with OpenCL. The offset returned by STARPU_VECTOR_GET_OFFSET has to be used in addition to this.

30.9.3.34  STARPU_VECTOR_GET_OFFSET

#define STARPU_VECTOR_GET_OFFSET(interface)

Return the offset in the array designated by interface, to be used with the device handle.

30.9.3.35  STARPU_VECTOR_GET_NX

#define STARPU_VECTOR_GET_NX(interface)

Return the number of elements registered into the array designated by interface.

30.9.3.36  STARPU_VECTOR_GET_ELEMSIZE

#define STARPU_VECTOR_GET_ELEMSIZE(interface)

Return the size of each element of the array designated by interface.

30.9.3.37  STARPU_VECTOR_GET_ALLOCSIZE

#define STARPU_VECTOR_GET_ALLOCSIZE(interface)

Return the size of each element of the array designated by interface.

30.9.3.38  STARPU_VECTOR_GET_SLICE_BASE

#define STARPU_VECTOR_GET_SLICE_BASE(interface)

Return the OpenMP slice base annotation of each element of the array designated by interface.

30.9.3.39  STARPU_VECTOR_SET_NX

#define STARPU_VECTOR_SET_NX(interface, newnx)

Set the number of elements registered into the array designated by interface.

30.9.3.40  STARPU_VARIABLE_GET_PTR

#define STARPU_VARIABLE_GET_PTR(interface)

Return a pointer to the variable designated by interface.

30.9.3.41  STARPU_VARIABLE_GET_OFFSET

#define STARPU_VARIABLE_GET_OFFSET(interface)

Return the offset in the variable designated by interface, to be used with the device handle.

30.9.3.42  STARPU_VARIABLE_GET_ELEMSIZE

#define STARPU_VARIABLE_GET_ELEMSIZE(interface)

Return the size of the variable designated by interface.
30.9.3.43 STARPU_VARIABLE_GET_DEV_HANDLE

#define STARPU_VARIABLE_GET_DEV_HANDLE(
    interface
)

Return a device handle for the variable designated by interface, to be used with OpenCL. The offset returned by STARPU_VARIABLE_GET_OFFSET has to be used in addition to this.

30.9.3.44 STARPU_CSR_GET_NNZ

#define STARPU_CSR_GET_NNZ(
    interface
)

Return the number of non-zero values in the matrix designated by interface.

30.9.3.45 STARPU_CSR_GET_NROW

#define STARPU_CSR_GET_NROW(
    interface
)

Return the size of the row pointer array of the matrix designated by interface.

30.9.3.46 STARPU_CSR_GET_NZVAL

#define STARPU_CSR_GET_NZVAL(
    interface
)

Return a pointer to the non-zero values of the matrix designated by interface.

30.9.3.47 STARPU_CSR_GET_NZVAL_DEV_HANDLE

#define STARPU_CSR_GET_NZVAL_DEV_HANDLE(
    interface
)

Return a device handle for the array of non-zero values in the matrix designated by interface. The offset returned by STARPU_CSR_GET_OFFSET has to be used in addition to this.

30.9.3.48 STARPU_CSR_GET_COLIND

#define STARPU_CSR_GET_COLIND(
    interface
)

Return a pointer to the column index of the matrix designated by interface.

30.9.3.49 STARPU_CSR_GET_COLIND_DEV_HANDLE

#define STARPU_CSR_GET_COLIND_DEV_HANDLE(
    interface
)

Return a device handle for the column index of the matrix designated by interface. The offset returned by STARPU_CSR_GET_OFFSET has to be used in addition to this.

30.9.3.50 STARPU_CSR_GET_ROWPTR

#define STARPU_CSR_GET_ROWPTR(
    interface
)

Return a pointer to the row pointer array of the matrix designated by interface.

30.9.3.51 STARPU_CSR_GET_ROWPTR_DEV_HANDLE

#define STARPU_CSR_GET_ROWPTR_DEV_HANDLE(
    interface
)

Return a device handle for the row pointer array of the matrix designated by interface. The offset returned by STARPU_CSR_GET_OFFSET has to be used in addition to this.
30.9.3.52  **STARPU_CSR_GET_OFFSET**

#define STARPU_CSR_GET_OFFSET

Return the offset in the arrays (colind, rowptr, nzval) of the matrix designated by interface, to be used with the device handles.

30.9.3.53  **STARPU_CSR_GET_FIRSTENTRY**

#define STARPU_CSR_GET_FIRSTENTRY(interface)

Return the index at which all arrays (the column indexes, the row pointers...) of the interface start.

30.9.3.54  **STARPU_CSR_GET_ELEM_SIZE**

#define STARPU_CSR_GET_ELEM_SIZE(interface)

Return the size of the elements registered into the matrix designated by interface.

30.9.3.55  **STARPU_BCSR_GET_NNZ**

#define STARPU_BCSR_GET_NNZ(interface)

Return the number of non-zero values in the matrix designated by interface.

30.9.3.56  **STARPU_BCSR_GET_NZVAL**

#define STARPU_BCSR_GET_NZVAL(interface)

Return a pointer to the non-zero values of the matrix designated by interface.

30.9.3.57  **STARPU_BCSR_GET_NZVAL_DEV_HANDLE**

#define STARPU_BCSR_GET_NZVAL_DEV_HANDLE(interface)

Return a device handle for the array of non-zero values in the matrix designated by interface. The offset returned by STARPU_BCSR_GET_OFFSET has to be used in addition to this.

30.9.3.58  **STARPU_BCSR_GET_COLIND**

#define STARPU_BCSR_GET_COLIND(interface)

Return a pointer to the column index of the matrix designated by interface.

30.9.3.59  **STARPU_BCSR_GET_COLIND_DEV_HANDLE**

#define STARPU_BCSR_GET_COLIND_DEV_HANDLE(interface)

Return a device handle for the column index of the matrix designated by interface. The offset returned by STARPU_BCSR_GET_OFFSET has to be used in addition to this.

30.9.3.60  **STARPU_BCSR_GET_ROWPTR**

#define STARPU_BCSR_GET_ROWPTR(interface)

Return a pointer to the row pointer array of the matrix designated by interface.
30.9.3.61 STARPU_BCSR_GET_ROWPTR_DEV_HANDLE
#define STARPU_BCSR_GET_ROWPTR_DEV_HANDLE(
    interface )
Return a device handle for the row pointer array of the matrix designated by interface. The offset returned by STARPU_BCSR_GET_OFFSET has to be used in addition to this.

30.9.3.62 STARPU_BCSR_GET_OFFSET
#define STARPU_BCSR_GET_OFFSET
Return the offset in the arrays (coling, rowptr, nzval) of the matrix designated by interface, to be used with the device handles.

30.9.3.63 STARPU_MULTIFORMAT_GET_CPU_PTR
#define STARPU_MULTIFORMAT_GET_CPU_PTR(
    interface )
Return the local pointer to the data with CPU format.

30.9.3.64 STARPU_MULTIFORMAT_GET_CUDA_PTR
#define STARPU_MULTIFORMAT_GET_CUDA_PTR(
    interface )
Return the local pointer to the data with CUDA format.

30.9.3.65 STARPU_MULTIFORMAT_GET_OPENCL_PTR
#define STARPU_MULTIFORMAT_GET_OPENCL_PTR(
    interface )
Return the local pointer to the data with OpenCL format.

30.9.3.66 STARPU_MULTIFORMAT_GET_MIC_PTR
#define STARPU_MULTIFORMAT_GET_MIC_PTR(
    interface )
Return the local pointer to the data with MIC format.

30.9.3.67 STARPU_MULTIFORMAT_GET_NX
#define STARPU_MULTIFORMAT_GET_NX(
    interface )
Return the number of elements in the data.

30.9.4 Enumeration Type Documentation

30.9.4.1 starpu_data_interface_id
enum starpu_data_interface_id
Identifier for all predefined StarPU data interfaces

<table>
<thead>
<tr>
<th>Enumerator</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>STARPU_UNKNOWN_INTERFACE_ID</td>
<td>Unknown interface</td>
</tr>
<tr>
<td>STARPU_MATRIX_INTERFACE_ID</td>
<td>Identifier for the matrix data interface</td>
</tr>
<tr>
<td>STARPU_BLOCK_INTERFACE_ID</td>
<td>Identifier for the block data interface</td>
</tr>
<tr>
<td>STARPU_VECTOR_INTERFACE_ID</td>
<td>Identifier for the vector data interface</td>
</tr>
<tr>
<td>STARPU_CSR_INTERFACE_ID</td>
<td>Identifier for the CSR data interface</td>
</tr>
</tbody>
</table>
Module Documentation a.k.a StarPU's API

<table>
<thead>
<tr>
<th>Enumerator</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>STARPU_BCSR_INTERFACE_ID</td>
<td>Identifier for the BCSR data interface</td>
</tr>
<tr>
<td>STARPU_VARIABLE_INTERFACE_ID</td>
<td>Identifier for the variable data interface</td>
</tr>
<tr>
<td>STARPU_VOID_INTERFACE_ID</td>
<td>Identifier for the void data interface</td>
</tr>
<tr>
<td>STARPU_MULTIFORMAT_INTERFACE_ID</td>
<td>Identifier for the multiformat data interface</td>
</tr>
<tr>
<td>STARPU_COO_INTERFACE_ID</td>
<td>Identifier for the COO data interface</td>
</tr>
<tr>
<td>STARPU_MAX_INTERFACE_ID</td>
<td>Maximum number of data interfaces</td>
</tr>
</tbody>
</table>

30.9.5 Function Documentation

30.9.5.1 starpu_data_register()

```c
void starpu_data_register (  
    starpu_data_handle_t * handleptr,  
    int home_node,  
    void * data_interface,  
    struct starpu_data_interface_ops * ops)
```

Register a piece of data into the handle located at the handleptr address. The data_interface buffer contains the initial description of the data in the home_node. The ops argument is a pointer to a structure describing the different methods used to manipulate this type of interface. See starpu_data_interface_ops for more details on this structure. If home_node is -1, StarPU will automatically allocate the memory when it is used for the first time in write-only mode. Once such data handle has been automatically allocated, it is possible to access it using any access mode. Note that StarPU supplies a set of predefined types of interface (e.g. vector or matrix) which can be registered by the means of helper functions (e.g. starpu_vector_data_register() or starpu_matrix←data_register()).

30.9.5.2 starpu_data_ptr_register()

```c
void starpu_data_ptr_register (  
    starpu_data_handle_t handle,  
    unsigned node)
```

Register that a buffer for handle on node will be set. This is typically used by starpu_*ptr_register helpers before setting the interface pointers for this node, to tell the core that that is now allocated.

30.9.5.3 starpu_data_register_same()

```c
void starpu_data_register_same (  
    starpu_data_handle_t * handledst,  
    starpu_data_handle_t handlesrc)
```

Register a new piece of data into the handle handledst with the same interface as the handle handlesrc.

30.9.5.4 starpu_data_handle_to_pointer()

```c
void* starpu_data_handle_to_pointer (  
    starpu_data_handle_t handle,  
    unsigned node)
```

Return the pointer associated with handle on node or NULL if handle’s interface does not support this operation or data for this handle is not allocated on that node.

30.9.5.5 starpu_data_pointer_is_inside()

```c
int starpu_data_pointer_is_inside (  
    starpu_data_handle_t handle,
```
Return whether the given `ptr` is within the data for handle on node `node` (1) or not (0). If the handle interface does not support this operation, and thus the result is unknown, -1 is returned.

30.9.5.6 `starpu_data_get_local_ptr()`

```c
void* starpu_data_get_local_ptr(starpu_data_handle_t handle)
```

Return the local pointer associated with handle or NULL if handle’s interface does not have any data allocated locally.

30.9.5.7 `starpu_data_get_interface_on_node()`

```c
void* starpu_data_get_interface_on_node(starpu_data_handle_t handle, unsigned memory_node)
```

Return the interface associated with handle on `memory_node`.

30.9.5.8 `starpu_data_get_interface_id()`

```c
enum starpu_data_interface_id starpu_data_get_interface_id(starpu_data_handle_t handle)
```

Return the unique identifier of the interface associated with the given handle.

30.9.5.9 `starpu_data_pack()`

```c
int starpu_data_pack(starpu_data_handle_t handle, void** ptr, starpu_ssize_t* count)
```

Execute the packing operation of the interface of the data registered at handle (see `starpu_data_interface_ops`). This packing operation must allocate a buffer large enough at `ptr` and copy into the newly allocated buffer the data associated to handle. `count` will be set to the size of the allocated buffer. If `ptr` is NULL, the function should not copy the data in the buffer but just set `count` to the size of the buffer which would have been allocated. The special value -1 indicates the size is yet unknown.

30.9.5.10 `starpu_data_unpack()`

```c
int starpu_data_unpack(starpu_data_handle_t handle, void* ptr, size_t count)
```

Unpack in handle the data located at `ptr` of size `count` as described by the interface of the data. The interface registered at handle must define a unpacking operation (see `starpu_data_interface_ops`).

30.9.5.11 `starpu_data_get_size()`

```c
size_t starpu_data_get_size(starpu_data_handle_t handle)
```

Return the size of the data associated with handle.

30.9.5.12 `starpu_data_get_alloc_size()`

```c
size_t starpu_data_get_alloc_size(starpu_data_handle_t handle)
```

Return the size of the allocated data associated with handle.
30.9.5.13 starpu_data_lookup()

```c
starpu_data_handle_t starpu_data_lookup {
    const void * ptr
}
```

Return the handle corresponding to the data pointed to by the ptr host pointer.

30.9.5.14 starpu_data_interface_get_next_id()

```c
int starpu_data_interface_get_next_id {
    void
}
```

Return the next available id for a newly created data interface (Defining A New Data Interface).

30.9.5.15 starpu_interface_copy()

```c
int starpu_interface_copy {
    uintptr_t src,
    size_t src_offset,
    unsigned src_node,
    uintptr_t dst,
    size_t dst_offset,
    unsigned dst_node,
    size_t size,
    void * async_data
}
```

Copy size bytes from byte offset src_offset of src on src_node to byte offset dst_offset of dst on dst_node. This is to be used in the starpu_data_copy_methods::any_to_any copy method, which is provided with async_data to be passed to starpu_interface_copy(). This returns -EAGAIN if the transfer is still ongoing, or 0 if the transfer is already completed.

30.9.5.16 starpu_interface_start_driver_copy_async()

```c
void starpu_interface_start_driver_copy_async {
    unsigned src_node,
    unsigned dst_node,
    double * start
}
```

When an asynchronous implementation of the data transfer is implemented, the call to the underlying CUDA, OpenCL, etc. call should be surrounded by calls to starpu_interface_start_driver_copy_async() and starpu_interface_end_driver_copy_async(), so that it is recorded in offline execution traces, and the timing of the submission is checked. start must point to a variable whose value will be passed unchanged to starpu_interface_end_driver_copy_async().

30.9.5.17 starpu_interface_end_driver_copy_async()

```c
void starpu_interface_end_driver_copy_async {
    unsigned src_node,
    unsigned dst_node,
    double start
}
```

See starpu_interface_start_driver_copy_async().

30.9.5.18 starpu_interface_data_copy()

```c
void starpu_interface_data_copy {
    unsigned src_node,
    unsigned dst_node,
    size_t size
}
```

Record in offline execution traces the copy of size bytes from node src_node to node dst_node.

30.9.5.19 starpu_malloc_on_node_flags()

```c
uintptr_t starpu_malloc_on_node_flags {
    unsigned dst_node,
```
30.9 Data Interfaces

size_t size,
int flags);

Allocate size bytes on node dst_node with the given allocation flags. This returns 0 if allocation failed, the allocation method should then return -ENOMEM as allocated size. Deallocation must be done with starpu_free_on_node_flags().

30.9.5.20 starpu_malloc_on_node()

uintptr_t starpu_malloc_on_node (unsigned dst_node, size_t size)

Allocate size bytes on node dst_node with the default allocation flags. This returns 0 if allocation failed, the allocation method should then return -ENOMEM as allocated size. Deallocation must be done with starpu_free_on_node().

30.9.5.21 starpu_free_on_node_flags()

void starpu_free_on_node_flags (unsigned dst_node, uintptr_t addr, size_t size, int flags);

Free addr of size bytes on node dst_node which was previously allocated with starpu_malloc_on_node_flags() with the given allocation flags.

30.9.5.22 starpu_free_on_node()

void starpu_free_on_node (unsigned dst_node, uintptr_t addr, size_t size);

Free addr of size bytes on node dst_node which was previously allocated with starpu_malloc_on_node().

30.9.5.23 starpu_malloc_on_node_set_default_flags()

void starpu_malloc_on_node_set_default_flags (unsigned node, int flags);

Define the default flags for allocations performed by starpu_malloc_on_node() and starpu_free_on_node(). The default is STARPU_MALLOC_PINNED | STARPU_MALLOC_COUNT.

30.9.5.24 starpu_matrix_data_register()

void starpu_matrix_data_register (starpu_data_handle_t * handle, int home_node, uintptr_t ptr, uint32_t ld, uint32_t nx, uint32_t ny, size_t elemsize);

Register the nx x ny 2D matrix of elemsize-byte elements pointed by ptr and initialize handle to represent it. ld specifies the number of elements between rows. a value greater than nx adds padding, which can be useful for alignment purposes.

Here an example of how to use the function.

    float *matrix;
    starpu_data_handle_t matrix_handle;
    matrix = (float*)malloc(width * height * sizeof(float));
    starpu_matrix_data_register(&matrix_handle, STARPU_MAIN_RAM, matrix, width, width, height, sizeof(float));
30.9.25 starpu_matrix_data_register_allocsize()

```c
void starpu_matrix_data_register_allocsize (  
    starpu_data_handle_t * handle,  
    int home_node,  
    uintptr_t ptr,  
    uint32_t ld,  
    uint32_t nx,  
    uint32_t ny,  
    size_t elemsize,  
    size_t allocsize
)
```

Similar to starpu_matrix_data_register, but additionally specifies which allocation size should be used instead of the initial nx*ny*elemsize.

30.9.26 starpu_matrix_ptr_register()

```c
void starpu_matrix_ptr_register (  
    starpu_data_handle_t handle,  
    unsigned node,  
    uintptr_t ptr,  
    uintptr_t dev_handle,  
    size_t offset,  
    uint32_t ld
)
```

Register into the handle that to store data on node node it should use the buffer located at ptr, or device handle dev_handle and offset offset (for OpenCL, notably), with ld elements between rows.

30.9.27 starpu_matrix_get_nx()

```c
uint32_t starpu_matrix_get_nx (  
    starpu_data_handle_t handle
)
```

Return the number of elements on the x-axis of the matrix designated by handle.

30.9.28 starpu_matrix_get_ny()

```c
uint32_t starpu_matrix_get_ny (  
    starpu_data_handle_t handle
)
```

Return the number of elements on the y-axis of the matrix designated by handle.

30.9.29 starpu_matrix_get_local_ld()

```c
uint32_t starpu_matrix_get_local_ld (  
    starpu_data_handle_t handle
)
```

Return the number of elements between each row of the matrix designated by handle. Maybe be equal to nx when there is no padding.

30.9.30 starpu_matrix_get_local_ptr()

```c
uintptr_t starpu_matrix_get_local_ptr (  
    starpu_data_handle_t handle
)
```

Return the local pointer associated with handle.

30.9.31 starpu_matrix_get_elemsize()

```c
size_t starpu_matrix_get_elemsize (  
    starpu_data_handle_t handle
)
```

Return the size of the elements registered into the matrix designated by handle.
30.9.5.32  starpu_matrix_get_allocsize()

size_t starpu_matrix_get_allocsize (  
    starpu_data_handle_t handle )

Return the allocated size of the matrix designated by handle.

30.9.5.33  starpu_coo_data_register()

void starpu_coo_data_register (  
    starpu_data_handle_t *handleptr,  
    int home_node,  
    uint32_t nx,  
    uint32_t ny,  
    uint32_t n_values,  
    uint32_t *columns,  
    uint32_t *rows,  
    uintptr_t *values,  
    size_t elemsize  
)

Register the nx x ny 2D matrix given in the COO format, using the columns, rows, values arrays, which must have n_values elements of size elemsize. Initialize handleptr.

30.9.5.34  starpu_block_data_register()

void starpu_block_data_register (  
    starpu_data_handle_t *handle,  
    int home_node,  
    uintptr_t ptr,  
    uint32_t ldy,  
    uint32_t ldz,  
    uint32_t nx,  
    uint32_t ny,  
    uint32_t nz,  
    size_t elemsize  
)

Register the nx x ny x nz 3D matrix of elemsize byte elements pointed by ptr and initialize handle to represent it. Again, ldy and ldz specify the number of elements between rows and between z planes. Here an example of how to use the function.

```c
float *block;
starpu_data_handle_t block_handle;
block = (float*)malloc(nx*ny*nz*sizeof(float));
starpu_block_data_register(block_handle, STARPU_MAIN_RAM,  
    &block, nx, nx*ny, nx, ny, nz, sizeof(float));
```

30.9.5.35  starpu_block_ptr_register()

void starpu_block_ptr_register (  
    starpu_data_handle_t handle,  
    unsigned node,  
    uintptr_t ptr,  
    uintptr_t dev_handle,  
    size_t offset,  
    uint32_t ldy,  
    uint32_t ldz  
)

Register into the handle that to store data on node node it should use the buffer located at ptr, or device handle dev_handle and offset offset (for OpenCL, notably), with ldy elements between rows and ldz elements between z planes.
30.9.5.36 starpu_block_get_nx()

```c
uint32_t starpu_block_get_nx (starpu_data_handle_t handle)
```

Return the number of elements on the x-axis of the block designated by `handle`.

30.9.5.37 starpu_block_get_ny()

```c
uint32_t starpu_block_get_ny (starpu_data_handle_t handle)
```

Return the number of elements on the y-axis of the block designated by `handle`.

30.9.5.38 starpu_block_get_nz()

```c
uint32_t starpu_block_get_nz (starpu_data_handle_t handle)
```

Return the number of elements on the z-axis of the block designated by `handle`.

30.9.5.39 starpu_block_get_local_ldy()

```c
uint32_t starpu_block_get_local_ldy (starpu_data_handle_t handle)
```

Return the number of elements between each row of the block designated by `handle`, in the format of the current memory node.

30.9.5.40 starpu_block_get_local_ldz()

```c
uint32_t starpu_block_get_local_ldz (starpu_data_handle_t handle)
```

Return the number of elements between each z plane of the block designated by `handle`, in the format of the current memory node.

30.9.5.41 starpu_block_get_local_ptr()

```c
uintptr_t starpu_block_get_local_ptr (starpu_data_handle_t handle)
```

Return the local pointer associated with `handle`.

30.9.5.42 starpu_block_get_elemsize()

```c
size_t starpu_block_get_elemsize (starpu_data_handle_t handle)
```

Return the size of the elements of the block designated by `handle`.

30.9.5.43 starpu_vector_data_register()

```c
void starpu_vector_data_register (starpu_data_handle_t * handle, int home_node, uintptr_t ptr, uint32_t nx, size_t elemsize)
```

Register the `nx` `elemsize`-byte elements pointed to by `ptr` and initialize `handle` to represent it.

Here an example of how to use the function.

```c
float vector[NX];
starpu_data_handle_t vector_handle;
starpu_vector_data_register(&vector_handle, STARPU_MAIN_RAM, (uintptr_t)vector, NX, sizeof(vector[0]));
```
30.9 Data Interfaces

30.9.5.44 starpu_vector_data_register_allocsize()

```c
void starpu_vector_data_register_allocsize (  
    starpu_data_handle_t * handle,  
    int home_node,  
   uintptr_t ptr,  
    uint32_t nx,  
    size_t elemsize,  
    size_t allocsize )
```

Similar to starpu_matrix_data_register, but additionally specifies which allocation size should be used instead of the initial nx*elemsize.

30.9.5.45 starpu_vector_ptr_register()

```c
void starpu_vector_ptr_register (  
    starpu_data_handle_t handle,  
    unsigned node,  
    uintptr_t ptr,  
    uintptr_t dev_handle,  
    size_t offset )
```

Register into the `handle` that to store data on node `node` it should use the buffer located at `ptr`, or device handle `dev_handle` and offset `offset` (for OpenCL, notably)

30.9.5.46 starpu_vector_get_nx()

```c
uint32_t starpu_vector_get_nx (  
    starpu_data_handle_t handle )
```

Return the number of elements registered into the array designated by `handle`.

30.9.5.47 starpu_vector_get_elemsize()

```c
size_t starpu_vector_get elemsize (  
    starpu_data_handle_t handle )
```

Return the size of each element of the array designated by `handle`.

30.9.5.48 starpu_vector_get_allocsize()

```c
size_t starpu_vector_get allocsize (  
    starpu_data_handle_t handle )
```

Return the allocated size of the array designated by `handle`.

30.9.5.49 starpu_vector_get_local_ptr()

```c
uintptr_t starpu_vector_get local_ptr (  
    starpu_data_handle_t handle )
```

Return the local pointer associated with `handle`.

30.9.5.50 starpu_variable_data_register()

```c
void starpu_variable_data_register (  
    starpu_data_handle_t * handle,  
    int home_node,  
    uintptr_t ptr,  
    size_t size )
```

Register the `size` byte element pointed to by `ptr`, which is typically a scalar, and initialize `handle` to represent this data item.

Here an example of how to use the function.

```c
float var = 42.0;  
starpu_data_handle_t var_handle;  
starpu_variable_data_register(&var_handle, STARPU_MAIN_RAM, {  
    uintptr_t}4var, sizeof(var));
```
30.9.5.51 starpu_variable_ptr_register()

void starpu_variable_ptr_register (  
    starpu_data_handle_t handle,  
    unsigned node,  
    uintptr_t ptr,  
    uintptr_t dev_handle,  
    size_t offset )

Register into the handle that to store data on node node it should use the buffer located at ptr, or device handle dev_handle and offset offset (for OpenCL, notably).

30.9.5.52 starpu_variable_get_elemsize()

size_t starpu_variable_get_elemsize (  
    starpu_data_handle_t handle )

Return the size of the variable designated by handle.

30.9.5.53 starpu_variable_get_local_ptr()

uintptr_t starpu_variable_get_local_ptr (  
    starpu_data_handle_t handle )

Return a pointer to the variable designated by handle.

30.9.5.54 starpu_void_data_register()

void starpu_void_data_register (  
    starpu_data_handle_t * handle )

Register a void interface. There is no data really associated to that interface, but it may be used as a synchronization mechanism. It also permits to express an abstract piece of data that is managed by the application internally: this makes it possible to forbid the concurrent execution of different tasks accessing the same void data in read-write concurrently.

30.9.5.55 starpu_csr_data_register()

void starpu_csr_data_register (  
    starpu_data_handle_t * handle,  
    int home_node,  
    uint32_t nnz,  
    uint32_t nrow,  
    uintptr_t nzval,  
    uint32_t * colind,  
    uint32_t * rowptr,  
    uint32_t firstentry,  
    size_t elemsize )

Register a CSR (Compressed Sparse Row Representation) sparse matrix.

30.9.5.56 starpu_csr_get_nnz()

uint32_t starpu_csr_get_nnz (  
    starpu_data_handle_t handle )

Return the number of non-zero values in the matrix designated by handle.

30.9.5.57 starpu_csr_get_nrow()

uint32_t starpu_csr_get_nrow (  
    starpu_data_handle_t handle )

Return the size of the row pointer array of the matrix designated by handle.
30.9.58  starpu_csr_get_firstentry()

uint32_t starpu_csr_get_firstentry (
    starpu_data_handle_t handle )

Return the index at which all arrays (the column indexes, the row pointers...) of the matrix designated by handle.

30.9.59  starpu_csr_get_local_nzval()

uintptr_t starpu_csr_get_local_nzval ( 
    starpu_data_handle_t handle )

Return a local pointer to the non-zero values of the matrix designated by handle.

30.9.60  starpu_csr_get_local_colind()

uint32_t* starpu_csr_get_local_colind ( 
    starpu_data_handle_t handle )

Return a local pointer to the column index of the matrix designated by handle.

30.9.61  starpu_csr_get_local_rowptr()

uint32_t* starpu_csr_get_local_rowptr ( 
    starpu_data_handle_t handle )

Return a local pointer to the row pointer array of the matrix designated by handle.

30.9.62  starpu_csr_get_elemsize()

size_t starpu_csr_get_elemsize ( 
    starpu_data_handle_t handle )

Return the size of the elements registered into the matrix designated by handle.

30.9.63  starpu_bcsr_data_register()

void starpu_bcsr_data_register ( 
    starpu_data_handle_t * handle, 
    int home_node, 
    uint32_t nnz, 
    uint32_t nrow, 
    uintptr_t nzval, 
    uint32_t* colind, 
    uint32_t* rowptr, 
    uint32_t firstentry, 
    uint32_t r, 
    uint32_t c, 
    size_t elemsize )

This variant of starpu_data_register() uses the BCSR (Blocked Compressed Sparse Row Representation) sparse matrix interface. Register the sparse matrix made of $nnz$ non-zero blocks of elements of size $elemsize$ stored in $nzval$ and initializes $handle$ to represent it. Blocks have size $r \times c$. $nrow$ is the number of rows (in terms of blocks), $colind$ is an array of $nnz$ elements, $colind[i]$ is the block-column index for block i in $nzval$, $rowptr$ is an array of $nrow+1$ elements, $rowptr[i]$ is the block-index (in $nzval$) of the first block of row i. By convention, $rowptr[nrow]$ is the number of blocks, this allows an easier access of the matrix's elements for the kernels. $firstentry$ is the index of the first entry of the given arrays (usually 0 or 1).

Here an example with the following matrix:

| 0 1 0 0 |
| 2 3 0 0 |
| 4 5 8 9 |
| 6 7 10 11 |

Generated by Doxygen
nzval = [0, 1, 2, 3] ++ [4, 5, 6, 7] ++ [8, 9, 10, 11]
colind = [0, 0, 1]
rowptr = [0, 1, 3]
r = c = 2

which translates into the following code

```c
int R = 2; // Size of the blocks
int C = 2;
int NROWS = 2;
int NNZ_BLOCKS = 3; // out of 4
int NZVAL_SIZE = (R*C*NNZ_BLOCKS);
int nzval[NZVAL_SIZE] =
{ 0, 1, 2, 3, // First block
  4, 5, 6, 7, // Second block
  8, 9, 10, 11 // Third block
};
uint32_t colind[NNZ_BLOCKS] =
{ 0, // block-column index for first block in nzval
  0, // block-column index for second block in nzval
  1 // block-column index for third block in nzval
};
uint32_t rowptr[NROWS+1] =
{ 0, // block-index in nzval of the first block of the first row.
  1, // block-index in nzval of the first block of the second row.
  NNZ_BLOCKS // number of blocks, to allow an easier element’s access for the kernels
};

starpu_data_handle_t bcsr_handle;
starpu_bcsr_data_register(&bcsr_handle,
  STARPU_MAIN_RAM,
  NNZ_BLOCKS,
  NROWS,
  (uintptr_t) nzval,
  colind,
  rowptr,
  0, // firstentry
  R,
  C,
  sizeof(nzval[0]));
```

### 30.9.5.64 starpu_bcsr_get_nnz()

```c
uint32_t starpu_bcsr_get_nnz (starpu_data_handle_t handle)
```

Return the number of non-zero elements in the matrix designated by handle.

### 30.9.5.65 starpu_bcsr_get_nrow()

```c
uint32_t starpu_bcsr_get_nrow (starpu_data_handle_t handle)
```

Return the number of rows (in terms of blocks of size r*c) in the matrix designated by handle.

### 30.9.5.66 starpu_bcsr_get_firstentry()

```c
uint32_t starpu_bcsr_get_firstentry (starpu_data_handle_t handle)
```

Return the index at which all arrays (the column indexes, the row pointers...) of the matrix designated by handle.

### 30.9.5.67 starpu_bcsr_get_local_nzval()

```c
uintptr_t starpu_bcsr_get_local_nzval (starpu_data_handle_t handle)
```

Return a pointer to the non-zero values of the matrix designated by handle.
30.9.5.68 starpu_bcsr_get_local_colind()

uint32_t* starpu_bcsr_get_local_colind (starpu_data_handle_t handle)

Return a pointer to the column index, which holds the positions of the non-zero entries in the matrix designated by handle.

30.9.5.69 starpu_bcsr_get_local_rowptr()

uint32_t* starpu_bcsr_get_local_rowptr (starpu_data_handle_t handle)

Return the row pointer array of the matrix designated by handle.

30.9.5.70 starpu_bcsr_get_r()

uint32_t starpu_bcsr_get_r (starpu_data_handle_t handle)

Return the number of rows in a block.

30.9.5.71 starpu_bcsr_get_c()

uint32_t starpu_bcsr_get_c (starpu_data_handle_t handle)

Return the number of columns in a block.

30.9.5.72 starpu_bcsr_get_elem_size()

size_t starpu_bcsr_get_elem_size (starpu_data_handle_t handle)

Return the size of the elements in the matrix designated by handle.

30.9.5.73 starpu_multiformat_data_register()

void starpu_multiformat_data_register (starpu_data_handle_t *handle, int home_node, void *ptr, uint32_t nobjects, struct starpu_multiformat_data_interface_ops *format_ops)

Register a piece of data that can be represented in different ways, depending upon the processing unit that manipulates it. It allows the programmer, for instance, to use an array of structures when working on a CPU, and a structure of arrays when working on a GPU. nobjects is the number of elements in the data. format_ops describes the format.

30.9.5.74 starpu_hash_crc32c_be_n()

uint32_t starpu_hash_crc32c_be_n (const void *input, size_t n, uint32_t inputcrc)

Compute the CRC of a byte buffer seeded by the inputcrc current state. The return value should be considered as the new current state for future CRC computation. This is used for computing data size footprint.

30.9.5.75 starpu_hash_crc32c_be()
Compute the CRC of a 32bit number seeded by the inputcrc current state. The return value should be considered as the new current state for future CRC computation. This is used for computing data size footprint.

30.9.5.76 starpu_hash_crc32c_string()

```c
tuint32_t starpu_hash_crc32c_string (
    const char * str,
    uint32_t inputcrc
)
```

Compute the CRC of a string seeded by the inputcrc current state. The return value should be considered as the new current state for future CRC computation. This is used for computing data size footprint.

### 30.10 Data Partition

#### Data Structures

- struct starpu_data_filter

#### Basic API

- void starpu_data_partition (starpu_data_handle_t initial_handle, struct starpu_data_filter *f)
- void starpu_data_unpartition (starpu_data_handle_t root_data, unsigned gathering_node)
- starpu_data_handle_t starpu_data_get_child (starpu_data_handle_t handle, unsigned i)
- int starpu_data_get_nb_children (starpu_data_handle_t handle)
- starpu_data_handle_t starpu_data_get_sub_data (starpu_data_handle_t root_data, unsigned depth,....)
- starpu_data_handle_t starpu_data_vget_sub_data (starpu_data_handle_t root_data, unsigned depth, va_list pa)
- void starpu_data_map_filters (starpu_data_handle_t root_data, unsigned nfilters,....)
- void starpu_data_vmap_filters (starpu_data_handle_t root_data, unsigned nfilters, va_list pa)

#### Asynchronous API

- void starpu_data_partition_plan (starpu_data_handle_t initial_handle, struct starpu_data_filter *f, starpu_data_handle_t *children)
- void starpu_data_partition_submit (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t *children)
- void starpu_data_partition_readonly_submit (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t *children)
- void starpu_data_partition_readwrite_upgrade_submit (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t *children)
- void starpu_data_unpartition_submit (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t *children, int gathering_node)
- void starpu_data_unpartition_readonly_submit (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t *children, int gathering_node)
- void starpu_data_partition_clean (starpu_data_handle_t root_data, unsigned nparts, starpu_data_handle_t *children)
- void starpu_data_unpartition_submit_sequential_consistency_cb (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t *children, int gather_node, int sequential_consistency, void (*callback)(void *), void *callback_arg)
- void starpu_data_partition_not_automatic (starpu_data_handle_t handle)
Predefined BCSR Filter Functions
Predefined partitioning functions for BCSR data. Examples on how to use them are shown in Partitioning Data.

- void `starpu_bcsr_filter_canonical_block` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- struct starpu_data_interface_ops * `starpu_bcsr_filter_canonical_block_child_ops` (struct starpu_data_filter *f, unsigned child)

Predefined CSR Filter Functions
Predefined partitioning functions for CSR data. Examples on how to use them are shown in Partitioning Data.

- void `starpu_csr_filter_vertical_block` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)

Predefined Matrix Filter Functions
Predefined partitioning functions for matrix data. Examples on how to use them are shown in Partitioning Data.

- void `starpu_matrix_filter_block` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void `starpu_matrix_filter_block_shadow` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void `starpu_matrix_filter_vertical_block` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void `starpu_matrix_filter_vertical_block_shadow` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)

Predefined Vector Filter Functions
Predefined partitioning functions for vector data. Examples on how to use them are shown in Partitioning Data.

- void `starpu_vector_filter_block` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void `starpu_vector_filter_block_shadow` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void `starpu_vector_filter_list_long` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void `starpu_vector_filter_list` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void `starpu_vector_filter_divide_in_2` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)

Predefined Block Filter Functions
Predefined partitioning functions for block data. Examples on how to use them are shown in Partitioning Data. An example is available in examples/filters/shadow3d.c

- void `starpu_block_filter_block` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void `starpu_block_filter_block_shadow` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void `starpu_block_filter_vertical_block` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void `starpu_block_filter_vertical_block_shadow` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void `starpu_block_filter_depth_block` (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
• void starpu_block_filter_depth_block_shadow (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
• void starpu_filter_nparts_compute_chunk_size_and_offset (unsigned n, unsigned nparts, size_t elemsize, unsigned id, unsigned *chunk_size, size_t *offset)

30.10.1 Detailed Description

30.10.2 Data Structure Documentation

30.10.2.1 struct starpu_data_filter

Describe a data partitioning operation, to be given to starpu_data_partition()

Data Fields

• void(* filter_func ) (void *father_interface, void *child_interface, struct starpu_data_filter *, unsigned id, unsigned nparts)
• unsigned nchildren
• unsigned(* get_nchildren ) (struct starpu_data_filter *, starpu_data_handle_t initial_handle)
• struct starpu_data_interface_ops *(* get_child_ops ) (struct starpu_data_filter *, unsigned id)
• unsigned filter_arg
• void * filter_arg_ptr

30.10.2.1.1 Field Documentation

30.10.2.1.1.1 filter_func

void(* starpu_data_filter::filter_func) (void *father_interface, void *child_interface, struct starpu_data_filter *, unsigned id, unsigned nparts)

Fill the child_interface structure with interface information for the i-th child of the parent father_interface (among nparts). The filter structure is provided, allowing to inspect the starpu_data_filter::filter_arg and starpu_data_filter::filter_arg_ptr parameters. The details of what needs to be filled in child_interface vary according to the data interface, but generally speaking:

• id is usually just copied over from the father, when the sub data has the same structure as the father, e.g. a subvector is a vector, a submatrix is a matrix, etc. This is however not the case for instance when dividing a BCSR matrix into its dense blocks, which then are matrices.

• nx, ny and alike are usually divided by the number of subdata, depending how the subdivision is done (e.g. nx division vs ny division for vertical matrix division vs horizontal matrix division).

• ld for matrix interfaces are usually just copied over: the leading dimension (ld) usually does not change.

• elemsize is usually just copied over.

• ptr, the pointer to the data, has to be computed according to i and the father's ptr, so as to point to the start of the sub data. This should however be done only if the father has ptr different from NULL: in the OpenCL case notably, the dev_handle and offset fields are used instead.

• dev_handle should be just copied over from the parent.

• offset has to be computed according to i and the father's offset, so as to provide the offset of the start of the sub data. This is notably used for the OpenCL case.

30.10.2.1.1.2 nchildren

unsigned starpu_data_filter::nchildren

Number of parts to partition the data into.
30.10 Data Partition

30.10.2.1.3 get_nchildren

unsigned(* starpu_data_filter::get_nchildren) (struct starpu_data_filter *, starpu_data_t initial_handle)

Return the number of children. This can be used instead of starpu_data_filter::nchildren when the number of children depends on the actual data (e.g. the number of blocks in a sparse matrix).

30.10.2.1.4 get_child_ops

struct starpu_data_interface_ops *(* starpu_data_filter::get_child_ops) (struct starpu_data_t filter *, unsigned id)

When children use different data interface, return which interface is used by child number id.

30.10.2.1.5 filter_arg

unsigned starpu_data_filter::filter_arg

Additional parameter for the filter function

30.10.2.1.6 filter_arg_ptr

void * starpu_data_filter::filter_arg_ptr

Additional pointer parameter for the filter function, such as the sizes of the different parts.

30.10.3 Function Documentation

30.10.3.1 starpu_data_partition()

void starpu_data_partition (starpu_data_handle_t initial_handle, struct starpu_data_filter * f)

Request the partitioning of initial_handle into several subdata according to the filter f. Here an example of how to use the function.

struct starpu_data_filter f =
{
  .filter_func = starpu_matrix_filter_block,
  .nchildren = nslices x
};
starpu_data_partition(A_handle, &f);

30.10.3.2 starpu_data_unpartition()

void starpu_data_unpartition (starpu_data_handle_t root_data, unsigned gathering_node)

Unapply the filter which has been applied to root_data, thus unpartitioning the data. The pieces of data are collected back into one big piece in the gathering_node (usually STARPU_MAIN_RAM). Tasks working on the partitioned data will be waited for by starpu_data_unpartition(). Here an example of how to use the function.

starpu_data_unpartition(A_handle, STARPU_MAIN_RAM);

30.10.3.3 starpu_data_get_child()

starpu_data_handle_t starpu_data_get_child (starpu_data_handle_t handle, unsigned i)

Return the i-th child of the given handle, which must have been partitionned beforehand.

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30.10.3.4 starpu_data_get_nb_children()

```c
int starpu_data_get_nb_children (starpu_data_handle_t handle)
```

Return the number of children handle has been partitioned into.

30.10.3.5 starpu_data_get_sub_data()

```c
starpu_data_handle_t starpu_data_get_sub_data (starpu_data_handle_t root_data, unsigned depth, ...)
```

After partitioning a StarPU data by applying a filter, `starpu_data_get_sub_data()` can be used to get handles for each of the data portions. `root_data` is the parent data that was partitioned. `depth` is the number of filters to traverse (in case several filters have been applied, to e.g. partition in row blocks, and then in column blocks), and the subsequent parameters are the indexes. The function returns a handle to the subdata. Here an example of how to use the function.

```c
h = starpu_data_get_sub_data(A_handle, 1, taskx);
```

30.10.3.6 starpu_data_vget_sub_data()

```c
starpu_data_handle_t starpu_data_vget_sub_data (starpu_data_handle_t root_data, unsigned depth, va_list pa)
```

Similar to `starpu_data_get_sub_data()` but use a `va_list` for the parameter list.

30.10.3.7 starpu_data_map_filters()

```c
void starpu_data_map_filters (starpu_data_handle_t root_data, unsigned nfilters, ...)
```

Apply `nfilters` filters to the handle designated by `root_handle` recursively. `nfilters` pointers to variables of the type `starpu_data_filter` should be given.

30.10.3.8 starpu_data_vmap_filters()

```c
void starpu_data_vmap_filters (starpu_data_handle_t root_data, unsigned nfilters, va_list pa)
```

Apply `nfilters` filters to the handle designated by `root_handle` recursively. Use a `va_list` of pointers to variables of the type `starpu_data_filter`.

30.10.3.9 starpu_data_partition_plan()

```c
void starpu_data_partition_plan (starpu_data_handle_t initial_handle, struct starpu_data_filter * f, starpu_data_handle_t * children)
```

Plan to partition `initial_handle` into several subdata according to the filter `f`. The handles are returned into the `children` array, which has to be the same size as the number of parts described in `f`. These handles are not immediately usable, `starpu_data_partition_submit()` has to be called to submit the actual partitioning. Here is an example of how to use the function:

```c
starpu_data_handle_t children[nslicesx];
struct starpu_data_filter f =
```
30.10 Data Partition

```
//.filter_func = starpu_matrix_filter_block,
//.nchildren = nslicesx

starpu_data_partition_plan(A_handle, &f, children);
```

30.10.3.10 starpu_data_partition_submit()

```c
void starpu_data_partition_submit {
    starpu_data_handle_t initial_handle,
    unsigned nparts,
    starpu_data_handle_t * children
}
```

Submit the actual partitioning of `initial_handle` into the `nparts` children handles. This call is asynchronous, it only submits that the partitioning should be done, so that the children handles can now be used to submit tasks, and `initial_handle` can not be used to submit tasks any more (to guarantee coherency). For instance,

```
starpu_data_partition_submit(A_handle, nslicesx, children);
```

30.10.3.11 starpu_data_partition_readonly_submit()

```c
void starpu_data_partition_readonly_submit {
    starpu_data_handle_t initial_handle,
    unsigned nparts,
    starpu_data_handle_t * children
}
```

Similar to `starpu_data_partition_submit()`, but do not invalidate `initial_handle`. This allows to continue using it, but the application has to be careful not to write to `initial_handle` or children handles, only read from them, since the coherency is otherwise not guaranteed. This thus allows to submit various tasks which concurrently read from various partitions of the data.

When the application wants to write to `initial_handle` again, it should call `starpu_data_unpartition_submit()`, which will properly add dependencies between the reads on the children and the writes to be submitted.

If instead the application wants to write to children handles, it should call `starpu_data_partition_readwrite_upgrade_submit()`, which will correctly add dependencies between the reads on the `initial_handle` and the writes to be submitted.

30.10.3.12 starpu_data_partition_readwrite_upgrade_submit()

```c
void starpu_data_partition_readwrite_upgrade_submit {
    starpu_data_handle_t initial_handle,
    unsigned nparts,
    starpu_data_handle_t * children
}
```

Assume that a partitioning of `initial_handle` has already been submitted in readonly mode through `starpu_data_partition_readonly_submit()`, and will upgrade that partitioning into read-write mode for the children, by invalidating `initial_handle`, and adding the necessary dependencies.

30.10.3.13 starpu_data_unpartition_submit()

```c
void starpu_data_unpartition_submit {
    starpu_data_handle_t initial_handle,
    unsigned nparts,
    starpu_data_handle_t * children,
    int gathering_node
}
```

Assuming that `initial_handle` is partitioned into children, submit an unpartitioning of `initial_handle`, i.e. submit a gathering of the pieces on the requested `gathering_node` memory node, and submit an invalidation of the children.
30.10.3.14 starpu_data_unpartition_readonly_submit()

```c
void starpu_data_unpartition_readonly_submit (
  starpu_data_handle_t initial_handle,
  unsigned nparts,
  starpu_data_handle_t * children,
  int gathering_node )
```

Similar to starpu_data_partition_submit(), but do not invalidate initial_handle. This allows to continue using it, but the application has to be careful not to write to initial_handle or children handles, only read from them, since the coherency is otherwise not guaranteed. This thus allows to submit various tasks which concurrently read from various partitions of the data.

30.10.3.15 starpu_data_partition_clean()

```c
void starpu_data_partition_clean (
  starpu_data_handle_t root_data,
  unsigned nparts,
  starpu_data_handle_t * children )
```

Clear the partition planning established between root_data and children with starpu_data_partition_plan(). This will notably submit an unregister all the children, which can thus not be used any more afterwards.

30.10.3.16 starpu_data_unpartition_submit_sequential_consistency_cb()

```c
void starpu_data_unpartition_submit_sequential_consistency_cb (
  starpu_data_handle_t initial_handle,
  unsigned nparts,
  starpu_data_handle_t * children,
  int gathering_node,
  int sequential_consistency,
  void(*)(void *) callback_func,
  void * callback_arg )
```

Similar to starpu_data_unpartition_submit_sequential_consistency() but allow to specify a callback function for the unpartitioning task.

30.10.3.17 starpu_data_partition_submit_sequential_consistency()

```c
void starpu_data_partition_submit_sequential_consistency (
  starpu_data_handle_t initial_handle,
  unsigned nparts,
  starpu_data_handle_t * children,
  int sequential_consistency )
```

Similar to starpu_data_partition_submit() but also allow to specify the coherency to be used for the main data initial_handle through the parameter sequential_consistency.

30.10.3.18 starpu_data_unpartition_submit_sequential_consistency()

```c
void starpu_data_unpartition_submit_sequential_consistency ( 
  starpu_data_handle_t initial_handle,
  unsigned nparts,
  starpu_data_handle_t * children,
  int gathering_node,
  int sequential_consistency )
```

Similar to starpu_data_unpartition_submit() but also allow to specify the coherency to be used for the main data initial_handle through the parameter sequential_consistency.

30.10.3.19 starpu_data_partition_not_automatic()

```c
void starpu_data_partition_not_automatic ( 
  starpu_data_handle_t handle )
```
Disable the automatic partitioning of the data handle for which a asynchronous plan has previously been submitted.

### 30.10.3.20 starpu_bcsr_filter_canonical_block()

```c
void starpu_bcsr_filter_canonical_block ( 
    void * father_interface, 
    void * child_interface, 
    struct starpu_data_filter * f, 
    unsigned id, 
    unsigned nparts )
```

Partition a block-sparse matrix into dense matrices. `starpu_data_filter::get_child_ops` needs to be set to `starpu_bcsr_filter_canonical_block_child_ops()`.

### 30.10.3.21 starpu_bcsr_filter_canonical_block_child_ops()

```c
struct starpu_data_interface_ops* starpu_bcsr_filter_canonical_block_child_ops ( 
    struct starpu_data_filter * f, 
    unsigned child )
```

Return the child_ops of the partition obtained with `starpu_bcsr_filter_canonical_block()`.

### 30.10.3.22 starpu_csr_filter_vertical_block()

```c
void starpu_csr_filter_vertical_block ( 
    void * father_interface, 
    void * child_interface, 
    struct starpu_data_filter * f, 
    unsigned id, 
    unsigned nparts )
```

Partition a block-sparse matrix into vertical block-sparse matrices.

### 30.10.3.23 starpu_matrix_filter_block()

```c
void starpu_matrix_filter_block ( 
    void * father_interface, 
    void * child_interface, 
    struct starpu_data_filter * f, 
    unsigned id, 
    unsigned nparts )
```

Partition a dense Matrix along the x dimension, thus getting \((x/nparts,y)\) matrices. If \(nparts\) does not divide \(x\), the last submatrix contains the remainder.

### 30.10.3.24 starpu_matrix_filter_block_shadow()

```c
void starpu_matrix_filter_block_shadow ( 
    void * father_interface, 
    void * child_interface, 
    struct starpu_data_filter * f, 
    unsigned id, 
    unsigned nparts )
```

Partition a dense Matrix along the x dimension, with a shadow border `filter_arg_ptr`, thus getting \((x-2+shadow)/nparts +2+shadow,y)\) matrices. If \(nparts\) does not divide \(x-2+shadow\), the last submatrix contains the remainder.

**IMPORTANT:** This can only be used for read-only access, as no coherency is enforced for the shadowed parts. A usage example is available in examples/filters/shadow2d.c

### 30.10.3.25 starpu_matrix_filter_vertical_block()

```c
void starpu_matrix_filter_vertical_block ( 
    void * father_interface,
```
void *child_interface,
struct starpu_data_filter *f,
unsigned id,
unsigned nparts)

Partition a dense Matrix along the y dimension, thus getting \((x,y/nparts)\) matrices. If \(nparts\) does not divide \(y\), the last submatrix contains the remainder.

### 30.10.3.26 starpu_matrix_filter_vertical_block_shadow()

```c
void starpu_matrix_filter_vertical_block_shadow (  
  void *father_interface,  
  void *child_interface,  
  struct starpu_data_filter *f,  
  unsigned id,  
  unsigned nparts )
```

Partition a dense Matrix along the y dimension, with a shadow border \(\text{filter\_arg\_ptr}\), thus getting \((x,(y-2\times\text{shadow})/nparts + 2\times\text{shadow})\) matrices. If \(nparts\) does not divide \(y-2\times\text{shadow}\), the last submatrix contains the remainder.

**IMPORTANT:** This can only be used for read-only access, as no coherency is enforced for the shadowed parts. A usage example is available in examples/filters/shadow2d.c

### 30.10.3.27 starpu_vector_filter_block()

```c
void starpu_vector_filter_block (  
  void *father_interface,  
  void *child_interface,  
  struct starpu_data_filter *f,  
  unsigned id,  
  unsigned nparts )
```

Return in \(\text{child\_interface}\) the \(id\)th element of the vector represented by \(\text{father\_interface}\) once partitioned in \(nparts\) chunks of equal size.

### 30.10.3.28 starpu_vector_filter_block_shadow()

```c
void starpu_vector_filter_block_shadow (  
  void *father_interface,  
  void *child_interface,  
  struct starpu_data_filter *f,  
  unsigned id,  
  unsigned nparts )
```

Return in \(\text{child\_interface}\) the \(id\)th element of the vector represented by \(\text{father\_interface}\) once partitioned in \(nparts\) chunks of equal size with a shadow border \(\text{filter\_arg\_ptr}\), thus getting a vector of size \((n-2\times\text{shadow})/nparts + 2\times\text{shadow}\). The \text{filter\_arg\_ptr} field of \(f\) must be the shadow size casted into \(void^\star\).

**IMPORTANT:** This can only be used for read-only access, as no coherency is enforced for the shadowed parts. An usage example is available in examples/filters/shadow.c

### 30.10.3.29 starpu_vector_filter_list_long()

```c
void starpu_vector_filter_list_long (  
  void *father_interface,  
  void *child_interface,  
  struct starpu_data_filter *f,  
  unsigned id,  
  unsigned nparts )
```

Return in \(\text{child\_interface}\) the \(id\)th element of the vector represented by \(\text{father\_interface}\) once partitioned into \(nparts\) chunks according to the \text{filter\_arg\_ptr} field of \(f\). The \text{filter\_arg\_ptr} field must point to an array of \(nparts\) long elements, each of which specifies the number of elements in each chunk of the partition.
30.10.3.30  starpu_vector_filter_list()

void starpu_vector_filter_list (  
    void * father_interface,  
    void * child_interface,  
    struct starpu_data_filter * f,  
    unsigned id,  
    unsigned nparts );

Return in child_interface the id th element of the vector represented by father_interface once partitioned into nparts chunks according to the filter_arg_ptr field of f. The filter_arg_ptr field must point to an array of nparts uint32_t elements, each of which specifies the number of elements in each chunk of the partition.

30.10.3.31  starpu_vector_filter_divide_in_2()

void starpu_vector_filter_divide_in_2 (  
    void * father_interface,  
    void * child_interface,  
    struct starpu_data_filter * f,  
    unsigned id,  
    unsigned nparts );

Return in child_interface the id th element of the vector represented by father_interface once partitioned in 2 chunks of equal size, ignoring nparts. Thus, id must be 0 or 1.

30.10.3.32  starpu_block_filter_block()

void starpu_block_filter_block (  
    void * father_interface,  
    void * child_interface,  
    struct starpu_data_filter * f,  
    unsigned id,  
    unsigned nparts );

Partition a block along the X dimension, thus getting (x/nparts,y,z) 3D matrices. If nparts does not divide x, the last submatrix contains the remainder.

30.10.3.33  starpu_block_filter_block_shadow()

void starpu_block_filter_block_shadow (  
    void * father_interface,  
    void * child_interface,  
    struct starpu_data_filter * f,  
    unsigned id,  
    unsigned nparts );

Partition a block along the X dimension, with a shadow border filter_arg_ptr, thus getting ((x-2+shadow)/nparts +2+shadow,y,z) blocks. If nparts does not divide x, the last submatrix contains the remainder.  
IMPORTANT: This can only be used for read-only access, as no coherency is enforced for the shadowed parts.

30.10.3.34  starpu_block_filter_vertical_block()

void starpu_block_filter_vertical_block (  
    void * father_interface,  
    void * child_interface,  
    struct starpu_data_filter * f,  
    unsigned id,  
    unsigned nparts );

Partition a block along the Y dimension, thus getting (x,y/nparts,z) blocks. If nparts does not divide y, the last submatrix contains the remainder.
30.10.3.35 starpu_block_filter_vertical_block_shadow()

void starpu_block_filter_vertical_block_shadow (  
    void * father_interface,  
    void * child_interface,  
    struct starpu_data_filter * f,  
    unsigned id,  
    unsigned nparts )

Partition a block along the Y dimension, with a shadow border filter_arg_ptr, thus getting \((x, (y - 2 \times \text{shadow}) / \text{nparts} + 2 \times \text{shadow}, z)\) 3D matrices. If \text{nparts} does not divide \(y\), the last submatrix contains the remainder.

\textbf{IMPORTANT:} This can only be used for read-only access, as no coherency is enforced for the shadowed parts.

30.10.3.36 starpu_block_filter_depth_block()

void starpu_block_filter_depth_block (  
    void * father_interface,  
    void * child_interface,  
    struct starpu_data_filter * f,  
    unsigned id,  
    unsigned nparts )

Partition a block along the Z dimension, thus getting \((x, y, z / \text{nparts})\) blocks. If \text{nparts} does not divide \(z\), the last submatrix contains the remainder.

30.10.3.37 starpu_block_filter_depth_block_shadow()

void starpu_block_filter_depth_block_shadow (  
    void * father_interface,  
    void * child_interface,  
    struct starpu_data_filter * f,  
    unsigned id,  
    unsigned nparts )

Partition a block along the Z dimension, with a shadow border filter_arg_ptr, thus getting \((x, y, (z - 2 \times \text{shadow}) / \text{nparts} + 2 \times \text{shadow})\) blocks. If \text{nparts} does not divide \(z\), the last submatrix contains the remainder.

\textbf{IMPORTANT:} This can only be used for read-only access, as no coherency is enforced for the shadowed parts.

30.10.3.38 starpu_filter_nparts_compute_chunk_size_and_offset()

void starpu_filter_nparts_compute_chunk_size_and_offset (  
    unsigned n,  
    unsigned nparts,  
    size_t elemsize,  
    unsigned id,  
    unsigned ld,  
    unsigned * chunk_size,  
    size_t * offset )

Given an integer \(n\), \(n\) the number of parts it must be divided in, \(id\) the part currently considered, determines the \text{chunk_size} and the \text{offset}, taking into account the size of the elements stored in the data structure \text{elemsize} and \text{ld}, the leading dimension, which is most often 1.

30.11 Out Of Core

Data Structures

- struct starpu_disk_ops

Macros

- \#define STARPU_DISK_SIZE_MIN
Functions

- `void starpu_disk_close (unsigned node, void *obj, size_t size)`
- `void *starpu_disk_open (unsigned node, void *pos, size_t size)`
- `int starpu_disk_register (struct starpu_disk_ops *func, void *parameter, starpu_ssize_t size)`

Variables

- `struct starpu_disk_ops starpu_disk_stdio_ops`
- `struct starpu_disk_ops starpu_disk_hdf5_ops`
- `struct starpu_disk_ops starpu_disk_unistd_ops`
- `struct starpu_disk_ops starpu_disk_unistd_o_direct_ops`
- `struct starpu_disk_ops starpu_disk_leveldb_ops`
- `int starpu_disk_swap_node`

30.11.1 Detailed Description

30.11.2 Data Structure Documentation

30.11.2.1 `struct starpu_disk_ops`

Set of functions to manipulate datas on disk.

Data Fields

- `void *(* plug ) (void *parameter, starpu_ssize_t size)`
- `void(* unplug) (void *base)`
- `int(* bandwidth) (unsigned node, void *base)`
- `void(* alloc) (void *base, size_t size)`
- `void(* free) (void *base, void *obj, size_t size)`
- `void(* open) (void *base, void *pos, size_t size)`
- `void(* close) (void *base, void *obj, size_t size)`
- `int(* read) (void *base, void *obj, void *buf, off_t offset, size_t size)`
- `int(* write) (void *base, void *obj, const void *buf, off_t offset, size_t size)`
- `int(* full_read) (void *base, void *obj, void **ptr, size_t *size, unsigned dst_node)`
- `int(* full_write) (void *base, void *obj, void *ptr, size_t size)`
- `void(* async_write) (void *base, void *obj, void *buf, off_t offset, size_t size)`
- `void(* sync_read) (void *base, void *obj, void *buf, off_t offset, size_t size)`
- `void(* async_full_read) (void *base, void *obj, void **ptr, size_t *size, unsigned dst_node)`
- `void(* async_full_write) (void *base, void *obj, void *ptr, size_t size)`
- `void(* copy) (void *base_src, void *obj_src, off_t offset_src, void *base_dst, void *obj_dst, off_t offset_dst, size_t size)`
- `void(* wait_request) (void *async_channel)`
- `int(* test_request) (void *async_channel)`
- `void(* free_request) (void *async_channel)`

30.11.2.1.1 Field Documentation

30.11.2.1.1.1 `plug`

`void(* starpu_disk_ops::plug) (void *parameter, starpu_ssize_t size)`

Connect a disk memory at location `parameter` with size `size`, and return a base as `void*`, which will be passed by StarPU to all other methods.

30.11.2.1.1.2 `unplug`

`void(* starpu_disk_ops::unplug) (void *base)`

Disconnect a disk memory `base`. 

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272 Module Documentation a.k.a StarPU’s API

30.11.2.1.1.3 bandwidth

int(* starpu_disk_ops::bandwidth)(unsigned node, void *base)

Measure the bandwidth and the latency for the disk node and save it. Returns 1 if it could measure it.

30.11.2.1.1.4 alloc

void(* starpu_disk_ops::alloc)(void *base, size_t size)

Create a new location for datas of size size. Return an opaque object pointer.

30.11.2.1.1.5 free

void(* starpu_disk_ops::free)(void *base, void *obj, size_t size)

Free a data obj previously allocated with starpu_disk_ops::alloc.

30.11.2.1.1.6 open

void(* starpu_disk_ops::open)(void *base, void *pos, size_t size)

Open an existing location of datas, at a specific position pos dependent on the backend.

30.11.2.1.1.7 close

void(* starpu_disk_ops::close)(void *base, void *obj, size_t size)

Close, without deleting it, a location of datas obj.

30.11.2.1.1.8 read

int(* starpu_disk_ops::read)(void *base, void *obj, void *buf, off_t offset, size_t size)

Read size bytes of data from obj in base, at offset offset, and put into buf. Return the actual number of read bytes.

30.11.2.1.1.9 write

int(* starpu_disk_ops::write)(void *base, void *obj, const void *buf, off_t offset, size_t size)

Write size bytes of data to obj in base, at offset offset, from buf. Return 0 on success.

30.11.2.1.1.10 full_read

int(* starpu_disk_ops::full_read)(void *base, void *obj, void **ptr, size_t *size, unsigned dst_node)

Read all data from obj of base, from offset 0. Returns it in an allocated buffer ptr, of size size

30.11.2.1.1.11 full_write

int(* starpu_disk_ops::full_write)(void *base, void *obj, void *ptr, size_t size)

Write data in ptr to obj of base, from offset 0, and truncate obj to size, so that a full_read will get it.

30.11.2.1.1.12 async_write

void(* starpu_disk_ops::async_write)(void *base, void *obj, void *buf, off_t offset, size_t size)

Asynchronously write size bytes of data to obj in base, at offset offset, from buf. Return a void* pointer that StarPU will pass to xxx_request methods for testing for the completion.

30.11.2.1.1.13 async_read

void(* starpu_disk_ops::async_read)(void *base, void *obj, void *ptr, size_t size)

Asynchronously read size bytes of data from obj in base, at offset offset, and put into buf. Return a void* pointer that StarPU will pass to xxx_request methods for testing for the completion.

30.11.2.1.1.14 async_full_read

void(* starpu_disk_ops::async_full_read)(void *base, void *obj, void **ptr, size_t *size, unsigned dst_node)

Read all data from obj of base, from offset 0. Return it in an allocated buffer ptr, of size size

30.11.2.1.1.15 async_full_write

void(* starpu_disk_ops::async_full_write)(void *base, void *obj, void *ptr, size_t size)

Write data in ptr to obj of base, from offset 0, and truncate obj to size, so that a starpu_disk_ops::full_read will get it.

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### 30.11.2.1.16 copy

```c
void (* starpu_disk_ops::copy) (void *base_src, void *obj_src, off_t offset_src, void *base_dst, void *obj_dst, off_t offset_dst, size_t size)
```

Copy from offset offset_src of disk object obj_src in base_src to offset offset_dst of disk object obj_dst in base_dst. Return a void* pointer that StarPU will pass to xxx_request methods for testing for the completion.

### 30.11.2.1.17 wait_request

```c
void (* starpu_disk_ops::wait_request) (void *async_channel)
```

Wait for completion of request async_channel returned by a previous asynchronous read, write or copy.

### 30.11.2.1.18 test_request

```c
int (* starpu_disk_ops::test_request) (void *async_channel)
```

Test for completion of request async_channel returned by a previous asynchronous read, write or copy. Return 1 on completion, 0 otherwise.

### 30.11.2.1.19 free_request

```c
void (* starpu_disk_ops::free_request) (void *async_channel)
```

Free the request allocated by a previous asynchronous read, write or copy.

### 30.11.3 Macro Definition Documentation

#### 30.11.3.1 STARPU_DISK_SIZE_MIN

```c
#define STARPU_DISK_SIZE_MIN
```

Minimum size of a registered disk. The size of a disk is the last parameter of the function starpu_disk_register().

### 30.11.4 Function Documentation

#### 30.11.4.1 starpu_disk_close()

```c
void starpu_disk_close (unsigned node, void *obj, size_t size)
```

Close an existing data opened with starpu_disk_open().

#### 30.11.4.2 starpu_disk_open()

```c
void* starpu_disk_open (unsigned node, void *pos, size_t size)
```

Open an existing file memory in a disk node. size is the size of the file. pos is the specific position dependent on the backend, given to the open method of the disk operations. Return an opaque object pointer.

#### 30.11.4.3 starpu_disk_register()

```c
int starpu_disk_register (struct starpu_disk_ops * func, void * parameter, starpu_ssize_t size)
```

Register a disk memory node with a set of functions to manipulate datas. The plug member of func will be passed parameter, and return a base which will be passed to all func methods. SUCCESS: return the disk node.
FAIL: return an error code.
size must be at least STARPU_DISK_SIZE_MIN bytes! size being negative means infinite size.

30.11.5 Variable Documentation

30.11.5.1 starpu_disk_stdio_ops

struct starpu_disk_ops starpu_disk_stdio_ops
Use the stdio library (fwrite, fread...) to read/write on disk.
Warning: It creates one file per allocation!
Do not support asynchronous transfers.

30.11.5.2 starpu_disk_hdf5_ops

struct starpu_disk_ops starpu_disk_hdf5_ops
Use the HDF5 library.
It doesn't support multiple opening from different processes.
You may only allow one process to write in the HDF5 file.
If HDF5 library is not compiled with –thread-safe you can't open more than one HDF5 file at the same time.

30.11.5.3 starpu_disk_unistd_ops

struct starpu_disk_ops starpu_disk_unistd_ops
Use the unistd library (write, read...) to read/write on disk.
Warning: It creates one file per allocation!

30.11.5.4 starpu_disk_unistd_o_direct_ops

struct starpu_disk_ops starpu_disk_unistd_o_direct_ops
Use the unistd library (write, read...) to read/write on disk with the O_DIRECT flag.
Warning: It creates one file per allocation!
Only available on Linux systems.

30.11.5.5 starpu_disk_leveldb_ops

struct starpu_disk_ops starpu_disk_leveldb_ops
Use the leveldb created by Google. More information at https://code.google.com/p/leveldb/ Do not support asynchronous transfers.

30.11.5.6 starpu_disk_swap_node

int starpu_disk_swap_node
Contain the node number of the disk swap, if set up through the STARPU_DISK_SWAP variable.

30.12 Codelet And Tasks
This section describes the interface to manipulate codelets and tasks.

Data Structures

- struct starpu_codelet
- struct starpu_data_descr
- struct starpu_task
Macros

- #define STARPU_NMAXBUFS
- #define STARPU_NOWHERE
- #define STARPU_CPU
- #define STARPU_CUDA
- #define STARPU_OPENCL
- #define STARPU_MIC
- #define STARPU_MPI_MS
- #define STARPU_CODELET_SIMGRID_EXECUTE
- #define STARPU_CODELET_SIMGRID_EXECUTE_AND_INJECT
- #define STARPU_CODELET_NOPLANS
- #define STARPU_CUDA_ASYNC
- #define STARPU_OPENCL_ASYNC
- #define STARPU_MAIN_RAM
- #define STARPU_MULTIPLE_CPU_IMPLEMENTATIONS
- #define STARPU_MULTIPLE_CUDA_IMPLEMENTATIONS
- #define STARPU_MULTIPLE_OPENCL_IMPLEMENTATIONS
- #define STARPU_VARIABLE_NBUFFERS
- #define STARPU_SPECIFIC_NODE_LOCAL
- #define STARPU_SPECIFIC_NODE_CPU
- #define STARPU_SPECIFIC_NODE_SLOW
- #define STARPU_SPECIFIC_NODE_FAST
- #define STARPU_TASK_TYPE_NORMAL
- #define STARPU_TASK_TYPE_INTERNAL
- #define STARPU_TASK_TYPE_DATA_ACQUIRE
- #define STARPU_TASK_INITIALIZER
- #define STARPU_TASK_GET_NBUFFERS(task)
- #define STARPU_TASK_GET_HANDLE(task, i)
- #define STARPU_TASK_GET_HANDLES(task)
- #define STARPU_TASK_SET_HANDLE(task, handle, i)
- #define STARPU_CODELET_GET_MODE(codelet, i)
- #define STARPU_CODELET_SET_MODE(codelet, mode, i)
- #define STARPU_TASK_GET_MODE(task, i)
- #define STARPU_TASK_SET_MODE(task, mode, i)
- #define STARPU_CODELET_GET_NODE(codelet, i)
- #define STARPU_CODELET_SET_NODE(codelet, __node, i)

Typedefs

- typedef void(* starpu_cpu_func_t) (void **, void *)
- typedef void(* starpu_cuda_func_t) (void **, void *)
- typedef void(* starpu_opencl_func_t) (void **, void *)
- typedef void(* starpu_mic_kernel_t) (void **, void *)
- typedef starpu_mic_kernel_t(* starpu_mic_func_t) (void)
- typedef starpu_mpi_ms_kernel_t(* starpu_mpi_ms_func_t) (void)
- typedef void(* starpu_mpi_ms_kernel_t)(* starpu_mpi_ms_func_t) (void)

Enumerations

- enum starpu_codelet_type { STARPU_SEQ, STARPU_SPMD, STARPU_FORKJOIN }
- enum starpu_task_status { STARPU_TASK_INVALID, STARPU_TASK_INVALID, STARPU_TASK_BLOCKED, STARPU_TASK_RECOVERY, STARPU_TASK_RUNNING, STARPU_TASK_FINISHED, STARPU_TASK_BLOCKED_ON_TAG, STARPU_TASK_BLOCKED_ON_TASK, STARPU_TASK_BLOCKED_ON_DATA, STARPU_TASK_STOPPED }

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30.12 Functions

- `void starpu_task_init (struct starpu_task *task)`
- `void starpu_task_clean (struct starpu_task *task)`
- `struct starpu_task * starpu_task_create (void) STARPU_ATTRIBUTE_MALLOC`
- `void starpu_task_destroy (struct starpu_task *task)`
- `int starpu_task_submit (struct starpu_task *task) STARPU_WARN_UNUSED_RESULT`
- `int starpu_task_submit_to_ctx (struct starpu_task *task, unsigned sched_ctx_id)`
- `int starpu_task_finished (struct starpu_task *task) STARPU_WARN_UNUSED_RESULT`
- `int starpu_task_wait (struct starpu_task *task) STARPU_WARN_UNUSED_RESULT`
- `int starpu_task_wait_array (struct starpu_task **tasks, unsigned nb_tasks) STARPU_WARN_UNUSED_RESULT`
- `int starpu_task_wait_for_all (void)`
- `int starpu_task_wait_for_n_submitted (unsigned n)`
- `int starpu_task_wait_for_all_in_ctx (unsigned sched_ctx_id)`
- `int starpu_task_wait_for_n_submitted_in_ctx (unsigned sched_ctx_id, unsigned n)`
- `int starpu_task_wait_for_no_ready (void)`
- `int starpu_task_nready (void)`
- `int starpu_task_nsubmitted (void)`
- `void starpu_iteration_push (unsigned long iteration)`
- `void starpu_iteration_pop (void)`
- `void starpu_do_schedule (void)`
- `void starpu_codelet_init (struct starpu_codelet *cl)`
- `void starpu_codelet_display_stats (struct starpu_codelet *cl)`
- `struct starpu_task * starpu_task_get_current (void)`
- `int starpu_task_get_current_data_node (unsigned i)`
- `const char * starpu_task_get_model_name (struct starpu_task *task)`
- `const char * starpu_task_get_name (struct starpu_task *task)`
- `struct starpu_task * starpu_task_dup (struct starpu_task *task)`
- `void starpu_task_set_implementation (struct starpu_task *task, unsigned impl)`
- `unsigned starpu_task_get_implementation (struct starpu_task *task)`
- `void starpu_create_sync_task (starpu_tag_t sync_tag, unsigned ndeps, starpu_tag_t *deps, void (*callback)(void *callback_arg), void *callback_arg)`

30.12.1 Detailed Description

This section describes the interface to manipulate codelets and tasks.

30.12.2 Data Structure Documentation

30.12.2.1 struct starpu_codelet

The codelet structure describes a kernel that is possibly implemented on various targets. For compatibility, make sure to initialize the whole structure to zero, either by using explicit memset, or the function `starpu_codelet_init()`, or by letting the compiler implicitly do it in e.g. static storage case.

Data Fields

- `uint32_t where`
- `int (* can_execute )(unsigned workerid, struct starpu_task *task, unsigned nimpl)`
- `enum starpu_codelet_type type`
- `int max_parallelism`
- `starpu_cpu_func_t cpu_func`
- `starpu_cuda_func_t cuda_func`
- `starpu_opencl_func_t opencl_func`
- `starpu_cpu_func_t cpu_funcs [STARPU_MAXIMPLEMENTATIONS]`
- `starpu_cuda_func_t cuda_funcs [STARPU_MAXIMPLEMENTATIONS]`
- char `cuda_flags` [STARPU_MAXIMPLEMENTATIONS]
- `starpu_opencl_func_t opencl_funcs` [STARPU_MAXIMPLEMENTATIONS]
- char `opencl_flags` [STARPU_MAXIMPLEMENTATIONS]
- `starpu_mic_func_t mic_funcs` [STARPU_MAXIMPLEMENTATIONS]
- `starpu_mpi_ms_func_t mpi_ms_funcs` [STARPU_MAXIMPLEMENTATIONS]
- const char ∗`cpu_funcs_name` [STARPU_MAXIMPLEMENTATIONS]
- int `nbuffers`
- `enum starpu_data_access_mode modes` [STARPU_NMAXBUFS]
- `enum starpu_data_access_mode ∗dyn_modes`
- unsigned `specific_nodes`
- int `nodes` [STARPU_NMAXBUFS]
- ∗`dyn_nodes`
- `struct starpu_perfmodel ∗model`
- `struct starpu_perfmodel ∗energy_model`
- unsigned long `per_worker_stats` [STARPU_NMAXWORKERS]
- const char ∗`name`
- unsigned `color`
- int `flags`

### 30.12.2.1.1 Field Documentation

#### 30.12.2.1.1.1 where

```
void starpu_codelet::where
```

Optional field to indicate which types of processing units are able to execute the codelet. The different values `STARPU_CPU, STARPU_CUDA, STARPU_OPENCL` can be combined to specify on which types of processing units the codelet can be executed. `STARPU_CPU | STARPU_CUDA` for instance indicates that the codelet is implemented for both CPU cores and CUDA devices while `STARPU_OPENCL` indicates that it is only available on OpenCL devices. If the field is unset, its value will be automatically set based on the availability of the `XXX_funcs` fields defined below. It can also be set to `STARPU_NOWHERE` to specify that no computation has to be actually done.

#### 30.12.2.1.1.2 can_execute

```
int(* starpu_codelet::can_execute) (unsigned workerid, struct starpu_task ∗task, unsigned nimpl)
```

Define a function which should return 1 if the worker designated by `workerid` can execute the `nimpl`-th implementation of `task`, 0 otherwise.

#### 30.12.2.1.1.3 type

```
enum starpu_codelet_type starpu_codelet::type
```

Optional field to specify the type of the codelet. The default is `STARPU_SEQ`, i.e. usual sequential implementation. Other values (`STARPU_SPMD` or `STARPU_FORKJOIN`) declare that a parallel implementation is also available. See Parallel Tasks for details.

#### 30.12.2.1.1.4 max_parallelism

Optional field. If a parallel implementation is available, this denotes the maximum combined worker size that StarPU will use to execute parallel tasks for this codelet.

#### 30.12.2.1.1.5 cpu_func

```
starpu_cpu_func_t starpu_codelet::cpu_func
```

**Deprecated** Optional field which has been made deprecated. One should use instead the field `starpu_codelet::cpu_funcs`.

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30.12.2.1.1.6 cuda_func

starpu_cuda_func_t starpu_codelet::cuda_func

**Deprecated** Optional field which has been made deprecated. One should use instead the starpu_codelet::cuda_funcs field.

30.12.2.1.1.7 opencl_func

starpu_opencl_func_t starpu_codelet::opencl_func

**Deprecated** Optional field which has been made deprecated. One should use instead the starpu_codelet::opencl_funcs field.

30.12.2.1.1.8 cpu_funcs

starpu_cpu_func_t starpu_codelet::cpu_funcs[STARPU_MAXIMPLEMENTATIONS]

Optional array of function pointers to the CPU implementations of the codelet. The functions prototype must be:

```c
void cpu_func(void *buffers[], void *cl_arg)
```

The first argument being the array of data managed by the data management library, and the second argument is a pointer to the argument passed from the field starpu_task::cl_arg. If the field starpu_codelet::where is set, then the field starpu_codelet::cpu_funcs is ignored if STARPU_CPU does not appear in the field starpu_codelet::where, it must be non-NULL otherwise.

30.12.2.1.1.9 cuda_funcs

starpu_cuda_func_t starpu_codelet::cuda_funcs[STARPU_MAXIMPLEMENTATIONS]

Optional array of function pointers to the CUDA implementations of the codelet. The functions must be host-functions written in the CUDA runtime API. Their prototype must be:

```c
void cuda_func(void *buffers[], void *cl_arg)
```

If the field starpu_codelet::where is set, then the field starpu_codelet::cuda_funcs is ignored if STARPU_CUDA does not appear in the field starpu_codelet::where, it must be non-NULL otherwise.

30.12.2.1.1.10 cuda_flags

char starpu_codelet::cuda_flags[STARPU_MAXIMPLEMENTATIONS]

Optional array of flags for CUDA execution. They specify some semantic details about CUDA kernel execution, such as asynchronous execution.

30.12.2.1.1.11 opencl_funcs

starpu_opencl_func_t starpu_codelet::opencl_funcs[STARPU_MAXIMPLEMENTATIONS]

Optional array of function pointers to the OpenCL implementations of the codelet. The functions prototype must be:

```c
void opencl_func(void *buffers[], void *cl_arg)
```

If the field starpu_codelet::where is set, then the field starpu_codelet::opencl_funcs is ignored if STARPU_OPENCL does not appear in the field starpu_codelet::where, it must be non-NULL otherwise.

30.12.2.1.1.12 opencl_flags

char starpu_codelet::opencl_flags[STARPU_MAXIMPLEMENTATIONS]

Optional array of flags for OpenCL execution. They specify some semantic details about OpenCL kernel execution, such as asynchronous execution.

30.12.2.1.1.13 mic_funcs

starpu_mic_func_t starpu_codelet::mic_funcs[STARPU_MAXIMPLEMENTATIONS]

Optional array of function pointers to a function which returns the MIC implementation of the codelet. The functions prototype must be:

```c
starpu_mic_kernel_t mic_func(struct starpu_codelet *cl, unsigned nimpl)
```

If the field starpu_codelet::where is set, then the field starpu_codelet::mic_funcs is ignored if STARPU_MIC does not appear in the field starpu_codelet::where. It can be NULL if starpu_codelet::cpu_funcs_name is non-NULL, in which case StarPU will simply make a symbol lookup to get the implementation.
30.12.2.1.1.14 mpi_ms_funcs

starpu_mpi_ms_func_t starpu_codelet::mpi_ms_funcs[STARPU_MAXIMPLEMENTATIONS]

Optional array of function pointers to a function which returns the MPI Master Slave implementation of the codelet. The functions prototype must be:

starpu_mpi_ms_kernel_t mpi_ms_func(struct starpu_codelet *cl, unsigned nimpl)

If the field starpu_codelet::where is set, then the field starpu_codelet::mpi_ms_funcs is ignored if STARPU_M‐
PI_MS does not appear in the field starpu_codelet::where. It can be NULL if starpu_codelet::cpu_funcs_name is non‐NULL, in which case StarPU will simply make a symbol lookup to get the implementation.

30.12.2.1.1.15 cpu_funcs_name

const char * starpu_codelet::cpu_funcs_name[STARPU_MAXIMPLEMENTATIONS]

Optional array of strings which provide the name of the CPU functions referenced in the array starpu_codelet::cpu−
funcs. This can be used when running on MIC devices for StarPU to simply look up the MIC function implementation through its name.

30.12.2.1.1.16 nbuffers

int starpu_codelet::nbuffers

Specify the number of arguments taken by the codelet. These arguments are managed by the DSM and are accessed from the void *buffers[] array. The constant argument passed with the field starpu_task::cl_arg is not counted in this number. This value should not be above STARPU_NMAXBUFFS. It may be set to STARPU‐
VARIABLE_NBUFFERS to specify that the number of buffers and their access modes will be set in starpu_task−
::nbuffers and starpu_task::modes or starpu_task::dyn_modes, which thus permits to define codelets with a varying number of data.

30.12.2.1.1.17 modes

enum starpu_data_access_mode starpu_codelet::modes[STARPU_NMAXBUFFS]

Is an array of starpu_data_access_mode. It describes the required access modes to the data neeeded by the codelet (e.g. STARPU_RW). The number of entries in this array must be specified in the field starpu_codelet::nbuffers, and should not exceed STARPU_NMAXBUFFS. If unsufficient, this value can be set with the configure option --enable-maxbuffers.

30.12.2.1.1.18 dyn_modes

enum starpu_data_access_mode* starpu_codelet::dyn_modes

Is an array of starpu_data_access_mode. It describes the required access modes to the data needed by the codelet (e.g. STARPU_RW). The number of entries in this array must be specified in the field starpu_codelet::nbuffers. This field should be used for codelets having a number of datas greater than STARPU_NMAXBUFFS (see Setting Many Data Handles For a Task). When defining a codelet, one should either define this field or the field starpu_codelet::modes defined above.

30.12.2.1.1.19 specific_nodes

unsigned starpu_codelet::specific_nodes

Default value is 0. If this flag is set, StarPU will not systematically send all data to the memory node where the task will be executing, it will read the starpu_codelet::nodes or starpu_codelet::dyn_nodes array to determine, for each data, whether to send it on the memory node where the task will be executing (-1), or on a specific node (!= -1).

30.12.2.1.1.20 nodes

int starpu_codelet::nodes[STARPU_NMAXBUFFS]

Optional field. When starpu_codelet::specific_nodes is 1, this specifies the memory nodes where each data should be sent to for task execution. The number of entries in this array is starpu_codelet::nbuffers, and should not exceed STARPU_NMAXBUFFS.

30.12.2.1.1.21 dyn_nodes

int* starpu_codelet::dyn_nodes

Optional field. When starpu_codelet::specific_nodes is 1, this specifies the memory nodes where each data should be sent to for task execution. The number of entries in this array is starpu_codelet::nbuffers. This field should be used for codelets having a number of datas greater than STARPU_NMAXBUFFS (see Setting Many Data Handles For a Task). When defining a codelet, one should either define this field or the field starpu_codelet::nodes defined above.
Module Documentation a.k.a StarPU’s API

30.12.2.1.22 model

```c
struct starpu_perfmodel* starpu_codelet::model
```

Optional pointer to the task duration performance model associated to this codelet. This optional field is ignored when set to `NULL` or when its field `starpu_perfmodel::symbol` is not set.

30.12.2.1.23 energy_model

```c
struct starpu_perfmodel* starpu_codelet::energy_model
```

Optional pointer to the task energy consumption performance model associated to this codelet. This optional field is ignored when set to `NULL` or when its field `starpu_perfmodel::symbol` is not set. In the case of parallel codelets, this has to account for all processing units involved in the parallel execution.

30.12.2.1.24 per_worker_stats

```c
unsigned long starpu_codelet::per_worker_stats[STARPU_NMAXWORKERS]
```

Optional array for statistics collected at runtime: this is filled by StarPU and should not be accessed directly, but for example by calling the function `starpu_codelet_display_stats()` (See `starpu_codelet_display_stats()` for details).

30.12.2.1.25 name

```c
const char* starpu_codelet::name
```

Optional name of the codelet. This can be useful for debugging purposes.

30.12.2.1.26 color

```c
unsigned starpu_codelet::color
```

Optional color of the codelet. This can be useful for debugging purposes.

30.12.2.1.27 flags

```c
int starpu_codelet::flags
```

Various flags for the codelet.

30.12.2.2 struct starpu_data_descr

Describe a data handle along with an access mode.

**Data Fields**

<table>
<thead>
<tr>
<th>starpu_data_handle_t</th>
<th>handle</th>
<th>data</th>
</tr>
</thead>
<tbody>
<tr>
<td>enum starpu_data_access_mode</td>
<td>mode</td>
<td>access mode</td>
</tr>
</tbody>
</table>

30.12.2.3 struct starpu_task

Describe a task that can be offloaded on the various processing units managed by StarPU. It instantiates a codelet. It can either be allocated dynamically with the function `starpu_task_create()`, or declared statically. In the latter case, the programmer has to zero the structure `starpu_task` and to fill the different fields properly. The indicated default values correspond to the configuration of a task allocated with `starpu_task_create()`.

**Data Fields**

- const char * name
- struct starpu_codelet * cl
- int32_t where
- int nbuffers
- starpu_data_handle_t * dyn_handles
- void ** dyn_interfaces
- enum starpu_data_access_mode * dyn_modes
- starpu_data_handle_t handles [STARPU_NMAXBUFS]
- void * interfaces [STARPU_NMAXBUFS]
- enum starpu_data_access_mode modes [STARPU_NMAXBUFS]
- unsigned char * handles_sequential_consistency
• void *cl_arg
• size_t cl_arg_size
• void(*callback_func)(void *)
• void *callback_arg
• void(*prologue_callback_func)(void *)
• void *prologue_callback_arg
• void(*prologue_callback_pop_func)(void *)
• void *prologue_callback_pop_arg

starpu_tag_t tag_id
• unsigned cl_arg_free:1
• unsigned callback_arg_free:1
• unsigned prologue_callback_arg_free:1
• unsigned prologue_callback_pop_arg_free:1
• unsigned use_tag:1
• unsigned sequential_consistency:1
• unsigned synchronous:1
• unsigned execute_on_a_specific_worker:1
• unsigned detach:1
• unsigned destroy:1
• unsigned regenerate:1
• unsigned no_submitorder:1
• unsigned scheduled:1
• unsigned prefetched:1
• unsigned workerid
• unsigned workerorder
• uint32_t *workerids
• unsigned workerids_len
• int priority
• enum starpu_task_status status
• unsigned type
• unsigned color
• unsigned sched_ctx
• int hypervisor_tag
• unsigned possibly_parallel
• starpu_task_bundle_t bundle
• struct starpu_profiling_task_info *profiling_info
• double flops
• double predicted
• double predicted_transfer
• double predicted_start
• void *sched_data

Private Attributes
• unsigned mf_skip:1
• int magic
• struct starpu_task *prev
• struct starpu_task *next
• void *starpu_private
• struct starpu_omp_task *omp_task
• unsigned nb_termination_call_required

30.12.2.3.1 Field Documentation
30.12.2.3.1.1 name

const char* starpu_task::name

Optional name of the task. This can be useful for debugging purposes. With starpu_task_insert() and alike this can be specified thanks to STARPU_NAME followed by the const char *.

30.12.2.3.1.2 cl

struct starpu_codelet* starpu_task::cl

Pointer to the corresponding structure starpu_codelet. This describes where the kernel should be executed, and supplies the appropriate implementations. When set to NULL, no code is executed during the tasks, such empty tasks can be useful for synchronization purposes.

30.12.2.3.1.3 where

int32_t starpu_task::where

When set, specify where the task is allowed to be executed. When unset, take the value of starpu_codelet::where. With starpu_task_insert() and alike this can be specified thanks to STARPU_EXECUTE_WHERE followed by an unsigned long long.

30.12.2.3.1.4 nbuffers

int starpu_task::nbuffers

Specify the number of buffers. This is only used when starpu_codelet::nbuffers is STARPU_VARIABLE_NBUFFERS. With starpu_task_insert() and alike this is automatically computed when using ::STARPU_DATA_ARRAY and alike.

30.12.2.3.1.5 dyn_handles

starpu_data_handle_t* starpu_task::dyn_handles

Array of starpu_data_handle_t. Specify the handles to the different pieces of data accessed by the task. The number of entries in this array must be specified in the field starpu_codelet::nbuffers. This field should be used for tasks having a number of datas greater than STARPU_NMAXBUFS (see Setting Many Data Handles For a Task). When defining a task, one should either define this field or the field starpu_task::handles defined below.

With starpu_task_insert() and alike this is automatically filled when using ::STARPU_DATA_ARRAY and alike.

30.12.2.3.1.6 dyn_interfaces

void** starpu_task::dyn_interfaces

Array of data pointers to the memory node where execution will happen, managed by the DSM. Is used when the field starpu_task::dyn_handles is defined. This is filled by StarPU.

30.12.2.3.1.7 dyn_modes

enum starpu_data_access_mode* starpu_task::dyn_modes

Used only when starpu_codelet::nbuffers is STARPU_VARIABLE_NBUFFERS. Array of starpu_data_access_mode which describes the required access modes to the data needed by the codelet (e.g. STARPU_RW). The number of entries in this array must be specified in the field starpu_codelet::nbuffers. This field should be used for codelets having a number of datas greater than STARPU_NMAXBUFS (see Setting Many Data Handles For a Task). When defining a codelet, one should either define this field or the field starpu_task::modes defined below.

With starpu_task_insert() and alike this is automatically filled when using ::STARPU_DATA_MODE_ARRAY and alike.

30.12.2.3.1.8 handles

starpu_data_handle_t starpu_task::handles[STARPU_NMAXBUFS]

Array of starpu_data_handle_t. Specify the handles to the different pieces of data accessed by the task. The number of entries in this array must be specified in the field starpu_codelet::nbuffers, and should not exceed STARPU_NMAXBUFS. If insufficient, this value can be set with the configure option --enable-maxbuffers.

With starpu_task_insert() and alike this is automatically filled when using STARPU_R and alike.

30.12.2.3.1.9 interfaces

void* starpu_task::interfaces[STARPU_NMAXBUFS]

Array of Data pointers to the memory node where execution will happen, managed by the DSM. This is filled by StarPU.
30.12.2.3.1.10 modes

enum starpu_data_access_mode starpu_task::modes[STARPU_NMAXBUFS]

Used only when starpu_codelet::nbuffers is STARPU_VARIABLE_NBUFFERS. Array of starpu_data_access_mode which describes the required access modes to the data needed by the codelet (e.g. STARPU_RW). The number of entries in this array must be specified in the field starpu_task::nbuffers, and should not exceed STARPU_NMAXBUFS. If insufficient, this value can be set with the configure option --enable-maxbuffers.

With starpu_task_insert() and alike this is automatically filled when using ::STARPU_DATA_MODE_ARRAY and alike.

30.12.2.3.1.11 handles_sequential_consistency

unsigned char* starpu_task::handles_sequential_consistency

Optional pointer to an array of characters which allows to define the sequential consistency for each handle for the current task.

With starpu_task_insert() and alike this can be specified thanks to STARPU_HANDLES_SEQUENTIAL_CONSISTENCY followed by an unsigned char *

30.12.2.3.1.12 cl_arg

void* starpu_task::cl_arg

Optional pointer which is passed to the codelet through the second argument of the codelet implementation (e.g. starpu_codelet::cpu_func or starpu_codelet::cuda_func). The default value is NULL. starpu_codelet_pack_args() and starpu_codelet_unpack_args() are helpers that can be used to respectively pack and unpack data into and from it, but the application can manage it any way, the only requirement is that the size of the data must be set in starpu_task::cl_arg_size.

With starpu_task_insert() and alike this can be specified thanks to STARPU_CL_ARGS followed by a void* and a size_t.

30.12.2.3.1.13 cl_arg_size

size_t starpu_task::cl_arg_size

Optional field. For some specific drivers, the pointer starpu_task::cl_arg cannot not be directly given to the driver function. A buffer of size starpu_task::cl_arg_size needs to be allocated on the driver. This buffer is then filled with the starpu_task::cl_arg_size bytes starting at address starpu_task::cl_arg. In this case, the argument given to the codelet is therefore not the starpu_task::cl_arg pointer, but the address of the buffer in local store (LS) instead. This field is ignored for CPU, CUDA and OpenCL codelets, where the starpu_task::cl_arg pointer is given as such.

With starpu_task_insert() and alike this can be specified thanks to STARPU_CL_ARGS followed by a void* and a size_t.

30.12.2.3.1.14 callback_func

void(* starpu_task::callback_func) (void *)

Optional field, the default value is NULL. This is a function pointer of prototype void (*f)(void *) which specifies a possible callback. If this pointer is non-NULL, the callback function is executed on the host after the execution of the task. Tasks which depend on it might already be executing. The callback is passed the value contained in the starpu_task::callback_arg field. No callback is executed if the field is set to NULL.

With starpu_task_insert() and alike this can be specified thanks to STARPU_CALLBACK followed by the function pointer, or thanks to STARPU_CALLBACK_WITH_ARG followed by the function pointer and the argument.

30.12.2.3.1.15 callback_arg

void* starpu_task::callback_arg

Optional field, the default value is NULL. This is the pointer passed to the callback function. This field is ignored if the field starpu_task::callback_func is set to NULL.

With starpu_task_insert() and alike this can be specified thanks to STARPU_CALLBACK_WITH_ARG followed by the function pointer, or thanks to STARPU_CALLBACK_WITH_ARG followed by the function pointer and the argument.

30.12.2.3.1.16 prologue_callback_func

void(* starpu_task::prologue_callback_func) (void *)

Optional field, the default value is NULL. This is a function pointer of prototype void (*f)(void *) which specifies a possible callback. If this pointer is non-NULL, the callback function is executed on the host when the task becomes ready for execution, before getting scheduled. The callback is passed the value contained in the starpu_task::prologue_callback_arg field. No callback is executed if the field is set to NULL.
With `starpu_task_insert()` and alike this can be specified thanks to `::STARPU_PROLOGUE_CALLBACK` followed by the function pointer.

### 30.12.2.3.1.17 prologue_callback_arg

```c
void starpu_task::prologue_callback_arg
```

Optional field, the default value is `NULL`. This is the pointer passed to the prologue callback function. This field is ignored if the field `starpu_task::prologue_callback_func` is set to `NULL`. With `starpu_task_insert()` and alike this can be specified thanks to `::STARPU_PROLOGUE_CALLBACK` followed by the function pointer.

### 30.12.2.3.1.18 tag_id

```c
starpu_tag_t starpu_task::tag_id
```

Optional field. Contain the tag associated to the task if the field `starpu_task::use_tag` is set, ignored otherwise. With `starpu_task_insert()` and alike this can be specified thanks to `STARPU_TAG` followed by a `starpu_tag_t`.

### 30.12.2.3.1.19 cl_arg_free

```c
unsigned starpu_task::cl_arg_free
```

Optional field. In case `starpu_task::cl_arg` was allocated by the application through `malloc()`, setting `starpu_task::cl_arg_free` to 1 makes StarPU automatically call `free(cl_arg)` when destroying the task. This saves the user from defining a callback just for that. This is mostly useful when targeting MIC, where the codelet does not execute in the same memory space as the main thread. With `starpu_task_insert()` and alike this is set to 1 when using `STARPU_CL_ARGS`.

### 30.12.2.3.1.20 callback_arg_free

```c
unsigned starpu_task::callback_arg_free
```

Optional field. In case `starpu_task::callback_arg` was allocated by the application through `malloc()`, setting `starpu_task::callback_arg_free` to 1 makes StarPU automatically call `free(callback_arg)` when destroying the task. TODO: does not have a `starpu_task_insert()` equivalent

### 30.12.2.3.1.21 prologue_callback_arg_free

```c
unsigned starpu_task::prologue_callback_arg_free
```

Optional field. In case `starpu_task::prologue_callback_arg` was allocated by the application through `malloc()`, setting `starpu_task::prologue_callback_arg_free` to 1 makes StarPU automatically call `free(prologue_callback_arg)` when destroying the task. TODO: does not have a `starpu_task_insert()` equivalent

### 30.12.2.3.1.22 prologue_callback_pop_arg_free

```c
unsigned starpu_task::prologue_callback_pop_arg_free
```

Optional field. In case `starpu_task::prologue_callback_pop_arg` was allocated by the application through `malloc()`, setting `starpu_task::prologue_callback_pop_arg_free` to 1 makes StarPU automatically call `free(prologue_callback_pop_arg)` when destroying the task. TODO: does not have a `starpu_task_insert()` equivalent

### 30.12.2.3.1.23 use_tag

```c
unsigned starpu_task::use_tag
```

Optional field, the default value is 0. If set, this flag indicates that the task should be associated with the tag contained in the `starpu_task::tag_id` field. Tag allow the application to synchronize with the task and to express task dependencies easily. With `starpu_task_insert()` and alike this is set to 1 when using `STARPU_TAG`.

### 30.12.2.3.1.24 sequential_consistency

```c
unsigned starpu_task::sequential_consistency
```

If this flag is set (which is the default), sequential consistency is enforced for the data parameters of this task for which sequential consistency is enabled. Clearing this flag permits to disable sequential consistency for this task, even if data have it enabled. TODO: does not have a `starpu_task_insert()` equivalent

### 30.12.2.3.1.25 synchronous

```c
unsigned starpu_task::synchronous
```

Optional field.
If this flag is set, the function `starpu_task_submit()` is blocking and returns only when the task has been executed (or if no worker is able to process the task). Otherwise, `starpu_task_submit()` returns immediately.

With `starpu_task_insert()` and alike this can be specified thanks to `STARPU_TASK_SYNCHRONOUS` followed an int.

### 30.12.2.3.1.26 execute_on_a_specific_worker

```c
unsigned starpu_task::execute_on_a_specific_worker
```

Default value is 0. If this flag is set, StarPU will bypass the scheduler and directly affect this task to the worker specified by the field `starpu_task::workerid`.

With `starpu_task_insert()` and alike this is set to 1 when using `STARPU_EXECUTE_ON_WORKER`.

### 30.12.2.3.1.27 detach

```c
unsigned starpu_task::detach
```

Optional field, default value is 1. If this flag is set, it is not possible to synchronize with the task by the means of `starpu_task_wait()` later on. Internal data structures are only guaranteed to be freed once `starpu_task_wait()` is called if the flag is not set.

With `starpu_task_insert()` and alike this is set to 1.

### 30.12.2.3.1.28 destroy

```c
unsigned starpu_task::destroy
```

Optional value. Default value is 0 for `starpu_task_init()`, and 1 for `starpu_task_create()`. If this flag is set, the task structure will automatically be freed, either after the execution of the callback if the task is detached, or during `starpu_task_wait()` otherwise. If this flag is not set, dynamically allocated data structures will not be freed until `starpu_task_destroy()` is called explicitly. Setting this flag for a statically allocated task structure will result in undefined behaviour. The flag is set to 1 when the task is created by calling `starpu_task_create()`. Note that `starpu_task_wait_for_all()` will not free any task.

With `starpu_task_insert()` and alike this is set to 1.

### 30.12.2.3.1.29 regenerate

```c
unsigned starpu_task::regenerate
```

Optional field. If this flag is set, the task will be re-submitted to StarPU once it has been executed. This flag must not be set if the flag `starpu_task::destroy` is set. This flag must be set before making another task depend on this one.

With `starpu_task_insert()` and alike this is set to 0.

### 30.12.2.3.1.30 mf_skip [private]

This is only used for tasks that use multiformat handle. This should only be used by StarPU.

### 30.12.2.3.1.31 no_submitorder

```c
unsigned starpu_task::no_submitorder
```

Do not allocate a submitorder id for this task

TODO: does not have a `starpu_task_insert()` equivalent

### 30.12.2.3.1.32 scheduled

```c
unsigned starpu_task::scheduled
```

Whether the scheduler has pushed the task on some queue

Set by StarPU.

### 30.12.2.3.1.33 workerid

```c
unsigned starpu_task::workerid
```

Optional field. If the field `starpu_task::execute_on_a_specific_worker` is set, this field indicates the identifier of the worker that should process this task (as returned by `starpu_worker_get_id()`). This field is ignored if the field `starpu_task::execute_on_a_specific_worker` is set to 0.

With `starpu_task_insert()` and alike this can be specified thanks to `STARPU_EXECUTE_ON_WORKER` followed by an int.

### 30.12.2.3.1.34 workerorder

```c
unsigned starpu_task::workerorder
```

Optional field. If the field `starpu_task::execute_on_a_specific_worker` is set, this field indicates the per-worker
consecutive order in which tasks should be executed on the worker. Tasks will be executed in consecutive `starpu_task::workerorder` values, thus ignoring the availability order or task priority. See Static Scheduling for more details. This field is ignored if the field `starpu_task::execute_on_a_specific_worker` is set to 0.

With `starpu_task_insert()` and alike this can be specified thanks to `STARPU_WORKER_ORDER` followed by an unsigned.

30.12.2.3.1.35 workerids

`uint32_t* starpu_task::workerids`

Optional field. If the field `starpu_task::workerids_len` is different from 0, this field indicates an array of bits (stored as `uint32_t` values) which indicate the set of workers which are allowed to execute the task. `starpu_task::workerid` takes precedence over this.

TODO: does not have a `starpu_task_insert()` equivalent

30.12.2.3.1.36 workerids_len

`unsigned starpu_task::workerids_len`

Optional field. This provides the number of `uint32_t` values in the `starpu_task::workerids` array.

TODO: does not have a `starpu_task_insert()` equivalent

30.12.2.3.1.37 priority

`int starpu_task::priority`

Optional field, the default value is `STARPU_DEFAULT_PRIO`. This field indicates a level of priority for the task. This is an integer value that must be set between the return values of the function `starpu_sched_get_min_priority()` for the least important tasks, and that of the function `starpu_sched_get_max_priority()` for the most important tasks (included). The `STARPU_MIN_PRIO` and `STARPU_MAX_PRIO` macros are provided for convenience and respectively return the value of `starpu_sched_get_min_priority()` and `starpu_sched_get_max_priority()`. Default priority is `STARPU_DEFAULT_PRIO`, which is always defined as 0 in order to allow static task initialization. Scheduling strategies that take priorities into account can use this parameter to take better scheduling decisions, but the scheduling policy may also ignore it.

With `starpu_task_insert()` and alike this can be specified thanks to `STARPU_PRIORITY` followed by an unsigned long long.

30.12.2.3.1.38 status

`enum starpu_task_status starpu_task::status`

Current state of the task.
Set by StarPU.

30.12.2.3.1.39 magic

`int starpu_task::magic [private]`

This field is set when initializing a task. The function `starpu_task_submit()` will fail if the field does not have the correct value. This will hence avoid submitting tasks which have not been properly initialised.

30.12.2.3.1.40 type

`unsigned starpu_task::type`

Allow to get the type of task, for filtering out tasks in profiling outputs, whether it is really internal to StarPU (::STARPU_TASK_TYPE_INTERNAL), a data acquisition synchronization task (::STARPU_TASK_TYPE_DATA_ACQUIRE), or a normal task (::STARPU_TASK_TYPE_NORMAL)
Set by StarPU.

30.12.2.3.1.41 color

`unsigned starpu_task::color`

Color of the task to be used in dag.dot.
With `starpu_task_insert()` and alike this can be specified thanks to `STARPU_TASK_COLOR` followed by an int.

30.12.2.3.1.42 sched_ctx

`unsigned starpu_task::sched_ctx`

Scheduling context.
With `starpu_task_insert()` and alike this can be specified thanks to `STARPU_SCHED_CTX` followed by an unsigned.
30.12 Codelet And Tasks

30.12.3.1.43 hypervisor_tag

int starpu_task::hypervisor_tag
Help the hypervisor monitor the execution of this task.
With starpu_task_insert() and alike this can be specified thanks to ::STARPU_HYPERVISOR_TAG followed by an int.

30.12.3.1.44 possibly_parallel

unsigned starpu_task::possibly_parallel
TODO: related with sched contexts and parallel tasks
With starpu_task_insert() and alike this can be specified thanks to ::STARPU_POSSIBLY_PARALLEL followed by an unsigned.

30.12.3.1.45 bundle

starpu_task_bundle_t starpu_task::bundle
Optional field. The bundle that includes this task. If no bundle is used, this should be NULL.

30.12.3.1.46 profiling_info

struct starpu_profiling_task_info* starpu_task::profiling_info
Optional field. Profiling information for the task.
TODO: does not have a starpu_task_insert() equivalent

30.12.3.1.47 flops

double starpu_task::flops
This can be set to the number of floating points operations that the task will have to achieve. This is useful for easily getting GFlops curves from the tool starpu_perfmodel_plot, and for the hypervisor load balancing.
With starpu_task_insert() and alike this can be specified thanks to STARPU_FLOPS followed by a double.

30.12.3.1.48 predicted

double starpu_task::predicted
Output field. Predicted duration of the task. This field is only set if the scheduling strategy uses performance models.
Set by StarPU.

30.12.3.1.49 predicted_transfer

double starpu_task::predicted_transfer
Output field. Predicted data transfer duration for the task in microseconds. This field is only valid if the scheduling strategy uses performance models.
Set by StarPU.

30.12.3.1.50 prev

struct starpu_task* starpu_task::prev [private]
A pointer to the previous task. This should only be used by StarPU schedulers.

30.12.3.1.51 next

struct starpu_task* starpu_task::next [private]
A pointer to the next task. This should only be used by StarPU schedulers.

30.12.3.1.52 starpu_private

void* starpu_task::starpu_private [private]
This is private to StarPU, do not modify.

30.12.3.1.53 omp_task

struct starpu_omp_task* starpu_task::omp_task [private]
This is private to StarPU, do not modify.

30.12.3.1.54 nb_termination_call_required

unsigned starpu_task::nb_termination_call_required [private]
This is private to StarPU, do not modify.

30.12.3.1.55 sched_data

void* starpu_task::sched_data

Generated by Doxygen
This field is managed by the scheduler, is it allowed to do whatever with it. Typically, some area would be allocated on push, and released on pop.

### 30.12.3 Macro Definition Documentation

#### 30.12.3.1 STARPU_NMAXBUFS

```c
#define STARPU_NMAXBUFS
```

Define the maximum number of buffers that tasks will be able to take as parameters. The default value is 8, it can be changed by using the configure option `--enable-maxbuffers`.

#### 30.12.3.2 STARPU_NOWHERE

```c
#define STARPU_NOWHERE
```

To be used when setting the field `starpu_codelet::where` to specify that the codelet has no computation part, and thus does not need to be scheduled, and data does not need to be actually loaded. This is thus essentially used for synchronization tasks.

#### 30.12.3.3 STARPU_CPU

```c
#define STARPU_CPU
```

To be used when setting the field `starpu_codelet::where` (or `starpu_task::where`) to specify the codelet (or the task) may be executed on a CPU processing unit.

#### 30.12.3.4 STARPU_CUDA

```c
#define STARPU_CUDA
```

To be used when setting the field `starpu_codelet::where` (or `starpu_task::where`) to specify the codelet (or the task) may be executed on a CUDA processing unit.

#### 30.12.3.5 STARPU_OPENCL

```c
#define STARPU_OPENCL
```

To be used when setting the field `starpu_codelet::where` (or `starpu_task::where`) to specify the codelet (or the task) may be executed on a OpenCL processing unit.

#### 30.12.3.6 STARPU_MIC

```c
#define STARPU_MIC
```

To be used when setting the field `starpu_codelet::where` (or `starpu_task::where`) to specify the codelet (or the task) may be executed on a MIC processing unit.

#### 30.12.3.7 STARPU_MPI_MS

```c
#define STARPU_MPI_MS
```

To be used when setting the field `starpu_codelet::where` (or `starpu_task::where`) to specify the codelet (or the task) may be executed on a MPI Slave processing unit.

#### 30.12.3.8 STARPU_CODELET_SIMGRID_EXECUTE

```c
#define STARPU_CODELET_SIMGRID_EXECUTE
```

Value to be set in `starpu_codelet::flags` to execute the codelet functions even in simgrid mode.

#### 30.12.3.9 STARPU_CODELET_SIMGRID_EXECUTE_AND_INJECT

```c
#define STARPU_CODELET_SIMGRID_EXECUTE_AND_INJECT
```

Value to be set in `starpu_codelet::flags` to execute the codelet functions even in simgrid mode, and later inject the measured timing inside the simulation.
30.12.3.10  STARPU_CODELET_NOPLANS

#define STARPU_CODELET_NOPLANS
Value to be set in starpu_codelet::flags to make starpu_task_submit() not submit automatic asynchronous partitioning/unpartitioning.

30.12.3.11  STARPU_CUDA_ASYNC

#define STARPU_CUDA_ASYNC
Value to be set in starpu_codelet::cuda_flags to allow asynchronous CUDA kernel execution.

30.12.3.12  STARPU_OPENCL_ASYNC

#define STARPU_OPENCL_ASYNC
Value to be set in starpu_codelet::opencl_flags to allow asynchronous OpenCL kernel execution.

30.12.3.13  STARPU_MAIN_RAM

#define STARPU_MAIN_RAM
To be used when the RAM memory node is specified.

30.12.3.14  STARPU_MULTIPLE_CPU_IMPLEMENTATIONS

#define STARPU_MULTIPLE_CPU_IMPLEMENTATIONS
Deprecated Setting the field starpu_codelet::cpu_func with this macro indicates the codelet will have several implementations. The use of this macro is deprecated. One should always only define the field starpu_codelet::cpu_funcs.

30.12.3.15  STARPU_MULTIPLE_CUDA_IMPLEMENTATIONS

#define STARPU_MULTIPLE_CUDA_IMPLEMENTATIONS
Deprecated Setting the field starpu_codelet::cuda_func with this macro indicates the codelet will have several implementations. The use of this macro is deprecated. One should always only define the field starpu_codelet::cuda_funcs.

30.12.3.16  STARPU_MULTIPLE_OPENCL_IMPLEMENTATIONS

#define STARPU_MULTIPLE_OPENCL_IMPLEMENTATIONS
Deprecated Setting the field starpu_codelet::opencl_func with this macro indicates the codelet will have several implementations. The use of this macro is deprecated. One should always only define the field starpu_codelet::opencl_funcs.

30.12.3.17  STARPU_VARIABLE_NBUFFERS

#define STARPU_VARIABLE_NBUFFERS
Value to set in starpu_codelet::nbuffers to specify that the codelet can accept a variable number of buffers, specified in starpu_task::nbuffers.

30.12.3.18  STARPU_SPECIFIC_NODE_LOCAL

#define STARPU_SPECIFIC_NODE_LOCAL
Value to be set in the field starpu_codelet::nodes to request StarPU to put the data in CPU-accessible memory (and let StarPU choose the NUMA node).
30.12.19 **STARPU_TASK_INITIALIZER**

```c
#define STARPU_TASK_INITIALIZER
```

Value to be used to initialize statically allocated tasks. This is equivalent to initializing a structure `starpu_task` with the function `starpu_task_init()`.

30.12.20 **STARPU_TASK_GET_NBUFFERS**

```c
#define STARPU_TASK_GET_NBUFFERS(task)
```

Return the number of buffers for `task`, i.e. `starpu_codelet::nbuffers`, or `starpu_task::nbuffers` if the former is `STARPU_VARIABLE_NBUFFERS`.

30.12.21 **STARPU_TASK_GET_HANDLE**

```c
#define STARPU_TASK_GET_HANDLE(task, i)
```

Return the `i`-th data handle of `task`. If `task` is defined with a static or dynamic number of handles, will either return the `i`-th element of the field `starpu_task::handles` or the `i`-th element of the field `starpu_task::dyn_handles` (see Setting Many Data Handles For a Task)

30.12.22 **STARPU_TASK_SET_HANDLE**

```c
#define STARPU_TASK_SET_HANDLE(task, handle, i)
```

Set the `i`-th data handle of `task` with `handle`. If `task` is defined with a static or dynamic number of handles, will either set the `i`-th element of the field `starpu_task::handles` or the `i`-th element of the field `starpu_task::dyn_handles` (see Setting Many Data Handles For a Task)

30.12.23 **STARPU_CODELET_GET_MODE**

```c
#define STARPU_CODELET_GET_MODE(codelet, i)
```

Return the access mode of the `i`-th data handle of `codelet`. If `codelet` is defined with a static or dynamic number of handles, will either return the `i`-th element of the field `starpu_codelet::modes` or the `i`-th element of the field `starpu_codelet::dyn_modes` (see Setting Many Data Handles For a Task)

30.12.24 **STARPU_CODELET_SET_MODE**

```c
#define STARPU_CODELET_SET_MODE(codelet, mode, i)
```

Set the access mode of the `i`-th data handle of `codelet`. If `codelet` is defined with a static or dynamic number of handles, will either set the `i`-th element of the field `starpu_codelet::modes` or the `i`-th element of the field `starpu_codelet::dyn_modes` (see Setting Many Data Handles For a Task)

30.12.25 **STARPU_TASK_GET_MODE**

```c
#define STARPU_TASK_GET_MODE(task, i)
```

Return the access mode of the `i`-th data handle of `task`. If `task` is defined with a static or dynamic number of handles, will either return the `i`-th element of the field `starpu_task::modes` or the `i`-th element of the field `starpu_task::dyn_modes` (see Setting Many Data Handles For a Task)
30.12.3.26  **STARPU_TASK_SET_MODE**

```c
#define STARPU_TASK_SET_MODE(
    task,
    mode,
    i
)
```

Set the access mode of the \( i \)-th data handle of `task`. If `task` is defined with a static or dynamic number of handles, will either set the \( i \)-th element of the field `starpu_task::modes` or the \( i \)-th element of the field `starpu_task::dyn_modes` (see Setting Many Data Handles For a Task).

30.12.3.27  **STARPU_CODELET_GET_NODE**

```c
#define STARPU_CODELET_GET_NODE(
    codelet,
    i
)
```

Return the target node of the \( i \)-th data handle of `codelet`. If `node` is defined with a static or dynamic number of handles, will either return the \( i \)-th element of the field `starpu_codelet::nodes` or the \( i \)-th element of the field `starpu_codelet::dyn_nodes` (see Setting Many Data Handles For a Task).

30.12.3.28  **STARPU_CODELET_SET_NODE**

```c
#define STARPU_CODELET_SET_NODE(
    codelet,
    __node,
    i
)
```

Set the target node of the \( i \)-th data handle of `codelet`. If `codelet` is defined with a static or dynamic number of handles, will either set the \( i \)-th element of the field `starpu_codelet::nodes` or the \( i \)-th element of the field `starpu_codelet::dyn_nodes` (see Setting Many Data Handles For a Task).

30.12.4  **Typedef Documentation**

30.12.4.1  **starpu_cpu_func_t**

```c
typedef void(* starpu_cpu_func_t) (void **, void *)
```

CPU implementation of a `codelet`.

30.12.4.2  **starpu_cuda_func_t**

```c
typedef void(* starpu_cuda_func_t) (void **, void *)
```

CUDA implementation of a `codelet`.

30.12.4.3  **starpu_opencl_func_t**

```c
typedef void(* starpu_opencl_func_t) (void **, void *)
```

OpenCL implementation of a `codelet`.

30.12.4.4  **starpu_mic_kernel_t**

```c
typedef void(* starpu_mic_kernel_t) (void **, void *)
```

MIC implementation of a `codelet`.

30.12.4.5  **starpu_mic_func_t**

```c
typedef starpu_mic_kernel_t(* starpu_mic_func_t) (void)
```

MIC kernel for a `codelet`.
30.12.4.6 starpu_mpi_ms_kernel_t

typedef void(* starpu_mpi_ms_kernel_t) (void **, void *) MPI Master Slave kernel for a codelet

30.12.4.7 starpu_mpi_ms_func_t
typedef starpu_mpi_ms_kernel_t(* starpu_mpi_ms_func_t) (void) MPI Master Slave implementation of a codelet.

30.12.5 Enumeration Type Documentation

30.12.5.1 starpu_codelet_type

enum starpu_codelet_type
Describe the type of parallel task. See Parallel Tasks for details.

<table>
<thead>
<tr>
<th>Enumerator</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>STARPU_SEQ</td>
<td>(default) for classical sequential tasks.</td>
</tr>
<tr>
<td>STARPU_SPMD</td>
<td>for a parallel task whose threads are handled by StarPU, the code has to use starpu_combined_worker_get_size() and starpu_combined_worker_get_rank() to distribute the work.</td>
</tr>
<tr>
<td>STARPU_FORKJOIN</td>
<td>for a parallel task whose threads are started by the codelet function, which has to use starpu_combined_worker_get_size() to determine how many threads should be started.</td>
</tr>
</tbody>
</table>

30.12.5.2 starpu_task_status

enum starpu_task_status

<table>
<thead>
<tr>
<th>Enumerator</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>STARPU_TASK_INVALID</td>
<td>The task has just been initialized.</td>
</tr>
<tr>
<td>STARPU_TASK_INVALID</td>
<td>The task has just been initialized.</td>
</tr>
<tr>
<td>STARPU_TASK_BLOCKED</td>
<td>The task has just been submitted, and its dependencies has not been checked yet.</td>
</tr>
<tr>
<td>STARPU_TASK_READY</td>
<td>The task is ready for execution.</td>
</tr>
<tr>
<td>STARPU_TASK_RUNNING</td>
<td>The task is running on some worker.</td>
</tr>
<tr>
<td>STARPU_TASK_FINISHED</td>
<td>The task is finished executing.</td>
</tr>
<tr>
<td>STARPU_TASK_BLOCKED_ON_TAG</td>
<td>The task is waiting for a tag.</td>
</tr>
<tr>
<td>STARPU_TASK_BLOCKED_ON_TASK</td>
<td>The task is waiting for a task.</td>
</tr>
<tr>
<td>STARPU_TASK_BLOCKED_ON_DATA</td>
<td>The task is waiting for some data.</td>
</tr>
<tr>
<td>STARPU_TASK_STOPPED</td>
<td>The task is stopped.</td>
</tr>
</tbody>
</table>

30.12.6 Function Documentation
30.12.6.1 starpu_task_init()

```c
void starpu_task_init (  
    struct starpu_task * task )
```

Initialize `task` with default values. This function is implicitly called by `starpu_task_create()`. By default, tasks initialized with `starpu_task_init()` must be deinitialized explicitly with `starpu_task_clean()`. Tasks can also be initialized statically, using `STARPU_TASK_INITIALIZER`.

30.12.6.2 starpu_task_clean()

```c
void starpu_task_clean (  
    struct starpu_task * task )
```

Release all the structures automatically allocated to execute `task`, but not the task structure itself and values set by the user remain unchanged. It is thus useful for statically allocated tasks for instance. It is also useful when users want to execute the same operation several times with as least overhead as possible. It is called automatically by `starpu_task_destroy()`. It has to be called only after explicitly waiting for the task or after `starpu_shutdown()` (waiting for the callback is not enough, since StarPU still manipulates the task after calling the callback).

30.12.6.3 starpu_task_create()

```c
struct starpu_task* starpu_task_create (  
    void )
```

Allocate a task structure and initialize it with default values. Tasks allocated dynamically with `starpu_task_create()` are automatically freed when the task is terminated. This means that the task pointer can not be used any more once the task is submitted, since it can be executed at any time (unless dependencies make it wait) and thus freed at any time. If the field `starpu_task::destroy` is explicitly unset, the resources used by the task have to be freed by calling `starpu_task_destroy()`.

30.12.6.4 starpu_task_destroy()

```c
void starpu_task_destroy (  
    struct starpu_task * task )
```

Free the resource allocated during `starpu_task_create()` and associated with `task`. This function is called automatically after the execution of a task when the field `starpu_task::destroy` is set, which is the default for tasks created by `starpu_task_create()`. Calling this function on a statically allocated task results in an undefined behaviour.

30.12.6.5 starpu_task_submit()

```c
int starpu_task_submit (  
    struct starpu_task * task )
```

Submit `task` to StarPU. Calling this function does not mean that the task will be executed immediately as there can be data or task (tag) dependencies that are not fulfilled yet: StarPU will take care of scheduling this task with respect to such dependencies. This function returns immediately if the field `starpu_task::synchronous` is set to 0, and block until the termination of the task otherwise. It is also possible to synchronize the application with asynchronous tasks by the means of tags, using the function `starpu_tag_wait()` function for instance. In case of success, this function returns 0, a return value of −ENODEV means that there is no worker able to process this task (e.g. there is no GPU available and this task is only implemented for CUDA devices). `starpu_task_submit()` can be called from anywhere, including codelet functions and callbacks, provided that the field `starpu_task::synchronous` is set to 0.

30.12.6.6 starpu_task_submit_to_ctx()

```c
int starpu_task_submit_to_ctx (  
    struct starpu_task * task,  
    unsigned sched_ctx_id )
```

Submit `task` to the context `sched_ctx_id`. By default, `starpu_task_submit()` submits the task to a global context that is created automatically by StarPU.
30.12.6.7  starpu_task_wait()

int starpu_task_wait (  
  struct starpu_task * task )  
Block until task has been executed. It is not possible to synchronize with a task more than once. It is not possible to wait for synchronous or detached tasks. Upon successful completion, this function returns 0. Otherwise, -EINVAL indicates that the specified task was either synchronous or detached.

30.12.6.8  starpu_task_wait_array()

int starpu_task_wait_array (  
  struct starpu_task ** tasks,  
  unsigned nb_tasks )  
Allow to wait for an array of tasks. Upon successful completion, this function returns 0. Otherwise, -EINVAL indicates that one of the tasks was either synchronous or detached.

30.12.6.9  starpu_task_wait_for_all()

int starpu_task_wait_for_all (  
  void )  
Block until all the tasks that were submitted (to the current context or the global one if there is no current context) are terminated. It does not destroy these tasks.

30.12.6.10  starpu_task_wait_for_n_submitted()

int starpu_task_wait_for_n_submitted (  
  unsigned n )  
Block until there are n submitted tasks left (to the current context or the global one if there is no current context) to be executed. It does not destroy these tasks.

30.12.6.11  starpu_task_wait_for_all_in_ctx()

int starpu_task_wait_for_all_in_ctx (  
  unsigned sched_ctx_id )  
Wait until all the tasks that were already submitted to the context sched_ctx_id have been terminated.

30.12.6.12  starpu_task_wait_for_n_submitted_in_ctx()

int starpu_task_wait_for_n_submitted_in_ctx (  
  unsigned sched_ctx_id,  
  unsigned n )  
Wait until there are n tasks submitted left to be executed that were already submitted to the context sched_ctx_id.

30.12.6.13  starpu_task_wait_for_no_ready()

int starpu_task_wait_for_no_ready (  
  void )  
Wait until there is no more ready task.

30.12.6.14  starpu_task_nready()

int starpu_task_nready (  
  void )  
Return the number of submitted tasks which are ready for execution are already executing. It thus does not include tasks waiting for dependencies.
30.12.6.15  starpu_task_nsubmitted()

int starpu_task_nsubmitted (  
    void )  

Return the number of submitted tasks which have not completed yet.

30.12.6.16  starpu_iteration_push()

void starpu_iteration_push (  
    unsigned long iteration )  

Set the iteration number for all the tasks to be submitted after this call. This is typically called at the beginning of a task submission loop. This number will then show up in tracing tools. A corresponding starpu_iteration_pop() call must be made to match the call to starpu_iteration_push(), at the end of the same task submission loop, typically. Nested calls to starpu_iteration_push() and starpu_iteration_pop() are allowed, to describe a loop nest for instance, provided that they match properly.

30.12.6.17  starpu_iteration_pop()

void starpu_iteration_pop (  
    void )  

Drop the iteration number for submitted tasks. This must match a previous call to starpu_iteration_push(), and is typically called at the end of a task submission loop.

30.12.6.18  starpu_codelet_init()

void starpu_codelet_init (  
    struct starpu_codelet * cl )  

Initialize cl with default values. Codelets should preferably be initialized statically as shown in Defining A Codelet. However such a initialisation is not always possible, e.g. when using C++.

30.12.6.19  starpu_codelet_display_stats()

void starpu_codelet_display_stats {  
    struct starpu_codelet * cl )  

Output on stderr some statistics on the codelet cl.

30.12.6.20  starpu_task_get_current()

struct starpu_task* starpu_task_get_current (  
    void )  

Return the task currently executed by the worker, or NULL if it is called either from a thread that is not a task or simply because there is no task being executed at the moment.

30.12.6.21  starpu_task_get_current_data_node()

int starpu_task_get_current_data_node (  
    unsigned i )  

Return the memory node number of parameter i of the task currently executed, or -1 if it is called either from a thread that is not a task or simply because there is no task being executed at the moment. Usually, the returned memory node number is simply the memory node for the current worker. That may however be different when using e.g. starpu_codelet::specific_nodes.

30.12.6.22  starpu_task_get_model_name()

const char* starpu_task_get_model_name (  
    struct starpu_task * task )  

Return the name of the performance model of task.
### 30.12.6.23 starpu_task_get_name()

```c
const char* starpu_task_get_name (struct starpu_task * task)
```

Return the name of `task`, i.e. either its `starpu_task::name` field, or the name of the corresponding performance model.

### 30.12.6.24 starpu_task_dup()

```c
struct starpu_task* starpu_task_dup (struct starpu_task * task)
```

Allocate a task structure which is the exact duplicate of `task`.

### 30.12.6.25 starpu_task_set_implementation()

```c
void starpu_task_set_implementation (struct starpu_task * task, unsigned impl)
```

This function should be called by schedulers to specify the codelet implementation to be executed when executing `task`.

### 30.12.6.26 starpu_task_get_implementation()

```c
unsigned starpu_task_get_implementation (struct starpu_task * task)
```

Return the codelet implementation to be executed when executing `task`.

### 30.12.6.27 starpu_create_sync_task()

```c
void starpu_create_sync_task (starpu_tag_t sync_tag, unsigned ndeps, starpu_tag_t * deps, void(*)(void *) callback, void * callback_arg)
```

Create (and submit) an empty task that unlocks a tag once all its dependencies are fulfilled.

### 30.13 Task Insert Utility

#### Data Structures

- `struct starpu_codelet_pack_arg_data`

#### Macros

- `#define STARPU_MODE_SHIFT`
- `#define STARPU_VALUE`
- `#define STARPU_CALLBACK`
- `#define STARPU_CALLBACK_WITH_ARG`
- `#define STARPU_CALLBACK_ARG`
- `#define STARPU_PRIORITY`
- `#define STARPU_DATA_ARRAY`
- `#define STARPU_DATA_MODE_ARRAY`
- `#define STARPU_TAG`
- `#define STARPU_HYPERVISOR_TAG`
- `#define STARPU_FLOPS`
- `#define STARPU_SCHED_CTX`
- `#define STARPU_PROLOGUE_CALLBACK`
• #define STARPU_PROLOGUE_CALLBACK_ARG
• #define STARPU_PROLOGUE_CALLBACK_POP
• #define STARPU_PROLOGUE_CALLBACK_POP_ARG
• #define STARPU_EXECUTE_ON_WORKER
• #define STARPU_EXECUTE_WHERE
• #define STARPU_TAG_ONLY
• #define STARPU_POSSIBLY_PARALLEL
• #define STARPU_WORKER_ORDER
• #define STARPU_NAME
• #define STARPU_CL_ARGS
• #define STARPU_CL_ARGS_NFREE
• #define STARPU_TASK_DEPS_ARRAY
• #define STARPU_TASK_COLOR
• #define STARPU_HANDLEsSEQUENTIAL_CONSISTENCY
• #define STARPU_TASK_SYNCHRONOUS
• #define STARPU_TASK_END_DEPS_ARRAY
• #define STARPU_TASK_END_DEP
• #define STARPU_SHIFTED_MODE_MAX

Functions
• int starpu_task_set (struct starpu_task *task, struct starpu_codelet *cl,...)
• struct starpu_task * starpu_task_build (struct starpu_codelet *cl,...)
• int starpu_task_insert (struct starpu_codelet *cl,...)
• int starpu_insert_task (struct starpu_codelet *cl,...)
• void starpu_task_insert_data_make_room (struct starpu_codelet *cl, struct starpu_task *task, int *allocated_buffers, int current_buffer, int room)
• void starpu_task_insert_data_process_arg (struct starpu_codelet *cl, struct starpu_task *task, int *allocated_buffers, int current_buffer, int arg_type, starpu_data_handle_t handle)
• void starpu_task_insert_data_process_array_arg (struct starpu_codelet *cl, struct starpu_task *task, int *allocated_buffers, int current_buffer, int nb_handles, starpu_data_handle_t *handles)
• void starpu_task_insert_data_process_mode_array_arg (struct starpu_codelet *cl, struct starpu_task *task, int *allocated_buffers, int current_buffer, int nb_descrs, struct starpu_data_descr *descrs)
• void starpu_codelet_pack_args (void **arg_buffer, size_t *arg_buffer_size,...)
• void starpu_codelet_pack_arg_init (struct starpu_codelet_pack_arg_data *state)
• void starpu_codelet_pack_arg (struct starpu_codelet_pack_arg_data *state, const void *ptr, size_t ptr_size)
• void starpu_codelet_pack_arg_fini (struct starpu_codelet_pack_arg_data *state, void **cl_arg, size_t cl_arg_size)
• void starpu_codelet_unpack_args (void *cl_arg,...)
• void starpu_codelet_unpack_args_and_copyleft (void *cl_arg, void *buffer, size_t buffer_size,...)

30.13.1 Detailed Description
30.13.2 Data Structure Documentation
30.13.2.1 struct starpu_codelet_pack_arg_data

Data Fields

<table>
<thead>
<tr>
<th>char</th>
<th>arg_buffer</th>
</tr>
</thead>
<tbody>
<tr>
<td>size_t</td>
<td>arg_buffer_size</td>
</tr>
<tr>
<td>size_t</td>
<td>current_offset</td>
</tr>
<tr>
<td>int</td>
<td>nargs</td>
</tr>
</tbody>
</table>
30.13.3 Macro Definition Documentation

30.13.3.1 STARPU_VALUE

#define STARPU_VALUE
Used when calling starpu_task_insert(), must be followed by a pointer to a constant value and the size of the constant

30.13.3.2 STARPU_CALLBACK

#define STARPU_CALLBACK
Used when calling starpu_task_insert(), must be followed by a pointer to a callback function

30.13.3.3 STARPU_CALLBACK_WITH_ARG

#define STARPU_CALLBACK_WITH_ARG
Used when calling starpu_task_insert(), must be followed by two pointers: one to a callback function, and the other to be given as an argument to the callback function; this is equivalent to using both STARPU_CALLBACK and STARPU_CALLBACK_WITH_ARG.

30.13.3.4 STARPU_CALLBACK_ARG

#define STARPU_CALLBACK_ARG
Used when calling starpu_task_insert(), must be followed by a pointer to be given as an argument to the callback function

30.13.3.5 STARPU_PRIORITY

#define STARPU_PRIORITY
Used when calling starpu_task_insert(), must be followed by a integer defining a priority level

30.13.3.6 STARPU_TAG

#define STARPU_TAG
Used when calling starpu_task_insert(), must be followed by a tag.

30.13.3.7 STARPU_FLOPS

#define STARPU_FLOPS
Used when calling starpu_task_insert(), must be followed by an amount of floating point operations, as a double. Users MUST explicitly cast into double, otherwise parameter passing will not work.

30.13.3.8 STARPU_SCHED_CTX

#define STARPU_SCHED_CTX
Used when calling starpu_task_insert(), must be followed by the id of the scheduling context to which to submit the task to.

30.13.3.9 STARPU_EXECUTE_ON_WORKER

#define STARPU_EXECUTE_ON_WORKER
Used when calling starpu_task_insert(), must be followed by an integer value specifying the worker on which to execute the task (as specified by starpu_task::execute_on_a_specific_worker)

30.13.3.10 STARPU_EXECUTE_WHERE

#define STARPU_EXECUTE_WHERE
Used when calling starpu_task_insert(), must be followed by an unsigned long long value specifying the mask of worker on which to execute the task (as specified by starpu_task::where)
30.13.3.11 STARPU_TAG_ONLY

#define STARPU_TAG_ONLY
Used when calling starpu_task_insert(), must be followed by a tag stored in starpu_task::tag_id. Leave starpu_task::use_tag as 0.

30.13.3.12 STARPU_WORKER_ORDER

#define STARPU_WORKER_ORDER
Used when calling starpu_task_insert(), must be followed by an integer value specifying the worker order in which to execute the tasks (as specified by starpu_task::workerorder)

30.13.3.13 STARPU_NAME

#define STARPU_NAME
Used when calling starpu_task_insert(), must be followed by a char * stored in starpu_task::name.

30.13.3.14 STARPU_CL_ARGS

#define STARPU_CL_ARGS
Used when calling starpu_task_insert(), must be followed by a memory buffer containing the arguments to be given to the task, and by the size of the arguments. The memory buffer should be the result of a previous call to starpu_codelet_pack_args(), and will be freed (i.e. starpu_task::cl_arg_free will be set to 1)

30.13.3.15 STARPU_CL_ARGS_NFREE

#define STARPU_CL_ARGS_NFREE
Used when calling starpu_task_insert(), similarly to STARPU_CL_ARGS, must be followed by a memory buffer containing the arguments to be given to the task, and by the size of the arguments. The memory buffer should be the result of a previous call to starpu_codelet_pack_args(), and will NOT be freed (i.e. starpu_task::cl_arg_free will be set to 0)

30.13.3.16 STARPU_TASK_DEPS_ARRAY

#define STARPU_TASK_DEPS_ARRAY
Used when calling starpu_task_insert(), must be followed by a number of tasks as int, and an array containing these tasks. The function starpu_task_declare_deps_array() will be called with the given values.

30.13.3.17 STARPU_TASK_COLOR

#define STARPU_TASK_COLOR
Used when calling starpu_task_insert(), must be followed by an integer representing a color

30.13.3.18 STARPU_HANDLES_SEQUENTIAL_CONSISTENCY

#define STARPU_HANDLES_SEQUENTIAL_CONSISTENCY
Used when calling starpu_task_insert(), must be followed by an array of characters representing the sequential consistency for each buffer of the task.

30.13.3.19 STARPU_TASK_SYNCHRONOUS

#define STARPU_TASK_SYNCHRONOUS
Used when calling starpu_task_insert(), must be followed by an integer stating if the task is synchronous or not

30.13.3.20 STARPU_TASK_END_DEPS_ARRAY

#define STARPU_TASK_END_DEPS_ARRAY
Used when calling starpu_task_insert(), must be followed by a number of tasks as int, and an array containing these tasks. The function starpu_task_declare_end_deps_array() will be called with the given values.
30.13.3.21  STARPU_TASK_END_DEP

#define STARPU_TASK_END_DEP
Used when calling starpu_task_insert(), must be followed by an integer which will be given to starpu_task_end← dep_add()

30.13.4  Function Documentation

30.13.4.1  starpu_task_set()

int starpu_task_set (
    struct starpu_task * task,
    struct starpu_codelet * cl,
    ... )

Set the given task corresponding to cl with the following arguments. The argument list must be zero-terminated. The arguments following the codelet are the same as the ones for the function starpu_task_insert(). If some arguments of type STARPU_VALUE are given, the parameter starpu_task::cl_arg_free will be set to 1.

30.13.4.2  starpu_task_build()

struct starpu_task* starpu_task_build (
    struct starpu_codelet * cl,
    ... )

Create a task corresponding to cl with the following arguments. The argument list must be zero-terminated. The arguments following the codelet are the same as the ones for the function starpu_task_insert(). If some arguments of type STARPU_VALUE are given, the parameter starpu_task::cl_arg_free will be set to 1.

30.13.4.3  starpu_task_insert()

int starpu_task_insert {
    struct starpu_codelet * cl,
    ... )

Create and submit a task corresponding to cl with the following given arguments. The argument list must be zero-terminated. The arguments following the codelet can be of the following types:

- STARPU_R, STARPU_W, STARPU_RW, STARPU_SCRATCH, STARPU_REDUX an access mode followed by a data handle;
- ::STARPU_DATA_ARRAY followed by an array of data handles and its number of elements;
- ::STARPU_DATA_MODE_ARRAY followed by an array of struct starpu_data_descr, i.e data handles with their associated access modes, and its number of elements;
- STARPU_EXECUTE_ON_WORKER, STARPU_WORKER_ORDER followed by an integer value specifying the worker on which to execute the task (as specified by starpu_task::execute_on_a_specific_worker)
- the specific values STARPU_VALUE, STARPU_CALLBACK, STARPU_CALLBACK_ARG, STARPU_CLARRBACK_WITH_ARG, STARPU_PRIORITY, STARPU_TAG, STARPU_TAG_ONLY, STARPU_FLOPS, STARPU_SCHED_CTX, STARPU_CL_ARGS, STARPU_CL_ARGS_NFREE, STARPU_TASK_DEPS_array, STARPU_TASK_COLOR, STARPU_HANDLES_SEQUENTIAL_CONSISTENCY, STARPU_TASK_SYNCHRONOUS, STARPU_TASK_END_DEP followed by the appropriated objects as defined elsewhere.

When using ::STARPU_DATA_ARRAY, the access mode of the data handles is not defined, it will be taken from the codelet starpu_codelet::modes or starpu_codelet::dyn_modes field. One should use ::STARPU_DATA_MODE_ARRAY to define the data handles along with the access modes.
Parameters to be passed to the codelet implementation are defined through the type STARPU_VALUE. The function starpu_codelet_unpack_args() must be called within the codelet implementation to retrieve them.
30.13 Task Insert Utility

30.13.4.4 *starpu_insert_task()*

```c
int starpu_insert_task (
    struct starpu_codelet * cl,
    ...
)
```

Similar to *starpu_task_insert*. Kept to avoid breaking old codes.

30.13.4.5 *starpu_task_insert_data_make_room()*

```c
void starpu_task_insert_data_make_room (
    struct starpu_codelet * cl,
    struct starpu_task * task,
    int * allocated_buffers,
    int current_buffer,
    int room
)
```

Assuming that there are already `current_buffer` data handles passed to the task, and if `allocated_buffers` is not 0, the `task->dyn_handles array` has size `allocated_buffers`, this function makes room for `room` other data handles, allocating or reallocating `task->dyn_handles` as necessary and updating `allocated_buffers` accordingly. One can thus start with `allocated_buffers` equal to 0 and `current_buffer` equal to 0, then make room by calling this function, then store handles with `STARPU_TASK_SET_HANDLE()`, make room again with this function, store yet more handles, etc.

30.13.4.6 *starpu_task_insert_data_process_arg()*

```c
void starpu_task_insert_data_process_arg (
    struct starpu_codelet * cl,
    struct starpu_task * task,
    int * allocated_buffers,
    int * current_buffer,
    int arg_type, 
    starpu_data_handle_t handle
)
```

Store data handle `handle` into task `task` with mode `arg_type`, updating `allocated_buffers` and `current_buffer` accordingly.

30.13.4.7 *starpu_task_insert_data_process_array_arg()*

```c
void starpu_task_insert_data_process_array_arg (
    struct starpu_codelet * cl,
    struct starpu_task * task,
    int * allocated_buffers,
    int * current_buffer,
    int nb_handles,
    starpu_data_handle_t * handles
)
```

Store `nb_handles` data handles `handles` into task `task`, updating `allocated_buffers` and `current_buffer` accordingly.

30.13.4.8 *starpu_task_insert_data_process_mode_array_arg()*

```c
void starpu_task_insert_data_process_mode_array_arg (
    struct starpu_codelet * cl,
    struct starpu_task * task,
    int * allocated_buffers,
    int * current_buffer,
    int nb_descrs,
    struct starpu_data_descr * descrs
)
```

Store `nb_descrs` data handles described by `descrs` into task `task`, updating `allocated_buffers` and `current_buffer` accordingly.
30.13.9 starpu_codelet_pack_args()

```c
void starpu_codelet_pack_args (  
    void ** arg_buffer,  
    size_t * arg_buffer_size,  
    ... )
```

Pack arguments of type STARPU_VALUE into a buffer which can be given to a codelet and later unpacked with the function starpu_codelet_unpack_args().

Instead of calling starpu_codelet_pack_args(), one can also call starpu_codelet_pack_arg_init(), then starpu_codelet_pack_arg() for each data, then starpu_codelet_pack_arg_fini().

30.13.10 starpu_codelet_pack_arg_init()

```c
void starpu_codelet_pack_arg_init {  
    struct starpu_codelet_pack_arg_data * state  
}
```

Initialize struct starpu_codelet_pack_arg before calling starpu_codelet_pack_arg() and starpu_codelet_pack_arg_fini(). This will simply initialize the content of the structure.

30.13.11 starpu_codelet_pack_arg()

```c
void starpu_codelet_pack_arg {  
    struct starpu_codelet_pack_arg_data * state,  
    const void * ptr,  
    size_t ptr_size  
}
```

Pack one argument into struct starpu_codelet_pack_arg state. That structure has to be initialized before with starpu_codelet_pack_arg_init(), and after all starpu_codelet_pack_arg() calls performed, starpu_codelet_pack_arg_fini() has to be used to get the cl_arg and cl_arg_size to be put in the task.

30.13.12 starpu_codelet_pack_arg_fini()

```c
void starpu_codelet_pack_arg_fini {  
    struct starpu_codelet_pack_arg_data * state,  
    void ** cl_arg,  
    size_t * cl_arg_size  
}
```

Finish packing data, after calling starpu_codelet_pack_arg_init() once and starpu_codelet_pack_arg() several times.

30.13.13 starpu_codelet_unpack_args()

```c
void starpu_codelet_unpack_args (  
    void * cl_arg,  
    ... )
```

Retrieve the arguments of type STARPU_VALUE associated to a task automatically created using the function starpu_task_insert(). If any parameter's value is 0, unpacking will stop there and ignore the remaining parameters.

30.13.14 starpu_codelet_unpack_args_and_copyleft()

```c
void starpu_codelet_unpack_args_and_copyleft {  
    void * cl_arg,  
    void * buffer,  
    size_t buffer_size,  
    ... )
```

Similar to starpu_codelet_unpack_args(), but if any parameter is 0, copy the part of cl_arg that has not been read in buffer which can then be used in a later call to one of the unpack functions.

30.14 Explicit Dependencies
Typedefs

- typedef uint64_t starpu_tag_t

Functions

- void starpu_task_declare_deps_array (struct starpu_task *task, unsigned ndeps, struct starpu_task *task←_array[])
- void starpu_task_declare_deps (struct starpu_task *task, unsigned ndeps,...)
- void starpu_task_declare_end_deps_array (struct starpu_task *task, unsigned ndeps, struct starpu_task *task_array[])
- void starpu_task_declare_end_deps (struct starpu_task *task, unsigned ndeps,...)
- int starpu_task_get_task_succs (struct starpu_task *task, unsigned ndeps, struct starpu_task *task_array[])
- int starpu_task_get_task_scheduled_succs (struct starpu_task *task, unsigned ndeps, struct starpu_task *task_array[])
- void starpu_task_end_dep_add (struct starpu_task *t, int nb_deps)
- void starpu_task_end_dep_release (struct starpu_task *t)
- void starpu_tag_declare_deps (starpu_tag_t id, unsigned ndeps,...)
- void starpu_tag_declare_deps_array (starpu_tag_t id, unsigned ndeps, starpu_tag_t *array)
- int starpu_tag_wait (starpu_tag_t id)
- int starpu_tag_wait_array (unsigned ntags, starpu_tag_t *id)
- void starpu_tag_restart (starpu_tag_t id)
- void starpu_tag_remove (starpu_tag_t id)
- void starpu_tag_notify_from_apps (starpu_tag_t id)
- struct starpu_task *starpu_tag_get_task (starpu_tag_t id)

30.14.1 Detailed Description

30.14.2 Typedef Documentation

30.14.2.1 starpu_tag_t

typedef uint64_t starpu_tag_t

Define a task logical identifier. It is possible to associate a task with a unique tag chosen by the application, and to express dependencies between tasks by the means of those tags. To do so, fill the field starpu_task::tag_id with a tag number (can be arbitrary) and set the field starpu_task::use_tag to 1. If starpu_tag_declare_deps() is called with this tag number, the task will not be started until the tasks which holds the declared dependency tags are completed.

30.14.3 Function Documentation

30.14.3.1 starpu_task_declare_deps_array()

void starpu_task_declare_deps_array (struct starpu_task *task, unsigned ndeps, struct starpu_task *task←_array[])

Declare task dependencies between a task and an array of tasks of length ndeps. This function must be called prior to the submission of the task, but it may called after the submission or the execution of the tasks in the array, provided the tasks are still valid (i.e. they were not automatically destroyed). Calling this function on a task that was already submitted or with an entry of task_array that is no longer a valid task results in an undefined behaviour. If ndeps is 0, no dependency is added. It is possible to call starpu_task_declare_deps_array() several times on the same task, in this case, the dependencies are added. It is possible to have redundancy in the task dependencies.
30.14.3.2 starpu_task_declare_deps()

```c
void starpu_task_declare_deps (struct starpu_task * task, unsigned ndeps, ...)
```

Declare task dependencies between a task and an series of ndeps tasks, similarly to starpu_task_declare←_deps_array(), but the tasks are passed after ndeps, which indicates how many tasks task shall be made to depend on. If ndeps is 0, no dependency is added.

30.14.3.3 starpu_task_declare_end_deps_array()

```c
void starpu_task_declare_end_deps_array (struct starpu_task * task, unsigned ndeps, struct starpu_task * task_array[])
```

Declare task end dependencies between a task and an array of tasks of length ndeps. task will appear as terminated not only when task is termination, but also when the tasks of task_array have terminated. This function must be called prior to the termination of the task, but it may called after the submission or the execution of the tasks in the array, provided the tasks are still valid (i.e. they were not automatically destroyed). Calling this function on a task that was already terminated or with an entry of task_array that is no longer a valid task results in an undefined behaviour. If ndeps is 0, no dependency is added. It is possible to call starpu_task_declare←_end_deps_array() several times on the same task, in this case, the dependencies are added. It is currently not implemented to have redundancy in the task dependencies.

30.14.3.4 starpu_task_declare_end_deps()

```c
void starpu_task_declare_end_deps (struct starpu_task * task, unsigned ndeps, ...)
```

Declare task end dependencies between a task and an series of ndeps tasks, similarly to starpu_task_declare←_end_deps_array(), but the tasks are passed after ndeps, which indicates how many tasks task 's termination shall be made to depend on. If ndeps is 0, no dependency is added.

30.14.3.5 starpu_task_get_task_succs()

```c
int starpu_task_get_task_succs (struct starpu_task * task, unsigned ndeps, struct starpu_task * task_array[])
```

Fill task_array with the list of tasks which are direct children of task. ndeps is the size of task_array. This function returns the number of direct children. task_array can be set to NULL if ndeps is 0, which allows to compute the number of children before allocating an array to store them. This function can only be called if task has not completed yet, otherwise the results are undefined. The result may also be outdated if some additional dependency has been added in the meanwhile.

30.14.3.6 starpu_task_get_task_scheduled_succs()

```c
int starpu_task_get_task_scheduled_succs (struct starpu_task * task, unsigned ndeps, struct starpu_task * task_array[])
```

Behave like starpu_task_get_task_succs(), except that it only reports tasks which will go through the scheduler, thus avoiding tasks with not codelet, or with explicit placement.

30.14.3.7 starpu_task_end_dep_add()

```c
void starpu_task_end_dep_add ( ...
```
struct starpu_task * t,
    int nb_deps );

Add nb_deps end dependencies to the task t. This means the task will not terminate until the required number of calls to the function starpu_task_end_dep_release() has been made.

30.14.3.8 starpu_task_end_dep_release()

void starpu_task_end_dep_release ( struct starpu_task * t )

Unlock 1 end dependency to the task t. This function must be called after starpu_task_end_dep_add().

30.14.3.9 starpu_tag_declare_deps()

void starpu_tag_declare_deps ( starpu_tag_t id,
    unsigned ndeps,
    ...
 )

Specify the dependencies of the task identified by tag id. The first argument specifies the tag which is configured, the second argument gives the number of tag(s) on which id depends. The following arguments are the tags which have to be terminated to unlock the task. This function must be called before the associated task is submitted to StarPU with starpu_task_submit().

WARNING! Use with caution. Because of the variable arity of starpu_tag_declare_deps(), note that the last arguments must be of type starpu_tag_t: constant values typically need to be explicitly casted. Otherwise, due to integer sizes and argument passing on the stack, the C compiler might consider the tag 0x200000003 instead of 0x2 and 0x3 when calling starpu_tag_declare_deps(0x1, 2, 0x2, 0x3). Using the starpu_tag_declare_deps_array() function avoids this hazard.

// Tag 0x1 depends on tags 0x32 and 0x52
starpu_tag_t tag_array[2] = {0x32, 0x52};
starpu_tag_declare_deps_array((starpu_tag_t)0x1, 2, tag_array);

30.14.3.10 starpu_tag_declare_deps_array()

void starpu_tag_declare_deps_array ( starpu_tag_t id,
    unsigned ndeps,
    starpu_tag_t * array )

Similar to starpu_tag_declare_deps(), except that its does not take a variable number of arguments but an array of tags of size ndeps.

// Tag 0x1 depends on tags 0x32 and 0x52
starpu_tag_t tag_array[2] = {0x32, 0x52};
starpu_tag_declare_deps_array((starpu_tag_t)0x1, 2, tag_array);

30.14.3.11 starpu_tag_wait()

int starpu_tag_wait ( starpu_tag_t id )

Block until the task associated to tag id has been executed. This is a blocking call which must therefore not be called within tasks or callbacks, but only from the application directly. It is possible to synchronize with the same tag multiple times, as long as the starpu_tag_remove() function is not called. Note that it is still possible to synchronize with a tag associated to a task for which the structure starpu_task was freed (e.g. if the field starpu_task::destroy was enabled).

30.14.3.12 starpu_tag_wait_array()

int starpu_tag_wait_array ( unsigned ntags,
    starpu_tag_t * id )
Similar to `starpu_tag_wait()` except that it blocks until all the `ntags` tags contained in the array `id` are terminated.

### 30.14.3.13 `starpu_tag_restart()`

```c
void starpu_tag_restart (starpu_tag_t id)
```

Clear the already notified status of a tag which is not associated with a task. Before that, calling `starpu_tag_notify_from_apps()` again will not notify the successors. After that, the next call to `starpu_tag_notify_from_apps()` will notify the successors.

### 30.14.3.14 `starpu_tag_remove()`

```c
void starpu_tag_remove (starpu_tag_t id)
```

Release the resources associated to tag `id`. It can be called once the corresponding task has been executed and when there is no other tag that depend on this tag anymore.

### 30.14.3.15 `starpu_tag_notify_from_apps()`

```c
void starpu_tag_notify_from_apps (starpu_tag_t id)
```

Explicitly unlock tag `id`. It may be useful in the case of applications which execute part of their computation outside StarPU tasks (e.g. third-party libraries). It is also provided as a convenient tool for the programmer, for instance to entirely construct the task DAG before actually giving StarPU the opportunity to execute the tasks. When called several times on the same tag, notification will be done only on first call, thus implementing "OR" dependencies, until the tag is restarted using `starpu_tag_restart()`.

### 30.15 Performance Model

#### Data Structures
- `struct starpu_perfmodel_device`
- `struct starpu_perfmodel_arch`
- `struct starpu_perfmodel_history_entry`
- `struct starpu_perfmodel_history_list`
- `struct starpu_perfmodel_regression_model`
- `struct starpu_perfmodel_per_arch`
- `struct starpu_perfmodel`

#### Macros
- `#define STARPU_NARCH`
- `#define starpu_per_arch_perfmodel`

#### Typedefs
- `typedef double(* starpu_perfmodel_per_arch_cost_function)(struct starpu_task *task, struct starpu_perfmodel_arch *arch, unsigned nimpl)`
- `typedef size_t(* starpu_perfmodel_per_arch_size_base)(struct starpu_task *task, struct starpu_perfmodel_arch *arch, unsigned nimpl)`
- `typedef struct _starpu_perfmodel_state * starpu_perfmodel_state_t`
Enumerations

- enum starpu_perfmodel_type {
  STARPU_PERFMODEL_INVALID, STARPU_PER_ARCH, STARPU_COMMON, STARPU_HISTORY_BASED, STARPU_REGRESSION_BASED, STARPU_NL_REGRESSION_BASED, STARPU_MULTIPLE_REGRESSION_BASED
}

Functions

- void starpu_perfmodel_init (struct starpu_perfmodel *model)
- int starpu_perfmodel_load_file (const char *filename, struct starpu_perfmodel *model)
- int starpu_perfmodel_load_symbol (const char *symbol, struct starpu_perfmodel *model)
- int starpu_perfmodel_unload_model (struct starpu_perfmodel *model)
- void starpu_perfmodel_get_model_path (const char *symbol, char *path, size_t maxlen)
- void starpu_perfmodel_dump_xml (FILE *output, struct starpu_perfmodel *model)
- void starpu_perfmodel_free_sampling_directories (void)
- struct starpu_perfmodel_arch *starpu_worker_get_perf_archtype (int workerid, unsigned sched_ctx_id)
- int starpu_perfmodel_get_narch_combs (void)
- int starpu_perfmodel_arch_comb_add (int ndevices, struct starpu_perfmodel_device *devices)
- int starpu_perfmodel_arch_comb_get (int ndevices, struct starpu_perfmodel_device *devices)
- struct starpu_perfmodel_arch *starpu_perfmodel_arch_comb_fetch (int comb)
- struct starpu_perfmodel_per_arch *starpu_perfmodel_get_model_per_arch (struct starpu_perfmodel *model, struct starpu_perfmodel_arch *arch, unsigned impl)
- struct starpu_perfmodel_per_arch *starpu_perfmodel_get_model_per_devices (struct starpu_perfmodel *model, int impl, ...)
- int starpu_perfmodel_set_per_devices_cost_function (struct starpu_perfmodel *model, int impl, starpu_perfmodel_per_arch_cost_function func, ...)
- int starpu_perfmodel_set_per_devices_size_base (struct starpu_perfmodel *model, int impl, starpu_perfmodel_per_arch_size_base func, ...)
- void starpu_perfmodel_debugfilepath (struct starpu_perfmodel *model, struct starpu_perfmodel_arch *arch, char *path, size_t maxlen, unsigned nimpl)
- char *starpu_perfmodel_get_archtype_name (enum starpu_worker_archtype archtype)
- void starpu_perfmodel_get_arch_name (struct starpu_perfmodel_arch *arch, char *archname, size_t maxlen, unsigned nimpl)
- double starpu_perfmodel_history_based_expected_perf (struct starpu_perfmodel *model, struct starpu_perfmodel_arch *arch, uint32_t footprint)
- void starpu_perfmodel_initialize (void)
- int starpu_perfmodel_list (FILE *output)
- void starpu_perfmodel_print (struct starpu_perfmodel *model, struct starpu_perfmodel_arch *arch, unsigned nimpl, char *parameter, uint32_t *footprint, FILE *output)
- int starpu_perfmodel_print_all (struct starpu_perfmodel *model, char *arch, char *parameter, uint32_t *footprint, FILE *output)
- int starpu_perfmodel_print_estimations (struct starpu_perfmodel *model, uint32_t *footprint, FILE *output)
- int starpu_perfmodel_list_combs (FILE *output, struct starpu_perfmodel *model)
- void starpu_perfmodel_update_history (struct starpu_perfmodel *model, struct starpu_task *task, struct starpu_perfmodel_arch *arch, unsigned cpuid, unsigned nimpl, double measured)
- void starpu_perfmodel_directory (FILE *output)
- void starpu_bus_print_bandwidth (FILE *f)
- void starpu_bus_print_affinity (FILE *f)
- void starpu_bus_print_filenames (FILE *f)
- double starpu_transfer_bandwidth (unsigned src_node, unsigned dst_node)
- double starpu_transfer_latency (unsigned src_node, unsigned dst_node)
- double starpu_transfer_predict (unsigned src_node, unsigned dst_node, size_t size)
Variables

- struct starpu_perfmodel starpu_perfmodel_nop

30.15.1 Detailed Description

30.15.2 Data Structure Documentation

30.15.2.1 struct starpu_perfmodel_device
todo

Data Fields

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<th>type of the device</th>
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<td>identifier of the precise device</td>
</tr>
<tr>
<td>int</td>
<td>ncores</td>
<td>number of execution in parallel, minus 1</td>
</tr>
</tbody>
</table>

30.15.2.2 struct starpu_perfmodel_arch
todo

Data Fields

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<tr>
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<th>ndevices</th>
<th>number of the devices for the given arch</th>
</tr>
</thead>
<tbody>
<tr>
<td>struct starpu_perfmodel_device *</td>
<td>devices</td>
<td>list of the devices for the given arch</td>
</tr>
</tbody>
</table>

30.15.2.3 struct starpu_perfmodel_history_entry

Data Fields

<table>
<thead>
<tr>
<th>double</th>
<th>mean</th>
<th>mean_n = 1/n sum</th>
</tr>
</thead>
<tbody>
<tr>
<td>double</td>
<td>deviation</td>
<td>n dev_n = sum2 - 1/n (sum)²</td>
</tr>
<tr>
<td>double</td>
<td>sum</td>
<td>sum of samples (in µs)</td>
</tr>
<tr>
<td>double</td>
<td>sum2</td>
<td>sum of samples²</td>
</tr>
<tr>
<td>unsigned</td>
<td>nsample</td>
<td>number of samples</td>
</tr>
<tr>
<td>unsigned</td>
<td>nerror</td>
<td></td>
</tr>
<tr>
<td>uint32_t</td>
<td>footprint</td>
<td>data footprint</td>
</tr>
<tr>
<td>size_t</td>
<td>size</td>
<td>in bytes</td>
</tr>
<tr>
<td>double</td>
<td>flops</td>
<td>Provided by the application</td>
</tr>
<tr>
<td>double</td>
<td>duration</td>
<td></td>
</tr>
<tr>
<td>struct starpu_tag_t</td>
<td>tag</td>
<td></td>
</tr>
<tr>
<td>double *</td>
<td>parameters</td>
<td></td>
</tr>
</tbody>
</table>

30.15.2.4 struct starpu_perfmodel_history_list

Data Fields

<table>
<thead>
<tr>
<th>struct starpu_perfmodel_history_list *</th>
<th>next</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>struct starpu_perfmodel_history_entry *</td>
<td>entry</td>
<td></td>
</tr>
</tbody>
</table>
30.15.2.5 struct starpu_perfmodel_regression_model
todo

Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>double</td>
<td>sumlny</td>
<td>sum of ln(measured)</td>
</tr>
<tr>
<td>double</td>
<td>sumlnx</td>
<td>sum of ln(size)</td>
</tr>
<tr>
<td>double</td>
<td>sumlnx2</td>
<td>sum of ln(size)(^2)</td>
</tr>
<tr>
<td>unsigned long</td>
<td>minx</td>
<td>minimum size</td>
</tr>
<tr>
<td>unsigned long</td>
<td>maxx</td>
<td>maximum size</td>
</tr>
<tr>
<td>double</td>
<td>sumlnxlny</td>
<td>sum of ln(size)(\times)ln(measured)</td>
</tr>
<tr>
<td>double</td>
<td>alpha</td>
<td>estimated = alpha (\times) size(^\beta)</td>
</tr>
<tr>
<td>double</td>
<td>beta</td>
<td>estimated = alpha (\times) size(^\beta)</td>
</tr>
<tr>
<td>unsigned</td>
<td>valid</td>
<td>whether the linear regression model is valid</td>
</tr>
<tr>
<td>double</td>
<td>a</td>
<td>estimated = a size(^b) + c</td>
</tr>
<tr>
<td>double</td>
<td>b</td>
<td>estimated = a size(^b) + c</td>
</tr>
<tr>
<td>double</td>
<td>c</td>
<td>estimated = a size(^b) + c</td>
</tr>
<tr>
<td>unsigned</td>
<td>nl_valid</td>
<td>whether the non-linear regression model is valid</td>
</tr>
<tr>
<td>unsigned</td>
<td>nsample</td>
<td>number of sample values for non-linear regression</td>
</tr>
<tr>
<td>double *</td>
<td>coeff</td>
<td>list of computed coefficients for multiple linear regression model</td>
</tr>
<tr>
<td>unsigned</td>
<td>ncoeff</td>
<td>number of coefficients for multiple linear regression model</td>
</tr>
<tr>
<td>unsigned</td>
<td>multi_valid</td>
<td>whether the multiple linear regression model is valid</td>
</tr>
</tbody>
</table>

30.15.2.6 struct starpu_perfmodel_per_arch
information about the performance model of a given arch.

Data Fields

- starpu_perfmodel_per_arch_cost_function cost_function
- starpu_perfmodel_per_arch_size_base size_base
- char debug_path[256]

Private Attributes

- struct starpu_perfmodel_history_table * history
- struct starpu_perfmodel_history_list * list
- struct starpu_perfmodel_regression_model regression

30.15.2.6.1 Field Documentation

30.15.2.6.1.1 cost_function
starpu_perfmodel_per_arch_cost_function starpu_perfmodel_per_arch::cost_function
Used by STARPU_PER_ARCH, must point to functions which take a task, the target arch and implementation number (as mere conveniency, since the array is already indexed by these), and must return a task duration estimation in micro-seconds.

30.15.2.6.1.2 size_base
starpu_perfmodel_per_arch_size_base starpu_perfmodel_per_arch::size_base
Same as in structure starpu_perfmodel, but per-arch, in case it depends on the architecture-specific implementation.
30.15.2.6.1.3 history

struct starpu_perfmodel_history_table* starpu_perfmodel_per_arch::history [private]
The history of performance measurements.

30.15.2.6.1.4 list

struct starpu_perfmodel_history_list* starpu_perfmodel_per_arch::list [private]
Used by STARPU_HISTORY_BASED, STARPU_NL_REGRESSION_BASED and STARPU_MULTIPLE_REGRESSION_BASED, records all execution history measures.

30.15.2.6.1.5 regression

struct starpu_perfmodel_regression_model starpu_perfmodel_per_arch::regression [private]
Used by STARPU_REGRESSION_BASED, STARPU_NL_REGRESSION_BASED and STARPU_MULTIPLE_REGRESSION_BASED, contains the estimated factors of the regression.

30.15.2.7 struct starpu_perfmodel

Contain all information about a performance model. At least the type and symbol fields have to be filled when defining a performance model for a codelet. For compatibility, make sure to initialize the whole structure to zero, either by using explicit memset, or by letting the compiler implicitly do it in e.g. static storage case. If not provided, other fields have to be zero.

Data Fields

- enum starpu_perfmodel_type type
- double(* cost_function )(struct starpu_task *, unsigned nimpl)
- double(* arch_cost_function )(struct starpu_task *, struct starpu_perfmodel_arch *arch, unsigned nimpl)
- size_t(* size_base )(struct starpu_task *, unsigned nimpl)
- uint32_t(* footprint )(struct starpu_task *)
- const char *symbol
- void(* parameters )(struct starpu_task *task, double *parameters)

Private Attributes

- unsigned is_loaded
- unsigned benchmarking
- unsigned is_init
- const char **parameters_names
- unsigned nparameters
- unsigned **combinations
- unsigned ncombinations
- starpu_perfmodel_state_t state

30.15.2.7.1 Field Documentation

30.15.2.7.1.1 type

enum starpu_perfmodel_type starpu_perfmodel::type
type of performance model

- STARPU_HISTORY_BASED, STARPU_REGRESSION_BASED, STARPU_NL_REGRESSION_BASED: No other fields needs to be provided, this is purely history-based.

- STARPU_MULTIPLE_REGRESSION_BASED: Need to provide fields starpu_perfmodel::nparameters (number of different parameters), starpu_perfmodel::ncombinations (number of parameters combinations-tuples) and table starpu_perfmodel::combinations which defines exponents of the equation. Function cl_perf_func also needs to define how to extract parameters from the task.

- STARPU_PER_ARCH: either field starpu_perfmodel::arch_cost_function has to be filled with a function that returns the cost in micro-seconds on the arch given as parameter, or field starpu_perfmodel::per_arch has to be filled with functions which return the cost in micro-seconds.
• **STARPU_COMMON**: field `starpu_perfmodel::cost_function` has to be filled with a function that returns the cost in micro-seconds on a CPU, timing on other archs will be determined by multiplying by an arch-specific factor.

### 30.15.2.7.1.2 cost_function

```c
double(* starpu_perfmodel::cost_function)(struct starpu_task *, unsigned nimpl)
```

Used by **STARPU_COMMON**. Take a task and implementation number, and must return a task duration estimation in micro-seconds.

### 30.15.2.7.1.3 arch_cost_function

```c
double(* starpu_perfmodel::arch_cost_function)(struct starpu_task *, struct starpu_perfmodel←_arch *arch, unsigned nimpl)
```

Used by **STARPU_COMMON**. Take a task, an arch and implementation number, and must return a task duration estimation in micro-seconds on that arch.

### 30.15.2.7.1.4 size_base

```c
size_t(* starpu_perfmodel::size_base)(struct starpu_task *, unsigned nimpl)
```

Used by **STARPU_HISTORY_BASED, STARPU_REGRESSION_BASED and STARPU_NL_REGRESSION_BASED**. If not NULL, take a task and implementation number, and return the size to be used as index to distinguish histories and as a base for regressions.

### 30.15.2.7.1.5 footprint

```c
uint32_t(* starpu_perfmodel::footprint)(struct starpu_task *)
```

Used by **STARPU_HISTORY_BASED**. If not NULL, take a task and return the footprint to be used as index to distinguish histories. The default is to use the `starpu_task_data_footprint()` function.

### 30.15.2.7.1.6 symbol

```c
const char* starpu_perfmodel::symbol
```

Symbol name for the performance model, which will be used as file name to store the model. It must be set otherwise the model will be ignored.

### 30.15.2.7.1.7 is_loaded

```c
unsigned starpu_perfmodel::is_loaded [private]
```

Whether the performance model is already loaded from the disk.

### 30.15.2.7.1.8 parameters_names

```c
const char** starpu_perfmodel::parameters_names [private]
```

Names of parameters used for multiple linear regression models (M, N, K)

### 30.15.2.7.1.9 nparameters

```c
unsigned starpu_perfmodel::nparameters [private]
```

Number of parameters used for multiple linear regression models

### 30.15.2.7.1.10 combinations

```c
unsigned** starpu_perfmodel::combinations [private]
```

Table of combinations of parameters (and the exponents) used for multiple linear regression models

### 30.15.2.7.1.11 ncombinations

```c
unsigned starpu_perfmodel::ncombinations [private]
```

Number of combination of parameters used for multiple linear regression models

### 30.15.3 Enumeration Type Documentation

#### 30.15.3.1 starpu_perfmodel_type

```c
enum starpu_perfmodel_type
todo
```
### 30.15.4 Function Documentation

#### 30.15.4.1 `starpu_perfmodel_init()`

```c
void starpu_perfmodel_init (  
    struct starpu_perfmodel * model  
)
```

Initialize the `model` performance model structure. This is automatically called when e.g. submitting a task using a codelet using this performance model.

#### 30.15.4.2 `starpu_perfmodel_load_file()`

```c
int starpu_perfmodel_load_file (  
    const char * filename,  
    struct starpu_perfmodel * model  
)
```

Load the performance model found in the file named `filename`. `model` has to be completely zero, and will be filled with the information stored in the given file.

#### 30.15.4.3 `starpu_perfmodel_load_symbol()`

```c
int starpu_perfmodel_load_symbol (  
    const char * symbol,  
    struct starpu_perfmodel * model  
)
```

Load a given performance model. `model` has to be completely zero, and will be filled with the information stored in `$STARPU_HOME/.starpu`. The function is intended to be used by external tools that want to read the performance model files.

#### 30.15.4.4 `starpu_perfmodel_unload_model()`

```c
int starpu_perfmodel_unload_model (  
    struct starpu_perfmodel * model  
)
```

Unload `model` which has been previously loaded through the function `starpu_perfmodel_load_symbol()`.

#### 30.15.4.5 `starpu_perfmodel_get_model_path()`

```c
void starpu_perfmodel_get_model_path (  
    const char * symbol,  
    char * path,  
    size_t maxlen  
)
```

Fills `path` (supposed to be `maxlen` long) with the full path to the performance model file for symbol `symbol`. This path can later on be used for instance with `starpu_perfmodel_load_file()`.

---

**Enumerator**

<table>
<thead>
<tr>
<th>Enumerated Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>STARPU_PER_ARCH</td>
<td>Application-provided per-arch cost model function</td>
</tr>
<tr>
<td>STARPU_COMMON</td>
<td>Application-provided common cost model function, with per-arch factor</td>
</tr>
<tr>
<td>STARPU_HISTORY_BASED</td>
<td>Automatic history-based cost model</td>
</tr>
<tr>
<td>STARPU_REGRESSION_BASED</td>
<td>Automatic linear regression-based cost model (alpha * size ^ beta)</td>
</tr>
<tr>
<td>STARPU_NL_REGRESSION_BASED</td>
<td>Automatic non-linear regression-based cost model (a * size ^ b + c)</td>
</tr>
<tr>
<td>STARPU_MULTIPLE_REGRESSION_BASED</td>
<td>Automatic multiple linear regression-based cost model. Application provides parameters, their combinations and exponents.</td>
</tr>
</tbody>
</table>
30.15.4.6  starpu_perfmodel_dump_xml()

void starpu_perfmodel_dump_xml (  
    FILE * output,  
    struct starpu_perfmodel * model )
Dump performance model model to output stream output, in XML format.

30.15.4.7  starpu_perfmodel_free_sampling_directories()

void starpu_perfmodel_free_sampling_directories (  
    void )
Free internal memory used for sampling directory management. It should only be called by an application which is not calling starpu_shutdown() as this function already calls it. See for example tools/starpu_perfmodel←_display.c.

30.15.4.8  starpu_worker_get_perf_archtype()

struct starpu_perfmodel_arch* starpu_worker_get_perf_archtype (  
    int workerid,  
    unsigned sched_ctx_id )
Return the architecture type of the worker workerid.

30.15.4.9  starpu_perfmodel_debugfilepath()

void starpu_perfmodel_debugfilepath (  
    struct starpu_perfmodel * model,  
    struct starpu_perfmodel_arch * arch,  
    char * path,  
    size_t maxlen,  
    unsigned nimpl )
Return the path to the debugging information for the performance model.

30.15.4.10  starpu_perfmodel_get_arch_name()

void starpu_perfmodel_get_arch_name (  
    struct starpu_perfmodel_arch * arch,  
    char * archname,  
    size_t maxlen,  
    unsigned nimpl )
Return the architecture name for arch

30.15.4.11  starpu_perfmodel_history_based_expected_perf()

double starpu_perfmodel_history_based_expected_perf (  
    struct starpu_perfmodel * model,  
    struct starpu_perfmodel_arch * arch,  
    uint32_t footprint )
Return the estimated time of a task with the given model and the given footprint.

30.15.4.12  starpu_perfmodel_initialize()

void starpu_perfmodel_initialize (  
    void )
If starpu_init() is not used, starpu_perfmodel_initialize() should be used called calling starpu_perfmodel_* functions.

30.15.4.13  starpu_perfmodel_list()

int starpu_perfmodel_list (  
    FILE * output )
Print a list of all performance models on output.

30.15.4.14 starpu_perfmodel_update_history()

```c
void starpu_perfmodel_update_history (  
    struct starpu_perfmodel * model,  
    struct starpu_task * task,  
    struct starpu_perfmodel_arch * arch,  
    unsigned cpuid,  
    unsigned nimpl,  
    double measured )
```

Feed the performance model model with an explicit measurement measured (in µs), in addition to measurements done by StarPU itself. This can be useful when the application already has an existing set of measurements done in good conditions, that StarPU could benefit from instead of doing on-line measurements. An example of use can be seen in Performance Model Example.

30.15.4.15 starpu_perfmodel_directory()

```c
void starpu_perfmodel_directory (  
    FILE * output )
```

Print the directory name storing performance models on output.

30.15.4.16 starpu_bus_print_bandwidth()

```c
void starpu_bus_print_bandwidth (  
    FILE * f )
```

Print a matrix of bus bandwidths on f.

30.15.4.17 starpu_bus_print_affinity()

```c
void starpu_bus_print_affinity (  
    FILE * f )
```

Print the affinity devices on f.

30.15.4.18 starpu_bus_print_filenames()

```c
void starpu_bus_print_filenames (  
    FILE * f )
```

Print on f the name of the files containing the matrix of bus bandwidths, the affinity devices and the latency.

30.15.4.19 starpu_transfer_bandwidth()

```c
double starpu_transfer_bandwidth (  
    unsigned src_node,  
    unsigned dst_node )
```

Return the bandwidth of data transfer between two memory nodes.

30.15.4.20 starpu_transfer_latency()

```c
double starpu_transfer_latency (  
    unsigned src_node,  
    unsigned dst_node )
```

Return the latency of data transfer between two memory nodes.

30.15.4.21 starpu_transfer_predict()

```c
double starpu_transfer_predict (  
    unsigned src_node,  
    unsigned dst_node,  
    size_t size )
```
Return the estimated time to transfer a given size between two memory nodes.

### 30.15.5 Variable Documentation

#### 30.15.5.1 starpu_perfmodel_nop

```c
def struct starpu_perfmodel starpu_perfmodel_nop
```

Performance model which just always return 1µs.

### 30.16 Profiling

#### Data Structures

- `struct starpu_profiling_task_info`
- `struct starpu_profiling_worker_info`
- `struct starpu_profiling_bus_info`

#### Macros

- `#define STARPU_PROFILING_DISABLE`
- `#define STARPU_PROFILING_ENABLE`
- `#define STARPU_NS_PER_S`  
- `#define starpu_timespec_cmp(a, b, CMP)`

#### Functions

- `void starpu_profiling_init (void)`
- `void starpu_profiling_set_id (int new_id)`
- `int starpu_profiling_status_set (int status)`
- `int starpu_profiling_status_get (void)`
- `int starpu_profiling_worker_get_info (int workerid, struct starpu_profiling_worker_info *worker_info)`
- `int starpu_bus_get_count (void)`
- `int starpu_bus_get_id (int src, int dst)`
- `int starpu_bus_get_src (int busid)`
- `int starpu_bus_get_dst (int busid)`
- `void starpu_bus_set_direct (int busid, int direct)`
- `int starpu_bus_get_direct (int busid)`
- `void starpu_bus_set_ngpus (int busid, int ngpus)`
- `int starpu_bus_get_ngpus (int busid)`
- `int starpu_bus_get_profiling_info (int busid, struct starpu_profiling_bus_info *bus_info)`
- `static __starpu_inline void starpu_timespec_clear (struct timespec *tsp)`
- `static __starpu_inline void starpu_timespec_add (struct timespec *a, struct timespec *b, struct timespec *result)`
- `static __starpu_inline void starpu_timespec_accumulate (struct timespec *result, struct timespec *a)`
- `static __starpu_inline void starpu_timespec_sub (const struct timespec *a, const struct timespec *b, struct timespec *result)`
- `double starpu_timing_timespec_delay_us (struct timespec *start, struct timespec *end)`
- `double starpu_timing_timespec_to_us (struct timespec *ts)`
- `void starpu_profiling_bus_helper_display_summary (void)`
- `void starpu_profiling_worker_helper_display_summary (void)`
- `void starpu_data_display_memory_stats ();`
30.16.1 Detailed Description

30.16.2 Data Structure Documentation

30.16.2.1 struct starpu_profiling_task_info

Information about the execution of a task. It is accessible from the field `starpu_task::profiling_info` if profiling was enabled.

Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>struct timespec</td>
<td>submit_time</td>
<td>Date of task submission (relative to the initialization of StarPU).</td>
</tr>
<tr>
<td>struct timespec</td>
<td>push_start_time</td>
<td>Time when the task was submitted to the scheduler.</td>
</tr>
<tr>
<td>struct timespec</td>
<td>push_end_time</td>
<td>Time when the scheduler finished with the task submission.</td>
</tr>
<tr>
<td>struct timespec</td>
<td>pop_start_time</td>
<td>Time when the scheduler started to be requested for a task, and eventually gave that task.</td>
</tr>
<tr>
<td>struct timespec</td>
<td>pop_end_time</td>
<td>Time when the scheduler finished providing the task for execution.</td>
</tr>
<tr>
<td>struct timespec</td>
<td>acquire_data_start_time</td>
<td>Time when the worker started fetching input data.</td>
</tr>
<tr>
<td>struct timespec</td>
<td>acquire_data_end_time</td>
<td>Time when the worker finished fetching input data.</td>
</tr>
<tr>
<td>struct timespec</td>
<td>start_time</td>
<td>Date of task execution beginning (relative to the initialization of StarPU).</td>
</tr>
<tr>
<td>struct timespec</td>
<td>end_time</td>
<td>Date of task execution termination (relative to the initialization of StarPU).</td>
</tr>
<tr>
<td>struct timespec</td>
<td>release_data_start_time</td>
<td>Time when the worker started releasing data.</td>
</tr>
<tr>
<td>struct timespec</td>
<td>release_data_end_time</td>
<td>Time when the worker finished releasing data.</td>
</tr>
<tr>
<td>int</td>
<td>workerid</td>
<td>Identifier of the worker which has executed the task.</td>
</tr>
<tr>
<td>uint64_t</td>
<td>used_cycles</td>
<td>Number of cycles used by the task, only available in the MoviSim.</td>
</tr>
<tr>
<td>uint64_t</td>
<td>stall_cycles</td>
<td>Number of cycles stalled within the task, only available in the MoviSim</td>
</tr>
<tr>
<td>double</td>
<td>energy_consumed</td>
<td>Energy consumed by the task, in Joules.</td>
</tr>
</tbody>
</table>

30.16.2.2 struct starpu_profiling_worker_info

Profiling information associated to a worker. The timing is provided since the previous call to `starpu_profiling←worker_get_info()`

Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>struct timespec</td>
<td>start_time</td>
<td>Starting date for the reported profiling measurements.</td>
</tr>
<tr>
<td>struct timespec</td>
<td>total_time</td>
<td>Duration of the profiling measurement interval.</td>
</tr>
<tr>
<td>struct timespec</td>
<td>executing_time</td>
<td>Time spent by the worker to execute tasks during the profiling measurement interval.</td>
</tr>
<tr>
<td>struct timespec</td>
<td>sleeping_time</td>
<td>Time spent idling by the worker during the profiling measurement interval.</td>
</tr>
<tr>
<td>int</td>
<td>executed_tasks</td>
<td>Number of tasks executed by the worker during the profiling measurement interval.</td>
</tr>
<tr>
<td>uint64_t</td>
<td>used_cycles</td>
<td>Number of cycles used by the worker, only available in the MoviSim</td>
</tr>
<tr>
<td>uint64_t</td>
<td>stall_cycles</td>
<td>Number of cycles stalled within the worker, only available in the MoviSim</td>
</tr>
<tr>
<td>double</td>
<td>energy_consumed</td>
<td>Energy consumed by the worker, in Joules.</td>
</tr>
</tbody>
</table>
Data Fields

<table>
<thead>
<tr>
<th>Data Field</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>double</td>
<td>flops</td>
<td></td>
</tr>
</tbody>
</table>

30.16.2.3 struct starpu_profiling_bus_info

Data Fields

<table>
<thead>
<tr>
<th>Data Field</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>struct timespec</td>
<td>start_time</td>
<td>Time of bus profiling startup.</td>
</tr>
<tr>
<td>struct timespec</td>
<td>total_time</td>
<td>Total time of bus profiling.</td>
</tr>
<tr>
<td>int long long</td>
<td>transferred_bytes</td>
<td>Number of bytes transferred during profiling.</td>
</tr>
<tr>
<td>int</td>
<td>transfer_count</td>
<td>Number of transfers during profiling.</td>
</tr>
</tbody>
</table>

30.16.3 Macro Definition Documentation

30.16.3.1 STARPU_PROFILING_DISABLE

#define STARPU_PROFILING_DISABLE

Used when calling the function starpu_profiling_status_set() to disable profiling.

30.16.3.2 STARPU_PROFILING_ENABLE

#define STARPU_PROFILING_ENABLE

Used when calling the function starpu_profiling_status_set() to enable profiling.

30.16.4 Function Documentation

30.16.4.1 starpu_profiling_init()

void starpu_profiling_init ( void )

Reset performance counters and enable profiling if the environment variable STARPU_PROFILING is set to a positive value.

30.16.4.2 starpu_profiling_set_id()

void starpu_profiling_set_id ( int new_id )

Set the ID used for profiling trace filename. Has to be called before starpu_init().

30.16.4.3 starpu_profiling_status_set()

int starpu_profiling_status_set ( int status )

Set the profiling status. Profiling is activated by passing STARPU_PROFILING_ENABLE in status. Passing STARPU_PROFILING_DISABLE disables profiling. Calling this function resets all profiling measurements. When profiling is enabled, the field starpu_task::profiling_info points to a valid structure starpu_profiling_task_info containing information about the execution of the task. Negative return values indicate an error, otherwise the previous status is returned.
30.16.4.4 starpu_profiling_status_get()

int starpu_profiling_status_get ( void )

Return the current profiling status or a negative value in case there was an error.

30.16.4.5 starpu_profiling_worker_get_info()

int starpu_profiling_worker_get_info ( int workerid, struct starpu_profiling_worker_info * worker_info )

Get the profiling info associated to the worker identified by workerid, and reset the profiling measurements. If the argument worker_info is NULL, only reset the counters associated to worker workerid. Upon successful completion, this function returns 0. Otherwise, a negative value is returned.

30.16.4.6 starpu_bus_get_count()

int starpu_bus_get_count ( void )

Return the number of buses in the machine

30.16.4.7 starpu_bus_get_id()

int starpu_bus_get_id ( int src, int dst )

Return the identifier of the bus between src and dst

30.16.4.8 starpu_bus_get_src()

int starpu_bus_get_src ( int busid )

Return the source point of bus busid

30.16.4.9 starpu_bus_get_dst()

int starpu_bus_get_dst ( int busid )

Return the destination point of bus busid

30.16.4.10 starpu_bus_get_profiling_info()

int starpu_bus_get_profiling_info ( int busid, struct starpu_profiling_bus_info * bus_info )

See _starpu_profiling_bus_helper_display_summary in src/profiling/profiling_helpers.c for a usage example. Note that calling starpu_bus_get_profiling_info() resets the counters to zero.

30.16.4.11 starpu_timing_timespec_delay_us()

double starpu_timing_timespec_delay_us ( struct timespec * start, struct timespec * end )

Return the time elapsed between start and end in microseconds.

30.16.4.12 starpu_timing_timespec_to_us()

double starpu_timing_timespec_to_us ( struct timespec * ts )

Convert the given timespec ts into microseconds
30.16.4.13 starpu_profiling_bus_helper_display_summary()

void starpu_profiling_bus_helper_display_summary ( void )
Display statistics about the bus on stderr. if the environment variable STARPU_BUS_STATS is defined. The function is called automatically by starpu_shutdown().

30.16.4.14 starpu_profiling_worker_helper_display_summary()

void starpu_profiling_worker_helper_display_summary ( void )
Display statistic about the workers on stderr if the environment variable STARPU_WORKER_STATS is defined. The function is called automatically by starpu_shutdown().

30.16.4.15 starpu_data_display_memory_stats()

void starpu_data_display_memory_stats ( )
Display statistics about the current data handles registered within StarPU. StarPU must have been configured with the configure option --enable-memory-stats (see Memory Feedback).

30.17 Theoretical Lower Bound on Execution Time

Compute theoretical upper computation efficiency bound corresponding to some actual execution.

Functions

- void starpu_bound_start (int deps, int prio)
- void starpu_bound_stop (void)
- void starpu_bound_print_dot (FILE *output)
- void starpu_bound_compute (double *res, double *integer_res, int integer)
- void starpu_bound_print_lp (FILE *output)
- void starpu_bound_print_mps (FILE *output)
- void starpu_bound_print (FILE *output, int integer)

30.17.1 Detailed Description

Compute theoretical upper computation efficiency bound corresponding to some actual execution.

30.17.2 Function Documentation

30.17.2.1 starpu_bound_start()

void starpu_bound_start ( int deps, int prio )
Start recording tasks (resets stats). deps tells whether dependencies should be recorded too (this is quite expensive)

30.17.2.2 starpu_bound_stop()

void starpu_bound_stop ( void )
Stop recording tasks
Module Documentation a.k.a StarPU's API

30.17.2.3 starpu_bound_print_dot()

```c
void starpu_bound_print_dot (  
    FILE * output )
```

Emit the DAG that was recorded on `output`.

30.17.2.4 starpu_bound_compute()

```c
void starpu_bound_compute (  
    double * res,  
    double * integer_res,  
    int integer )
```

Get theoretical upper bound (in ms) (needs glpk support detected by configure script). It returns 0 if some performance models are not calibrated.

30.17.2.5 starpu_bound_print_lp()

```c
void starpu_bound_print_lp (  
    FILE * output )
```

Emit the Linear Programming system on `output` for the recorded tasks, in the lp format.

30.17.2.6 starpu_bound_print_mps()

```c
void starpu_bound_print_mps (  
    FILE * output )
```

Emit the Linear Programming system on `output` for the recorded tasks, in the mps format.

30.17.2.7 starpu_bound_print()

```c
void starpu_bound_print (  
    FILE * output,  
    int integer )
```

Emit on `output` the statistics of actual execution vs theoretical upper bound. `integer` permits to choose between integer solving (which takes a long time but is correct), and relaxed solving (which provides an approximate solution).

30.18 CUDA Extensions

**Macros**

- `#define STARPU_CUBLAS_REPORT_ERROR(status)`
- `#define STARPU_CUDA_REPORT_ERROR(status)`

**Functions**

- `void starpu_cublas_report_error (const char *func, const char *file, int line, int status)`
- `void starpu_cuda_report_error (const char *func, const char *file, int line, cudaError_t status)`
- `cudaStream_t starpu_cuda_get_local_stream (void)`
- `const struct cudaDeviceProp * starpu_cuda_get_device_properties (unsigned workerid)`
- `int starpu_cuda_copy_async_sync (void *src_ptr, unsigned src_node, void *dst_ptr, unsigned dst_node, size_t ssize, cudaStream_t stream, enum cudaMemcpyKind kind)`
- `void starpu_cuda_set_device (unsigned devid)`
- `void starpu_cusparse_init (void)`
- `void starpu_cusparse_shutdown (void)`
- `cusparseHandle_t starpu_cusparse_get_local_handle (void)`
- `void starpu_cublas_init (void)`
- `void starpu_cublas_set_stream (void)`
- `void starpu_cublas_shutdown (void)`
30.18 CUDA Extensions

30.18.1 Detailed Description

30.18.2 Macro Definition Documentation

30.18.2.1 STARPU_CUBLAS_REPORT_ERROR

#define STARPU_CUBLAS_REPORT_ERROR(
  status )

Call `starpu_cublas_report_error()`, passing the current function, file and line position.

30.18.2.2 STARPU_CUDA_REPORT_ERROR

#define STARPU_CUDA_REPORT_ERROR(
  status )

Call `starpu_cuda_report_error()`, passing the current function, file and line position.

30.18.3 Function Documentation

30.18.3.1 starpu_cusparse_init()

void starpu_cusparse_init (  
  void )

Initialize CUSPARSE on every CUDA device controlled by StarPU. This call blocks until CUSPARSE has been properly initialized on every device.

30.18.3.2 starpu_cublas_init()

void starpu_cublas_init (  
  void )

Initialize CUBLAS on every CUDA device. The CUBLAS library must be initialized prior to any CUBLAS call. Calling `starpu_cublas_init()` will initialize CUBLAS on every CUDA device controlled by StarPU. This call blocks until CUBLAS has been properly initialized on every device.

30.18.3.3 starpu_cublas_report_error()

void starpu_cublas_report_error (  
  const char * func,  
  const char * file,  
  int line,  
  int status )

Report a CUBLAS error.

30.18.3.4 starpu_cuda_report_error()

void starpu_cuda_report_error (  
  const char * func,  
  const char * file,  
  int line,  
  cudaError_t status )

Report a CUDA error.

30.18.3.5 starpu_cuda_get_local_stream()

cudaStream_t starpu_cuda_get_local_stream (  
  void )

Generated by Doxygen
Return the current worker’s CUDA stream. StarPU provides a stream for every CUDA device controlled by StarPU. This function is only provided for convenience so that programmers can easily use asynchronous operations within codelets without having to create a stream by hand. Note that the application is not forced to use the stream provided by starpu_cuda_get_local_stream() and may also create its own streams. Synchronizing with cudaThreadSynchronize() is allowed, but will reduce the likelihood of having all transfers overlapped.

30.18.3.6 starpu_cuda_get_device_properties()

const struct cudaDeviceProp* starpu_cuda_get_device_properties (unsigned workerid)

Return a pointer to device properties for worker workerid (assumed to be a CUDA worker).

30.18.3.7 starpu_cuda_copy_async_sync()

int starpu_cuda_copy_async_sync (void * src_ptr, unsigned src_node, void * dst_ptr, unsigned dst_node, size_t ssize, cudaStream_t stream, enum cudaMemcpyKind kind)

Copy ssize bytes from the pointer src_ptr on src_node to the pointer dst_ptr on dst_node. The function first tries to copy the data asynchronous (unless stream is NULL). If the asynchronous copy fails or if stream is NULL, it copies the data synchronously. The function returns -EAGAIN if the asynchronous launch was successfull. It returns 0 if the synchronous copy was successful, or fails otherwise.

30.18.3.8 starpu_cuda_set_device()

void starpu_cuda_set_device (unsigned devid)

Call cudaSetDevice(devid) or cudaGLSetGLDevice(devid), according to whether devid is among the field starpu_conf::cuda_opengl_interoperability.

30.18.3.9 starpu_cublas_set_stream()

void starpu_cublas_set_stream (void)

Set the proper CUBLAS stream for CUBLAS v1. This must be called from the CUDA codelet before calling CUBLAS v1 kernels, so that they are queued on the proper CUDA stream. When using one thread per CUDA worker, this function does not do anything since the CUBLAS stream does not change, and is set once by starpu_cublas_init().

30.18.3.10 starpu_cublas_shutdown()

void starpu_cublas_shutdown (void)

Synchronously deinitialize the CUBLAS library on every CUDA device.

30.18.3.11 starpu_cusparse_shutdown()

void starpu_cusparse_shutdown (void)

Synchronously deinitialize the CUSPARSE library on every CUDA device.

30.18.3.12 starpu_cusparse_get_local_handle()

cusparseHandle_t starpu_cusparse_get_local_handle (void)
Return the CUSPARSE handle to be used to queue CUSPARSE kernels. It is properly initialized and configured for
multistream by starpu_cusparse_init().

30.19 OpenCL Extensions

Data Structures

- struct starpu_opencl_program

Macros

- #define STARPU_USE_OPENCL
- #define STARPU_MAXOPENCLDEVS
- #define STARPU_OPENCL_DATADIR

Writing OpenCL kernels

- void starpu_opencl_get_context (int devid, cl_context ∗context)
- void starpu_opencl_get_device (int devid, cl_device_id ∗device)
- void starpu_opencl_get_queue (int devid, cl_command_queue ∗queue)
- void starpu_opencl_get_current_context (cl_context ∗context)
- void starpu_opencl_get_current_queue (cl_command_queue ∗queue)
- int starpu_opencl_set_kernel_args (cl_int ∗err, cl_kernel ∗kernel,...)

Compiling OpenCL kernels

Source codes for OpenCL kernels can be stored in a file or in a string. StarPU provides functions to build the
program executable for each available OpenCL device as a cl_program object. This program executable can then
be loaded within a specific queue as explained in the next section. These are only helpers, Applications can also fill
a starpu_opencl_program array by hand for more advanced use (e.g. different programs on the different OpenCL
devices, for relocation purpose for instance).

- void starpu_opencl_load_program_source (const char ∗source_file_name, char ∗located_file_name, char ∗located_dir_name, char ∗opencl_program_source)
- void starpu_opencl_load_program_source_malloc (const char ∗source_file_name, char ∗∗located_file_name, char ∗∗located_dir_name, char ∗∗opencl_program_source)
- int starpu_opencl_compile_opencl_from_file (const char ∗source_file_name, const char ∗build_options)
- int starpu_opencl_compile_opencl_from_string (const char ∗opencl_program_source, const char ∗file_name, const char ∗build_options)
- int starpu_opencl_load_binary_opencl (const char ∗kernel_id, struct starpu_opencl_program ∗opencl_programs)
- int starpu_opencl_load_opencl_from_file (const char ∗source_file_name, struct starpu_opencl_program ∗opencl_programs, const char ∗build_options)
- int starpu_opencl_load_opencl_from_string (const char ∗opencl_program_source, struct starpu_opencl_program ∗opencl_programs, const char ∗build_options)
- int starpu_opencl_unload_opencl (struct starpu_opencl_program ∗opencl_programs)

Loading OpenCL kernels

- int starpu_opencl_load_kernel (cl_kernel ∗kernel, cl_command_queue ∗queue, struct starpu_opencl_program ∗opencl_programs, const char ∗kernel_name, int devid)
- int starpu_opencl_release_kernel (cl_kernel kernel)

OpenCL Statistics

- int starpu_opencl_collect_stats (cl_event event)
OpenCL Utilities

- const char * starpu_opencl_error_string (cl_int status)
- void starpu_opencl_display_error (const char *func, const char *file, int line, const char *msg, cl_int status)
- static __starpu_inline void starpu_opencl_report_error (const char *func, const char *file, int line, const char *msg, cl_int status)
- cl_int starpu_opencl_allocate_memory (int devid, cl_mem *addr, size_t size, cl_mem_flags flags)
- cl_int starpu_opencl_copy_ram_to_opencl (void *ptr, unsigned src_node, cl_mem buffer, unsigned dst_node, size_t size, size_t offset, cl_event *event, int *ret)
- cl_int starpu_opencl_copy_opencl_to_ram (cl_mem buffer, unsigned src_node, void *ptr, unsigned dst_node, size_t size, size_t offset, cl_event *event, int *ret)
- cl_int starpu_opencl_copy_opencl_to_opencl (cl_mem src, unsigned src_node, size_t src_offset, cl_mem dst, unsigned dst_node, size_t dst_offset, size_t size, cl_event *event, int *ret)
- cl_int starpu_opencl_copy_async_sync (uintptr_t src, size_t src_offset, unsigned src_node, uintptr_t dst, size_t dst_offset, unsigned dst_node, size_t size, cl_event *event)
- #define STARPU_OPENCL_DISPLAY_ERROR(status)
- #define STARPU_OPENCL_REPORT_ERROR(status)
- #define STARPU_OPENCL_REPORT_ERROR_WITH_MSG(msg, status)

30.19.1 Detailed Description
30.19.2 Data Structure Documentation
30.19.2.1 struct starpu_opencl_program

Store the OpenCL programs as compiled for the different OpenCL devices.

Data Fields

| cl_program | programs[STARPU_MAXOPENCLDEVS] | Store each program for each OpenCL device. |

30.19.3 Macro Definition Documentation

30.19.3.1 STARPU_USE_OPENCL

#define STARPU_USE_OPENCL
Defined when StarPU has been installed with OpenCL support. It should be used in your code to detect the availability of OpenCL as shown in Full source code for the 'Scaling a Vector' example.

30.19.3.2 STARPU_MAXOPENCLDEVS

#define STARPU_MAXOPENCLDEVS
Define the maximum number of OpenCL devices that are supported by StarPU.

30.19.3.3 STARPU_OPENCL_DATADIR

#define STARPU_OPENCL_DATADIR
Define the directory in which the OpenCL codelets of the applications provided with StarPU have been installed.

30.19.3.4 STARPU_OPENCL_DISPLAY_ERROR

#define STARPU_OPENCL_DISPLAY_ERROR{
    status }
Call the function starpu_opencl_display_error() with the error status, the current function name, current file and line number, and a empty message.

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30.19.3.5 STARPU_OPENCL_REPORT_ERROR

#define STARPU_OPENCL_REPORT_ERROR(
    status
) Call the function starpu_opencl_report_error() with the error status, the current function name, current file and line number, and a empty message.

30.19.3.6 STARPU_OPENCL_REPORT_ERROR_WITH_MSG

#define STARPU_OPENCL_REPORT_ERROR_WITH_MSG(
    msg,
    status
) Call the function starpu_opencl_report_error() with msg and status, the current function name, current file and line number.

30.19.4 Function Documentation

30.19.4.1 starpu_opencl_get_context()

void starpu_opencl_get_context ( 
    int devid, 
    cl_context * context ) 
Return the OpenCL context of the device designated by devid in context.

30.19.4.2 starpu_opencl_get_device()

void starpu_opencl_get_device ( 
    int devid, 
    cl_device_id * device ) 
Return the cl_device_id corresponding to devid in device.

30.19.4.3 starpu_opencl_get_queue()

void starpu_opencl_get_queue ( 
    int devid, 
    cl_command_queue * queue ) 
Return the command queue of the device designated by devid into queue.

30.19.4.4 starpu_opencl_get_current_context()

void starpu_opencl_get_current_context ( 
    cl_context * context ) 
Return the context of the current worker.

30.19.4.5 starpu_opencl_get_current_queue()

void starpu_opencl_get_current_queue ( 
    cl_command_queue * queue ) 
Return the computation kernel command queue of the current worker.

30.19.4.6 starpu_opencl_set_kernel_args()

int starpu_opencl_set_kernel_args ( 
    cl_int * err, 
    cl_kernel * kernel, 
    ... ) 
Set the arguments of a given kernel. The list of arguments must be given as (size_t size_of_the_argument, cl_mem * pointer_to_the_argument). The last argument must be 0. Return the number...
of arguments that were successfully set. In case of failure, return the id of the argument that could not be set and
\texttt{err} is set to the error returned by OpenCL. Otherwise, return the number of arguments that were set.

Here an example:

```c
int n;
cl_int err;
cl_kernel kernel;
int n = starpu_opencl_set_kernel_args(&err, 2, &kernel, sizeof(foo), &foo, sizeof(bar), &bar, 0);
if (n != 2) fprintf(stderr, "Error : %d\n", err);
```

### 30.19.4.7 starpu_opencl_load_program_source()

```c
void starpu_opencl_load_program_source {
    const char * source_file_name,
    char * located_file_name,
    char * located_dir_name,
    char * opencl_program_source ;
}
```

Store the contents of the file \texttt{source\_file\_name} in the buffer \texttt{opencl\_program\_source}. The file
\texttt{source\_file\_name} can be located in the current directory, or in the directory specified by the environment
variable \texttt{STARPU\_OPENCL\_PROGRAM\_DIR}, or in the directory share/starpu/opencl of the installation
directory of StarPU, or in the source directory of StarPU. When the file is found, \texttt{located\_file\_name} is the
full name of the file as it has been located on the system, \texttt{located\_dir\_name} the directory where it has been
located. Otherwise, they are both set to the empty string.

### 30.19.4.8 starpu_opencl_load_program_source_malloc()

```c
void starpu_opencl_load_program_source_malloc {
    const char * source_file_name,
    char ** located_file_name,
    char ** located_dir_name,
    char ** opencl_program_source ;
}
```

Similar to function \texttt{starpu\_opencl\_load\_program\_source()} but allocate the buffers \texttt{located\_file\_name},
\texttt{located\_dir\_name} and \texttt{opencl\_program\_source}.

### 30.19.4.9 starpu_opencl_compile_opencl_from_file()

```c
int starpu_opencl_compile_opencl_from_file {
    const char * source_file_name,
    const char * build_options ;
}
```

Compile the OpenCL kernel stored in the file \texttt{source\_file\_name} with the given options \texttt{build\_options}
and store the result in the directory 

\$STARPU\_HOME/\$.starpu/opencl with the same filename as \texttt{source\_file\_name}. The compilation is done for every OpenCL device, and the filename is suffixed with the vendor id and
the device id of the OpenCL device.

### 30.19.4.10 starpu_opencl_compile_opencl_from_string()

```c
int starpu_opencl_compile_opencl_from_string {
    const char * opencl_program_source,
    const char * file_name,
    const char * build_options ;
}
```

Compile the OpenCL kernel in the string \texttt{opencl\_program\_source} with the given options \texttt{build\_options}
and store the result in the directory 

\$STARPU\_HOME/\$.starpu/opencl with the filename \texttt{file\_name}. The compilation is done for every OpenCL device, and the filename is suffixed with the vendor id and the device id of
the OpenCL device.
30.19.4.11  starpu_opencl_load_binary_opencl()

int starpu_opencl_load_binary_opencl (
    const char * kernel_id,
    struct starpu_opencl_program * opencl_programs )

Compile the binary OpenCL kernel identified with kernel_id. For every OpenCL device, the binary OpenCL kernel will be loaded from the file $STARPU_HOME/.starpu/opencl/<kernel_id>.<device_type>.vendor_id_<vendor_id>_device_id_<device_id>.

30.19.4.12  starpu_opencl_load_opencl_from_file()

int starpu_opencl_load_opencl_from_file (
    const char * source_file_name,
    struct starpu_opencl_program * opencl_programs,
    const char * build_options )

Compile an OpenCL source code stored in a file.

30.19.4.13  starpu_opencl_load_opencl_from_string()

int starpu_opencl_load_opencl_from_string (
    const char * opencl_program_source,
    struct starpu_opencl_program * opencl_programs,
    const char * build_options )

Compile an OpenCL source code stored in a string.

30.19.4.14  starpu_opencl_unload_opencl()

int starpu_opencl_unload_opencl ( struct starpu_opencl_program * opencl_programs )

Unload an OpenCL compiled code.

30.19.4.15  starpu_opencl_load_kernel()

int starpu_opencl_load_kernel ( cl_kernel * kernel,
    cl_command_queue * queue,
    struct starpu_opencl_program * opencl_programs,
    const char * kernel_name,
    int devid )

Create a kernel kernel for device devid, on its computation command queue returned in queue, using program opencl_programs and name kernel_name.

30.19.4.16  starpu_opencl_release_kernel()

int starpu_opencl_release_kernel ( cl_kernel kernel )

Release the given kernel, to be called after kernel execution.

30.19.4.17  starpu_opencl_collect_stats()

int starpu_opencl_collect_stats ( cl_event event )

Collect statistics on a kernel execution. After termination of the kernels, the OpenCL codelet should call this function with the event returned by clEnqueueNDRangeKernel(), to let StarPU collect statistics about the kernel execution (used cycles, consumed energy).

30.19.4.18  starpu_opencl_error_string()

const char* starpu_opencl_error_string ( cl_int status )
Return the error message in English corresponding to \texttt{status}, an OpenCL error code.

30.19.19 \texttt{starpu_opencl_display_error()}

\begin{verbatim}
void starpu_opencl_display_error ( 
    const char * func, 
    const char * file, 
    int line, 
    const char * msg, 
    cl_int status ) 
\end{verbatim}

Given a valid error status, print the corresponding error message on \texttt{stdout}, along with the function name \texttt{func}, the filename \texttt{file}, the line number \texttt{line} and the message \texttt{msg}.

30.19.20 \texttt{starpu_opencl_report_error()}

\begin{verbatim}
static __starpu_inline void starpu_opencl_report_error ( 
    const char * func, 
    const char * file, 
    int line, 
    const char * msg, 
    cl_int status ) [static] 
\end{verbatim}

Call the function \texttt{starpu_opencl_display_error()} and abort.

30.19.21 \texttt{starpu_openclAllocateMemory()}

\begin{verbatim}
cl_int starpu_openclAllocateMemory ( 
    int devid, 
    cl_mem * addr, 
    size_t size, 
    cl_mem_flags flags ) 
\end{verbatim}

Allocate \texttt{size} bytes of memory, stored in \texttt{addr}. \texttt{flags} must be a valid combination of \texttt{cl_mem_flags} values.

30.19.22 \texttt{starpu_openclCopyRamToOpencl()}

\begin{verbatim}
cl_int starpu_openclCopyRamToOpencl ( 
    void * ptr, 
    unsigned src_node, 
    cl_mem buffer, 
    unsigned dst_node, 
    size_t size, 
    size_t offset, 
    cl_event * event, 
    int * ret ) 
\end{verbatim}

Copy \texttt{size} bytes from the given \texttt{ptr} on RAM \texttt{src_node} to the given \texttt{buffer} on OpenCL \texttt{dst_node}. \texttt{offset} is the offset, in bytes, in \texttt{buffer}. If \texttt{event} is \texttt{NULL}, the copy is synchronous, i.e the queue is synchronised before returning. If not \texttt{NULL}, \texttt{event} can be used after the call to wait for this particular copy to complete. This function returns \texttt{CL_SUCCESS} if the copy was successful, or a valid OpenCL error code otherwise. The integer pointed to by \texttt{ret} is set to \texttt{-EAGAIN} if the asynchronous launch was successful, or to \texttt{0} if \texttt{event} was \texttt{NULL}.

30.19.23 \texttt{starpu_openclCopyOpenclToRam()}

\begin{verbatim}
cl_int starpu_openclCopyOpenclToRam ( 
    cl_mem buffer, 
    unsigned src_node, 
    void * ptr, 
    unsigned dst_node, 
    size_t size, 
    size_t offset, 
\end{verbatim}
cl_event * event,
int * ret )
Copy size bytes asynchronously from the given buffer on OpenCL src_node to the given ptr on RAM dst_node. offset is the offset, in bytes, in buffer. If event is NULL, the copy is synchronous, i.e. the queue is synchronised before returning. If not NULL, event can be used after the call to wait for this particular copy to complete. This function returns CL_SUCCESS if the copy was successful, or a valid OpenCL error code otherwise. The integer pointed to by ret is set to -EAGAIN if the asynchronous launch was successful, or to 0 if event was NULL.

30.19.4.24 starpu_opencl_copy_opencl_to_opencl()

cl_int starpu_opencl_copy_opencl_to_opencl ( 
cl_mem src,
unsigned src_node,
size_t src_offset,
cl_mem dst,
unsigned dst_node,
size_t dst_offset,
size_t size,
cl_event * event,
int * ret )
Copy size bytes asynchronously from byte offset src_offset of src on OpenCL src_node to byte offset dst_offset of dst on OpenCL dst_node. If event is NULL, the copy is synchronous, i.e. the queue is synchronised before returning. If not NULL, event can be used after the call to wait for this particular copy to complete. This function returns CL_SUCCESS if the copy was successful, or a valid OpenCL error code otherwise. The integer pointed to by ret is set to -EAGAIN if the asynchronous launch was successful, or to 0 if event was NULL.

30.19.4.25 starpu_opencl_copy_async_sync()

cl_int starpu_opencl_copy_async_sync ( 
uintptr_t src,
size_t src_offset,
unsigned src_node,
uintptr_t dst,
size_t dst_offset,
unsigned dst_node,
size_t size,
cl_event * event )
Copy size bytes from byte offset src_offset of src on OpenCL src_node to byte offset dst_offset of dst on dst_node. If event is NULL, the copy is synchronous, i.e. the queue is synchronised before returning. If not NULL, event can be used after the call to wait for this particular copy to complete. The function returns -EAGAIN if the asynchronous launch was successful. It returns 0 if the synchronous copy was successful, or fails otherwise.

30.20 OpenMP Runtime Support

This section describes the interface provided for implementing OpenMP runtimes on top of StarPU.

Data Structures

- struct starpu_omp_lock_t
- struct starpu_omp_nest_lock_t
- struct starpu_omp_parallel_region_attr
- struct starpu_omp_task_region_attr

Macros

- #define STARPU_OPENMP
• `#define __STARPU_OMP_NOTHROW`

Enumerations

• `enum starpu_omp_sched_value { starpu_omp_sched_undefined, starpu_omp_sched_static, starpu_omp_sched_dynamic, starpu_omp_sched_guided, starpu_omp_sched_auto, starpu_omp_sched_runtime }`

• `enum starpu_omp_proc_bind_value { starpu_omp_proc_bind_undefined, starpu_omp_proc_bind_false, starpu_omp_proc_bind_true, starpu_omp_proc_bind_master, starpu_omp_proc_bind_close, starpu_omp_proc_bind_spread }`

Initialisation

• `int starpu_omp_init (void) __STARPU_OMP_NOTHROW`

• `void starpu_omp_shutdown (void) __STARPU_OMP_NOTHROW`

Parallel

• `void starpu_omp_parallel_region (const struct starpu_omp_parallel_region_attr *attr) __STARPU_OMP_NOTHROW`

• `void starpu_omp_master (void (*)(void *)arg), void *arg) __STARPU_OMP_NOTHROW`

• `int starpu_omp_master_inline (void) __STARPU_OMP_NOTHROW`

Synchronization

• `void starpu_omp_barrier (void) __STARPU_OMP_NOTHROW`

• `void starpu_omp_critical (void (*)(void *)f)(void *arg), void *arg, const char *name) __STARPU_OMP_NOTHROW`

• `void starpu_omp_critical_inline_begin (const char *name) __STARPU_OMP_NOTHROW`

• `void starpu_omp_critical_inline_end (const char *name) __STARPU_OMP_NOTHROW`

Worksharing

• `void starpu_omp_single (void (*)(void *)f)(void *arg), void *arg, int nowait) __STARPU_OMP_NOTHROW`

• `int starpu_omp_single_inline (void) __STARPU_OMP_NOTHROW`

• `void starpu_omp_single_copyprivate (void (*)(void *)f)(void *arg, void *data, unsigned long long data_size), void *arg, void *data, unsigned long long data_size) __STARPU_OMP_NOTHROW`

• `void * starpu_omp_single_copyprivate_inline_begin (void *data) __STARPU_OMP_NOTHROW`

• `void starpu_omp_single_copyprivate_inline_end (void) __STARPU_OMP_NOTHROW`

• `void starpu_omp_for (void (*)(unsigned long long _first_i, unsigned long long _nb_i, void *arg), void *arg, unsigned long long nb_iterations, unsigned long long chunk, int schedule, int ordered, int nowait) __STARPU_OMP_NOTHROW`

• `int starpu_omp_for_inline_first (unsigned long long nb_iterations, unsigned long long chunk, int schedule, int ordered, unsigned long long *_first_i, unsigned long long *_nb_i) __STARPU_OMP_NOTHROW`

• `int starpu_omp_for_inline_next (unsigned long long nb_iterations, unsigned long long chunk, int schedule, int ordered, unsigned long long *_first_i, unsigned long long *_nb_i) __STARPU_OMP_NOTHROW`

• `void starpu_omp_for_alt (void (*)(unsigned long long _begin_i, unsigned long long _end_i, void *arg), void *arg, unsigned long long nb_iterations, unsigned long long chunk, int schedule, int ordered, int nowait) __STARPU_OMP_NOTHROW`

• `int starpu_omp_for_inline_first_alt (unsigned long long nb_iterations, unsigned long long chunk, int schedule, int ordered, unsigned long long *_begin_i, unsigned long long *_end_i) __STARPU_OMP_NOTHROW`

• `int starpu_omp_for_inline_next_alt (unsigned long long nb_iterations, unsigned long long chunk, int schedule, int ordered, unsigned long long *_begin_i, unsigned long long *_end_i) __STARPU_OMP_NOTHROW`

• `void starpu_omp_ordered (void (*)(void *)f)(void *arg), void *arg) __STARPU_OMP_NOTHROW`

• `void starpu_omp_ordered_inline_begin (void) __STARPU_OMP_NOTHROW`

• `void starpu_omp_ordered_inline_end (void) __STARPU_OMP_NOTHROW`

• `void starpu_omp_ordered_inline_begin (void) __STARPU_OMP_NOTHROW`

• `void starpu_omp_ordered_inline_end (void) __STARPU_OMP_NOTHROW`

• `void starpu_omp_ordered_inline_end (void) __STARPU_OMP_NOTHROW`

• `void starpu_omp_ordered_inline_end (void) __STARPU_OMP_NOTHROW`
• void starpu_omp_sections (unsigned long long nb_sections, void(**section_f)(void *arg), void **section_arg, int nowait) __STARPU_OMP_NOTHROW
• void starpu_omp_sections_combined (unsigned long long nb_sections, void(**section_f)(void **arg), void **section_arg, int nowait) __STARPU_OMP_NOTHROW

Task

• void starpu_omp_task_region (const struct starpu_omp_task_region_attr *attr) __STARPU_OMP_NOTHROW
• void starpu_omp_taskwait (void) __STARPU_OMP_NOTHROW
• void starpu_omp_taskgroup (void (*)(void *arg), void *arg) __STARPU_OMP_NOTHROW
• void starpu_omp_taskgroup_inline_begin (void) __STARPU_OMP_NOTHROW
• void starpu_omp_taskgroup_inline_end (void) __STARPU_OMP_NOTHROW
• void starpu_omp_taskloop_inline_begin (struct starpu_omp_task_region_attr *attr) __STARPU_OMP_NOTHROW
• void starpu_omp_taskloop_inline_end (const struct starpu_omp_task_region_attr *attr) __STARPU_OMP_NOTHROW

API

• void starpu_omp_set_num_threads (int threads) __STARPU_OMP_NOTHROW
• int starpu_omp_get_num_threads () __STARPU_OMP_NOTHROW
• int starpu_omp_get_thread_num () __STARPU_OMP_NOTHROW
• int starpu_omp_get_max_threads () __STARPU_OMP_NOTHROW
• int starpu_omp_get_num_procs (void) __STARPU_OMP_NOTHROW
• int starpu_omp_in_parallel (void) __STARPU_OMP_NOTHROW
• void starpu_omp_set_dynamic (int dynamic_threads) __STARPU_OMP_NOTHROW
• int starpu_omp_get_dynamic (void) __STARPU_OMP_NOTHROW
• void starpu_omp_set_nested (int nested) __STARPU_OMP_NOTHROW
• int starpu_omp_get_nested (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_cancellation (void) __STARPU_OMP_NOTHROW
• void starpu_omp_set_schedule (enum starpu_omp_sched_value kind, int modifier) __STARPU_OMP_NOTHROW
• void starpu_omp_get_schedule (enum starpu_omp_sched_value *kind, int *modifier) __STARPU_OMP_NOTHROW
• int starpu_omp_get_thread_limit (void) __STARPU_OMP_NOTHROW
• void starpu_omp_set_max_active_levels (int max_levels) __STARPU_OMP_NOTHROW
• int starpu_omp_get_max_active_levels (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_level (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_ancestor_thread_num (int level) __STARPU_OMP_NOTHROW
• int starpu_omp_get_team_size (int level) __STARPU_OMP_NOTHROW
• int starpu_omp_get_active_level (void) __STARPU_OMP_NOTHROW
• int starpu_omp_in_final (void) __STARPU_OMP_NOTHROW
• enum starpu_omp_proc_bind_value starpu_omp_get_proc_bind (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_num_places (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_place_num_procs (int place_num) __STARPU_OMP_NOTHROW
• int starpu_omp_get_place_proc_ids (int place_num, int *ids) __STARPU_OMP_NOTHROW
• int starpu_omp_get_partition_num_places (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_num_devices (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_num_teams (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_team_num (void) __STARPU_OMP_NOTHROW

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• int starpu_omp_is_initial_device (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_initial_device (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_max_task_priority (void) __STARPU_OMP_NOTHROW
• void starpu_omp_init_lock (starpu_omp_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_destroy_lock (starpu_omp_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_set_lock (starpu_omp_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_unset_lock (starpu_omp_lock_t *lock) __STARPU_OMP_NOTHROW
• int starpu_omp_test_lock (starpu_omp_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_init_nest_lock (starpu_omp_nest_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_destroy_nest_lock (starpu_omp_nest_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_set_nest_lock (starpu_omp_nest_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_unset_nest_lock (starpu_omp_nest_lock_t *lock) __STARPU_OMP_NOTHROW
• int starpu_omp_test_nest_lock (starpu_omp_nest_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_atomic_fallback_inline_begin (void) __STARPU_OMP_NOTHROW
• void starpu_omp_atomic_fallback_inline_end (void) __STARPU_OMP_NOTHROW
• double starpu_omp_get_wtime (void) __STARPU_OMP_NOTHROW
• double starpu_omp_get_wtick (void) __STARPU_OMP_NOTHROW
• void starpu_omp_vector_annotate (starpu_data_handle_t handle, uint32_t slice_base) __STARPU_OMP_NOTHROW
• struct starpu_arbiter * starpu_omp_get_default_arbiter (void) __STARPU_OMP_NOTHROW

30.20.1 Detailed Description

This section describes the interface provided for implementing OpenMP runtimes on top of StarPU.

30.20.2 Data Structure Documentation

30.20.2.1 struct starpu_omp_lock_t

Opaque Simple Lock object (Simple Locks) for inter-task synchronization operations.

See also

starpu_omp_init_lock()
starpu_omp_destroy_lock()
starpu_omp_set_lock()
starpu_omp_unset_lock()
starpu_omp_test_lock()

Data Fields

| void * | internal | opaque pointer for internal use |

30.20.2.2 struct starpu_omp_nest_lock_t

Opaque Nestable Lock object (Nestable Locks) for inter-task synchronization operations.

See also

starpu_omp_init_nest_lock()
starpu_omp_destroy_nest_lock()
starpu_omp_set_nest_lock()
starpu_omp_unset_nest_lock()
starpu_omp_test_nest_lock()
30.20 OpenMP Runtime Support

Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>void *</td>
<td>internal</td>
<td>opaque pointer for internal use</td>
</tr>
</tbody>
</table>

30.20.2.3 struct starpu_omp_parallel_region_attr

Set of attributes used for creating a new parallel region.

See also

starpu_omp_parallel_region()

Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>struct starpu_codelet</td>
<td>cl</td>
<td>starpu_codelet (Codelet And Tasks) to use for the parallel region implicit tasks. The codelet must provide a CPU implementation function.</td>
</tr>
<tr>
<td>starpu_data_handle_t *</td>
<td>handles</td>
<td>Array of zero or more starpu_data_handle_t data handle to be passed to the parallel region implicit tasks.</td>
</tr>
<tr>
<td>void *</td>
<td>cl_arg</td>
<td>Optional pointer to an inline argument to be passed to the region implicit tasks.</td>
</tr>
<tr>
<td>size_t</td>
<td>cl_arg_size</td>
<td>Size of the optional inline argument to be passed to the region implicit tasks, or 0 if unused.</td>
</tr>
<tr>
<td>unsigned</td>
<td>cl_arg_free</td>
<td>Boolean indicating whether the optional inline argument should be automatically freed (true), or not (false).</td>
</tr>
<tr>
<td>int</td>
<td>if_clause</td>
<td>Boolean indicating whether the if clause of the corresponding pragma omp parallel is true or false.</td>
</tr>
<tr>
<td>int</td>
<td>num_threads</td>
<td>Integer indicating the requested number of threads in the team of the newly created parallel region, or 0 to let the runtime choose the number of threads alone. This attribute may be ignored by the runtime system if the requested number of threads is higher than the number of threads that the runtime can create.</td>
</tr>
</tbody>
</table>

30.20.2.4 struct starpu_omp_task_region_attr

Set of attributes used for creating a new task region.

See also

starpu_omp_task_region()

Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>struct starpu_codelet</td>
<td>cl</td>
<td>starpu_codelet (Codelet And Tasks) to use for the task region explicit task. The codelet must provide a CPU implementation function or an accelerator implementation for offloaded target regions.</td>
</tr>
<tr>
<td>starpu_data_handle_t *</td>
<td>handles</td>
<td>Array of zero or more starpu_data_handle_t data handle to be passed to the task region explicit tasks.</td>
</tr>
<tr>
<td>void *</td>
<td>cl_arg</td>
<td>Optional pointer to an inline argument to be passed to the region implicit tasks.</td>
</tr>
<tr>
<td>size_t</td>
<td>cl_arg_size</td>
<td>Size of the optional inline argument to be passed to the region implicit tasks, or 0 if unused.</td>
</tr>
<tr>
<td>unsigned</td>
<td>cl_arg_free</td>
<td>Boolean indicating whether the optional inline argument should be automatically freed (true), or not (false).</td>
</tr>
</tbody>
</table>
Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>priority</td>
</tr>
<tr>
<td>int</td>
<td>if_clause</td>
</tr>
<tr>
<td>int</td>
<td>final_clause</td>
</tr>
<tr>
<td>int</td>
<td>untied_clause</td>
</tr>
<tr>
<td>int</td>
<td>mergeable_clause</td>
</tr>
<tr>
<td>int</td>
<td>is_loop</td>
</tr>
<tr>
<td>int</td>
<td>nogroup_clause</td>
</tr>
<tr>
<td>int</td>
<td>collapse</td>
</tr>
<tr>
<td>int</td>
<td>num_tasks</td>
</tr>
<tr>
<td>unsigned long long</td>
<td>nb_iterations</td>
</tr>
<tr>
<td>unsigned long long</td>
<td>grainsize</td>
</tr>
<tr>
<td>unsigned long long</td>
<td>begin_i</td>
</tr>
<tr>
<td>unsigned long long</td>
<td>end_i</td>
</tr>
<tr>
<td>unsigned long long</td>
<td>chunk</td>
</tr>
</tbody>
</table>

30.20.3 Macro Definition Documentation

30.20.3.1 STARPU_OPENMP

#define STARPU_OPENMP

This macro is defined when StarPU has been installed with OpenMP Runtime support. It should be used in your code to detect the availability of the runtime support for OpenMP.

30.20.4 Enumeration Type Documentation

30.20.4.1 starpu_omp_sched_value

enum starpu_omp_sched_value

Set of constants for selecting the for loop iteration scheduling algorithm (Parallel For) as defined by the OpenMP specification.

See also

- starpu_omp_for()
- starpu_omp_for_inline_first()
- starpu_omp_for_inline_next()
- starpu_omp_for_alt()
- starpu_omp_for_inline_first_alt()
- starpu_omp_for_inline_next_alt()

Enumerator

<table>
<thead>
<tr>
<th>Enumerant</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>starpu_omp_sched_undefined</td>
<td>Undefined iteration scheduling algorithm.</td>
</tr>
<tr>
<td>starpu_omp_sched_static</td>
<td>Static iteration scheduling algorithm.</td>
</tr>
<tr>
<td>starpu_omp_sched_dynamic</td>
<td>Dynamic iteration scheduling algorithm.</td>
</tr>
</tbody>
</table>

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30.20.4.2 starpu_omp_proc_bind_value

enum starpu_omp_proc_bind_value
Set of constants for selecting the processor binding method, as defined in the OpenMP specification.

See also

starpu_omp_get_proc_bind()

Enumerators

<table>
<thead>
<tr>
<th>starpu_omp_proc_bind_undefined</th>
<th>Undefined processor binding method.</th>
</tr>
</thead>
<tbody>
<tr>
<td>starpu_omp_proc_bind_false</td>
<td>Team threads may be moved between places at any time.</td>
</tr>
<tr>
<td>starpu_omp_proc_bind_true</td>
<td>Team threads may not be moved between places.</td>
</tr>
<tr>
<td>starpu_omp_proc_bind_master</td>
<td>Assign every thread in the team to the same place as the master thread.</td>
</tr>
<tr>
<td>starpu_omp_proc_bind_close</td>
<td>Assign every thread in the team to a place close to the parent thread.</td>
</tr>
<tr>
<td>starpu_omp_proc_bind_spread</td>
<td>Assign team threads as a sparse distribution over the selected places.</td>
</tr>
</tbody>
</table>

30.20.5 Function Documentation

30.20.5.1 starpu_omp_init()

int starpu_omp_init ( void )
Initialize StarPU and its OpenMP Runtime support.

30.20.5.2 starpu_omp_shutdown()

void starpu_omp_shutdown ( void )
Shutdown StarPU and its OpenMP Runtime support.

30.20.5.3 starpu_omp_parallel_region()

void starpu_omp_parallel_region ( const struct starpu_omp_parallel_region_attr * attr )
Generate and launch an OpenMP parallel region and return after its completion. attr specifies the attributes for the generated parallel region. If this function is called from inside another, generating, parallel region, the generated parallel region is nested within the generating parallel region. This function can be used to implement #pragma omp parallel.

30.20.5.4 starpu_omp_master()

void starpu_omp_master ( void (*)(void *arg) f, void * arg )
Execute a function only on the master thread of the OpenMP parallel region it is called from. When called from a thread that is not the master of the parallel region it is called from, this function does nothing. \( f \) is the function to be called. \( \text{arg} \) is an argument passed to function \( f \).

This function can be used to implement \#pragma omp master.

#### 30.20.5.5 starpu_omp_master_inline()

```c
int starpu_omp_master_inline ( void )
```

Determine whether the calling thread is the master of the OpenMP parallel region it is called from or not.

This function can be used to implement \#pragma omp master without code outlining.

**Returns**

- 1 if called by the region's master thread.
- 0 if not called by the region's master thread.

#### 30.20.5.6 starpu_omp_barrier()

```c
void starpu_omp_barrier ( void )
```

Wait until each participating thread of the innermost OpenMP parallel region has reached the barrier and each explicit OpenMP task bound to this region has completed its execution.

This function can be used to implement \#pragma omp barrier.

#### 30.20.5.7 starpu_omp_critical()

```c
void starpu_omp_critical ( void(*) (void *arg) f, void * arg, const char * name )
```

Wait until no other thread is executing within the context of the selected critical section, then proceeds to the exclusive execution of a function within the critical section. \( f \) is the function to be executed in the critical section. \( \text{arg} \) is an argument passed to function \( f \). \( \text{name} \) is the name of the selected critical section. If \text{name} == NULL, the selected critical section is the unique anonymous critical section.

This function can be used to implement \#pragma omp critical.

#### 30.20.5.8 starpu_omp_critical_inline_begin()

```c
void starpu_omp_critical_inline_begin ( const char * name )
```

Wait until execution can proceed exclusively within the context of the selected critical section. \( \text{name} \) is the name of the selected critical section. If \text{name} == NULL, the selected critical section is the unique anonymous critical section.

This function together with starpu_omp_critical_inline_end can be used to implement \#pragma omp critical without code outlining.

#### 30.20.5.9 starpu_omp_critical_inline_end()

```c
void starpu_omp_critical_inline_end ( const char * name )
```

End the exclusive execution within the context of the selected critical section. \( \text{name} \) is the name of the selected critical section. If \text{name}==NULL, the selected critical section is the unique anonymous critical section.

This function together with starpu_omp_critical_inline_begin can be used to implement \#pragma omp critical without code outlining.
30.20.5.10 starpu_omp_single()

```c
void starpu_omp_single(
    void(*)(void *arg) f,
    void * arg,
    int nowait)
```

Ensure that a single participating thread of the innermost OpenMP parallel region executes a function. `f` is the function to be executed by a single thread. `arg` is an argument passed to function `f`. `nowait` is a flag indicating whether an implicit barrier is requested after the single section (`nowait==0`) or not (`nowait=!0`). This function can be used to implement `#pragma omp single`.

30.20.5.11 starpu_omp_single_inline()

```c
int starpu_omp_single_inline (void)
```

Decide whether the current thread is elected to run the following single section among the participating threads of the innermost OpenMP parallel region. This function can be used to implement `#pragma omp single` without code outlining.

Returns

- `!0` if the calling thread has won the election.
- `0` if the calling thread has lost the election.

30.20.5.12 starpu_omp_single_copyprivate()

```c
void starpu_omp_single_copyprivate (           
    void(*)(void *arg, void *data, unsigned long long data_size) f,
    void * arg,
    void * data,
    unsigned long long data_size)
```

Execute `f` on a single task of the current parallel region task, and then broadcast the contents of the memory block pointed by the `copyprivate` pointer `data` and of size `data_size` to the corresponding `data` pointed memory blocks of all the other participating region tasks. This function can be used to implement `#pragma omp single` with a `copyprivate` clause.

See also

- `starpu_omp_single_copyprivate_inline`
- `starpu_omp_single_copyprivate_inline_begin`
- `starpu_omp_single_copyprivate_inline_end`

30.20.5.13 starpu_omp_single_copyprivate_inline_begin()

```c
void* starpu_omp_single_copyprivate_inline_begin (void *data)
```

Elect one task among the tasks of the current parallel region task to execute the following single section, and then broadcast the `copyprivate` pointer `data` to all the other participating region tasks. This function can be used to implement `#pragma omp single` with a `copyprivate` clause without code outlining.

See also

- `starpu_omp_single_copyprivate_inline`
- `starpu_omp_single_copyprivate_inline_end`
30.20.5.14 starpu_omp_single_copyprivate_inline_end()

void starpu_omp_single_copyprivate_inline_end ( void )

Complete the execution of a single section and return the broadcasted copyprivate pointer for tasks that lost the election and NULL for the task that won the election. This function can be used to implement #pragma omp single with a copyprivate clause without code outlining.

Returns

the copyprivate pointer for tasks that lost the election and therefore did not execute the code of the single section.
NULL for the task that won the election and executed the code of the single section.

See also

starpu_omp_single_copyprivate_inline
starpu_omp_single_copyprivate_inline_begin

30.20.5.15 starpu_omp_for()

void starpu_omp_for ( 
    void(*)(unsigned long long __first_i, unsigned long long __nb_i, void *arg) f,
    void * arg,
    unsigned long long nb_iterations,
    unsigned long long chunk,
    int schedule,
    int ordered,
    int nowait )

Execute a parallel loop together with the other threads participating to the innermost parallel region. f is the function to be executed iteratively. arg is an argument passed to function f. nb_iterations is the number of iterations to be performed by the parallel loop. chunk is the number of consecutive iterations that should be affected to the same thread when scheduling the loop workshares, it follows the semantics of the modifier argument in OpenMP #pragma omp for specification. schedule is the scheduling mode according to the OpenMP specification. ordered is a flag indicating whether the loop region may contain an ordered section (ordered==!0) or not (ordered==0). nowait is a flag indicating whether an implicit barrier is requested after the for section (nowait==0) or not (nowait==!0).

The function f will be called with arguments __first_i, the first iteration to perform, __nb_i, the number of consecutive iterations to perform before returning, arg, the free arg argument.

This function can be used to implement #pragma omp for.

30.20.5.16 starpu_omp_for_inline_first()

int starpu_omp_for_inline_first ( 
    unsigned long long nb_iterations,
    unsigned long long chunk,
    int schedule,
    int ordered,
    unsigned long long * __first_i,
    unsigned long long * __nb_i )

Decide whether the current thread should start to execute a parallel loop section. See starpu_omp_for for the argument description.

This function together with starpu_omp_for_inline_next can be used to implement #pragma omp for without code outlining.
Returns

\(!0\) if the calling thread participates to the loop region and should execute a first chunk of iterations. In that case, \(\_\text{first}_i\) will be set to the first iteration of the chunk to perform and \(\_\text{nb}_i\) will be set to the number of iterations of the chunk to perform.

\(0\) if the calling thread does not participate to the loop region because all the available iterations have been affected to the other threads of the parallel region.

See also

\texttt{starpu\_omp\_for}

30.20.5.17 \texttt{starpu\_omp\_for\_inline\_next()}

\begin{verbatim}
int starpu_omp_for_inline_next (  

 unsigned long long nb_iterations,  
 unsigned long long chunk,  
 int schedule,  
 int ordered,  
 unsigned long long \_first_i,  
 unsigned long long \_nb_i  
)
\end{verbatim}

Decide whether the current thread should continue to execute a parallel loop section. See \texttt{starpu\_omp\_for} for the argument description.

This function together with \texttt{starpu\_omp\_for\_inline\_first} can be used to implement \texttt{#pragma omp for} without code outlining.

Returns

\(!0\) if the calling thread should execute a next chunk of iterations. In that case, \(\_\text{first}_i\) will be set to the first iteration of the chunk to perform and \(\_\text{nb}_i\) will be set to the number of iterations of the chunk to perform.

\(0\) if the calling thread does not participate anymore to the loop region because all the available iterations have been affected to the other threads of the parallel region.

See also

\texttt{starpu\_omp\_for}

30.20.5.18 \texttt{starpu\_omp\_for\_alt()}

\begin{verbatim}
void starpu_omp_for_alt (  

 void(*)(unsigned long long _begin_i, unsigned long long _end_i, void *arg) f,  
 void * arg,  
 unsigned long long nb_iterations,  
 unsigned long long chunk,  
 int schedule,  
 int ordered,  
 int nowait  
)
\end{verbatim}

Alternative implementation of a parallel loop. Differ from \texttt{starpu\_omp\_for} in the expected arguments of the loop function \(f\).

The function \(f\) will be called with arguments \_begin\_i, the first iteration to perform, \_end\_i, the first iteration not to perform before returning, \arg, the free \arg argument.

This function can be used to implement \texttt{#pragma omp for}.

See also

\texttt{starpu\_omp\_for}
### 30.20.5.19 starpu_omp_for_inline_first_alt()

```c
int starpu_omp_for_inline_first_alt (      
    unsigned long long nb_iterations,      
    unsigned long long chunk,             
    int schedule,                         
    int ordered,                          
    unsigned long long * _begin_i,        
    unsigned long long * _end_i )
```

Inline version of the alternative implementation of a parallel loop.
This function together with `starpu_omp_for_inline_next_alt` can be used to implement `#pragma omp for` without code outlining.

See also
- `starpu_omp_for`
- `starpu_omp_for_alt`
- `starpu_omp_for_inline_first`

### 30.20.5.20 starpu_omp_for_inline_next_alt()

```c
int starpu_omp_for_inline_next_alt (      
    unsigned long long nb_iterations,      
    unsigned long long chunk,             
    int schedule,                         
    int ordered,                          
    unsigned long long * _begin_i,        
    unsigned long long * _end_i )
```

Inline version of the alternative implementation of a parallel loop.
This function together with `starpu_omp_for_inline_first_alt` can be used to implement `#pragma omp for` without code outlining.

See also
- `starpu_omp_for`
- `starpu_omp_for_alt`
- `starpu_omp_for_inline_next`

### 30.20.5.21 starpu_omp_ordered()

```c
void starpu_omp_ordered (      
    void(*)(void *)arg) f,      
    void * arg )
```

Ensure that a function is sequentially executed once for each iteration in order within a parallel loop, by the thread that owns the iteration. `f` is the function to be executed by the thread that owns the current iteration. `arg` is an argument passed to function `f`.
This function can be used to implement `#pragma omp ordered`.

### 30.20.5.22 starpu_omp_ordered_inline_begin()

```c
void starpu_omp_ordered_inline_begin (      
    void )
```

Wait until all the iterations of a parallel loop below the iteration owned by the current thread have been executed.
This function together with `starpu_omp_ordered_inline_end` can be used to implement `#pragma omp ordered` without code outlining.
30.20.5.23 starpu_omp_ordered_inline_end()

```c
void starpu_omp_ordered_inline_end ( void )
```

Notify that the ordered section for the current iteration has been completed. This function together with `starpu_omp_ordered_inline_begin` can be used to implement `#pragma omp ordered` without code outlining.

30.20.5.24 starpu_omp_sections()

```c
void starpu_omp_sections ( 
    unsigned long long nb_sections, 
    void(**)(void *arg) section_f, 
    void ** section_arg, 
    int nowait )
```

Ensure that each function of a given array of functions is executed by one and only one thread. `nb_sections` is the number of functions in the array `section_f`. `section_f` is the array of functions to be executed as sections. `section_arg` is an array of arguments to be passed to the corresponding function. `nowait` is a flag indicating whether an implicit barrier is requested after the execution of all the sections (`nowait==0`) or not (`nowait==!0`). This function can be used to implement `#pragma omp sections` and `#pragma omp section`.

30.20.5.25 starpu_omp_sections_combined()

```c
void starpu_omp_sections_combined ( 
    unsigned long long nb_sections, 
    void(*)(unsigned long long section_num, void *arg) section_f, 
    void * section_arg, 
    int nowait )
```

Alternative implementation of sections. Differ from `starpu_omp_sections` in that all the sections are combined within a single function in this version. `section_f` is the function implementing the combined sections. The function `section_f` will be called with arguments `section_num`, the section number to be executed, `arg`, the entry of `section_arg` corresponding to this section. This function can be used to implement `#pragma omp sections` and `#pragma omp section`. See also `starpu_omp_sections`.

30.20.5.26 starpu_omp_task_region()

```c
void starpu_omp_task_region ( 
    const struct starpu_omp_task_region_attr * attr )
```

Generate an explicit child task. The execution of the generated task is asynchronous with respect to the calling code unless specified otherwise. `attr` specifies the attributes for the generated task region. This function can be used to implement `#pragma omp task`.

30.20.5.27 starpu_omp_taskwait()

```c
void starpu_omp_taskwait ( void )
```

Wait for the completion of the tasks generated by the current task. This function does not wait for the descendants of the tasks generated by the current task. This function can be used to implement `#pragma omp taskwait`.

30.20.5.28 starpu_omp_taskgroup()

```c
void starpu_omp_taskgroup ( 
    void(*)(void *arg) f, 
    void * arg )
```
Launch a function and wait for the completion of every descendant task generated during the execution of the function. This function can be used to implement `#pragma omp taskgroup`.

See also
- `starpu_omp_taskgroup_inline_begin`
- `starpu_omp_taskgroup_inline_end`

### 30.20.5.29 starpu_omp_taskgroup_inline_begin()  

```c
void starpu_omp_taskgroup_inline_begin ( void )
```

Launch a function and gets ready to wait for the completion of every descendant task generated during the dynamic scope of the taskgroup. This function can be used to implement `#pragma omp taskgroup` without code outlining.

See also
- `starpu_omp_taskgroup`
- `starpu_omp_taskgroup_inline_end`

### 30.20.5.30 starpu_omp_taskgroup_inline_end()  

```c
void starpu_omp_taskgroup_inline_end ( void )
```

Wait for the completion of every descendant task generated during the dynamic scope of the taskgroup. This function can be used to implement `#pragma omp taskgroup` without code outlining.

See also
- `starpu_omp_taskgroup`
- `starpu_omp_taskgroup_inline_begin`

### 30.20.5.31 starpu_omp_set_num_threads()  

```c
void starpu_omp_set_num_threads ( int threads )
```

Set ICVS nthreads_var for the parallel regions to be created with the current region. Note: The StarPU OpenMP runtime support currently ignores this setting for nested parallel regions.

See also
- `starpu_omp_get_num_threads`
- `starpu_omp_get_thread_num`
- `starpu_omp_get_max_threads`
- `starpu_omp_get_num_procs`

### 30.20.5.32 starpu_omp_get_num_threads()  

```c
int starpu_omp_get_num_threads ( )
```

Return the number of threads of the current region.

Returns
- the number of threads of the current region.
See also

- starpu_omp_set_num_threads
- starpu_omp_get_thread_num
- starpu_omp_get_max_threads
- starpu_omp_get_num_procs

### 30.20.5.33 starpu_omp_get_thread_num()

```c
int starpu_omp_get_thread_num ( )
```

Returns

the rank of the current thread among the threads of the current region.

See also

- starpu_omp_set_num_threads
- starpu_omp_get_num_threads
- starpu_omp_get_max_threads
- starpu_omp_get_num_procs

### 30.20.5.34 starpu_omp_get_max_threads()

```c
int starpu_omp_get_max_threads ( )
```

Returns

the maximum number of threads that can be used to create a region from the current region.

See also

- starpu_omp_set_num_threads
- starpu_omp_get_num_threads
- starpu_omp_get_thread_num
- starpu_omp_get_num_procs

### 30.20.5.35 starpu_omp_get_num_procs()

```c
int starpu_omp_get_num_procs ( void )
```

Returns

the number of StarPU CPU workers.

See also

- starpu_omp_set_num_threads
- starpu_omp_get_num_threads
- starpu_omp_get_thread_num
- starpu_omp_get_max_threads

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30.20.5.36  starpu_omp_in_parallel()

int starpu_omp_in_parallel (  
   void )  

Return whether it is called from the scope of a parallel region or not.

Returns
   
   !0 if called from a parallel region scope.  
   0 otherwise.

30.20.5.37  starpu_omp_set_dynamic()

void starpu_omp_set_dynamic (  
   int dynamic_threads )  

Enable (1) or disable (0) dynamically adjusting the number of parallel threads.  
Note: The StarPU OpenMP runtime support currently ignores the argument of this function.

See also
   
   starpu_omp_get_dynamic

30.20.5.38  starpu_omp_get_dynamic()

int starpu_omp_get_dynamic (  
   void )  

Return the state of dynamic thread number adjustment.

Returns
   
   !0 if dynamic thread number adjustment is enabled.  
   0 otherwise.

See also
   
   starpu_omp_set_dynamic

30.20.5.39  starpu_omp_set_nested()

void starpu_omp_set_nested (  
   int nested )  

Enable (1) or disable (0) nested parallel regions.  
Note: The StarPU OpenMP runtime support currently ignores the argument of this function.

See also
   
   starpu_omp_get_nested  
   starpu_omp_get_max_active_levels  
   starpu_omp_set_max_active_levels  
   starpu_omp_get_level  
   starpu_omp_get_active_level
30.20.5.40 starpu_omp_get_nested()

```c
int starpu_omp_get_nested (
    void )
```

Return whether nested parallel sections are enabled or not.

Returns

- 1 if nested parallel sections are enabled.
- 0 otherwise.

See also

- `starpu_omp_set_nested`
- `starpu_omp_get_max_active_levels`
- `starpu_omp_set_max_active_levels`
- `starpu_omp_get_level`
- `starpu_omp_get_active_level`

30.20.5.41 starpu_omp_get_cancellation()

```c
int starpu_omp_get_cancellation ( 
    void )
```

Return the state of the cancel ICVS var.

30.20.5.42 starpu_omp_set_schedule()

```c
void starpu_omp_set_schedule ( 
    enum starpu_omp_sched_value kind, 
    int modifier )
```

Set the default scheduling kind for upcoming loops within the current parallel section. `kind` is the scheduler kind, `modifier` complements the scheduler kind with informations such as the chunk size, in accordance with the OpenMP specification.

See also

- `starpu_omp_get_schedule`

30.20.5.43 starpu_omp_get_schedule()

```c
void starpu_omp_get_schedule ( 
    enum starpu_omp_sched_value * kind, 
    int * modifier )
```

Return the current selected default loop scheduler.

Returns

- the kind and the modifier of the current default loop scheduler.

See also

- `starpu_omp_set_schedule`
30.20.5.44 starpu_omp_get_thread_limit()

```c
int starpu_omp_get_thread_limit ( void )
```

Return the number of StarPU CPU workers.

Returns

the number of StarPU CPU workers.

30.20.5.45 starpu_omp_set_max_active_levels()

```c
void starpu_omp_set_max_active_levels ( int max_levels )
```

Set the maximum number of allowed active parallel section levels.

Note: The StarPU OpenMP runtime support currently ignores the argument of this function and assume `max_levels` equals 1 instead.

See also

- starpu_omp_set_nested
- starpu_omp_get_nested
- starpu_omp_get_max_active_levels
- starpu_omp_get_level
- starpu_omp_get_active_level

30.20.5.46 starpu_omp_get_max_active_levels()

```c
int starpu_omp_get_max_active_levels ( void )
```

Return the current maximum number of allowed active parallel section levels.

Returns

the current maximum number of allowed active parallel section levels.

See also

- starpu_omp_set_nested
- starpu_omp_get_nested
- starpu_omp_get_max_active_levels
- starpu_omp_get_level
- starpu_omp_get_active_level

30.20.5.47 starpu_omp_get_level()

```c
int starpu_omp_get_level ( void )
```

Return the nesting level of the current parallel section.

Returns

the nesting level of the current parallel section.

See also

- starpu_omp_set_nested
- starpu_omp_get_nested
- starpu_omp_get_max_active_levels
- starpu_omp_get_level
- starpu_omp_get_active_level
30.20.5.48  starpu_omp_get_ancestor_thread_num()

    int starpu_omp_get_ancestor_thread_num (   
        int level )

    Return the number of the ancestor of the current parallel section.
    
    Returns
    
        the number of the ancestor of the current parallel section.

30.20.5.49  starpu_omp_get_team_size()

    int starpu_omp_get_team_size (   
        int level )

    Return the size of the team of the current parallel section.
    
    Returns
    
        the size of the team of the current parallel section.

30.20.5.50  starpu_omp_get_active_level()

    int starpu_omp_get_active_level (   
        void )

    Return the nestinglevel of the current innermost active parallel section.
    
    Returns
    
        the nestinglevel of the current innermost active parallel section.

    See also

        starpu_omp_set_nested
        starpu_omp_get_nested
        starpu_omp_get_max_active_levels
        starpu_omp_set_max_active_levels
        starpu_omp_get_level

30.20.5.51  starpu_omp_in_final()

    int starpu_omp_in_final (   
        void )

    Check whether the current task is final or not.
    
    Returns
    
        !0 if called from a final task.
        0 otherwise.

30.20.5.52  starpu_omp_get_proc_bind()

    enum starpu_omp_proc_bind_value starpu_omp_get_proc_bind (   
        void )

    Return the proc_bind setting of the current parallel region.
    
    Returns
    
        the proc_bind setting of the current parallel region.
30.20.5.53  

starpu_omp_set_default_device()

void starpu_omp_set_default_device (  
  int device_num   
)  

Set the number of the device to use as default. 
Note: The StarPU OpenMP runtime support currently ignores the argument of this function.  

See also  
  
  starpu_omp_get_default_device  
  starpu_omp_is_initial_device

30.20.5.54  

starpu_omp_get_default_device()

int starpu_omp_get_default_device (  
  void   
)  

Return the number of the device used as default.  

Returns  
  
  the number of the device used as default.  

See also  
  
  starpu_omp_set_default_device  
  starpu_omp_is_initial_device

30.20.5.55  

starpu_omp_get_num_devices()

int starpu_omp_get_num_devices (  
  void   
)  

Return the number of the devices.  

Returns  
  
  the number of the devices.  

30.20.5.56  

starpu_omp_get_num_teams()

int starpu_omp_get_num_teams (  
  void   
)  

Return the number of teams in the current teams region.  

Returns  
  
  the number of teams in the current teams region.  

See also  
  
  starpu_omp_get_num_teams

30.20.5.57  

starpu_omp_get_team_num()

int starpu_omp_get_team_num (  
  void   
)  

Return the team number of the calling thread.
30.20 OpenMP Runtime Support

Returns
the team number of the calling thread.

See also
starpu_omp_get_num_teams

30.20.5.58 starpu_omp_is_initial_device()

int starpu_omp_is_initial_device (  
   void  )

Check whether the current device is the initial device or not.

30.20.5.59 starpu_omp_get_max_task_priority()

int starpu_omp_get_max_task_priority (  
   void  )

Return the maximum value that can be specified in the priority clause.

Returns
!0 if called from the host device.
0 otherwise.

See also
starpu_omp_set_default_device
starpu_omp_get_default_device

30.20.5.60 starpu_omp_init_lock()

void starpu_omp_init_lock (  
   starpu_omp_lock_t * lock  )

Initialize an opaque lock object.

See also
starpu_omp_destroy_lock
starpu_omp_set_lock
starpu_omp_unset_lock
starpu_omp_test_lock

30.20.5.61 starpu_omp_destroy_lock()

void starpu_omp_destroy_lock (  
   starpu_omp_lock_t * lock  )

Destroy an opaque lock object.

See also
starpu_omp_init_lock
starpu_omp_set_lock
starpu_omp_unset_lock
starpu_omp_test_lock
30.20.5.62  starpu_omp_set_lock()

void starpu_omp_set_lock (  
    starpu_omp_lock_t * lock  
)

Lock an opaque lock object. If the lock is already locked, the function will block until it succeeds in exclusively acquiring the lock.

See also
    starpu_omp_init_lock
    starpu_omp_destroy_lock
    starpu_omp_unset_lock
    starpu_omp_test_lock

30.20.5.63  starpu_omp_unset_lock()

void starpu_omp_unset_lock (  
    starpu_omp_lock_t * lock  
)

Unlock a previously locked lock object. The behaviour of this function is unspecified if it is called on an unlocked lock object.

See also
    starpu_omp_init_lock
    starpu_omp_destroy_lock
    starpu_omp_set_lock
    starpu_omp_test_lock

30.20.5.64  starpu_omp_test_lock()

int starpu_omp_test_lock (  
    starpu_omp_lock_t * lock  
)

Unblockingly attempt to lock a lock object and return whether it succeeded or not.

Returns
    !0 if the function succeeded in acquiring the lock.
    0 if the lock was already locked.

See also
    starpu_omp_init_lock
    starpu_omp_destroy_lock
    starpu_omp_set_lock
    starpu_omp_unset_lock

30.20.5.65  starpu_omp_init_nest_lock()

void starpu_omp_init_nest_lock (  
    starpu_omp_nest_lock_t * lock  
)

Initialize an opaque lock object supporting nested locking operations.

See also
    starpu_omp_destroy_nest_lock
    starpu_omp_set_nest_lock
    starpu_omp_unset_nest_lock
    starpu_omp_test_nest_lock
30.20 OpenMP Runtime Support

30.20.5.66 starpu_omp_destroy_nest_lock()

```c
void starpu_omp_destroy_nest_lock ( starpu_omp_nest_lock_t * lock )
```

Destroy an opaque lock object supporting nested locking operations.

See also:
- `starpu_omp_init_nest_lock`
- `starpu_omp_set_nest_lock`
- `starpu_omp_unset_nest_lock`
- `starpu_omp_test_nest_lock`

30.20.5.67 starpu_omp_set_nest_lock()

```c
void starpu_omp_set_nest_lock ( starpu_omp_nest_lock_t * lock )
```

Lock an opaque lock object supporting nested locking operations. If the lock is already locked by another task, the function will block until it succeeds in exclusively acquiring the lock. If the lock is already taken by the current task, the function will increase the nested locking level of the lock object.

See also:
- `starpu_omp_init_nest_lock`
- `starpu_omp_destroy_nest_lock`
- `starpu_omp_unset_nest_lock`
- `starpu_omp_test_nest_lock`

30.20.5.68 starpu_omp_unset_nest_lock()

```c
void starpu_omp_unset_nest_lock ( starpu_omp_nest_lock_t * lock )
```

Unlock a previously locked lock object supporting nested locking operations. If the lock has been locked multiple times in nested fashion, the nested locking level is decreased and the lock remains locked. Otherwise, if the lock has only been locked once, it becomes unlocked. The behaviour of this function is unspecified if it is called on an unlocked lock object. The behaviour of this function is unspecified if it is called from a different task than the one that locked the lock object.

See also:
- `starpu_omp_init_nest_lock`
- `starpu_omp_destroy_nest_lock`
- `starpu_omp_set_nest_lock`
- `starpu_omp_test_nest_lock`

30.20.5.69 starpu_omp_test_nest_lock()

```c
int starpu_omp_test_nest_lock ( starpu_omp_nest_lock_t * lock )
```

Unblocking attempt to lock an opaque lock object supporting nested locking operations and returns whether it succeeded or not. If the lock is already locked by another task, the function will return without having acquired the lock. If the lock is already taken by the current task, the function will increase the nested locking level of the lock object.

Returns:
- `-1` if the function succeeded in acquiring the lock.
- `0` if the lock was already locked.
See also

- starpu_omp_init_nest_lock
- starpu_omp_destroy_nest_lock
- starpu_omp_set_nest_lock
- starpu_omp_unset_nest_lock

30.20.5.70  starpu_omp_atomic_fallback_inline_begin()

```c
void starpu_omp_atomic_fallback_inline_begin (  
    void  
)
```
Implement the entry point of a fallback global atomic region. Block until it succeeds in acquiring exclusive access to
the global atomic region.

See also

- starpu_omp_atomic_fallback_inline_end

30.20.5.71  starpu_omp_atomic_fallback_inline_end()

```c
void starpu_omp_atomic_fallback_inline_end (  
    void  
)
```
Implement the exit point of a fallback global atomic region. Release the exclusive access to the global atomic region.

See also

- starpu_omp_atomic_fallback_inline_begin

30.20.5.72  starpu_omp_get_wtime()

```c
double starpu_omp_get_wtime (  
    void  
)
```
Return the elapsed wallclock time in seconds.

Returns

the elapsed wallclock time in seconds.

See also

- starpu_omp_get_wtick

30.20.5.73  starpu_omp_get_wtick()

```c
double starpu_omp_get_wtick (  
    void  
)
```
Return the precision of the time used by starpu_omp_get_wtime().

Returns

the precision of the time used by starpu_omp_get_wtime().

See also

- starpu_omp_get_wtime
30.20.5.74 starpu_omp_vector_annotate()

```c
void starpu_omp_vector_annotate(
    starpu_data_handle_t handle,
    uint32_t slice_base)
```

Enable setting additional vector metadata needed by the OpenMP Runtime Support.

- `handle`: vector data handle.
- `slice_base`: is the base of an array slice, expressed in number of vector elements from the array base.

See also

- `STARPU_VECTOR_GET_SLICE_BASE`

## 30.21 MIC Extensions

### Macros

- `#define STARPU_USE_MIC`
- `#define STARPU_MAXMICDEVS`

### Typedefs

- `typedef void * starpu_mic_func_symbol_t`

### Functions

- `int starpu_mic_register_kernel(starpu_mic_func_symbol_t *symbol, const char *func_name)`
- `starpu_mic_kernel_t starpu_mic_get_kernel(starpu_mic_func_symbol_t symbol)`

## 30.21.1 Detailed Description

## 30.21.2 Macro Definition Documentation

### 30.21.2.1 STARPU_USE_MIC

```c
#define STARPU_USE_MIC
```

Defined when StarPU has been installed with MIC support. It should be used in your code to detect the availability of MIC.

### 30.21.2.2 STARPU_MAXMICDEVS

```c
#define STARPU_MAXMICDEVS
```

Define the maximum number of MIC devices that are supported by StarPU.

## 30.21.3 Typedef Documentation

### 30.21.3.1 starpu_mic_func_symbol_t

```c
typedef void * starpu_mic_func_symbol_t
```

Type for MIC function symbols

## 30.21.4 Function Documentation

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30.21.4.1 starpu_mic_register_kernel()

```c
int starpu_mic_register_kernel (  
    starpu_mic_func_symbol_t ∗ symbol,  
    const char * func_name )
```
Initiate a lookup on each MIC device to find the address of the function named `func_name`, store it in the global array `kernels` and return the index in the array through `symbol`.

30.21.4.2 starpu_mic_get_kernel()

```c
starpu_mic_kernel_t starpu_mic_get_kernel (  
    starpu_mic_func_symbol_t symbol )
```
If successfull, return the pointer to the function defined by `symbol` on the device linked to the called device. This can for instance be used in a `starpu_mic_func_t` implementation.

### 30.22 Miscellaneous Helpers

#### Macros

- `#define STARPU_MIN(a, b)`
- `#define STARPU_MAX(a, b)`
- `#define STARPU_POISON_PTR`

#### Functions

- `char ∗ starpu_getenv (const char ∗str)`
- `static __starpu_inline int starpu_get_env_number (const char ∗str)`
- `static __starpu_inline int starpu_get_env_number_default (const char ∗str, int defval)`
- `static __starpu_inline float starpu_get_env_float_default (const char ∗str, float defval)`
- `void starpu_execute_on_each_worker (void( ∗func)(void ∗), void ∗arg, uint32_t where)`
- `void starpu_execute_on_each_worker_ex (void( ∗func)(void ∗), void ∗arg, uint32_t where, const char ∗name)`
- `void starpu_execute_on_specific_workers (void( ∗func)(void ∗), void ∗arg, unsigned num_workers, unsigned ∗workers, const char ∗name)`
- `double starpu_timing_now (void)`
- `int starpu_data_cpy (starpu_data_handle_t dst_handle, starpu_data_handle_t src_handle, int asynchronous,  
  void( ∗callback_func)(void ∗), void ∗callback_arg)`

#### Variables

- `int _starpu_silent`

### 30.22.1 Detailed Description

### 30.22.2 Macro Definition Documentation

#### STARPU_MIN

```c
#define STARPU_MIN(a, b)
```
Return the min of the two parameters.
30.22 Miscellaneous Helpers

30.22.2 STARPU_MAX

#define STARPU_MAX(a, b)
Return the max of the two parameters.

30.22.3 STARPU_POISON_PTR

#define STARPU_POISON_PTR
Define a value which can be used to mark pointers as invalid values.

30.22.3 Function Documentation

30.22.3.1 starpu_get_env_number()

static __starpu_inline int starpu_get_env_number (const char ∗str) [static]
Return the integer value of the environment variable named str. Return 0 otherwise (the variable does not exist or has a non-integer value).

30.22.3.2 starpu_execute_on_each_worker()

void starpu_execute_on_each_worker (
    void(*) (void *) func,
    void * arg,
    uint32_t where)
Execute the given function func on a subset of workers. When calling this method, the offloaded function func is executed by every StarPU worker that are eligible to execute the function. The argument arg is passed to the offloaded function. The argument where specifies on which types of processing units the function should be executed. Similarly to the field starpu_codelet::where, it is possible to specify that the function should be executed on every CUDA device and every CPU by passing STARPU_CPU|STARPU_CUDA. This function blocks until func has been executed on every appropriate processing units, and thus may not be called from a callback function for instance.

30.22.3.3 starpu_execute_on_each_worker_ex()

void starpu_execute_on_each_worker_ex (void(*) (void *) func,
    void * arg,
    uint32_t where,
    const char * name)
Same as starpu_execute_on_each_worker(), except that the task name is specified in the argument name.

30.22.3.4 starpu_execute_on_specific_workers()

void starpu_execute_on_specific_workers (void(*) (void *) func,
    void * arg,
    unsigned num_workers,
    unsigned * workers,
    const char * name)
Call func(arg) on every worker in the workers array. num_workers indicates the number of workers in this array. This function is synchronous, but the different workers may execute the function in parallel.

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30.22.3.5 starpu_timing_now()

```c
double starpu_timing_now ( void )
```

Return the current date in micro-seconds.

30.22.3.6 starpu_data_cpy()

```c
int starpu_data_cpy ( starpu_data_handle_t dst_handle, starpu_data_handle_t src_handle, int asynchronous, void(*) void *) callback_func, void * callback_arg )
```

Copy the content of src_handle into dst_handle. The parameter asynchronous indicates whether the function should block or not. In the case of an asynchronous call, it is possible to synchronize with the termination of this operation either by the means of implicit dependencies (if enabled) or by calling starpu_task_wait_for_all(). If callback_func is not NULL, this callback function is executed after the handle has been copied, and it is given the pointer callback_arg as argument.

30.23 FxT Support

Data Structures

- struct starpu_fxt_codelet_event
- struct starpu_fxt_options

Macros

- \#define STARPU_FXT_MAX_FILES

Functions

- void starpu_fxt_options_init (struct starpu_fxt_options *options)
- void starpu_fxt_generate_trace (struct starpu_fxt_options *options)
- void starpu_fxt_autostart_profiling (int autostart)
- void starpu_fxt_start_profiling (void)
- void starpu_fxt_stop_profiling (void)
- void starpu_fxt_write_data_trace (char *filename_in)
- void starpu_fxt_trace_user_event (unsigned long code)
- void starpu_fxt_trace_user_event_string (const char *s)

30.23.1 Detailed Description

30.23.2 Data Structure Documentation

30.23.2.1 struct starpu_fxt_codelet_event

Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>char</td>
<td>symbol[256]</td>
</tr>
<tr>
<td>int</td>
<td>workerid</td>
</tr>
<tr>
<td>char</td>
<td>perfmodel_archname[256]</td>
</tr>
<tr>
<td>uint32_t</td>
<td>hash</td>
</tr>
<tr>
<td>size_t</td>
<td>size</td>
</tr>
<tr>
<td>float</td>
<td>time</td>
</tr>
</tbody>
</table>
### 30.23.2.2 struct starpu_fxt_options

**Data Fields**

<table>
<thead>
<tr>
<th>Type</th>
<th>Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>unsigned</td>
<td>per_task_colour</td>
<td></td>
</tr>
<tr>
<td>unsigned</td>
<td>no_events</td>
<td></td>
</tr>
<tr>
<td>unsigned</td>
<td>no_counter</td>
<td></td>
</tr>
<tr>
<td>unsigned</td>
<td>no_bus</td>
<td></td>
</tr>
<tr>
<td>unsigned</td>
<td>no_flops</td>
<td></td>
</tr>
<tr>
<td>unsigned</td>
<td>ninputfiles</td>
<td></td>
</tr>
<tr>
<td>unsigned</td>
<td>no_smooth</td>
<td></td>
</tr>
<tr>
<td>unsigned</td>
<td>no_acquire</td>
<td></td>
</tr>
<tr>
<td>unsigned</td>
<td>memory_states</td>
<td></td>
</tr>
<tr>
<td>unsigned</td>
<td>internal</td>
<td></td>
</tr>
<tr>
<td>unsigned</td>
<td>label_deps</td>
<td></td>
</tr>
<tr>
<td>char[STARPU_FXT_MAX_FILES]</td>
<td>filenames</td>
<td>In case we are going to gather multiple traces (e.g. in the case of MPI processes), we may need to prefix the name of the containers.</td>
</tr>
<tr>
<td>char</td>
<td>out_paje_path</td>
<td></td>
</tr>
<tr>
<td>char</td>
<td>distrib_time_path</td>
<td></td>
</tr>
<tr>
<td>char</td>
<td>activity_path</td>
<td></td>
</tr>
<tr>
<td>char</td>
<td>dag_path</td>
<td></td>
</tr>
<tr>
<td>char</td>
<td>tasks_path</td>
<td></td>
</tr>
<tr>
<td>char</td>
<td>data_path</td>
<td></td>
</tr>
<tr>
<td>char</td>
<td>anim_path</td>
<td></td>
</tr>
<tr>
<td>char</td>
<td>states_path</td>
<td></td>
</tr>
<tr>
<td>char</td>
<td>file_prefix</td>
<td>In case we are going to gather multiple traces (e.g. in the case of MPI processes), we may need to prefix the name of the containers.</td>
</tr>
<tr>
<td>uint64_t</td>
<td>file_offset</td>
<td>In case we are going to gather multiple traces (e.g. in the case of MPI processes), we may need to prefix the name of the containers.</td>
</tr>
<tr>
<td>int</td>
<td>file_rank</td>
<td>In case we are going to gather multiple traces (e.g. in the case of MPI processes), we may need to prefix the name of the containers.</td>
</tr>
<tr>
<td>char[STARPU_NMAXWORKERS][256]</td>
<td>worker_names</td>
<td>Output parameters</td>
</tr>
<tr>
<td>struct</td>
<td>starpu_perfmodel_arch</td>
<td>Output parameters</td>
</tr>
<tr>
<td>struct</td>
<td>starpu_fxt_codelet_event</td>
<td>**             In case we want to dump the list of codelets to an external tool</td>
</tr>
<tr>
<td>long</td>
<td>dumped_codelets_count</td>
<td>In case we want to dump the list of codelets to an external tool</td>
</tr>
</tbody>
</table>

### 30.23.3 Function Documentation

#### 30.23.3.1 starpu_fxt_autostart_profiling()

```c
void starpu_fxt_autostart_profiling (  
    int autostart  )
```
Determine whether profiling should be started by `starpu_init()`, or only when `starpu_fxt_start_profiling()` is called. `autostart` should be 1 to do so, or 0 to prevent it.

### 30.23.3.2 `starpu_fxt_start_profiling()`

```c
void starpu_fxt_start_profiling ()
```

Start recording the trace. The trace is by default started from `starpu_init` call, but can be paused by using `starpu_fxt_stop_profiling()`, in which case `starpu_fxt_start_profiling()` should be called to resume recording events.

### 30.23.3.3 `starpu_fxt_stop_profiling()`

```c
void starpu_fxt_stop_profiling ()
```

Stop recording the trace. The trace is by default stopped when calling `starpu_shutdown()`. `starpu_fxt_stop_profiling()` can however be used to stop it earlier. `starpu_fxt_start_profiling()` can then be called to start recording it again, etc.

### 30.23.3.4 `starpu_fxt_trace_user_event()`

```c
void starpu_fxt_trace_user_event ( unsigned long code )
```

Add an event in the execution trace if FxT is enabled.

### 30.23.3.5 `starpu_fxt_trace_user_event_string()`

```c
void starpu_fxt_trace_user_event_string ( const char * s )
```

Add a string event in the execution trace if FxT is enabled.

### 30.24 FFT Support

Functions

- `void * starpufft_malloc (size_t n)`
- `void starpufft_free (void *p)`
- `starpufft_plan starpufft_plan_dft_1d (int n, int sign, unsigned flags)`
- `starpufft_plan starpufft_plan_dft_2d (int n, int m, int sign, unsigned flags)`
- `struct starpu_task * starpufft_start (starpufft_plan p, void *in, void *out)`
- `struct starpu_task * starpufft_start_handle (starpufft_plan p, starpu_data_handle_t in, starpu_data_handle_t out)`
- `int starpufft_execute (starpufft_plan p, void *in, void *out)`
- `int starpufft_execute_handle (starpufft_plan p, starpu_data_handle_t in, starpu_data_handle_t out)`
- `void starpufft_cleanup (starpufft_plan p)`
- `void starpufft_destroy_plan (starpufft_plan p)`

### 30.24.1 Detailed Description

### 30.24.2 Function Documentation

#### 30.24.2.1 `starpufft_malloc()`

```c
void * starpufft_malloc ( size_t n )
```

Allocate memory for `n` bytes. This is preferred over `malloc()`, since it allocates pinned memory, which allows overlapped transfers.
30.24.2.2 starpufft_free()

```c
void * starpufft_free ( 
    void * p )
```
Release memory previously allocated.

30.24.2.3 starpufft_plan_dft_1d()

```c
struct starpufft_plan * starpufft_plan_dft_1d ( 
    int n, 
    int sign, 
    unsigned flags )
```
Initialize a plan for 1D FFT of size \( n \). \( \text{sign} \) can be STARPUFFT_FORWARD or STARPUFFT_INVERSE. \( \text{flags} \) must be 0.

30.24.2.4 starpufft_plan_dft_2d()

```c
struct starpufft_plan * starpufft_plan_dft_2d ( 
    int n, 
    int m, 
    int sign, 
    unsigned flags )
```
Initialize a plan for 2D FFT of size \((n,m)\). \( \text{sign} \) can be STARPUFFT_FORWARD or STARPUFFT_INVERSE. \( \text{flags} \) must be 0.

30.24.2.5 starpufft_start()

```c
struct starpu_task * starpufft_start ( 
    starpufft_plan p, 
    void * in, 
    void * out )
```
Start an FFT previously planned as \( p \), using \( \text{in} \) and \( \text{out} \) as input and output. This only submits the task and does not wait for it. The application should call `starpufft_cleanup()` to unregister the

30.24.2.6 starpufft_start_handle()

```c
struct starpu_task * starpufft_start_handle ( 
    starpufft_plan p, 
    starpu_data_handle_t in, 
    starpu_data_handle_t out )
```
Start an FFT previously planned as \( p \), using data handles \( \text{in} \) and \( \text{out} \) as input and output (assumed to be vectors of elements of the expected types). This only submits the task and does not wait for it.

30.24.2.7 starpufft_execute()

```c
void starpufft_execute ( 
    starpufft_plan p, 
    void * in, 
    void * out )
```
Execute an FFT previously planned as \( p \), using \( \text{in} \) and \( \text{out} \) as input and output. This submits and waits for the task.

30.24.2.8 starpufft_execute_handle()

```c
void starpufft_execute_handle ( 
    starpufft_plan p, 
    starpu_data_handle_t in, 
    starpu_data_handle_t out )
```
Execute an FFT previously planned as \( p \), using data handles \( \text{in} \) and \( \text{out} \) as input and output (assumed to be vectors of elements of the expected types). This submits and waits for the task.
30.24.2.9 starpufft_cleanup()

void starpufft_cleanup (starpufft_plan p)

Release data for plan p, in the starpufft_start() case.

30.24.2.10 starpufft_destroy_plan()

void starpufft_destroy_plan (starpufft_plan p)

Destroy plan p, i.e. release all CPU (fftw) and GPU (cufft) resources.

30.25 MPI Support

Macros

• #define STARPU_USE_MPI
• #define STARPU_EXECUTE_ON_NODE
• #define STARPU_EXECUTE_ON_DATA
• #define STARPU_NODE_SELECTION_POLICY

Functions

• int starpu_mpi_pre_submit_hook_register (void (*)(struct starpu_task *))
• int starpu_mpi_pre_submit_hook_unregister ()

MPI Master Slave

• #define STARPU_USE_MPI_MASTER_SLAVE

Initialisation

• int starpu_mpi_init_conf (int *argc, char **argv, int initialize_mpi, MPI_Comm comm, struct starpu_conf *conf)
• int starpu_mpi_init_comm (int *argc, char **argv, int initialize_mpi, MPI_Comm comm)
• int starpu_mpi_init (int *argc, char **argv, int initialize_mpi)
• int starpu_mpi_initialize (void)
• int starpu_mpi_initialize_extended (int *rank, int *world_size)
• int starpu_mpi_shutdown (void)
• void starpu_mpi_comm_amounts_retrieve (size_t *comm_amounts)
• int starpu_mpi_comm_size (MPI_Comm comm, int *size)
• int starpu_mpi_comm_rank (MPI_Comm comm, int *rank)
• int starpu_mpi_world_rank (void)
• int starpu_mpi_world_size (void)
• int starpu_mpi_comm_get_attr (MPI_Comm comm, int keyval, void *attribute_val, int *flag)
• int starpu_mpi_get_communication_tag (void)
• void starpu_mpi_set_communication_tag (int tag)
• #define STARPU_MPI_TAG_UB

Communication

• typedef void * starpu_mpi_req
• typedef int64_t starpu_mpi_tag_t
• typedef void (* starpu_mpi_datatype_allocate_func_t) (starpu_data_handle_t, MPI_Datatype *)
• typedef void (* starpu_mpi_datatype_free_func_t) (MPI_Datatype *)
• int starpu_mpi_isend (starpu_data_handle_t data_handle, starpu_mpi_req *req, int dest, starpu_mpi_tag_t data_tag, MPI_Comm comm)
• int starpu_mpi_isend_prio (starpu_data_handle_t data_handle, starpu_mpi_req *req, int dest, starpu_mpi_tag_t data_tag, int prio, MPI_Comm comm)
• int starpu_mpi_irecv (starpu_data_handle_t data_handle, starpu_mpi_req *req, int source, starpu_mpi_tag_t data_tag, MPI_Comm comm)
• int starpu_mpi_send (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag, MPI_Comm comm)
• int starpu_mpi_send_prio (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag, int prio, MPI_Comm comm)
• int starpu_mpi_recv (starpu_data_handle_t data_handle, int source, starpu_mpi_tag_t data_tag, MPI_Comm comm, MPI_Status *status)
• int starpu_mpi_isend_detached (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag, MPI_Comm comm, void(*callback)(void *), void *arg)
• int starpu_mpi_isend_detached_prio (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag, int prio, MPI_Comm comm, void(*callback)(void *), void *arg)
• int starpu_mpi_irecv_detached (starpu_data_handle_t data_handle, int source, starpu_mpi_tag_t data_tag, MPI_Comm comm, void(*callback)(void *), void *arg)
• int starpu_mpi_irecv_detached_sequential_consistency (starpu_data_handle_t data_handle, int source, starpu_mpi_tag_t data_tag, MPI_Comm comm, void(*callback)(void *), void *arg, int sequential_consistency)
• int starpu_mpi_issend (starpu_data_handle_t data_handle, starpu_mpi_req *req, int dest, starpu_mpi_tag_t data_tag, MPI_Comm comm)
• int starpu_mpi_issend_prio (starpu_data_handle_t data_handle, starpu_mpi_req *req, int dest, starpu_mpi_tag_t data_tag, int prio, MPI_Comm comm)
• int starpu_mpi_issend_detached (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag, MPI_Comm comm, void(*callback)(void *), void *arg)
• int starpu_mpi_issend_detached_prio (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag, int prio, MPI_Comm comm, void(*callback)(void *), void *arg)
• int starpu_mpi_wait (starpu_mpi_req *req, MPI_Status *status)
• int starpu_mpi_test (starpu_mpi_req *req, int *flag, MPI_Status *status)
• int starpu_mpi_barrier (MPI_Comm comm)
• int starpu_mpi_wait_for_all (MPI_Comm comm)
• int starpu_mpi_isend_detached_unlock_tag (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag, MPI_Comm comm, starpu_tag_t tag)
• int starpu_mpi_isend_detached_unlock_tag_prio (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag, int prio, MPI_Comm comm, starpu_tag_t tag)
• int starpu_mpi_irecv_detached_unlock_tag (starpu_data_handle_t data_handle, int source, starpu_mpi_tag_t data_tag, MPI_Comm comm, starpu_tag_t tag)
• int starpu_mpi_isend_array_detached_unlock_tag (unsigned array_size, starpu_data_handle_t *data_handle, int *dest, starpu_mpi_tag_t *data_tag, MPI_Comm *comm, starpu_tag_t tag)
• int starpu_mpi_isend_array_detached_unlock_tag_prio (unsigned array_size, starpu_data_handle_t *data_handle, int *dest, starpu_mpi_tag_t *data_tag, int *prio, MPI_Comm *comm, starpu_tag_t tag)
• int starpu_mpi_irecv_array_detached_unlock_tag (unsigned array_size, starpu_data_handle_t *data_handle, int *source, starpu_mpi_tag_t *data_tag, MPI_Comm *comm, starpu_tag_t tag)
• int starpu_mpi_datatype_register (starpu_data_handle_t handle, starpu_mpi_datatype_allocate_func_t allocate_datatype_func, starpu_mpi_datatype_free_func_t free_datatype_func)
• int starpu_mpi_datatype_unregister (starpu_data_handle_t handle)

Communication Cache

• int starpu_mpi_cache_is_enabled ()
• int starpu_mpi_cache_set (int enabled)
• void starpu_mpi_cache_flush (MPI_Comm comm, starpu_data_handle_t data_handle)
• void starpu_mpi_cache_flush_all_data (MPI_Comm comm)
• int starpu_mpi_cached_receive (starpu_data_handle_t data_handle)
• int starpu_mpi_cached_send (starpu_data_handle_t data_handle, int dest)

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MPI Insert Task

- void starpu_mpi_data_register_comm (starpu_data_handle_t data_handle, starpu_mpi_tag_t data_tag, int rank, MPI_Comm comm)
- void starpu_mpi_data_set_tag (starpu_data_handle_t handle, starpu_mpi_tag_t data_tag)
- void starpu_mpi_data_set_rank_comm (starpu_data_handle_t handle, int rank, MPI_Comm comm)
- int starpu_mpi_data_get_rank (starpu_data_handle_t handle)
- starpu_mpi_tag_t starpu_mpi_data_get_tag (starpu_data_handle_t handle)
- int starpu_mpi_task_insert (MPI_Comm comm, struct starpu_codelet *codelet,...)
- int starpu_mpi_insert_task (MPI_Comm comm, struct starpu_codelet *codelet,...)
- struct starpu_task *starpu_mpi_task_build (MPI_Comm comm, struct starpu_codelet *codelet,...)
- int starpu_mpi_task_post_build (MPI_Comm comm, struct starpu_codelet *codelet,...)
- void starpu_mpi_get_data_on_node (MPI_Comm comm, starpu_data_handle_t data_handle, int node)
- void starpu_mpi_get_data_on_node_detached (MPI_Comm comm, starpu_data_handle_t data_handle, int node, void(*callback)(void *), void *arg)
- void starpu_mpi_get_data_on_all_nodes_detached (MPI_Comm comm, starpu_data_handle_t data_handle)
- void starpu_mpi_data_migrate (MPI_Comm comm, starpu_data_handle_t handle, int new_rank)
- #define STARPU_MPI_PER_NODE
- #define starpu_mpi_data_register(data_handle, data_tag, rank)
- #define starpu_data_set_tag
- #define starpu_mpi_data_set_rank(handle, rank)
- #define starpu_data_get_rank
- #define starpu_data_get_tag

Node Selection Policy

- typedef int(* starpu_mpi_select_node_policy_func_t) (int me, int nb_nodes, struct starpu_data_descr *descr, int nb_data)
- int starpu_mpi_node_selection_register_policy (starpu_mpi_select_node_policy_func_t policy_func)
- int starpu_mpi_node_selection_unregister_policy (int policy)
- int starpu_mpi_node_selection_get_current_policy ()
- int starpu_mpi_node_selection_set_current_policy (int policy)
- #define STARPU_MPI_NODE_SELECTION_CURRENT_POLICY
- #define STARPU_MPI_NODE_SELECTION_MOST_R_DATA

Collective Operations

- void starpu_mpi_redux_data (MPI_Comm comm, starpu_data_handle_t data_handle)
- void starpu_mpi_redux_data_prio (MPI_Comm comm, starpu_data_handle_t data_handle, int prio)
- void starpu_mpi_scatter_detached (starpu_data_handle_t *data_handles, int count, int root, MPI_Comm comm, void(*scallback)(void *), void *sarg, void(*rcallback)(void *), void *rarg)
- void starpu_mpi_gather_detached (starpu_data_handle_t *data_handles, int count, int root, MPI_Comm comm, void(*scallback)(void *), void *sarg, void(*rcallback)(void *), void *rarg)

30.25.1 Detailed Description

30.25.2 Macro Definition Documentation

30.25.2.1 STARPU_USE_MPI

#define STARPU_USE_MPI
Defined when StarPU has been installed with MPI support. It should be used in your code to detect the availability of MPI.
30.25.2.2 STARPU_USE_MPI_MASTER_SLAVE

#define STARPU_USE_MPI_MASTER_SLAVE
Defined when StarPU has been installed with MPI Master Slave support. It should be used in your code to detect the availability of MPI Master Slave.

30.25.2.3 STARPU_EXECUTE_ON_NODE

#define STARPU_EXECUTE_ON_NODE
Used when calling starpu_mpi_task_insert(), must be followed by a integer value which specified the node on which to execute the codelet.

30.25.2.4 STARPU_EXECUTE_ON_DATA

#define STARPU_EXECUTE_ON_DATA
Used when calling starpu_mpi_task_insert(), must be followed by a data handle to specify that the node owning the given data will execute the codelet.

30.25.2.5 STARPU_NODE_SELECTION_POLICY

#define STARPU_NODE_SELECTION_POLICY
Used when calling starpu_mpi_task_insert(), must be followed by a identifier to a node selection policy. This is needed when several nodes own data in STARPU_W mode.

30.25.2.6 STARPU_MPI_TAG_UB

#define STARPU_MPI_TAG_UB
When given to the function starpu_mpi_comm_get_attr(), retrieve the value for the upper bound for tag value.

30.25.2.7 STARPU_MPI_PER_NODE

#define STARPU_MPI_PER_NODE
Can be used as rank when calling starpu_mpi_data_register() and alike, to specify that the data is per-node: each node will have its own value. Tasks writing to such data will be replicated on all nodes (and all parameters then have to be per-node). Tasks not writing to such data will just take the node-local value without any MPI communication.

30.25.2.8 starpu_mpi_data_register

#define starpu_mpi_data_register(
    data_handle,  
data_tag,  
    rank )
Register to MPI a StarPU data handle with the given tag, rank and the MPI communicator MPI_COMM_WORLD. It also automatically clears the MPI communication cache when unregistering the data.

30.25.2.9 starpu_data_set_tag

#define starpu_data_set_tag
Symbol kept for backward compatibility. Call function starpu_mpi_data_set_tag()

30.25.2.10 starpu_mpi_data_set_rank

#define starpu_mpi_data_set_rank(
    handle,  
    rank )
Register to MPI a StarPU data handle with the given rank and the MPI communicator MPI_COMM_WORLD. No tag will be defined. It also automatically clears the MPI communication cache when unregistering the data.
30.25.2.11 starpu_data_set_rank

#define starpu_data_set_rank
Symbol kept for backward compatibility. Call function starpu_mpi_data_set_rank()

30.25.2.12 starpu_data_get_rank

#define starpu_data_get_rank
Symbol kept for backward compatibility. Call function starpu_mpi_data_get_rank()

30.25.2.13 starpu_data_get_tag

#define starpu_data_get_tag
Symbol kept for backward compatibility. Call function starpu_mpi_data_get_tag()

30.25.3 Typedef Documentation

30.25.3.1 starpu_mpi_req

typedef void* starpu_mpi_req
Opaque type for communication request

30.25.3.2 starpu_mpi_tag_t

typedef int64_t starpu_mpi_tag_t
Define the type which can be used to set communication tag when exchanging data.

30.25.4 Function Documentation

30.25.4.1 starpu_mpi_init_conf()

int starpu_mpi_init_conf (  
    int * argc,
    char *** argv,
    int initialize_mpi,
    MPI_Comm comm,
    struct starpu_conf * conf )
Initialize the StarPU library with the given conf, and initialize the StarPU-MPI library with the given MPI communicator comm. initialize_mpi indicates if MPI should be initialized or not by StarPU. StarPU-MPI takes the opportunity to modify conf to either reserve a core for its MPI thread (by default), or execute MPI calls on the CPU driver 0 between tasks.

30.25.4.2 starpu_mpi_init_comm()

int starpu_mpi_init_comm (  
    int * argc,
    char *** argv,
    int initialize_mpi,
    MPI_Comm comm )
Same as starpu_mpi_init_conf(), except that this does not initialize the StarPU library. The caller thus has to call starpu_init() before this.
30.25.4.3 starpu_mpi_init()

```c
int starpu_mpi_init (  
    int * argc, 
    char *** argv, 
    int initialize_mpi
)
```

Call `starpu_mpi_init_comm()` with the MPI communicator `MPI_COMM_WORLD`.

30.25.4.4 starpu_mpi_initialize()

```c
int starpu_mpi_initialize (  
    void
)
```

**Deprecated** This function has been made deprecated. One should use instead the function `starpu_mpi_init()`. This function does not call `MPI_Init()`, it should be called beforehand.

30.25.4.5 starpu_mpi_initialize_extended()

```c
int starpu_mpi_initialize_extended (  
    int * rank,  
    int * world_size
)
```

**Deprecated** This function has been made deprecated. One should use instead the function `starpu_mpi_init()`. `MPI` will be initialized by starpumpi by calling `MPI_Init_Thread(argc, argv, MPI_THREAD_SERIALIZED, ...)`.  

30.25.4.6 starpu_mpi_shutdown()

```c
int starpu_mpi_shutdown (  
    void
)
```

Clean the starpumpi library. This must be called after calling any `starpu_mpi` functions and before the call to `starpu_shutdown()`, if any. `MPI_Finalize()` will be called if StarPU-MPI has been initialized by `starpu_mpi_init()`.

30.25.4.7 starpu_mpi_comm_amounts_retrieve()

```c
void starpu_mpi_comm_amounts_retrieve (  
    size_t * comm_amounts
)
```

Retrieve the current amount of communications from the current node in the array `comm_amounts` which must have a size greater or equal to the world size. Communications statistics must be enabled (see `STARPU_COMM_M_STATS`).

30.25.4.8 starpu_mpi_comm_size()

```c
int starpu_mpi_comm_size (  
    MPI_Comm comm,  
    int * size
)
```

Return in `size` the size of the communicator `comm`.

30.25.4.9 starpu_mpi_comm_rank()

```c
int starpu_mpi_comm_rank (  
    MPI_Comm comm,  
    int * rank
)
```

Return in `rank` the rank of the calling process in the communicator `comm`.

---

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30.25.10 starpu_mpi_world_rank()

int starpu_mpi_world_rank (void)

Return the rank of the calling process in the communicator MPI_COMM_WORLD

30.25.11 starpu_mpi_world_size()

int starpu_mpi_world_size (void)

Return the size of the communicator MPI_COMM_WORLD

30.25.12 starpu_mpi_comm_get_attr()

int starpu_mpi_comm_get_attr (MPI_Comm comm, int keyval, void * attribute_val, int * flag)

Retrieve an attribute value by key, similarly to the MPI function MPI_comm_get_attr(), except that the value is a pointer to int64_t instead of int. If an attribute is attached on comm to keyval, then the call returns flag equal to 1, and the attribute value in attribute_val. Otherwise, flag is set to 0.

30.25.13 starpu_mpi_isend()

int starpu_mpi_isend (starpu_data_handle_t data_handle, starpu_mpi_req * req, int dest, starpu_mpi_tag_t data_tag, MPI_Comm comm)

Post a standard-mode, non blocking send of data_handle to the node dest using the message tag data_tag within the communicator comm. After the call, the pointer to the request req can be used to test or to wait for the completion of the communication.

30.25.14 starpu_mpi_isend_prio()

int starpu_mpi_isend_prio (starpu_data_handle_t data_handle, starpu_mpi_req * req, int dest, starpu_mpi_tag_t data_tag, int prio, MPI_Comm comm)

Similar to starpu_mpi_isend(), but take a priority prio.

30.25.15 starpu_mpi_irecv()

int starpu_mpi_irecv (starpu_data_handle_t data_handle, starpu_mpi_req * req, int source, starpu_mpi_tag_t data_tag, MPI_Comm comm)

Post a nonblocking receive in data_handle from the node source using the message tag data_tag within the communicator comm. After the call, the pointer to the request req can be used to test or to wait for the completion of the communication.
30.25.4.16  starpu_mpi_send()

int starpu_mpi_send (     
  starpu_data_handle_t data_handle,  
  int dest,  
  starpu_mpi_tag_t data_tag,  
  MPI_Comm comm )
Perform a standard-mode, blocking send of data_handle to the node dest using the message tag data_tag within the communicator comm.

30.25.4.17  starpu_mpi_send_prio()

int starpu_mpi_send_prio (     
  starpu_data_handle_t data_handle,  
  int dest,  
  starpu_mpi_tag_t data_tag,  
  int prio,  
  MPI_Comm comm )
Similar to starpu_mpi_send(), but take a priority prio.

30.25.4.18  starpu_mpi_recv()

int starpu_mpi_recv (     
  starpu_data_handle_t data_handle,  
  int source,  
  starpu_mpi_tag_t data_tag,  
  MPI_Comm comm,  
  MPI_Status * status )
Perform a standard-mode, blocking receive in data_handle from the node source using the message tag data_tag within the communicator comm.

30.25.4.19  starpu_mpi_isend_detached()

int starpu_mpi_isend_detached (     
  starpu_data_handle_t data_handle,  
  int dest,  
  starpu_mpi_tag_t data_tag,  
  MPI_Comm comm,  
  void(*)(void *) callback,  
  void * arg )
Post a standard-mode, non blocking send of data_handle to the node dest using the message tag data_tag within the communicator comm. On completion, the callback function is called with the argument arg. Similarly to the pthread detached functionality, when a detached communication completes, its resources are automatically released back to the system, there is no need to test or to wait for the completion of the request.

30.25.4.20  starpu_mpi_isend_detached_prio()

int starpu_mpi_isend_detached_prio (     
  starpu_data_handle_t data_handle,  
  int dest,  
  starpu_mpi_tag_t data_tag,  
  int prio,  
  MPI_Comm comm,  
  void(*)(void *) callback,  
  void * arg )
Similar to starpu_mpi_isend_detached, but take a priority prio.
30.25.4.21 starpu_mpi_irecv_detached()

```c
int starpu_mpi_irecv_detached(
    starpu_data_handle_t data_handle,
    int source,
    starpu_mpi_tag_t data_tag,
    MPI_Comm comm,
    void(*) (void *) callback,
    void * arg)
```

Post a nonblocking receive in `data_handle` from the node `source` using the message tag `data_tag` within the communicator `comm`. On completion, the `callback` function is called with the argument `arg`. Similarly to the pthread detached functionality, when a detached communication completes, its resources are automatically released back to the system, there is no need to test or to wait for the completion of the request.

30.25.4.22 starpu_mpi_irecv_detached_sequential_consistency()

```c
int starpu_mpi_irecv_detached_sequential_consistency(
    starpu_data_handle_t data_handle,
    int source,
    starpu_mpi_tag_t data_tag,
    MPI_Comm comm,
    void(*) (void *) callback,
    void * arg,
    int sequential_consistency)
```

Post a nonblocking receive in `data_handle` from the node `source` using the message tag `data_tag` within the communicator `comm`. On completion, the `callback` function is called with the argument `arg`. The parameter `sequential_consistency` allows to enable or disable the sequential consistency for `data_handle` (sequential consistency will be enabled or disabled based on the value of the parameter `sequential_consistency` and the value of the sequential consistency defined for `data_handle`). Similarly to the pthread detached functionality, when a detached communication completes, its resources are automatically released back to the system, there is no need to test or to wait for the completion of the request.

30.25.4.23 starpu_mpi_issend()

```c
int starpu_mpi_issend(
    starpu_data_handle_t data_handle,
    starpu_mpi_req * req,
    int dest,
    starpu_mpi_tag_t data_tag,
    MPI_Comm comm)
```

Perform a synchronous-mode, non-blocking send of `data_handle` to the node `dest` using the message tag `data_tag` within the communicator `comm`.

30.25.4.24 starpu_mpi_issend_prio()

```c
int starpu_mpi_issend_prio(
    starpu_data_handle_t data_handle,
    starpu_mpi_req * req,
    int dest,
    starpu_mpi_tag_t data_tag,
    int prio,
    MPI_Comm comm)
```

Similar to `starpu_mpi_issend()`, but take a priority `prio`.

30.25.4.25 starpu_mpi_issend_detached()

```c
int starpu_mpi_issend_detached(
    starpu_data_handle_t data_handle,
    int dest,
```
Perform a synchronous-mode, non-blocking send of `data_handle` to the node `dest` using the message tag `data_tag` within the communicator `comm`. On completion, the `callback` function is called with the argument `arg`. Similarly to the pthread detached functionality, when a detached communication completes, its resources are automatically released back to the system, there is no need to test or to wait for the completion of the request.

30.25.4.26 `starpu_mpi_isend_detached_prio()`

```c
int starpu_mpi_isend_detached_prio (  
    starpu_data_handle_t data_handle,  
    int dest,  
    starpu_mpi_tag_t data_tag,  
    int prio,  
    MPI_Comm comm,  
    void(*)(void *) callback,  
    void * arg )
```

Similar to `starpu_mpi_isend_detached()`, but take a priority `prio`.

30.25.4.27 `starpu_mpi_wait()`

```c
int starpu_mpi_wait (  
    starpu_mpi_req * req,  
    MPI_Status * status )
```

Return when the operation identified by request `req` is complete.

30.25.4.28 `starpu_mpi_test()`

```c
int starpu_mpi_test (  
    starpu_mpi_req * req,  
    int * flag,  
    MPI_Status * status )
```

If the operation identified by `req` is complete, set `flag` to 1. The `status` object is set to contain information on the completed operation.

30.25.4.29 `starpu_mpi_barrier()`

```c
int starpu_mpi_barrier (  
    MPI_Comm comm )
```

Block the caller until all group members of the communicator `comm` have called it.

30.25.4.30 `starpu_mpi_wait_for_all()`

```c
int starpu_mpi_wait_for_all (  
    MPI_Comm comm )
```

Wait until all StarPU tasks and communications for the given communicator are completed.

30.25.4.31 `starpu_mpi_isend_detached_unlock_tag()`

```c
int starpu_mpi_isend_detached_unlock_tag (  
    starpu_data_handle_t data_handle,  
    int dest,  
    starpu_mpi_tag_t data_tag,  
    MPI_Comm comm,  
    starpu_tag_t tag )
```

Post a standard-mode, non blocking send of `data_handle` to the node `dest` using the message tag `data_tag` within the communicator `comm`. On completion, `tag` is unlocked.
30.25.4.32 starpu_mpi_isend_detached_unlock_tag_prio()

```c
int starpu_mpi_isend_detached_unlock_tag_prio(
    starpu_data_handle_t data_handle,
    int dest,
    starpu_mpi_tag_t data_tag,
    int prio,
    MPI_Comm comm,
    starpu_tag_t tag)
```

Similar to `starpu_mpi_isend_detached_unlock_tag()`, but take a priority `prio`.

30.25.4.33 starpu_mpi_irecv_detached_unlock_tag()

```c
int starpu_mpi_irecv_detached_unlock_tag(
    starpu_data_handle_t data_handle,
    int source,
    starpu_mpi_tag_t data_tag,
    MPI_Comm comm,
    starpu_tag_t tag)
```

Post a nonblocking receive in `data_handle` from the node `source` using the message tag `data_tag` within the communicator `comm`. On completion, `tag` is unlocked.

30.25.4.34 starpu_mpi_isend_array_detached_unlock_tag()

```c
int starpu_mpi_isend_array_detached_unlock_tag(
    unsigned array_size,
    starpu_data_handle_t *data_handle,
    int *dest,
    starpu_mpi_tag_t *data_tag,
    MPI_Comm *comm,
    starpu_tag_t tag)
```

Post `array_size` standard-mode, non blocking send. Each post sends the n-th data of the array `data_handle` to the n-th node of the array `dest` using the n-th message tag of the array `data_tag` within the n-th communicator of the array `comm`. On completion of all the requests, `tag` is unlocked.

30.25.4.35 starpu_mpi_isend_array_detached_unlock_tag_prio()

```c
int starpu_mpi_isend_array_detached_unlock_tag_prio(
    unsigned array_size,
    starpu_data_handle_t *data_handle,
    int *dest,
    starpu_mpi_tag_t *data_tag,
    int *prio,
    MPI_Comm *comm,
    starpu_tag_t tag)
```

Similar to `starpu_mpi_isend_array_detached_unlock_tag()`, but take a priority `prio`.

30.25.4.36 starpu_mpi_irecv_array_detached_unlock_tag()

```c
int starpu_mpi_irecv_array_detached_unlock_tag(
    unsigned array_size,
    starpu_data_handle_t *data_handle,
    int *source,
    starpu_mpi_tag_t *data_tag,
    MPI_Comm *comm,
    starpu_tag_t tag)
```

Post `array_size` nonblocking receive. Each post receives in the n-th data of the array `data_handle` from the n-th node of the array `source` using the n-th message tag of the array `data_tag` within the n-th communicator of the array `comm`. On completion of all the requests, `tag` is unlocked.
30.25.4.37  starpu_mpi_datatype_register()

int starpu_mpi_datatype_register (  
    starpu_data_handle_t handle,  
    starpu_mpi_datatype_allocate_func_t allocate_datatype_func,  
    starpu_mpi_datatype_free_func_t free_datatype_func )

Register functions to create and free a MPI datatype for the given handle. It is important that the function is called before any communication can take place for a data with the given handle. See Exchanging User Defined Data Interface for an example.

30.25.4.38  starpu_mpi_datatype_unregister()

int starpu_mpi_datatype_unregister (  
    starpu_data_handle_t handle )

Unregister the MPI datatype functions stored for the interface of the given handle.

30.25.4.39  starpu_mpi_cache_is_enabled()

int starpu_mpi_cache_is_enabled ( )

Return 1 if the communication cache is enabled, 0 otherwise.

30.25.4.40  starpu_mpi_cache_set()

int starpu_mpi_cache_set (  
    int enabled )

If enabled is 1, enable the communication cache. Otherwise, clean the cache if it was enabled and disable it.

30.25.4.41  starpu_mpi_cache_flush()

void starpu_mpi_cache_flush (  
    MPI_Comm comm,  
    starpu_data_handle_t data_handle )

Clear the send and receive communication cache for the data data_handle and invalidate the value. The function has to be called at the same point of task graph submission by all the MPI nodes on which the handle was registered. The function does nothing if the cache mechanism is disabled (see STARPU_MPI_CACHE).

30.25.4.42  starpu_mpi_cache_flush_all_data()

void starpu_mpi_cache_flush_all_data (  
    MPI_Comm comm )

Clear the send and receive communication cache for all data and invalidate their values. The function has to be called at the same point of task graph submission by all the MPI nodes. The function does nothing if the cache mechanism is disabled (see STARPU_MPI_CACHE).

30.25.4.43  starpu_mpi_cached_receive()

int starpu_mpi_cached_receive (  
    starpu_data_handle_t data_handle )

Test whether data_handle is cached for reception, i.e. the value was previously received from the owner node, and not flushed since then.

30.25.4.44  starpu_mpiCached_send()

int starpu_mpiCached_send (  
    starpu_data_handle_t data_handle,  
    int dest )

Test whether data_handle is cached for emission to node dest, i.e. the value was previously sent to dest, and not flushed since then.
30.25.45  starpu_mpi_data_register_comm()

```c
void starpu_mpi_data_register_comm (  
    starpu_data_handle_t data_handle,  
    starpu_mpi_tag_t data_tag,  
    int rank,  
    MPI_Comm comm  
)  
```

Register to MPI a StarPU data handle with the given tag, rank and MPI communicator. It also automatically clears the MPI communication cache when unregistering the data.

30.25.46  starpu_mpi_data_set_tag()

```c
void starpu_mpi_data_set_tag (  
    starpu_data_handle_t handle,  
    starpu_mpi_tag_t data_tag  
)  
```

Register to MPI a StarPU data handle with the given tag. No rank will be defined. It also automatically clears the MPI communication cache when unregistering the data.

30.25.47  starpu_mpi_data_set_rank_comm()

```c
void starpu_mpi_data_set_rank_comm (  
    starpu_data_handle_t handle,  
    int rank,  
    MPI_Comm comm  
)  
```

Register to MPI a StarPU data handle with the given rank and given communicator. No tag will be defined. It also automatically clears the MPI communication cache when unregistering the data.

30.25.48  starpu_mpi_data_get_rank()

```c
int starpu_mpi_data_get_rank (  
    starpu_data_handle_t handle  
)  
```

Return the rank of the given data.

30.25.49  starpu_mpi_data_get_tag()

```c
starpu_mpi_tag_t starpu_mpi_data_get_tag (  
    starpu_data_handle_t handle  
)  
```

Return the tag of the given data.

30.25.50  starpu_mpi_task_insert()

```c
int starpu_mpi_task_insert (  
    MPI_Comm comm,  
    struct starpu_codelet ∗ codelet,  
    ...  
)  
```

Create and submit a task corresponding to codelet with the following arguments. The argument list must be zero-terminated. The arguments following the codelet are the same types as for the function starpu_task_insert(). Access modes for data can also be set with STARPU_SSEND to specify the data has to be sent using a synchronous and non-blocking mode (see starpu_mpi_issend()). The extra argument STARPU_EXECUTE_ON_NODE followed by an integer allows to specify the MPI node to execute the codelet. It is also possible to specify that the node owning a specific data will execute the codelet, by using STARPU_EXECUTE_ON_DATA followed by a data handle. The internal algorithm is as follows:

1. Find out which MPI node is going to execute the codelet.
   - If there is only one node owning data in STARPU_W mode, it will be selected;
   - If there is several nodes owning data in STARPU_W mode, a node will be selected according to a given node selection policy (see STARPU_NODE_SELECTION_POLICY or starpu_mpi_node_selection←set_current_policy());
   - The argument STARPU_EXECUTE_ON_NODE followed by an integer can be used to specify the node;
• The argument `STARPU_EXECUTE_ON_DATA` followed by a data handle can be used to specify that
the node owning the given data will execute the codelet.

2. Send and receive data as requested. Nodes owning data which need to be read by the task are sending them
to the MPI node which will execute it. The latter receives them.

3. Execute the codelet. This is done by the MPI node selected in the 1st step of the algorithm.

4. If several MPI nodes own data to be written to, send written data back to their owners.

The algorithm also includes a communication cache mechanism that allows not to send data twice to the same MPI
node, unless the data has been modified. The cache can be disabled (see `STARPU_MPI_CACHE`).

### 30.25.4.51 starpu_mpi_insert_task()

```c
int starpu_mpi_insert_task (
    MPI_Comm comm,
    struct starpu_codelet * codelet,
    ...
)
```

Call `starpu_mpi_task_insert()`. Symbol kept for backward compatibility.

### 30.25.4.52 starpu_mpi_task_build()

```c
struct starpu_task* starpu_mpi_task_build (
    MPI_Comm comm,
    struct starpu_codelet * codelet,
    ...
)
```

Create a task corresponding to `codelet` with the following given arguments. The argument list must be zero-
terminated. The function performs the first two steps of the function `starpu_mpi_task_insert()`, i.e. submitting
the MPI communications needed before the execution of the task, and the creation of the task on one node. Only the
MPI node selected in the first step of the algorithm will return a valid task structure which can then be submitted,
others will return `NULL`. The function `starpu_mpi_task_post_build()` MUST be called after that on all nodes, and
after the submission of the task on the node which creates it, with the SAME list of arguments.

### 30.25.4.53 starpu_mpi_task_post_build()

```c
int starpu_mpi_task_post_build (
    MPI_Comm comm,
    struct starpu_codelet * codelet,
    ...
)
```

MUST be called after a call to `starpu_mpi_task_build()`, with the SAME list of arguments. Perform the fourth – last
– step of the algorithm described in `starpu_mpi_task_insert()`.

### 30.25.4.54 starpu_mpi_get_data_on_node()

```c
void starpu_mpi_get_data_on_node (
    MPI_Comm comm,
    starpu_data_handle_t data_handle,
    int node
)
```

Transfer data `data_handle` to MPI node `node`, sending it from its owner if needed. At least the target node and
the owner have to call the function.

### 30.25.4.55 starpu_mpi_get_data_on_node_detached()

```c
void starpu_mpi_get_data_on_node_detached (
    MPI_Comm comm,
    starpu_data_handle_t data_handle,
    int node,
    void(*)(void *) callback,
    void * arg
)
```

---

Generated by Doxygen
Transfer data `data_handle` to MPI node `node`, sending it from its owner if needed. At least the target node and the owner have to call the function. On reception, the callback function is called with the argument `arg`.

30.25.4.56 starpu_mpi_get_data_on_all_nodes_detached()

```c
void starpu_mpi_get_data_on_all_nodes_detached ((MPI_Comm comm, starpu_data_handle_t data_handle)
```

Transfer data `data_handle` to all MPI nodes, sending it from its owner if needed. All nodes have to call the function.

30.25.4.57 starpu_mpi_data_migrate()

```c
void starpu_mpi_data_migrate (MPI_Comm comm, starpu_data_handle_t handle, int new_rank)
```

Submit migration of the data onto the `new_rank` MPI node. This means both submitting the transfer of the data to node `new_rank` if it hasn’t been submitted already, and setting the home node of the data to the new node. Further data transfers submitted by `starpu_mpi_task_insert()` will be done from that new node. This function thus needs to be called on all nodes which have registered the data at the same point of tasks submissions. This also flushes the cache for this data to avoid incoherencies.

30.25.4.58 starpu_mpi_node_selection_register_policy()

```c
int starpu_mpi_node_selection_register_policy (starpu_mpi_select_node_policy_func_t policy_func)
```

Register a new policy which can then be used when there is several nodes owning data in STARPU_W mode. Here an example of function defining a node selection policy. The codelet will be executed on the node owning the first data with a size bigger than 1M, or on the node 0 if no data fits the given size.

```c
int my_node_selection_policy(int me, int nb_nodes, struct starpu_data_descr *descr, int nb_data)
{
    // me is the current MPI rank
    // nb_nodes is the number of MPI nodes
    // descr is the description of the data specified when calling starpu_mpi_task_insert
    // nb_data is the number of data in descr
    int i;
    for(i= 0 ; i<nb_data ; i++)
    {
        starpu_data_handle_t data = descr[i].handle;
        enum starpu_data_access_mode mode = descr[i].mode;
        if (mode & STARPU_R)
        {
            int rank = starpu_data_get_rank(data);
            size_t size = starpu_data_get_size(data);
            if (size > 1024*1024) return rank;
        }
    }
    return 0;
}
```

30.25.4.59 starpu_mpi_node_selection_unregister_policy()

```c
int starpu_mpi_node_selection_unregister_policy (int policy)
```

Unregister a previously registered policy.

30.25.4.60 starpu_mpi_node_selection_get_current_policy()

```c
int starpu_mpi_node_selection_get_current_policy ()
```

Return the current policy used to select the node which will execute the codelet.
30.25.4.61 starpu_mpi_node_selection_set_current_policy()

int starpu_mpi_node_selection_set_current_policy (  
    int policy  )

Set the current policy used to select the node which will execute the codelet. The policy ::STARPU_MPI_NODE_SELECTION_MOST_R_DATA selects the node having the most data in STARPU_R mode so as to minimize the amount of data to be transferred.

30.25.4.62 starpu_mpi_redux_data()

void starpu_mpi_redux_data (  
    MPI_Comm comm,  
    starpu_data_handle_t data_handle )

Perform a reduction on the given data handle. All nodes send the data to its owner node which will perform a reduction.

30.25.4.63 starpu_mpi_redux_data_prio()

void starpu_mpi_redux_data_prio (  
    MPI_Comm comm,  
    starpu_data_handle_t data_handle,  
    int prio  )

Similar to starpu_mpi_redux_data, but take a priority prio.

30.25.4.64 starpu_mpi_scatter_detached()

int starpu_mpi_scatter_detached (  
    starpu_data_handle_t * data_handles,  
    int count,  
    int root,  
    MPI_Comm comm,  
    void(*)(void *) scallback,  
    void * sarg,  
    void(*)(void *) rcallback,  
    void * rarg  )

Scatter data among processes of the communicator based on the ownership of the data. For each data of the array data_handles, the process root sends the data to the process owning this data. Processes receiving data must have valid data handles to receive them. On completion of the collective communication, the scallback function is called with the argument sarg on the process root, the rcallback function is called with the argument rarg on any other process.

30.25.4.65 starpu_mpi_gather_detached()

int starpu_mpi_gather_detached (  
    starpu_data_handle_t * data_handles,  
    int count,  
    int root,  
    MPI_Comm comm,  
    void(*)(void *) scallback,  
    void * sarg,  
    void(*)(void *) rcallback,  
    void * rarg  )

Gather data from the different processes of the communicator onto the process root. Each process owning data handle in the array data_handles will send them to the process root. The process root must have valid data handles to receive the data. On completion of the collective communication, the rcallback function is called with the argument rarg on the process root, the scallback function is called with the argument sarg on any other process.
30.26 Task Bundles

Typedefs

- typedef struct _starpu_task_bundle ∗ starpu_task_bundle_t

Functions

- void starpu_task_bundle_create (starpu_task_bundle_t ∗bundle)
- int starpu_task_bundle_insert (starpu_task_bundle_t bundle, struct starpu_task ∗task)
- int starpu_task_bundle_remove (starpu_task_bundle_t bundle, struct starpu_task ∗task)
- void starpu_task_bundle_close (starpu_task_bundle_t bundle)
- double starpu_task_bundle_expected_length (starpu_task_bundle_t bundle, struct starpu_perfmodel_arch ∗arch, unsigned nimpl)
- double starpu_task_bundle_expected_data_transfer_time (starpu_task_bundle_t bundle, unsigned memory_node)
- double starpu_task_bundle_expected_energy (starpu_task_bundle_t bundle, struct starpu_perfmodel_arch ∗arch, unsigned nimpl)

30.26.1 Detailed Description

30.26.2 Typedef Documentation

30.26.2.1 starpu_task_bundle_t

typedef struct _starpu_task_bundle* starpu_task_bundle_t
Opaque structure describing a list of tasks that should be scheduled on the same worker whenever it’s possible. It must be considered as a hint given to the scheduler as there is no guarantee that they will be executed on the same worker.

30.26.3 Function Documentation

30.26.3.1 starpu_task_bundle_create()

void starpu_task_bundle_create (  
    starpu_task_bundle_t * bundle )
Factory function creating and initializing bundle, when the call returns, memory needed is allocated and bundle is ready to use.

30.26.3.2 starpu_task_bundle_insert()

int starpu_task_bundle_insert (  
    starpu_task_bundle_t bundle,  
    struct starpu_task * task )
Insert task in bundle. Until task is removed from bundle its expected length and data transfer time will be considered along those of the other tasks of bundle. This function must not be called if bundle is already closed and/or task is already submitted. On success, it returns 0. There are two cases of error: if bundle is already closed it returns -EPERM, if task was already submitted it returns -EINVAL.

30.26.3.3 starpu_task_bundle_remove()

int starpu_task_bundle_remove (  
    starpu_task_bundle_t bundle,  
    struct starpu_task * task )
Remove task from bundle. Of course task must have been previously inserted in bundle. This function must not be called if bundle is already closed and/or task is already submitted. Doing so would result in undefined behaviour. On success, it returns 0. If bundle is already closed it returns -ENOENT.

30.26.3.4 starpu_task_bundle_close()

void starpu_task_bundle_close (  
starpu_task_bundle_t bundle  )

Inform the runtime that the user will not modify bundle anymore, it means no more inserting or removing task. Thus the runtime can destroy it when possible.

30.26.3.5 starpu_task_bundle_expected_length()

double starpu_task_bundle_expected_length (  
starpu_task_bundle_t bundle,  
struct starpu_perfmodel_arch * arch,  
unsigned nimpl  )

Return the expected duration of bundle in micro-seconds.

30.26.3.6 starpu_task_bundle_expected_data_transfer_time()

double starpu_task_bundle_expected_data_transfer_time (  
starpu_task_bundle_t bundle,  
unsigned memory_node  )

Return the time (in micro-seconds) expected to transfer all data used within bundle.

30.26.3.7 starpu_task_bundle_expected_energy()

double starpu_task_bundle_expected_energy (  
starpu_task_bundle_t bundle,  
struct starpu_perfmodel_arch * arch,  
unsigned nimpl  )

Return the expected energy consumption of bundle in J.

30.27 Task Lists

Data Structures

- struct starpu_task_list

Functions

- void starpu_task_list_init (struct starpu_task_list *list)
- void starpu_task_list_push_front (struct starpu_task_list *list, struct starpu_task *task)
- void starpu_task_list_push_back (struct starpu_task_list *list, struct starpu_task *task)
- struct starpu_task * starpu_task_list_front (const struct starpu_task_list *list)
- struct starpu_task * starpu_task_list_back (const struct starpu_task_list *list)
- int starpu_task_list_empty (const struct starpu_task_list *list)
- void starpu_task_list_erase (struct starpu_task_list *list, struct starpu_task *task)
- struct starpu_task * starpu_task_list_pop_front (struct starpu_task_list *list)
- struct starpu_task * starpu_task_list_pop_back (struct starpu_task_list *list)
- struct starpu_task * starpu_task_list_begin (const struct starpu_task_list *list)
- struct starpu_task * starpu_task_list_end (const struct starpu_task_list *list)
- struct starpu_task * starpu_task_list_next (const struct starpu_task_list *list)
- int starpu_task_list_ismember (const struct starpu_task_list *list, const struct starpu_task *look)
- void starpu_task_list_move (struct starpu_task_list *ldst, struct starpu_task_list *lsrc)
30.27.1 Detailed Description

30.27.2 Data Structure Documentation

30.27.2.1 struct starpu_task_list

Store a double-chained list of tasks

Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>struct starpu_task *</td>
<td>head</td>
</tr>
<tr>
<td>struct starpu_task *</td>
<td>tail</td>
</tr>
</tbody>
</table>

30.27.3 Function Documentation

30.27.3.1 starpu_task_list_init()

```c
void starpu_task_list_init (  
    struct starpu_task_list * list )
```
Initialize a list structure

30.27.3.2 starpu_task_list_push_front()

```c
void starpu_task_list_push_front (  
    struct starpu_task_list * list,  
    struct starpu_task * task )
```
Push task at the front of list

30.27.3.3 starpu_task_list_push_back()

```c
void starpu_task_list_push_back (  
    struct starpu_task_list * list,  
    struct starpu_task * task )
```
Push task at the back of list

30.27.3.4 starpu_task_list_front()

```c
struct starpu_task* starpu_task_list_front (  
    const struct starpu_task_list * list )
```
Get the front of list (without removing it)

30.27.3.5 starpu_task_list_back()

```c
struct starpu_task* starpu_task_list_back (  
    const struct starpu_task_list * list )
```
Get the back of list (without removing it)

30.27.3.6 starpu_task_list_empty()

```c
int starpu_task_list_empty (  
    const struct starpu_task_list * list )
```
Test if list is empty
30.27.3.7  starpu_task_list_erase()

void starpu_task_list_erase (  
   struct starpu_task_list * list,  
   struct starpu_task * task  )
Remove task from list

30.27.3.8  starpu_task_list_pop_front()

struct starpu_task* starpu_task_list_pop_front (  
   struct starpu_task_list * list  )
Remove the element at the front of list

30.27.3.9  starpu_task_list_pop_back()

struct starpu_task* starpu_task_list_pop_back (  
   struct starpu_task_list * list  )
Remove the element at the back of list

30.27.3.10  starpu_task_list_begin()

struct starpu_task* starpu_task_list_begin (  
   const struct starpu_task_list * list  )
Get the first task of list.

30.27.3.11  starpu_task_list_end()

struct starpu_task* starpu_task_list_end (  
   const struct starpu_task_list * list  )
Get the end of list.

30.27.3.12  starpu_task_list_next()

struct starpu_task* starpu_task_list_next (  
   const struct starpu_task * task  )
Get the next task of list. This is not erase-safe.

30.27.3.13  starpu_task_list_ismember()

int starpu_task_list_ismember (  
   const struct starpu_task_list * list,  
   const struct starpu_task * look  )
Test whether the given task look is contained in the list.

30.28 Parallel Tasks

Functions

- unsigned starpu_combined_worker_get_count (void)
- unsigned starpu_worker_is_combined_worker (int id)
- int starpu_combined_worker_get_id (void)
- int starpu_combined_worker_get_size (void)
- int starpu_combined_worker_get_rank (void)
- int starpu_combined_worker_assign_workerid (int nworkers, int workerid_array[])
- int starpu_combined_worker_get_description (int workerid, int *worker_size, int **combined_workerid)
- int starpu_combined_worker_can_execute_task (unsigned workerid, struct starpu_task *task, unsigned nimpl)
- void starpu_parallel_task_barrier_init (struct starpu_task *task, int workerid)
- void starpu_parallel_task_barrier_init_n (struct starpu_task *task, int worker_size)
30.28.1 Detailed Description

30.28.2 Function Documentation

30.28.2.1 starpu_combined_worker_get_count()

unsigned starpu_combined_worker_get_count ( 
    void )

Return the number of different combined workers.

30.28.2.2 starpu_combined_worker_get_id()

int starpu_combined_worker_get_id ( 
    void )

Return the identifier of the current combined worker.

30.28.2.3 starpu_combined_worker_get_size()

int starpu_combined_worker_get_size ( 
    void )

Return the size of the current combined worker, i.e. the total number of CPUs running the same task in the case of STARPU_SPMD parallel tasks, or the total number of threads that the task is allowed to start in the case of STARPU_FORKJOIN parallel tasks.

30.28.2.4 starpu_combined_worker_get_rank()

int starpu_combined_worker_get_rank ( 
    void )

Return the rank of the current thread within the combined worker. Can only be used in STARPU_FORKJOIN parallel tasks, to know which part of the task to work on.

30.28.2.5 starpu_combined_worker_assign_workerid()

int starpu_combined_worker_assign_workerid ( 
    int nworkers, 
    int workerid_array[] )

Register a new combined worker and get its identifier

30.28.2.6 starpu_combined_worker_get_description()

int starpu_combined_worker_get_description ( 
    int workerid, 
    int * worker_size, 
    int ** combined_workerid )

Get the description of a combined worker

30.28.2.7 starpu_combined_worker_can_execute_task()

int starpu_combined_worker_can_execute_task ( 
    unsigned workerid, 
    struct starpu_task * task, 
    unsigned nimpl )

Variant of starpu_worker_can_execute_task() compatible with combined workers

30.28.2.8 starpu_parallel_task_barrier_init()

void starpu_parallel_task_barrier_init ( 
    struct starpu_task * task, 
    int workerid )
Initialise the barrier for the parallel task, and dispatch the task between the different workers of the given combined worker.

30.28.2.9 starpu_parallel_task_barrier_init_n()

```c
void starpu_parallel_task_barrier_init_n ( 
    struct starpu_task * task,
    int worker_size )
```

Initialise the barrier for the parallel task, to be pushed to worker_size workers (without having to explicit a given combined worker).

## 30.29 Running Drivers

### Data Structures

- struct starpu_driver
- union starpu_driver.id

### Functions

- int starpu_driver_run (struct starpu_driver *d)
- void starpu_drivers_request_termination (void)
- int starpu_driver_init (struct starpu_driver *d)
- int starpu_driver_run_once (struct starpu_driver *d)
- int starpu_driver_deinit (struct starpu_driver *d)

### 30.29.1 Detailed Description

### 30.29.2 Data Structure Documentation

#### 30.29.2.1 struct starpu_driver

Structure for a driver

**Data Fields**

<table>
<thead>
<tr>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>enum starpu_worker_archtype</td>
<td>Type of the driver. Only STARPU_CPU_WORKER, STARPU_CUDA_WORKER and STARPU_OPENCL_WORKER are currently supported.</td>
</tr>
<tr>
<td>union starpu_driver</td>
<td>Identifier of the driver.</td>
</tr>
</tbody>
</table>

#### 30.29.2.2 union starpu_driver.id

Identifier of the driver.

**Data Fields**

<table>
<thead>
<tr>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>unsigned</td>
<td>cpu_id</td>
</tr>
<tr>
<td>unsigned</td>
<td>cuda_id</td>
</tr>
<tr>
<td>cl_device_id</td>
<td>opencl_id</td>
</tr>
</tbody>
</table>

### 30.29.3 Function Documentation
### 30.29.3.1 starpu_driver_run()

```c
int starpu_driver_run (struct starpu_driver *d)
```

Initialize the given driver, run it until it receives a request to terminate, deinitialize it and return 0 on success. Return -EINVAL if `starpu_driver::type` is not a valid StarPU device type (STARPU_CPU_WORKER, STARPU_CUDA_WORKER or STARPU_OPENCL_WORKER).

This is the same as using the following functions: calling `starpu_driver_init()`, then calling `starpu_driver_run_once()` in a loop, and finally `starpu_driver_deinit()`.

### 30.29.3.2 starpu_drivers_request_termination()

```c
void starpu_drivers_request_termination()
```

Notify all running drivers that they should terminate.

### 30.29.3.3 starpu_driver_init()

```c
int starpu_driver_init (struct starpu_driver *d)
```

Initialize the given driver. Return 0 on success, -EINVAL if `starpu_driver::type` is not a valid starpu_worker_archtype.

### 30.29.3.4 starpu_driver_run_once()

```c
int starpu_driver_run_once (struct starpu_driver *d)
```

Run the driver once, then return 0 on success, -EINVAL if `starpu_driver::type` is not a valid starpu_worker_archtype.

### 30.29.3.5 starpu_driver_deinit()

```c
int starpu_driver_deinit (struct starpu_driver *d)
```

Deinitialize the given driver. Return 0 on success, -EINVAL if `starpu_driver::type` is not a valid starpu_worker_archtype.

### 30.30 Expert Mode

#### Functions

- void `starpu_wake_all_blocked_workers` (void)
- int `starpu_progression_hook_register` (unsigned(*)(func)(void *arg), void *arg)
- void `starpu_progression_hook_deregister` (int hook_id)
- int `starpu_idle_hook_register` (unsigned(*)(func)(void *arg), void *arg)
- void `starpu_idle_hook_deregister` (int hook_id)

#### Detailed Description

#### Function Documentation

### 30.30.1 starpu_wake_all_blocked_workers()

```c
void starpu_wake_all_blocked_workers (void)
```

Wake all the workers, so they can inspect data requests and task submissions again.
30.30.2.2 starpu_progression_hook_register()

```c
int starpu_progression_hook_register (unsigned (*)(void *)arg) func,
void * arg )
```

Register a progression hook, to be called when workers are idle.

30.30.2.3 starpu_progression_hook_deregister()

```c
void starpu_progression_hook_deregister (int hook_id )
```

Unregister a given progression hook.

### 30.31 Scheduling Contexts

StarPU permits on one hand grouping workers in combined workers in order to execute a parallel task and on the other hand grouping tasks in bundles that will be executed by a single specified worker. In contrast when we group workers in scheduling contexts we submit starpu tasks to them and we schedule them with the policy assigned to the context. Scheduling contexts can be created, deleted and modified dynamically.

#### Scheduling Contexts Basic API

- void(unsigned) starpu_sched_ctx_get_sched_policy_init (unsigned sched_ctx_id)
- unsigned starpu_sched_ctx_create (int *workerids_ctx, int nworkers_ctx, const char *sched_ctx_name,...)
- unsinged starpu_sched_ctx_create_inside_interval (const char *policy_name, const char *sched_ctx_name, int min_ncpus, int max_ncpus, int min_ngpus, int max_ngpus, unsigned allow_overlap)
- void starpu_sched_ctx_register_close_callback (unsigned sched_ctx_id, void(close_callback)(unsigned sched_ctx_id, void *args), void *args)
- void starpu_sched_ctx_add_workers (int *workerids_ctx, unsigned nworkers_ctx, unsigned sched_ctx_id)
- void starpu_sched_ctx_remove_workers (int *workerids_ctx, unsigned nworkers_ctx, unsigned sched_ctx_id)
- void starpu_sched_ctx_display_workers (unsigned sched_ctx_id, FILE *f)
- void starpu_sched_ctx_delete (unsigned sched_ctx_id)
- void starpu_sched_ctx_set_inheritor (unsigned sched_ctx_id, unsigned inheritor)
- unsigned starpu_sched_ctx_get_inheritor (unsigned sched_ctx_id)
- unsigned starpu_sched_ctx_get_hierarchy_level (unsigned sched_ctx_id)
- void starpu_sched_ctx_set_context (unsigned *sched_ctx_id)
- void starpu_sched_ctx_stop_task_submission (void)
- void starpu_sched_ctx_finished_submit (unsigned sched_ctx_id)
- unsigned starpu_sched_ctx_get_workers_list (unsigned sched_ctx_id, int **workerids)
- unsigned starpu_sched_ctx_get_workers_list_raw (unsigned sched_ctx_id, int **workerids)
- unsigned starpu_sched_ctx_get_nworkers (unsigned sched_ctx_id)
- unsigned starpu_sched_ctx_get_nshared_workers (unsigned sched_ctx_id, unsigned sched_ctx_id2)
- unsigned starpu_sched_ctx_contains_worker (int workerid, unsigned sched_ctx_id)
- unsigned starpu_sched_ctx_contains_type_of_worker (enum starpu_worker_archtype arch, unsigned sched_ctx_id)
- unsigned starpu_sched_ctx_worker_get_id (unsigned sched_ctx_id)
- unsigned starpu_sched_ctx_get_ctx_for_task (struct starpu_task *task)
- unsigned starpu_sched_ctx_get_overlap_ctxs_on_worker (int workerid)
- void * starpu_sched_ctx_set_user_data (unsigned sched_ctx_id)
- void starpu_sched_ctx_set_user_data (unsigned sched_ctx_id, void *user_data)
- void starpu_sched_ctx_set_policy_data (unsigned sched_ctx_id, void *policy_data)
- void * starpu_sched_ctx_get_policy_data (unsigned sched_ctx_id)
- struct starpu_sched_policy * starpu_sched_ctx_get_sched_policy (unsigned sched_ctx_id)
- void * starpu_sched_ctx_exec_parallel_code (void *(*func)(void *), void *param, unsigned sched_ctx_id)
• int starpu_sched_ctx_get_nready_tasks (unsigned sched_ctx_id)
• double starpu_sched_ctx_get_nready_flops (unsigned sched_ctx_id)
• void starpu_sched_ctx_list_task_counters_increment (unsigned sched_ctx_id, int workerid)
• void starpu_sched_ctx_list_task_counters_decrement (unsigned sched_ctx_id, int workerid)
• void starpu_sched_ctx_list_task_counters_reset (unsigned sched_ctx_id, int workerid)
• void starpu_sched_ctx_list_task_counters_increment_all_ctx_locked (struct starpu_task *task, unsigned sched_ctx_id)
• void starpu_sched_ctx_list_task_counters_decrement_all_ctx_locked (struct starpu_task *task, unsigned sched_ctx_id)
• void starpu_sched_ctx_list_task_counters_reset_all (struct starpu_task *task, unsigned sched_ctx_id)
• void starpu_sched_ctx_list_task_counters_increment_all (struct starpu_task *task, unsigned sched_ctx_id)
• void starpu_sched_ctx_list_task_counters_decrement_all (struct starpu_task *task, unsigned sched_ctx_id)
• void starpu_sched_ctx_list_task_counters_reset_all (struct starpu_task *task, unsigned sched_ctx_id)
• void starpu_sched_ctx_set_priority (int *workers, int nworkers, unsigned sched_ctx_id, unsigned priority)
• unsigned starpu_sched_ctx_get_priority (int worker, unsigned sched_ctx_id)
• void starpu_sched_ctx_get_available_cpuids (unsigned sched_ctx_id, int **cpuids, int *ncpuids)
• void starpu_sched_ctx_bind_current_thread_to_cpuid (unsigned cpuid)
• int starpu_sched_ctx_book_workers_for_task (unsigned sched_ctx_id, int *workerids, int nworkers)
• void starpu_sched_ctx_unbook_workers_for_task (unsigned sched_ctx_id, int master)
• unsigned starpu_sched_ctx_worker_is_master_for_child_ctx (int workerid, unsigned sched_ctx_id)
• unsigned starpu_sched_ctx_master_get_context (int masterid)
• void starpu_sched_ctx_revert_task_counters_ctx_locked (unsigned sched_ctx_id, double flops)
• void starpu_sched_ctx_move_task_to_ctx_locked (struct starpu_task *task, unsigned sched_ctx, unsigned with_repush)
• int starpu_sched_ctx_get_worker_rank (unsigned sched_ctx_id)
• unsigned starpu_sched_ctx_has_starpu_scheduler (unsigned sched_ctx_id, unsigned *awake_workers)
• int starpu_sched_ctx_get_stream_worker (unsigned sub_ctx)
• int starpu_sched_ctx_get_sms (unsigned sched_ctx)
• void starpu_sched_ctx_get_sms_interval (int stream_workerid, int *start, int *end)
• #define STARPU_SCHED_CTX_POLICY_NAME
• #define STARPU_SCHED_CTX_POLICY_STRUCT
• #define STARPU_SCHED_CTX_POLICY_MIN_PRIO
• #define STARPU_SCHED_CTX_POLICY_MAX_PRIO
• #define STARPU_SCHED_CTX_HIERARCHY_LEVEL
• #define STARPU_SCHED_CTX_NESTED
• #define STARPU_SCHED_CTX_AWAKE_WORKERS
• #define STARPU_SCHED_CTX_POLICY_INIT
• #define STARPU_SCHED_CTX_USER_DATA
• #define STARPU_SCHED_CTX_CUDA_SMS
• #define STARPU_SCHED_CTX_SUB_CTXS

Scheduling Context Priorities

• int starpu_sched_ctx_get_min_priority (unsigned sched_ctx_id)
• int starpu_sched_ctx_get_max_priority (unsigned sched_ctx_id)
• int starpu_sched_ctx_set_min_priority (unsigned sched_ctx_id, int min_prio)
• int starpu_sched_ctx_set_max_priority (unsigned sched_ctx_id, int max_prio)
• int starpu_sched_ctx_min_priority_is_set (unsigned sched_ctx_id)
• int starpu_sched_ctx_max_priority_is_set (unsigned sched_ctx_id)
• #define STARPU_MIN_PRIO
• #define STARPU_MAX_PRIO
• #define STARPU_DEFAULT_PRIO

Scheduling Context Worker Collection

• struct starpu_worker_collection * starpu_sched_ctx_create_worker_collection (unsigned sched_ctx_id, enum starpu_worker_collection_type type) STARPU_ATTRIBUTE_MALLOC
• void starpu_sched_ctx_delete_worker_collection (unsigned sched_ctx_id)
• struct starpu_worker_collection * starpu_sched_ctx_get_worker_collection (unsigned sched_ctx_id)
30.31 Scheduling Contexts

30.31.1 Detailed Description

StarPU permits on one hand grouping workers in combined workers in order to execute a parallel task and on the other hand grouping tasks in bundles that will be executed by a single specified worker. In contrast when we group workers in scheduling contexts we submit starpu tasks to them and we schedule them with the policy assigned to the context. Scheduling contexts can be created, deleted and modified dynamically.

30.31.2 Macro Definition Documentation

30.31.2.1 STARPU_SCHED_CTX_POLICY_NAME

#define STARPU_SCHED_CTX_POLICY_NAME
Used when calling `starpu_sched_ctx_create()` to specify a name for a scheduling policy.

30.31.2.2 STARPU_SCHED_CTX_POLICY_STRUCT

#define STARPU_SCHED_CTX_POLICY_STRUCT
Used when calling `starpu_sched_ctx_create()` to specify a pointer to a scheduling policy.

30.31.2.3 STARPU_SCHED_CTX_POLICY_MIN_PRIO

#define STARPU_SCHED_CTX_POLICY_MIN_PRIO
Used when calling `starpu_sched_ctx_create()` to specify a minimum scheduler priority value.

30.31.2.4 STARPU_SCHED_CTX_POLICY_MAX_PRIO

#define STARPU_SCHED_CTX_POLICY_MAX_PRIO
Used when calling `starpu_sched_ctx_create()` to specify a maximum scheduler priority value.

30.31.2.5 STARPU_SCHED_CTX_AWAKE_WORKERS

#define STARPU_SCHED_CTX_AWAKE_WORKERS
Used when calling `starpu_sched_ctx_create()` to specify ???

30.31.2.6 STARPU_SCHED_CTX_POLICY_INIT

#define STARPU_SCHED_CTX_POLICY_INIT
Used when calling `starpu_sched_ctx_create()` to specify a function pointer allowing to initialize the scheduling policy.

30.31.2.7 STARPU_SCHED_CTX_USER_DATA

#define STARPU_SCHED_CTX_USER_DATA
Used when calling `starpu_sched_ctx_create()` to specify a pointer to some user data related to the context being created.

30.31.2.8 STARPU_SCHED_CTX_CUDA_NSMS

#define STARPU_SCHED_CTX_CUDA_NSMS
Used when calling `starpu_sched_ctx_create()` in order to create a context on the NVIDIA GPU to specify the number of SMs the context should have.

30.31.2.9 STARPU_SCHED_CTX_SUB_CTXS

#define STARPU_SCHED_CTX_SUB_CTXS
Used when calling `starpu_sched_ctx_create()` to specify a list of sub contexts of the current context.

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30.31.2.10 STARPU_MIN_PRIO

#define STARPU_MIN_PRIO
Provided for legacy reasons.

30.31.2.11 STARPU_MAX_PRIO

#define STARPU_MAX_PRIO
Provided for legacy reasons.

30.31.2.12 STARPU_DEFAULT_PRIO

#define STARPU_DEFAULT_PRIO
By convention, the default priority level should be 0 so that we can statically allocate tasks with a default priority.

30.31.3 Function Documentation

30.31.3.1 starpu_sched_ctx_create()

unsigned starpu_sched_ctx_create (  
  int * workerids_ctx,  
  int nworkers_ctx,  
  const char * sched_ctx_name,  
  ... )  

Create a scheduling context with the given parameters (see below) and assign the workers in workerids_ctx to execute the tasks submitted to it. The return value represents the identifier of the context that has just been created. It will be further used to indicate the context the tasks will be submitted to. The return value should be at most STARPU_NMAX_SCHED_CTXS.

The arguments following the name of the scheduling context can be of the following types:

- **STARPU_SCHED_CTX_POLICY_NAME**, followed by the name of a predefined scheduling policy. Use an empty string to create the context with the default scheduling policy.
- **STARPU_SCHED_CTX_POLICY_STRUCT**, followed by a pointer to a custom scheduling policy (struct starpu_sched_policy *)
- **STARPU_SCHED_CTX_POLICY_MIN_PRIO**, followed by an integer representing the minimum priority value to be defined for the scheduling policy.
- **STARPU_SCHED_CTX_POLICY_MAX_PRIO**, followed by an integer representing the maximum priority value to be defined for the scheduling policy.
- **STARPU_SCHED_CTX_POLICY_INIT**, followed by a function pointer (ie. void init_sched(void)) allowing to initialize the scheduling policy.
- **STARPU_SCHED_CTX_USER_DATA**, followed by a pointer to a custom user data structure, to be retrieved by starpu_sched_ctx_get_user_data().

30.31.3.2 starpu_sched_ctx_create_inside_interval()

unsigned starpu_sched_ctx_create_inside_interval (  
  const char * policy_name,  
  const char * sched_ctx_name,  
  int min_ncpus,  
  int max_ncpus,  
  int min_ngpus,  
  int max_ngpus,  
  unsigned allow_overlap )  

Create a context indicating an approximate interval of resources
30.31.3.3 starpu_sched_ctx_register_close_callback()

```c
void starpu_sched_ctx_register_close_callback {
    unsigned sched_ctx_id,
    void(*) (unsigned sched_ctx_id, void *args) close_callback,
    void * args 
}
```

Execute the callback whenever the last task of the context finished executing, it is called with the parameters sched_ctx and any other parameter needed by the application (packed in args)

30.31.3.4 starpu_sched_ctx_add_workers()

```c
void starpu_sched_ctx_add_workers {
    int * workerids_ctx,
    unsigned nworkers_ctx,
    unsigned sched_ctx_id
}
```

Add dynamically the workers in workerids_ctx to the context sched_ctx_id. The last argument cannot be greater than STARPU_NMAX_SCHED_CTXS.

30.31.3.5 starpu_sched_ctx_remove_workers()

```c
void starpu_sched_ctx_remove_workers {
    int * workerids_ctx,
    unsigned nworkers_ctx,
    unsigned sched_ctx_id
}
```

Remove the workers in workerids_ctx from the context sched_ctx_id. The last argument cannot be greater than STARPU_NMAX_SCHED_CTXS.

30.31.3.6 starpu_sched_ctx_display_workers()

```c
void starpu_sched_ctx_display_workers {
    unsigned sched_ctx_id,
    FILE * f
}
```

Print on the file f the worker names belonging to the context sched_ctx_id

30.31.3.7 starpu_sched_ctx_delete()

```c
void starpu_sched_ctx_delete {
    unsigned sched_ctx_id
}
```

Delete scheduling context sched_ctx_id and transfer remaining workers to the inheritor scheduling context.

30.31.3.8 starpu_sched_ctx_set_inheritor()

```c
void starpu_sched_ctx_set_inheritor {
    unsigned sched_ctx_id,
    unsigned inheritor
}
```

Indicate that the context inheritor will inherit the resources of the context sched_ctx_id when sched_ctx_id will be deleted.

30.31.3.9 starpu_sched_ctx_set_context()

```c
void starpu_sched_ctx_set_context {
    unsigned * sched_ctx_id
}
```

Set the scheduling context the subsequent tasks will be submitted to

30.31.3.10 starpu_sched_ctx_get_context()

```c
unsigned starpu_sched_ctx_get_context {
    void
}
```

Return the scheduling context the tasks are currently submitted to, or STARPU_NMAX_SCHED_CTXS if no default context has been defined by calling the function starpu_sched_ctx_set_context().
30.31.3.11 starpu_sched_ctx_stop_task_submission()

void starpu_sched_ctx_stop_task_submission (  
  void  )

Stop submitting tasks from the empty context list until the next time the context has time to check the empty context list.

30.31.3.12 starpu_sched_ctx_finished_submit()

void starpu_sched_ctx_finished_submit (  
  unsigned  sched_ctx_id  )

Indicate starpu that the application finished submitting to this context in order to move the workers to the inheritor as soon as possible.

30.31.3.13 starpu_sched_ctx_get_workers_list()

unsigned starpu_sched_ctx_get_workers_list (  
  unsigned  sched_ctx_id,  
  int ** workerids  )

Return the list of workers in the array workerids, the return value is the number of workers. The user should free the workerids table after finishing using it (it is allocated inside the function with the proper size).

30.31.3.14 starpu_sched_ctx_get_workers_list_raw()

unsigned starpu_sched_ctx_get_workers_list_raw (  
  unsigned  sched_ctx_id,  
  int ** workerids  )

Return the list of workers in the array workerids, the return value is the number of workers. This list is provided in raw order, i.e. not sorted by tree or list order, and the user should not free the workerids table. This function is thus much less costly than starpu_sched_ctx_get_workers_list().

30.31.3.15 starpu_sched_ctx_get_nworkers()

unsigned starpu_sched_ctx_get_nworkers (  
  unsigned  sched_ctx_id  )

Return the number of workers managed by the specified context (Usually needed to verify if it manages any workers or if it should be blocked).

30.31.3.16 starpu_sched_ctx_get_nshared_workers()

unsigned starpu_sched_ctx_get_nshared_workers (  
  unsigned  sched_ctx_id,  
  unsigned  sched_ctx_id2  )

Return the number of workers shared by two contexts.

30.31.3.17 starpu_sched_ctx_contains_worker()

unsigned starpu_sched_ctx_contains_worker (  
  int workerid,  
  unsigned  sched_ctx_id  )

Return 1 if the worker belongs to the context and 0 otherwise.

30.31.3.18 starpu_sched_ctx_worker_get_id()

unsigned starpu_sched_ctx_worker_get_id (  
  unsigned  sched_ctx_id  )

Return the workerid if the worker belongs to the context and -1 otherwise. If the thread calling this function is not a worker the function returns -1 as it calls the function starpu_worker_get_id().
30.31 Scheduling Contexts

30.31.3.19  

```
unsigned starpu_sched_ctx_overlapping_ctxs_on_worker ( int workerid )
```

Check if a worker is shared between several contexts

30.31.3.20  

```
void* starpu_sched_ctx_get_user_data ( unsigned sched_ctx_id )
```

Return the user data pointer associated to the scheduling context.

30.31.3.21  

```
void starpu_sched_ctx_set_policy_data ( unsigned sched_ctx_id, void* policy_data )
```

Allocate the scheduling policy data (private information of the scheduler like queues, variables, additional condition variables) the context

30.31.3.22  

```
void* starpu_sched_ctx_get_policy_data ( unsigned sched_ctx_id )
```

Return the scheduling policy data (private information of the scheduler) of the contexts previously assigned to.

30.31.3.23  

```
void* starpu_sched_ctx_exec_parallel_code ( void(**)(void*) func, void* param, unsigned sched_ctx_id )
```

Execute any parallel code on the workers of the sched_ctx (workers are blocked)

30.31.3.24  

```
unsigned starpu_sched_ctx_worker_is_master_for_child_ctx ( int workerid, unsigned sched_ctx_id )
```

Return the first context (child of sched_ctx_id) where the workerid is master

30.31.3.25  

```
unsigned starpu_sched_ctx_master_get_context ( int masterid )
```

Return the context id of masterid if it master of a context. If not, return STARPU_NMAX_SCHED_CTXS.

30.31.3.26  

```
int starpu_sched_ctx_get_min_priority ( unsigned sched_ctx_id )
```

Return the current minimum priority level supported by the scheduling policy of the given scheduler context.

30.31.3.27  

```
int starpu_sched_ctx_get_max_priority ( unsigned sched_ctx_id )
```

Return the current maximum priority level supported by the scheduling policy of the given scheduler context.
30.31.3.28  starpu_sched_ctx_set_min_priority()

int starpu_sched_ctx_set_min_priority (  
    unsigned sched_ctx_id,  
    int min_prio )

Define the minimum task priority level supported by the scheduling policy of the given scheduler context. The default minimum priority level is the same as the default priority level which is 0 by convention. The application may access that value by calling the function `starpu_sched_ctx_get_min_priority()`. This function should only be called from the initialization method of the scheduling policy, and should not be used directly from the application.

30.31.3.29  starpu_sched_ctx_set_max_priority()

int starpu_sched_ctx_set_max_priority (  
    unsigned sched_ctx_id,  
    int max_prio )

Define the maximum priority level supported by the scheduling policy of the given scheduler context. The default maximum priority level is 1. The application may access that value by calling the `starpu_sched_ctx_get_max_priority()` function. This function should only be called from the initialization method of the scheduling policy, and should not be used directly from the application.

30.31.3.30  starpu_sched_ctx_create_worker_collection()

struct starpu_worker_collection* starpu_sched_ctx_create_worker_collection (  
    unsigned sched_ctx_id,  
    enum starpu_worker_collection_type type )

Create a worker collection of the type indicated by the last parameter for the context specified through the first parameter.

30.31.3.31  starpu_sched_ctx_delete_worker_collection()

void starpu_sched_ctx_delete_worker_collection (  
    unsigned sched_ctx_id )

Delete the worker collection of the specified scheduling context

30.31.3.32  starpu_sched_ctx_get_worker_collection()

struct starpu_worker_collection* starpu_sched_ctx_get_worker_collection (  
    unsigned sched_ctx_id )

Return the worker collection managed by the indicated context

30.32  Scheduling Policy

TODO. While StarPU comes with a variety of scheduling policies (see Task Scheduling Policies), it may sometimes be desirable to implement custom policies to address specific problems. The API described below allows users to write their own scheduling policy.

Data Structures

- struct starpu_sched_policy

Macros

- #define STARPU_NMAX_SCHED_CTXS
- #define STARPU_MAXIMPLEMENTATIONS

Typedefs

- typedef void(\*) starpu_notify_ready_soon_func (void *data, struct starpu_task *task, double delay)
Functions

- struct starpu_sched_policy ** starpu_sched_get_predefined_policies ()
- void starpu_worker_get_sched_condition (int workerid, starpu_pthread_mutex_t ** sched_mutex, starpu_pthread_cond_t ** sched_cond)
- unsigned long starpu_task_get_job_id (struct starpu_task * task)
- int starpu_sched_get_min_priority (void)
- int starpu_sched_get_max_priority (void)
- int starpu_sched_set_min_priority (int min_prio)
- int starpu_sched_set_max_priority (int max_prio)
- int starpu_worker_can_execute_task (unsigned workerid, struct starpu_task * task, unsigned nimpl)
- int starpu_worker_can_execute_task_impl (unsigned workerid, struct starpu_task * task, unsigned * impl_mask)
- int starpu_worker_can_execute_task_first_impl (unsigned workerid, struct starpu_task * task, unsigned * nimpl)
- int starpu_push_local_task (int workerid, struct starpu_task * task, int back)
- int starpu_push_task_end (struct starpu_task * task)
- int starpu_get_prefetch_flag (void)
- int starpu_prefetch_task_input_on_node_prio (struct starpu_task * task, unsigned node, int prio)
- int starpu_idle_prefetch_task_input_on_node_prio (struct starpu_task * task, unsigned node, int prio)
- int starpu_prefetch_task_input_on_node (struct starpu_task * task, unsigned node)
- int starpu_idle_prefetch_task_input_on_node (struct starpu_task * task, unsigned node)
- int starpu_prefetch_task_input_for_prio (struct starpu_task * task, unsigned worker, int prio)
- int starpu_idle_prefetch_task_input_for_prio (struct starpu_task * task, unsigned worker, int prio)
- int starpu_prefetch_task_input_for (struct starpu_task * task, unsigned worker)
- int starpu_idle_prefetch_task_input_for (struct starpu_task * task, unsigned worker)
- uint32_t starpu_task_footprint (struct starpu_perfmodel * model, struct starpu_task * task, struct starpu_perfmodel_arch * arch, unsigned nimpl)
- uint32_t starpu_task_data_footprint (struct starpu_task * task)
- double starpu_task_expected_length (struct starpu_task * task, struct starpu_perfmodel_arch * arch, unsigned nimpl)
- double starpu_worker_get_relative_speedup (struct starpu_perfmodel_arch * perf_arch)
- double starpu_task_expected_data_transfer_time (unsigned memory_node, struct starpu_task * task)
- double starpu_task_expected_data_transfer_time_for (struct starpu_task * task, unsigned worker)
- double starpu_data_expected_transfer_time (starpu_data_handle_t handle, unsigned memory_node, enum starpu_data_access_mode mode)
- double starpu_task_expected_energy (struct starpu_task * task, struct starpu_perfmodel_arch * arch, unsigned nimpl)
- double starpu_task_expected_conversion_time (struct starpu_task * task, struct starpu_perfmodel_arch * arch, unsigned nimpl)
- void starpu_task_notify_ready_soon_register (starpu_notify_ready_soon_func f, void * data)
- void starpu_sched_ctx_worker_shares_tasks_lists (int workerid, int sched_ctx_id)
- void starpu_sched_task_break (struct starpu_task * task)

Worker operations

- int starpu_wake_worker_relax (int workerid)
- int starpu_wake_worker_no_relax (int workerid)
- int starpu_wake_worker_locked (int workerid)
- int starpu_wake_worker_relax_light (int workerid)

30.32.1 Detailed Description

TODO. While StarPU comes with a variety of scheduling policies (see Task Scheduling Policies), it may sometimes be desirable to implement custom policies to address specific problems. The API described below allows users to write their own scheduling policy.
30.32.2 Data Structure Documentation

30.32.2.1 struct starpu_sched_policy

Contain all the methods that implement a scheduling policy. An application may specify which scheduling strategy in the field `starpu_conf::sched_policy` passed to the function `starpu_init()`.

For each task going through the scheduler, the following methods get called in the given order:

- `starpu_sched_policy::submit_hook` when the task is submitted
- `starpu_sched_policy::push_task` when the task becomes ready. The scheduler is here given the task
- `starpu_sched_policy::pop_task` when the worker is idle. The scheduler here gives back the task to the core. It must not access this task any more
- `starpu_sched_policy::pre_exec_hook` right before the worker actually starts the task computation (after transferring any missing data).
- `starpu_sched_policy::post_exec_hook` right after the worker actually completes the task computation.

For each task not going through the scheduler (because `starpu_task::execute_on_a_specific_worker` was set), these get called:

- `starpu_sched_policy::submit_hook` when the task is submitted
- `starpu_sched_policy::push_task_notify` when the task becomes ready. This is just a notification, the scheduler does not have to do anything about the task.
- `starpu_sched_policy::pre_exec_hook` right before the worker actually starts the task computation (after transferring any missing data).
- `starpu_sched_policy::post_exec_hook` right after the worker actually completes the task computation.

Data Fields

- `void(* init_sched)(unsigned sched_ctx_id)`
- `void(* deinit_sched)(unsigned sched_ctx_id)`
- `int(* push_task)(struct starpu_task*)`
- `double(* simulate_push_task)(struct starpu_task*)`
- `void(* push_task_notify)(struct starpu_task*, int workerid, int perf_workerid, unsigned sched_ctx_id)`
- `struct starpu_task*(*) pop_task(unsigned sched_ctx_id)`
- `struct starpu_task*(*) pop_every_task(unsigned sched_ctx_id)`
- `void(* submit_hook)(struct starpu_task* task)`
- `void(* pre_exec_hook)(struct starpu_task* task)`
- `void(* post_exec_hook)(struct starpu_task* task)`
- `void(* do_schedule)(unsigned sched_ctx_id)`
- `void(* add_workers)(unsigned sched_ctx_id, int *workerids, unsigned nworkers)`
- `void(* remove_workers)(unsigned sched_ctx_id, int *workerids, unsigned nworkers)`
- `const char* policy_name`
- `const char* policy_description`
- `enum starpu_worker_collection_type worker_type`

30.32.2.1.1 Field Documentation

30.32.2.1.1.1 init_sched

`void(* starpu_sched_policy::init_sched)(unsigned sched_ctx_id)`

Initialize the scheduling policy, called before any other method.

30.32.2.1.1.2 deinit_sched

`void(* starpu_sched_policy::deinit_sched)(unsigned sched_ctx_id)`

Cleanup the scheduling policy
30.32 Scheduling Policy

30.32.1.1.3 push_task

```c
int(* starpu_sched_policy::push_task) (struct starpu_task *)
```

Insert a task into the scheduler, called when the task becomes ready for execution. This must call `starpu_push_task()` once it has effectively pushed the task to a queue (to note the time when this was done in the task), but before releasing mutexes (so that the task hasn’t been already taken by a worker).

30.32.1.1.4 push_task_notify

```c
void(* starpu_sched_policy::push_task_notify) (struct starpu_task *, int workerid, int perf_workerid, unsigned sched_ctx_id)
```

Notify the scheduler that a task was pushed on a given worker. This method is called when a task that was explicitly assigned to a worker becomes ready and is about to be executed by the worker. This method therefore permits to keep the state of the scheduler coherent even when StarPU bypasses the scheduling strategy.

30.32.1.1.5 pop_task

```c
struct starpu_task* (* starpu_sched_policy::pop_task) (unsigned sched_ctx_id)
```

Get a task from the scheduler. If this method returns NULL, the worker will start sleeping. If later on some task are pushed for this worker, `starpu_wake_worker()` must be called to wake the worker so it can call the `pop_task()` method again. The mutex associated to the worker is already taken when this method is called. This method may release it (e.g. for scalability reasons when doing work stealing), but it must acquire it again before taking the decision whether to return a task or NULL, so the atomicity of deciding to return NULL and making the worker actually sleep is preserved. Otherwise in simgrid or blocking driver mode the worker might start sleeping while a task has just been pushed for it. If this method is defined as NULL, the worker will only execute tasks from its local queue. In this case, the `push_task` method should use the `starpu_push_local_task` method to assign tasks to the different workers.

30.32.1.1.6 pop_every_task

```c
struct starpu_task* (* starpu_sched_policy::pop_every_task) (unsigned sched_ctx_id)
```

Remove all available tasks from the scheduler (tasks are chained by the means of the field `starpu_task::prev` and `starpu_task::next`). The mutex associated to the worker is already taken when this method is called. This is currently not used and can be discarded.

30.32.1.1.7 submit_hook

```c
void(* starpu_sched_policy::submit_hook) (struct starpu_task *)
```

Optional field. This method is called when a task is submitted.

30.32.1.1.8 pre_exec_hook

```c
void(* starpu_sched_policy::pre_exec_hook) (struct starpu_task *, unsigned sched_ctx_id)
```

Optional field. This method is called every time a task is starting.

30.32.1.1.9 post_exec_hook

```c
void(* starpu_sched_policy::post_exec_hook) (struct starpu_task *, unsigned sched_ctx_id)
```

Optional field. This method is called every time a task has been executed.

30.32.1.1.10 do_schedule

```c
void(* starpu_sched_policy::do_schedule) (unsigned sched_ctx_id)
```

Optional field. This method is called when it is a good time to start scheduling tasks. This is notably called when the application calls `starpu_task_wait_for_all()` or `starpu_do_schedule()` explicitly.

30.32.1.1.11 add_workers

```c
void(* starpu_sched_policy::add_workers) (unsigned sched_ctx_id, int *workerids, unsigned nworkers)
```

Initialize scheduling structures corresponding to each worker used by the policy.

30.32.1.1.12 remove_workers

```c
void(* starpu_sched_policy::remove_workers) (unsigned sched_ctx_id, int *workerids, unsigned nworkers)
```

Deinitialize scheduling structures corresponding to each worker used by the policy.

30.32.1.1.13 policy_name

```c
const char* starpu_sched_policy::policy_name
```

Generated by Doxygen
Optional field. Name of the policy.

30.32.2.1.1.14 policy_description

const char* starpu_sched_policy::policy_description

Optional field. Human readable description of the policy.

30.32.3 Macro Definition Documentation

30.32.3.1 STARPU_NMAX_SCHED_CTXS

#define STARPU_NMAX_SCHED_CTXS

Define the maximum number of scheduling contexts managed by StarPU. The default value can be modified at configure by using the option --enable-max-sched-ctxs.

30.32.3.2 STARPU_MAXIMPLEMENTATIONS

#define STARPU_MAXIMPLEMENTATIONS

Define the maximum number of implementations per architecture. The default value can be modified at configure by using the option --enable-maximplementations.

30.32.4 Function Documentation

30.32.4.1 starpu_sched_get_predefined_policies()

struct starpu_sched_policy** starpu_sched_get_predefined_policies ()

Return an NULL-terminated array of all the predefined scheduling policies.

30.32.4.2 starpu_worker_get_sched_condition()

void starpu_worker_get_sched_condition (
    int workerid,
    starpu_pthread_mutex_t ** sched_mutex,
    starpu_pthread_cond_t ** sched_cond )

When there is no available task for a worker, StarPU blocks this worker on a condition variable. This function specifies which condition variable (and the associated mutex) should be used to block (and to wake up) a worker. Note that multiple workers may use the same condition variable. For instance, in the case of a scheduling strategy with a single task queue, the same condition variable would be used to block and wake up all workers.

30.32.4.3 starpu_sched_get_min_priority()

int starpu_sched_get_min_priority ( void )

TODO: check if this is correct Return the current minimum priority level supported by the scheduling policy

30.32.4.4 starpu_sched_get_max_priority()

int starpu_sched_get_max_priority ( void )

TODO: check if this is correct Return the current maximum priority level supported by the scheduling policy

30.32.4.5 starpu_sched_set_min_priority()

int starpu_sched_set_min_priority ( int min_prio )

TODO: check if this is correct Define the minimum task priority level supported by the scheduling policy. The default minimum priority level is the same as the default priority level which is 0 by convention. The application may access
that value by calling the function `starpu_sched_get_min_priority()`. This function should only be called from the initialization method of the scheduling policy, and should not be used directly from the application.

30.32.4.6 `starpu_sched_set_max_priority()`

```c
int starpu_sched_set_max_priority {
    int max_prio
}
```

TODO: check if this is correct Define the maximum priority level supported by the scheduling policy. The default maximum priority level is 1. The application may access that value by calling the function `starpu_sched_get_max_priority()`. This function should only be called from the initialization method of the scheduling policy, and should not be used directly from the application.

30.32.4.7 `starpu_worker_can_execute_task()`

```c
int starpu_worker_can_execute_task {
    unsigned workerid,
    struct starpu_task * task,
    unsigned nimpl
}
```

Check if the worker specified by workerid can execute the codelet. Schedulers need to call it before assigning a task to a worker, otherwise the task may fail to execute.

30.32.4.8 `starpu_worker_can_execute_task_impl()`

```c
int starpu_worker_can_execute_task_impl {
    unsigned workerid,
    struct starpu_task * task,
    unsigned * impl_mask
}
```

Check if the worker specified by workerid can execute the codelet and return which implementation numbers can be used. Schedulers need to call it before assigning a task to a worker, otherwise the task may fail to execute. This should be preferred rather than calling `starpu_worker_can_execute_task()` for each and every implementation. It can also be used with `impl_mask == NULL` to check for at least one implementation without determining which.

30.32.4.9 `starpu_worker_can_execute_task_first_impl()`

```c
int starpu_worker_can_execute_task_first_impl {
    unsigned workerid,
    struct starpu_task * task,
    unsigned * nimpl
}
```

Check if the worker specified by workerid can execute the codelet and return the first implementation which can be used. Schedulers need to call it before assigning a task to a worker, otherwise the task may fail to execute. This should be preferred rather than calling `starpu_worker_can_execute_task()` for each and every implementation. It can also be used with `impl_mask == NULL` to check for at least one implementation without determining which.

30.32.4.10 `starpu_push_local_task()`

```c
int starpu_push_local_task {
    int workerid,
    struct starpu_task * task,
    int back
}
```

The scheduling policy may put tasks directly into a worker's local queue so that it is not always necessary to create its own queue when the local queue is sufficient. If `back` is not 0, `task` is put at the back of the queue where the worker will pop tasks first. Setting `back` to 0 therefore ensures a FIFO ordering.

30.32.4.11 `starpu_push_task_end()`

```c
int starpu_push_task_end {
    struct starpu_task * task
}
```

Must be called by a scheduler to notify that the given task has just been pushed.
30.32.4.12 starpu_get_prefetch_flag()

int starpu_get_prefetch_flag ( void )

Whether STARPU_PREFETCH was set

30.32.4.13 starpu_prefetch_task_input_on_node_prio()

int starpu_prefetch_task_input_on_node_prio ( struct starpu_task * task, unsigned node, int prio )

Prefetch data for a given p task on a given p node with a given priority

30.32.4.14 starpu_prefetch_task_input_on_node()

int starpu_prefetch_task_input_on_node ( struct starpu_task * task, unsigned node )

Prefetch data for a given p task on a given p node

30.32.4.15 starpu_idle_prefetch_task_input_on_node_prio()

int starpu_idle_prefetch_task_input_on_node_prio ( struct starpu_task * task, unsigned node, int prio )

Prefetch data for a given p task on a given p node when the bus is idle with a given priority

30.32.4.16 starpu_idle_prefetch_task_input_on_node()

int starpu_idle_prefetch_task_input_on_node ( struct starpu_task * task, unsigned node )

Prefetch data for a given p task on a given p node when the bus is idle

30.32.4.17 starpu_prefetch_task_input_for_prio()

int starpu_prefetch_task_input_for_prio ( struct starpu_task * task, unsigned worker, int prio )

Prefetch data for a given p task on a given p worker with a given priority

30.32.4.18 starpu_prefetch_task_input_for()

int starpu_prefetch_task_input_for ( struct starpu_task * task, unsigned worker )

Prefetch data for a given p task on a given p worker

30.32.4.19 starpu_idle_prefetch_task_input_for_prio()

int starpu_idle_prefetch_task_input_for_prio ( struct starpu_task * task, unsigned worker, int prio )

Prefetch data for a given p task on a given p worker when the bus is idle with a given priority
30.32.4.20 starpu_idle_prefetch_task_input_for()

```c
int starpu_idle_prefetch_task_input_for (  
    struct starpu_task * task,  
    unsigned worker )
```

Prefetch data for a given task on a given worker when the bus is idle.

30.32.4.21 starpu_task_footprint()

```c
uint32_t starpu_task_footprint (  
    struct starpu_perfmodel * model,  
    struct starpu_task * task,  
    struct starpu_perfmodel_arch * arch,  
    unsigned nimpl )
```

Return the footprint for a given task, taking into account user-provided perfmodel footprint or size_base functions.

30.32.4.22 starpu_task_data_footprint()

```c
uint32_t starpu_task_data_footprint (  
    struct starpu_task * task )
```

Return the raw footprint for the data of a given task (without taking into account user-provided functions).

30.32.4.23 starpu_task_expected_length()

```c
double starpu_task_expected_length (  
    struct starpu_task * task,  
    struct starpu_perfmodel_arch * arch,  
    unsigned nimpl )
```

Return expected task duration in micro-seconds.

30.32.4.24 starpu_worker_get_relative_speedup()

```c
double starpu_worker_get_relative_speedup (  
    struct starpu_perfmodel_arch * perf_arch )
```

Return an estimated speedup factor relative to CPU speed.

30.32.4.25 starpu_task_expected_data_transfer_time()

```c
double starpu_task_expected_data_transfer_time (  
    unsigned memory_node,  
    struct starpu_task * task )
```

Return expected data transfer time in micro-seconds for the given memory_node. Prefer using `starpu_task←expected_data_transfer_time_for()` which is more precise.

30.32.4.26 starpu_task_expected_data_transfer_time_for()

```c
double starpu_task_expected_data_transfer_time_for (  
    struct starpu_task * task,  
    unsigned worker )
```

Return expected data transfer time in micro-seconds for the given worker.

30.32.4.27 starpu_data_expected_transfer_time()

```c
double starpu_data_expected_transfer_time (  
    starpu_data_handle_t handle,  
    unsigned memory_node,  
    enum starpu_data_access_mode mode )
```

Predict the transfer time (in micro-seconds) to move handle to a memory node.
30.32.4.28  starpu_task_expected_energy()

double starpu_task_expected_energy (  
    struct starpu_task * task,  
    struct starpu_perfmodel_arch * arch,  
    unsigned nimpl  
)  

Return expected energy consumption in J

30.32.4.29  starpu_task_expected_conversion_time()

double starpu_task_expected_conversion_time (  
    struct starpu_task * task,  
    struct starpu_perfmodel_arch * arch,  
    unsigned nimpl  
)  

Return expected conversion time in ms (multiformat interface only)

30.32.4.30  starpu_task_notify_ready_soon_register()

void starpu_task_notify_ready_soon_register (  
    starpu_notify_ready_soon_func f,  
    void * data  
)  

Register a callback to be called when it is determined when a task will be ready an estimated amount of time from now, because its last dependency has just started and we know how long it will take.

30.32.4.31  starpu_sched_ctx_worker_shares_tasks_lists()

void starpu_sched_ctx_worker_shares_tasks_lists (  
    int workerid,  
    int sched_ctx_id  
)  

The scheduling policies indicates if the worker may pop tasks from the list of other workers or if there is a central list with task for all the workers

30.32.4.32  starpu_wake_worker_relax()

int starpu_wake_worker_relax (  
    int workerid  
)  

Wake up workerid while temporarily entering the current worker relax state if needed during the waiting process. Return 1 if workerid has been woken up or its state_keep_awake flag has been set to 1, and 0 otherwise (if workerid was not in the STATE_SLEEPING or in the STATE_SCHEDULING).

30.32.4.33  starpu_wake_worker_no_relax()

int starpu_wake_worker_no_relax (  
    int workerid  
)  

Must be called to wake up a worker that is sleeping on the cond. Return 0 whenever the worker is not in a sleeping state or has the state_keep_awake flag on.

30.32.4.34  starpu_wake_worker_locked()

int starpu_wake_worker_locked (  
    int workerid  
)  

Version of starpu_wake_worker_no_relax() which assumes that the sched mutex is locked

30.32.4.35  starpu_wake_worker_relax_light()

int starpu_wake_worker_relax_light (  
    int workerid  
)  

Light version of starpu_wake_worker_relax() which, when possible, speculatively set keep_awake on the target worker without waiting for the worker to enter the relax state.
30.33 Tree

This section describes the tree facilities provided by StarPU.

Data Structures

- struct starpu_tree

Functions

- void starpu_tree_reset_visited (struct starpu_tree *tree, char *visited)
- void starpu_tree_prepare_children (unsigned arity, struct starpu_tree *father)
- void starpu_tree_insert (struct starpu_tree *tree, int id, int level, int is_pu, int arity, struct starpu_tree *father)
- struct starpu_tree * starpu_tree_get (struct starpu_tree *tree, int id)
- struct starpu_tree * starpu_tree_get_neighbour (struct starpu_tree *tree, struct starpu_tree *node, char *visited, char *present)
- void starpu_tree_free (struct starpu_tree *tree)

30.33.1 Detailed Description

This section describes the tree facilities provided by StarPU.

30.33.2 Data Structure Documentation

30.33.2.1 struct starpu_tree

Data Fields

<table>
<thead>
<tr>
<th>struct starpu_tree * nodes</th>
</tr>
</thead>
<tbody>
<tr>
<td>struct starpu_tree * father</td>
</tr>
<tr>
<td>int arity</td>
</tr>
<tr>
<td>int id</td>
</tr>
<tr>
<td>int level</td>
</tr>
<tr>
<td>int is_pu</td>
</tr>
</tbody>
</table>

30.34 Scheduling Context Hypervisor - Building a new resizing policy

Data Structures

- struct sc_hypervisor_policy
- struct sc_hypervisor_resize_ack
- struct types_of_workers
- struct sc_hypervisor_policy_task_pool

Macros

- #define HYPERVISOR_REDIM_SAMPLE
- #define HYPERVISOR_START_REDIM_SAMPLE
- #define SC_NOTHING
- #define SC_IDLE
- #define SC_SPEED

Functions

- void sc_hypervisor_policy_add_task_to_pool (struct starpu_codelet *cl, unsigned sched_ctx, uint32_t footprint, struct sc_hypervisor_policy_task_pool **task_pools, size_t data_size)
• void sc_hypervisor_policy_remove_task_from_pool (struct starpu_task *task, uint32_t footprint, struct sc←
  hypervisor_policy_task_pool *task_pools)
• struct sc_hypervisor_policy_task_pool * sc_hypervisor_policy_clone_task_pool (struct sc←
  hypervisor_policy_task_pool *tp)
• void sc_hypervisor_get_tasks_times (int nw, int nt, double times[nw][nt], int *workers, unsigned size_ctxs,
  struct sc_hypervisor_policy_task_pool *task_pools)
• unsigned sc_hypervisor_find_lowest_prio_sched_ctx (unsigned req_sched_ctx, int nworkers_to_move)
• int * sc_hypervisor_get_idlest_workers (unsigned sched_ctx, int *nworkers, enum starpu_worker_archtype
  arch)
• int * sc_hypervisor_get_idlest_workers_in_list (int *start, int *workers, int null_workers, int *nworkers,
  enum starpu_worker_archtype arch)
• int sc_hypervisor_get_movable_nworkers (struct sc_hypervisor_policy_config *config, unsigned sched_ctx,
  enum starpu_worker_archtype arch)
• int sc_hypervisor_compute_nworkers_to_move (unsigned req_sched_ctx)
• unsigned sc_hypervisor_policy_resize (unsigned sender_sched_ctx, unsigned receiver_sched_ctx, unsigned
  force_resize, unsigned now)
• unsigned sc_hypervisor_policy_resize_to_unknown_receiver (unsigned sender_sched_ctx, unsigned now)
• double sc_hypervisor_get_ctx_speed (struct sc_hypervisor_wrapper *sc_w)
• double sc_hypervisor_get_slowest_ctx_exec_time (void)
• double sc_hypervisor_get_fastest_ctx_exec_time (void)
• double sc_hypervisor_get_speed_per_worker (struct sc_hypervisor_wrapper *sc_w, unsigned worker)
• double sc_hypervisor_get_speed_per_worker_type (struct sc_hypervisor_wrapper *sc_w, enum starpu←
  worker_archtype arch)
• double sc_hypervisor_get_ref_speed_per_worker_type (struct sc_hypervisor_wrapper *sc_w, enum
  starpu_worker_archtype arch)
• double sc_hypervisor_get_avg_speed (enum starpu_worker_archtype arch)
• void sc_hypervisor_check_if_consider_max (struct types_of_workers *tw)
• void sc_hypervisor_group_workers_by_type (struct types_of_workers *tw, int total_nrw)
• enum starpu_worker_archtype sc_hypervisor_get_arch_for_index (unsigned w, struct types_of_workers
  *tw)
• unsigned sc_hypervisor_get_index_for_arch (enum starpu_worker_archtype arch, struct types_of_workers
  *tw)
• unsigned sc_hypervisor_criteria_fulfilled (unsigned sched_ctx, int worker)
• unsigned sc_hypervisor_check_idle (unsigned sched_ctx, int worker)
• unsigned sc_hypervisor_check_speed_gap_btw_ctxs (unsigned *sched_ctxs, int nsched_ctxs, int *workers,
  int nworkers)
• unsigned sc_hypervisor_check_speed_gap_btw_ctxs_on_level (int level, int *workers_in, int nworkers_in,
  unsigned father_sched_ctx_id, unsigned **sched_ctxs, int *nsched_ctxs)
• unsigned sc_hypervisor_get_resize_criteria ()
• struct types_of_workers * sc_hypervisor_get_types_of_workers (int *workers, unsigned nworkers)
• void sc_hypervisor_set_config (unsigned sched_ctx, void *config)
• struct sc_hypervisor_policy_config * sc_hypervisor_get_config (unsigned sched_ctx)
• void sc_hypervisor_ctl (unsigned sched_ctx,...)
• #define SC_HYPERVISOR_MAX_IDLE
• #define SC_HYPERVISOR_MIN_WORKING
• #define SC_HYPERVISOR_PRIORITY
• #define SC_HYPERVISOR_MIN_WORKERS
• #define SC_HYPERVISOR_MAX_WORKERS
• #define SC_HYPERVISOR_GRANULARITY
• #define SC_HYPERVISOR_FIXED_WORKERS
• #define SC_HYPERVISOR_MIN_TASKS
• #define SC_HYPERVISOR_NEW_WORKERS_MAX_IDLE
• #define SC_HYPERVISOR_TIME_TO_APPLY
• #define SC_HYPERVISOR_NULL
• #define SC_HYPERVISOR_ISPEED_W_SAMPLE
• #define SC_HYPERVISOR_ISPEED_CTX_SAMPLE
# 30.34 Scheduling Context Hypervisor - Building a new resizing policy

- `#define SC_HYPERVISOR_TIME_SAMPLE`
- `#define MAX_IDLE_TIME`
- `#define MIN_WORKING_TIME`

- `struct sc_hypervisor_wrapper * sc_hypervisor_get_wrapper (unsigned sched_ctx)`
- `unsigned * sc_hypervisor_get_sched_ctxs ()`
- `int sc_hypervisor_get_nworkers_ctx (unsigned sched_ctx, enum starpu_worker_archtype arch)`
- `double sc_hypervisor_get_elapsed_flops_per_sched_ctx (struct sc_hypervisor_wrapper *sc_w)`
- `double sc_hypervisor_get_total_elapsed_flops_per_sched_ctx (struct sc_hypervisor_wrapper *sc_w, enum starpu_worker_archtype arch)`
- `double sc_hypervisor_get_speed_per_worker_type (struct sc_hypervisor_wrapper *sc_w, enum starpu_worker_archtype arch)`
- `double sc_hypervisor_get_speed (struct sc_hypervisor_wrapper *sc_w, enum starpu_worker_archtype arch)`

## 30.34.1 Detailed Description

## 30.34.2 Data Structure Documentation

### 30.34.2.1 struct sc_hypervisor_policy

Methods to implement a hypervisor resizing policy.

#### Data Fields

- `const char * name`
- `unsigned custom`
- `void(* size_ctxs) (unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)`
- `void(* resize_ctxs) (unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)`
- `void(* handle_idle_cycle) (unsigned sched_ctx, int worker)`
- `void(* handle_pushed_task) (unsigned sched_ctx, int worker)`
- `void(* handle_poped_task) (unsigned sched_ctx, int worker, struct starpu_task *task, uint32_t footprint)`
- `void(* handle_idle_end) (unsigned sched_ctx, int worker)`
- `void(* handle_post_exec_hook) (unsigned sched_ctx, int task_tag)`
- `void(* handle_submitted_job) (struct starpu_codelet *cl, unsigned sched_ctx, uint32_t footprint, size_t data size)`
- `void(* end_ctx) (unsigned sched_ctx)`
- `void(* start_ctx) (unsigned sched_ctx)`
- `void(* init_worker) (int workerid, unsigned sched_ctx)`

### 30.34.2.1.1 Field Documentation

#### 30.34.2.1.1.1 name

`const char* sc_hypervisor_policy::name`

Indicate the name of the policy, if there is not a custom policy, the policy corresponding to this name will be used by the hypervisor.

#### 30.34.2.1.1.2 custom

`unsigned sc_hypervisor_policy::custom`

Indicate whether the policy is custom or not.

#### 30.34.2.1.1.3 size_ctxs

`void(* sc_hypervisor_policy::size_ctxs) (unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)`

Distribute workers to contexts even at the beginning of the program.

#### 30.34.2.1.1.4 resize_ctxs

`void(* sc_hypervisor_policy::resize_ctxs) (unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)`

Require explicit resizing.

---

Generated by Doxygen.
30.34.2.1.5 handle_idle_cycle

```c
void(* sc_hypervisor_policy::handle_idle_cycle) (unsigned sched_ctx, int worker)
```

Called whenever the indicated worker executes another idle cycle in sched_ctx.

30.34.2.1.6 handle_pushed_task

```c
void(* sc_hypervisor_policy::handle_pushed_task) (unsigned sched_ctx, int worker)
```

Called whenever a task is pushed on the worker's queue corresponding to the context sched_ctx.

30.34.2.1.7 handle_poped_task

```c
void(* sc_hypervisor_policy::handle_poped_task) (unsigned sched_ctx, int worker, struct starpu←_task *task, uint32_t footprint)
```

Called whenever a task is popped from the worker's queue corresponding to the context sched_ctx.

30.34.2.1.8 handle_idle_end

```c
void(* sc_hypervisor_policy::handle_idle_end) (unsigned sched_ctx, int worker)
```

Called whenever a task is executed on the indicated worker and context after a long period of idle time.

30.34.2.1.9 handle_post_exec_hook

```c
void(* sc_hypervisor_policy::handle_post_exec_hook) (unsigned sched_ctx, int task_tag)
```

Called whenever a tag task has just been executed. The table of resize requests is provided as well as the tag.

30.34.2.1.10 handle_submitted_job

```c
void(* sc_hypervisor_policy::handle_submitted_job) (struct starpu_codelet *cl, unsigned sched←_ctx, uint32_t footprint, size_t data_size)
```

the hypervisor takes a decision when a job was submitted in this ctx.

30.34.2.1.11 end_ctx

```c
void(* sc_hypervisor_policy::end_ctx) (unsigned sched_ctx)
```

the hypervisor takes a decision when a certain ctx was deleted.

30.34.2.1.12 start_ctx

```c
void(* sc_hypervisor_policy::start_ctx) (unsigned sched_ctx)
```

the hypervisor takes a decision when a certain ctx was registered.

30.34.2.1.13 init_worker

```c
void(* sc_hypervisor_policy::init_worker) (int workerid, unsigned sched_ctx)
```

the hypervisor initializes values for the workers.

30.34.2.2 struct sc_hypervisor_resize_ack

Structure to check if the workers moved to another context are actually taken into account in that context.

**Data Fields**

<table>
<thead>
<tr>
<th>int</th>
<th>receiver_sched_ctx</th>
<th>The context receiving the new workers</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>moved_workers</td>
<td>List of workers required to be moved</td>
</tr>
<tr>
<td>int</td>
<td>nmoved_workers</td>
<td>Number of workers required to be moved</td>
</tr>
<tr>
<td>int</td>
<td>acked_workers</td>
<td>List of workers that actually got in the receiver ctx. If the value corresponding to a worker is 1, this worker got moved in the new context.</td>
</tr>
</tbody>
</table>

30.34.2.3 struct types_of_workers

**Data Fields**

<table>
<thead>
<tr>
<th>unsigned</th>
<th>ncpus</th>
</tr>
</thead>
<tbody>
<tr>
<td>unsigned</td>
<td>ncuda</td>
</tr>
<tr>
<td>unsigned</td>
<td>nw</td>
</tr>
</tbody>
</table>
### 30.34.2.4 struct sc_hypervisor_policy_task_pool
Task wrapper linked list

#### Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>struct starpu_codelet *</td>
<td>cl</td>
<td>Which codelet has been executed</td>
</tr>
<tr>
<td>uint32_t</td>
<td>footprint</td>
<td>Task footprint key</td>
</tr>
<tr>
<td>unsigned</td>
<td>sched_ctx_id</td>
<td>Context the task belongs to</td>
</tr>
<tr>
<td>unsigned long</td>
<td>n</td>
<td>Number of tasks of this kind</td>
</tr>
<tr>
<td>size_t</td>
<td>data_size</td>
<td>The quantity of data (in bytes) needed by the task to execute</td>
</tr>
<tr>
<td>struct</td>
<td>next</td>
<td>Other task kinds</td>
</tr>
</tbody>
</table>

### 30.34.3 Macro Definition Documentation

#### 30.34.3.1 SC_HYPERVISOR_MAX_IDLE

```c
#define SC_HYPERVISOR_MAX_IDLE
```
This macro is used when calling `sc_hypervisor_ctl()` and must be followed by 3 arguments: an array of int for the workerids to apply the condition, an int to indicate the size of the array, and a double value indicating the maximum idle time allowed for a worker before the resizing process should be triggered.

#### 30.34.3.2 SC_HYPERVISOR_PRIORITY

```c
#define SC_HYPERVISOR_PRIORITY
```
This macro is used when calling `sc_hypervisor_ctl()` and must be followed by 3 arguments: an array of int for the workerids to apply the condition, an int to indicate the size of the array, and an int value indicating the priority of the workers previously mentioned. The workers with the smallest priority are moved the first.

#### 30.34.3.3 SC_HYPERVISOR_MIN_WORKERS

```c
#define SC_HYPERVISOR_MIN_WORKERS
```
This macro is used when calling `sc_hypervisor_ctl()` and must be followed by 1 argument (int) indicating the minimum number of workers a context should have, underneath this limit the context cannot execute.

#### 30.34.3.4 SC_HYPERVISOR_MAX_WORKERS

```c
#define SC_HYPERVISOR_MAX_WORKERS
```
This macro is used when calling `sc_hypervisor_ctl()` and must be followed by 1 argument (int) indicating the maximum number of workers a context should have, above this limit the context would not be able to scale.

#### 30.34.3.5 SC_HYPERVISOR_GRANULARITY

```c
#define SC_HYPERVISOR_GRANULARITY
```
This macro is used when calling `sc_hypervisor_ctl()` and must be followed by 1 argument (int) indicating the granularity of the resizing process (the number of workers should be moved from the context once it is resized). This parameter is ignored for the Gflops rate based strategy (see Resizing Strategies), the number of workers that have to be moved is calculated by the strategy.

#### 30.34.3.6 SC_HYPERVISOR_FIXED_WORKERS

```c
#define SC_HYPERVISOR_FIXED_WORKERS
```
This macro is used when calling `sc_hypervisor_ctl()` and must be followed by 2 arguments: an array of int for the workerids to apply the condition and an int to indicate the size of the array. These workers are not allowed to be moved from the context.
30.34.3.7 SC_HYPervisor_MIN_TASKS

#define SC_HYPervisor_MIN_TASKS
This macro is used when calling sc_hypervisor_ctl() and must be followed by 1 argument (int) that indicated the minimum number of tasks that have to be executed before the context could be resized. This parameter is ignored for the Application Driven strategy (see Resizing Strategies) where the user indicates exactly when the resize should be done.

30.34.3.8 SC_HYPervisor_NEW_WORKERS_MAX_IDLE

#define SC_HYPervisor_NEW_WORKERS_MAX_IDLE
This macro is used when calling sc_hypervisor_ctl() and must be followed by 1 argument, a double value indicating the maximum idle time allowed for workers that have just been moved from other contexts in the current context.

30.34.3.9 SC_HYPervisor_TIME_TO_APPLY

#define SC_HYPervisor_TIME_TO_APPLY
This macro is used when calling sc_hypervisor_ctl() and must be followed by 1 argument (int) indicating the tag an executed task should have such that this configuration should be taken into account.

30.34.3.10 SC_HYPervisor_NULL

#define SC_HYPervisor_NULL
This macro is used when calling sc_hypervisor_ctl() and must be followed by 1 argument.

30.34.3.11 SC_HYPervisor_ISPEED_W_SAMPLE

#define SC_HYPervisor_ISPEED_W_SAMPLE
This macro is used when calling sc_hypervisor_ctl() and must be followed by 1 argument, a double, that indicates the number of flops needed to be executed before computing the speed of a worker.

30.34.3.12 SC_HYPervisor_ISPEED_CTX_SAMPLE

#define SC_HYPervisor_ISPEED_CTX_SAMPLE
This macro is used when calling sc_hypervisor_ctl() and must be followed by 1 argument, a double, that indicates the number of flops needed to be executed before computing the speed of a context.

30.34.4 Function Documentation

30.34.4.1 sc_hypervisor_get_wrapper()
struct sc_hypervisor_wrapper* sc_hypervisor_get_wrapper ( unsigned sched_ctx )
Return the wrapper of the given context.

30.34.4.2 sc_hypervisor_get_sched_ctxs()
unsigned* sc_hypervisor_get_sched_ctxs ( )
Get the list of registered contexts.

30.34.4.3 sc_hypervisor_get_nsched_ctxs()
int sc_hypervisor_get_nsched_ctxs ( )
Get the number of registered contexts.
30.34.4 `sc_hypervisor_get_elapsed_flops_per_sched_ctx()`

```c
double sc_hypervisor_get_elapsed_flops_per_sched_ctx (
    struct sc_hypervisor_wrapper * sc_w )
```

Get the number of flops executed by a context since last resizing (reset to 0 when a resizing is done)

30.34.5 `sc_hypervisor_policy_add_task_to_pool()`

```c
void sc_hypervisor_policy_add_task_to_pool ( 
    struct starpu_codelet * cl, 
    unsigned sched_ctx, 
    uint32_t footprint, 
    struct sc_hypervisor_policy_task_pool ** task_pools, 
    size_t data_size )
```

add task information to a task wrapper linked list

30.34.6 `sc_hypervisor_policy_remove_task_from_pool()`

```c
void sc_hypervisor_policy_remove_task_from_pool ( 
    struct starpu_task * task, 
    uint32_t footprint, 
    struct sc_hypervisor_policy_task_pool ** task_pools )
```

remove task information from a task wrapper linked list

30.34.7 `sc_hypervisor_policy_clone_task_pool()`

```c
struct sc_hypervisor_policy_task_pool * sc_hypervisor_policy_clone_task_pool ( 
    struct sc_hypervisor_policy_task_pool * tp )
```

clone a task wrapper linked list

30.34.8 `sc_hypervisor_get_tasks_times()`

```c
void sc_hypervisor_get_tasks_times ( 
    int nw, 
    int nt, 
    double times[nw][nt], 
    int * workers, 
    unsigned size_ctxs, 
    struct sc_hypervisor_policy_task_pool * task_pools )
```

get the execution time of the submitted tasks out of starpu's calibration files

30.34.9 `sc_hypervisor_find_lowest_prio_sched_ctx()`

```c
unsigned sc_hypervisor_find_lowest_prio_sched_ctx ( 
    unsigned req_sched_ctx, 
    int nworkers_to_move )
```

find the context with the lowest priority in order to move some workers

30.34.10 `sc_hypervisor_get_idlest_workers()`

```c
int* sc_hypervisor_get_idlest_workers ( 
    unsigned sched_ctx, 
    int * nworkers, 
    enum starpu_worker_archtype arch )
```

find the first most idle workers of a contex

30.34.11 `sc_hypervisor_get_idlest_workers_in_list()`

```c
int* sc_hypervisor_get_idlest_workers_in_list ( 
    int * start,
```
find the first most idle workers in a list

30.34.4.12   sc_hypervisor_get_movable_nworkers()

int sc_hypervisor_get_movable_nworkers (  
  struct sc_hypervisor_policy_config * config,  
  unsigned sched_ctx,  
  enum starpu_worker_archtype arch )

find workers that can be moved from a context (if the constraints of min, max, etc allow this)

30.34.4.13   sc_hypervisor_compute_nworkers_to_move()

int sc_hypervisor_compute_nworkers_to_move (  
  unsigned req_sched_ctx )

compute how many workers should be moved from this context

30.34.4.14   sc_hypervisor_policy_resize()

unsigned sc_hypervisor_policy_resize (  
  unsigned sender_sched_ctx,  
  unsigned receiver_sched_ctx,  
  unsigned force_resize,  
  unsigned now )

check the policy's constraints in order to resize

30.34.4.15   sc_hypervisor_policy_resize_to_unknown_receiver()

unsigned sc_hypervisor_policy_resize_to_unknown_receiver (  
  unsigned sender_sched_ctx,  
  unsigned now )

check the policy's constraints in order to resize and find a context willing the resources

30.34.4.16   sc_hypervisor_get_ctx_speed()

double sc_hypervisor_get_ctx_speed (  
  struct sc_hypervisor_wrapper * sc_w )

compute the speed of a context

30.34.4.17   sc_hypervisor_get_slowest_ctx_exec_time()

double sc_hypervisor_get_slowest_ctx_exec_time (  
  void )

get the time of execution of the slowest context

30.34.4.18   sc_hypervisor_get_fastest_ctx_exec_time()

double sc_hypervisor_get_fastest_ctx_exec_time (  
  void )

get the time of execution of the fastest context

30.34.4.19   sc_hypervisor_get_speed_per_worker()

double sc_hypervisor_get_speed_per_worker (  
  struct sc_hypervisor_wrapper * sc_w,  
  unsigned worker )

compute the speed of a workers in a context
30.34.4.20 sc_hypervisor_get_speed_per_worker_type()

double sc_hypervisor_get_speed_per_worker_type (  
  struct sc_hypervisor_wrapper * sc_w,  
  enum starpu_worker_archtype arch )

compute the speed of a type of worker in a context

30.34.4.21 sc_hypervisor_get_ref_speed_per_worker_type()

double sc_hypervisor_get_ref_speed_per_worker_type (  
  struct sc_hypervisor_wrapper * sc_w,  
  enum starpu_worker_archtype arch )

compute the speed of a type of worker in a context depending on its history

30.34.4.22 sc_hypervisor_get_avg_speed()

double sc_hypervisor_get_avg_speed (  
  enum starpu_worker_archtype arch )

compute the average speed of a type of worker in all ctxs from the begining of appl

30.34.4.23 sc_hypervisor_check_if_consider_max()

void sc_hypervisor_check_if_consider_max (  
  struct types_of_workers * tw )

verify if we need to consider the max in the lp

30.34.4.24 sc_hypervisor_group_workers_by_type()

void sc_hypervisor_group_workers_by_type (  
  struct types_of_workers * tw,  
  int * total_nw )

get the list of workers grouped by type

30.34.4.25 sc_hypervisor_get_arch_for_index()

enum starpu_worker_archtype sc_hypervisor_get_arch_for_index (  
  unsigned w,  
  struct types_of_workers * tw )

get what type of worker corresponds to a certain index of types of workers

30.34.4.26 sc_hypervisor_get_index_for_arch()

unsigned sc_hypervisor_get_index_for_arch (  
  enum starpu_worker_archtype arch,  
  struct types_of_workers * tw )

get the index of types of workers corresponding to the type of workers indicated

30.34.4.27 sc_hypervisor_criteria_fulfilled()

unsigned sc_hypervisor_criteria_fulfilled (  
  unsigned sched_ctx,  
  int worker )

check if we trigger resizing or not

30.34.4.28 sc_hypervisor_check_idle()

unsigned sc_hypervisor_check_idle (  
  unsigned sched_ctx,  
  int worker )

check if worker was idle long enough
30.34.4.29  sc_hypervisor_check_speed_gap_btw_ctxs()

unsigned sc_hypervisor_check_speed_gap_btw_ctxs (  
    unsigned * sched_ctxs,  
    int nsched_ctxs,  
    int * workers,  
    int nworkers )

check if there is a speed gap btw ctxs

30.34.4.30  sc_hypervisor_check_speed_gap_btw_ctxs_on_level()

unsigned sc_hypervisor_check_speed_gap_btw_ctxs_on_level (  
    int level,  
    int * workers_in,  
    int nworkers_in,  
    unsigned father_sched_ctx_id,  
    unsigned ** sched_ctxs,  
    int * nsched_ctxs )

check if there is a speed gap btw ctxs on one level

30.34.4.31  sc_hypervisor_get_resize_criteria()

unsigned sc_hypervisor_get_resize_criteria ()

check what triggers resizing (idle, speed, etc.

30.34.4.32  sc_hypervisor_get_types_of_workers()

struct types_of_workers* sc_hypervisor_get_types_of_workers (  
    int * workers,  
    unsigned nworkers )

load information concerning the type of workers into a types_of_workers struct

30.34.4.33  sc_hypervisor_set_config()

void sc_hypervisor_set_config (  
    unsigned sched_ctx,  
    void * config )

Specify the configuration for a context

30.34.4.34  sc_hypervisor_get_config()

struct sc_hypervisor_policy_config* sc_hypervisor_get_config (  
    unsigned sched_ctx )

Return the configuration of a context

30.34.4.35  sc_hypervisor_ctl()

void sc_hypervisor_ctl (  
    unsigned sched_ctx,  
    ... )

Specify different parameters for the configuration of a context. The list must be zero-terminated

30.34.4.36  sc_hypervisor_get_nworkers_ctx()

int sc_hypervisor_get_nworkers_ctx (  
    unsigned sched_ctx,  
    enum starpu_worker_archtype arch )

Get the number of workers of a certain architecture in a context
30.34.4.37  

```c
double sc_hypervisor_get_total_elapsed_flops_per_sched_ctx ( 
    struct sc_hypervisor_wrapper * sc_w )
```

Get the number of flops executed by a context since the beginning.

30.34.4.38  

```c
double sc_hypervisor_get_speed_per_worker_type ( 
    struct sc_hypervisor_wrapper * sc_w, 
    enum starpu_worker_archtype arch )
```

Compute an average value of the cpu/cuda speed.

30.34.4.39  

```c
double sc_hypervisor_get_speed ( 
    struct sc_hypervisor_wrapper * sc_w, 
    enum starpu_worker_archtype arch )
```

Compute the actual speed of all workers of a specific type of worker.

30.35  

Scheduling Context Hypervisor - Regular usage

Data Structures

- `struct sc_hypervisor_policy`

Functions

- `void sc_hypervisor_init (struct sc_hypervisor_policy *policy)`
- `void sc_hypervisor_shutdown (void)`
- `void sc_hypervisor_register_ctx (unsigned sched_ctx, double total_flops)`
- `void sc_hypervisor_unregister_ctx (unsigned sched_ctx)`
- `void sc_hypervisor_post_resize_request (unsigned sched_ctx, int task_tag)`
- `void sc_hypervisor_resize_ctxs (unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)`
- `void sc_hypervisor_stop_resize (unsigned sched_ctx)`
- `void sc_hypervisor_start_resize (unsigned sched_ctx)`
- `const char * sc_hypervisor_get_policy ()`
- `void sc_hypervisor_add_workers_to_sched_ctx (int *workers_to_add, unsigned nworkers_to_add, unsigned sched_ctx)`
- `void sc_hypervisor_remove_workers_from_sched_ctx (int *workers_to_remove, unsigned nworkers_to_remove, unsigned sched_ctx, unsigned now)`
- `void sc_hypervisor_move_workers (unsigned sender_sched_ctx, unsigned receiver_sched_ctx, int *workers_to_move, unsigned nworkers_to_move, unsigned now)`
- `unsigned sc_hypervisor_size_ctxs (unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)`
- `unsigned sc_hypervisor_get_size_req (unsigned **sched_ctxs, int *nsched_ctxs, int **workers, int nworkers)`
- `void sc_hypervisor_save_size_req (unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)`
- `void sc_hypervisor_free_size_req (void)`
- `unsigned sc_hypervisor_can_resize (unsigned sched_ctx)`
- `void sc_hypervisor_set_type_of_task (struct starpu_codelet *cl, unsigned sched_ctx, uint32_t footprint, size_t data_size)`
- `void sc_hypervisor_update_diff_total_flops (unsigned sched_ctx, double diff_total_flops)`
- `void sc_hypervisor_update_diff_elapsed_flops (unsigned sched_ctx, double diff_task_flops)`
- `void sc_hypervisor_update_resize_interval (unsigned *sched_ctxs, int nsched_ctxs, int max_nworkers)`
- `void sc_hypervisor_get_ctxs_on_level (unsigned **sched_ctxs, int nsched_ctxs, unsigned hierarchy_level, uint32_t footprint, size_t data_size)`
- `unsigned sc_hypervisor_get_nhierarchy_levels (void)`
• void sc_hypervisor_get_leaves (unsigned *sched_ctxs, int nsched_ctxs, unsigned *leaves, int *nleaves)
• double sc_hypervisor_get_nready_flops_of_all_sons_of_sched_ctx (unsigned sched_ctx)
• void sc_hypervisor_print_overhead ()
• void sc_hypervisor_init_worker (int workerid, unsigned sched_ctx)

Variables

- starpu_thread_mutex_t act_hypervisor_mutex

30.35.1 Detailed Description

There is a single hypervisor that is in charge of resizing contexts and the resizing strategy is chosen at the initialization of the hypervisor. A single resize can be done at a time.

The Scheduling Context Hypervisor Plugin provides a series of performance counters to StarPU. By incrementing them, StarPU can help the hypervisor in the resizing decision making process.

The function sc_hypervisor_init() initializes the hypervisor to use the strategy provided as parameter and creates the performance counters (see starpu_sched_ctx_performance_counters). These performance counters represent actually some callbacks that will be used by the contexts to notify the information needed by the hypervisor.

Scheduling Contexts that have to be resized by the hypervisor must be first registered to the hypervisor using the function sc_hypervisor_register_ctx()

Note: The Hypervisor is actually a worker that takes this role once certain conditions trigger the resizing process (there is no additional thread assigned to the hypervisor).

30.35.2 Data Structure Documentation

30.35.2.1 struct sc_hypervisor_policy

Methods to implement a hypervisor resizing policy.

Data Fields

- const char * name
- unsigned custom
- void(* size_ctxs )(unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)
- void(* resize_ctxs )(unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)
- void(* handle_idle_cycle )(unsigned sched_ctx, int worker)
- void(* handle_pushed_task )(unsigned sched_ctx, int worker)
- void(* handle_poped_task )(unsigned sched_ctx, int worker, struct starpu_task *task, uint32_t footprint)
- void(* handle_idle_end )(unsigned sched_ctx, int worker)
- void(* handle_post_exec_hook )(unsigned sched_ctx, int task_tag)
- void(* handle_submitted_job )(struct starpu_codelet *cl, unsigned sched_ctx, uint32_t footprint, size_t data_size)
- void(* end_ctx )(unsigned sched_ctx)
- void(* start_ctx )(unsigned sched_ctx)
- void(* init_worker )(int workerid, unsigned sched_ctx)

30.35.2.1.1 Field Documentation

30.35.2.1.1.1 name

const char* sc_hypervisor_policy::name
Indicate the name of the policy, if there is not a custom policy, the policy corresponding to this name will be used by the hypervisor

30.35.2.1.1.2 custom

unsigned sc_hypervisor_policy::custom
Indicate whether the policy is custom or not
30.35.2.1.1.3 size_ctxs

void(* sc_hypervisor_policy::size_ctxs) (unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)
Distribute workers to contexts even at the begining of the program

30.35.2.1.1.4 resize_ctxs

void(* sc_hypervisor_policy::resize_ctxs) (unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)
Require explicit resizing

30.35.2.1.1.5 handle_idle_cycle

void(* sc_hypervisor_policy::handle_idle_cycle) (unsigned sched_ctx, int worker)
Called whenever the indicated worker executes another idle cycle in sched_ctx

30.35.2.1.1.6 handle_pushed_task

void(* sc_hypervisor_policy::handle_pushed_task) (unsigned sched_ctx, int worker)
Called whenever a task is pushed on the worker’s queue corresponding to the context sched_ctx

30.35.2.1.1.7 handle_poped_task

void(* sc_hypervisor_policy::handle_poped_task) (unsigned sched_ctx, int worker, struct starpu_task *task, uint32_t footprint)
Called whenever a task is poped from the worker’s queue corresponding to the context sched_ctx

30.35.2.1.1.8 handle_idle_end

void(* sc_hypervisor_policy::handle_idle_end) (unsigned sched_ctx, int worker)
Called whenever a task is executed on the indicated worker and context after a long period of idle time

30.35.2.1.1.9 handle_post_exec_hook

void(* sc_hypervisor_policy::handle_post_exec_hook) (unsigned sched_ctx, int task_tag)
Called whenever a tag task has just been executed. The table of resize requests is provided as well as the tag

30.35.2.1.1.10 handle_submitted_job

void(* sc_hypervisor_policy::handle_submitted_job) (struct starpu_codelet *cl, unsigned sched_ctx, uint32_t footprint, size_t data_size)
The hypervisor takes a decision when a job was submitted in this ctx

30.35.2.1.1.11 end_ctx

void(* sc_hypervisor_policy::end_ctx) (unsigned sched_ctx)
The hypervisor takes a decision when a certain ctx was deleted

30.35.2.1.1.12 start_ctx

void(* sc_hypervisor_policy::start_ctx) (unsigned sched_ctx)
The hypervisor takes a decision when a certain ctx was registerd

30.35.2.1.1.13 init_worker

void(* sc_hypervisor_policy::init_worker) (int workerid, unsigned sched_ctx)
The hypervisor initializes values for the workers

30.35.3 Function Documentation

30.35.3.1 sc_hypervisor_init()

void* sc_hypervisor_init {
    struct sc_hypervisor_policy * policy
}Start the hypervisor with the given policy
30.35.3.2 sc_hypervisor_shutdown()

void sc_hypervisor_shutdown (  
                   void )

Shutdown the hypervisor. The hypervisor and all information concerning it is cleaned. There is no synchronization between this function and starpu_shutdown(). Thus, this should be called after starpu_shutdown(), because the performance counters will still need allocated callback functions.

30.35.3.3 sc_hypervisor_register_ctx()

void sc_hypervisor_register_ctx (  
        unsigned sched_ctx,  
        double total_flops )

Register the context to the hypervisor, and indicate the number of flops the context will execute (used for GFlops rate based strategy)

30.35.3.4 sc_hypervisor_unregister_ctx()

void sc_hypervisor_unregister_ctx (  
        unsigned sched_ctx )

Unregister a context from the hypervisor, and so exclude the context from the resizing process

30.35.3.5 sc_hypervisor_post_resize_request()

void sc_hypervisor_post_resize_request (  
        unsigned sched_ctx,  
        int task_tag )

Require resizing the context sched_ctx whenever a task tagged with the id task_tag finished executing

30.35.3.6 sc_hypervisor_resize_ctxs()

void sc_hypervisor_resize_ctxs (  
        unsigned * sched_ctxs,  
        int nsched_ctxs,  
        int * workers,  
        int nworkers )

Require reconsidering the distribution of ressources over the indicated scheduling contexts, i.e reevaluate the distribution of the resources and eventually resize if needed

30.35.3.7 sc_hypervisor_stop_resize()

void sc_hypervisor_stop_resize (  
        unsigned sched_ctx )

Do not allow the hypervisor to resize a context.

30.35.3.8 sc_hypervisor_start_resize()

void sc_hypervisor_start_resize (  
        unsigned sched_ctx )

Allow the hypervisor to resize a context if necessary.

30.35.3.9 sc_hypervisor_get_policy()

const char* sc_hypervisor_get_policy ( )

Return the name of the resizing policy used by the hypervisor

30.35.3.10 sc_hypervisor_add_workers_to_sched_ctx()

void sc_hypervisor_add_workers_to_sched_ctx (  
        int * workers_to_add,
## 30.35 Scheduling Context Hypervisor - Regular usage

Ask the hypervisor to add workers to a sched_ctx

### 30.35.3.11 sc_hypervisor_remove_workers_from_sched_ctx()

```c
void sc_hypervisor_remove_workers_from_sched_ctx ( 
    int∗ workers_to_remove, 
    unsigned nworkers_to_remove, 
    unsigned sched_ctx, 
    unsigned now )
```

Ask the hypervisor to remove workers from a sched_ctx

### 30.35.3.12 sc_hypervisor_move_workers()

```c
void sc_hypervisor_move_workers ( 
    unsigned sender_sched_ctx, 
    unsigned receiver_sched_ctx, 
    int∗ workers_to_move, 
    unsigned nworkers_to_move, 
    unsigned now )
```

Ask the hypervisor to move workers from one context to another

### 30.35.3.13 sc_hypervisor_size_ctxs()

```c
void sc_hypervisor_size_ctxs ( 
    unsigned∗ sched_ctxs, 
    int nsched_ctxs, 
    int∗ workers, 
    int nworkers )
```

Ask the hypervisor to choose a distribution of workers in the required contexts

### 30.35.3.14 sc_hypervisor_get_size_req()

```c
unsigned sc_hypervisor_get_size_req ( 
    unsigned∗∗ sched_ctxs, 
    int∗ nsched_ctxs, 
    int∗∗ workers, 
    int∗ nworkers )
```

Check if there are pending demands of resizing

### 30.35.3.15 sc_hypervisor_save_size_req()

```c
void sc_hypervisor_save_size_req ( 
    unsigned∗ sched_ctxs, 
    int nsched_ctxs, 
    int∗ workers, 
    int nworkers )
```

Save a demand of resizing

### 30.35.3.16 sc_hypervisor_free_size_req()

```c
void sc_hypervisor_free_size_req ( 
    void )
```

Clear the list of pending demands of resizing

### 30.35.3.17 sc_hypervisor_can_resize()

```c
unsigned sc_hypervisor_can_resize ( 
    unsigned sched_ctx )
```
Check out if a context can be resized

30.35.3.18    sc_hypervisor_set_type_of_task()

void sc_hypervisor_set_type_of_task (  
    struct starpu_codelet * cl,  
    unsigned sched_ctx,  
    uint32_t footprint,  
    size_t data_size )

Indicate the types of tasks a context will execute in order to better decide the sizing of ctxs

30.35.3.19    sc_hypervisor_update_diff_total_flops()

void sc_hypervisor_update_diff_total_flops (  
    unsigned sched_ctx,  
    double diff_total_flops )

Change dynamically the total number of flops of a context, move the deadline of the finishing time of the context

30.35.3.20    sc_hypervisor_update_diff_elapsed_flops()

void sc_hypervisor_update_diff_elapsed_flops (  
    unsigned sched_ctx,  
    double diff_task_flops )

Change dynamically the number of the elapsed flops in a context, modify the past in order to better compute the speed

30.35.3.21    sc_hypervisor_update_resize_interval()

void sc_hypervisor_update_resize_interval (  
    unsigned * sched_ctxs,  
    int nsched_ctxs,  
    int max_nworkers )

Update the min and max workers needed by each context

30.35.3.22    sc_hypervisor_get_ctxs_on_level()

void sc_hypervisor_get_ctxs_on_level (  
    unsigned ** sched_ctxs,  
    int * nsched_ctxs,  
    unsigned hierarchy_level,  
    unsigned father_sched_ctx_id )

Return a list of contexts that are on the same level in the hierarchy of contexts

30.35.3.23    sc_hypervisor_get_nhierarchy_levels()

unsigned sc_hypervisor_get_nhierarchy_levels (  
    void )

Returns the number of levels of ctxs registered to the hyp

30.35.3.24    sc_hypervisor_get_leaves()

void sc_hypervisor_get_leaves (  
    unsigned * sched_ctxs,  
    int nsched_ctxs,  
    unsigned * leaves,  
    int * nleaves )

Return the leaves ctxs from the list of ctxs
double sc_hypervisor_get_nready_flops_of_all_sons_of_sched_ctx (unsigned sched_ctx)

Return the nready flops of all ctxs below in hierarchy of sched_ctx.

30.35.4 Variable Documentation

30.35.4.1 act_hypervisor_mutex

starpu(pthread_mutex_t) act_hypervisor_mutex

synchronise the hypervisor when several workers try to update its information.

30.36 Scheduling Context Hypervisor - Linear Programming

Functions

- double sc_hypervisor_lp_get_nworkers_per_ctx (int nsched_ctxs, int ntypes_of_workers, double res[nsched_ctxs][ntypes_of_workers], int total_nw[ntypes_of_workers], struct types_of_workers *tw, unsigned *in_sched_ctxs)
- double sc_hypervisor_lp_get_tmax (int nw, int *workers)
- void sc_hypervisor_lp_round_double_to_int (int ns, int nw, double res[ns][nw], int res_rounded[ns][nw])
- void sc_hypervisor_lp_redistribute_resources_in_ctxs (int ns, int nw, int res_rounded[ns][nw], double res[ns][nw], unsigned *sched_ctxs, struct types_of_workers *tw)
- void sc_hypervisor_lp_distribute_resources_in_ctxs (int ns, int nw, int res_rounded[ns][nw], double res[ns][nw], unsigned *sched_ctxs, struct types_of_workers *tw)
- void sc_hypervisor_lp_place_resources_in_ctx (int ns, int nw, double w_in_s[ns][nw], unsigned *sched_ctxs, int *workers, unsigned do_size, struct types_of_workers *tw)
- void sc_hypervisor_lp_share_remaining_resources (int ns, unsigned *sched_ctxs, int nworkers, int *workers)
- double sc_hypervisor_lp_find_tmax (double t1, double t2)
- unsigned sc_hypervisor_lp_execute_dichotomy (int ns, int nw, double w_in_s[ns][nw], unsigned solve_lp_integer, void *specific_data, double tmin, double tmax, double smallest_tmax, double(*lp_estimated_distribution_func)(int ns, int nw, double draft_w_in_s[ns][nw], unsigned is_integer, double tmax, void *specific_data))
- double sc_hypervisor_lp_simulate_distrib_flops (int nsched_ctxs, int ntypes_of_workers, double speed[nsched_ctxs][ntypes_of_workers], double flops[nsched_ctxs], double res[nsched_ctxs][ntypes_of_workers], int total_nw[ntypes_of_workers], unsigned sched_ctxs[nsched_ctxs], double vmax)
- double sc_hypervisor_lp_simulate_distrib_tasks (int ns, int nw, int nt, double w_in_s[ns][nw], double tasks[nw][nt], double times[nw][nt], unsigned is_integer, double tmax, unsigned *in_sched_ctxs, struct sc_hypervisor_policy_task_pool *tmp_task_pools)
- double sc_hypervisor_lp_simulate_distrib_flops_on_sample (int ns, int nw, double final_w_in_s[ns][nw], unsigned is_integer, double tmax, double **speed, double flops[ns], double **final_flops_on_w)

30.36.1 Detailed Description

30.36.2 Function Documentation

30.36.2.1 sc_hypervisor_lp_get_nworkers_per_ctx()
int total_nw[ntypes_of_workers],
struct types_of_workers * tw,
unsigned * in_sched_ctxs )

return tmax, and compute in table res the nr of workers needed by each context st the system ends up in the
smallest tma

30.36.2.2 sc_hypervisor_lp_get_tmax()

double sc_hypervisor_lp_get_tmax (  
    int nw,  
    int * workers )

return tmax of the system

30.36.2.3 sc_hypervisor_lp_round_double_to_int()

void sc_hypervisor_lp_round_double_to_int (  
    int ns,  
    int nw,  
    double res[ns][nw],  
    int res_rounded[ns][nw] )

the linear programme determines a rational number of resources for each ctx, we round them depending on the
type of resource

30.36.2.4 sc_hypervisor_lp_redistribute_resources_in_ctxs()

void sc_hypervisor_lp_redistribute_resources_in_ctxs (  
    int ns,  
    int nw,  
    int res_rounded[ns][nw],  
    double res[ns][nw],  
    unsigned * sched_ctxs,  
    struct types_of_workers * tw )

redistribute the resource in contexts by assigning the first x available resources to each one

30.36.2.5 sc_hypervisor_lp_distribute_resources_in_ctxs()

void sc_hypervisor_lp_distribute_resources_in_ctxs (  
    unsigned * sched_ctxs,  
    int ns,  
    int nw,  
    int res_rounded[ns][nw],  
    double res[ns][nw],  
    int * workers,  
    int nworkers,  
    struct types_of_workers * tw )

make the first distribution of resource in contexts by assigning the first x available resources to each one

30.36.2.6 sc_hypervisor_lp_distribute_floating_no_resources_in_ctxs()

void sc_hypervisor_lp_distribute_floating_no_resources_in_ctxs (  
    unsigned * sched_ctxs,  
    int ns,  
    int nw,  
    double res[ns][nw],  
    int * workers,  
    int nworkers,  
    struct types_of_workers * tw )

make the first distribution of resource in contexts by assigning the first x available resources to each one, share
not integer no of workers
30.36.2.7 sc_hypervisor_lp_place_resources_in_ctx()

```c
void sc_hypervisor_lp_place_resources_in_ctx {
    int ns,
    int nw,
    double w_in_s[ns][nw],
    unsigned * sched_ctxs,
    int * workers,
    unsigned do_size,
    struct types_of_workers * tw )
```

place resources in contexts depending on whether they already have workers or not.

30.36.2.8 sc_hypervisor_lp_share_remaining_resources()

```c
void sc_hypervisor_lp_share_remaining_resources {
    int ns,
    unsigned * sched_ctxs,
    int nworkers,
    int * workers )
```

not used resources are shared between all contexts.

30.36.2.9 sc_hypervisor_lp_find_tmax()

```c
double sc_hypervisor_lp_find_tmax {
    double t1,
    double t2 )
```
dichotomy between t1 & t2.

30.36.2.10 sc_hypervisor_lp_execute_dichotomy()

```c
unsigned sc_hypervisor_lp_execute_dichotomy {
    int ns,
    int nw,
    double w_in_s[ns][nw],
    unsigned solve_lp_integer,
    void * specific_data,
    double tmin,
    double tmax,
    double smallest_tmax,
    double(*)(int ns, int nw, double draft_w_in_s[ns][nw], unsigned is_integer, double tmax, void *specific_data) lp_estimated_distrib_func )
```
execute the lp through dichotomy.

30.36.2.11 sc_hypervisor_lp_simulate_distrib_flops()

```c
double sc_hypervisor_lp_simulate_distrib_flops {
    int nsched_ctxs,
    int ntypes_of_workers,
    double speed[nsched_ctxs][ntypes_of_workers],
    double flops[nsched_ctxs],
    double res[nsched_ctxs][ntypes_of_workers],
    int total_nw[ntypes_of_workers],
    unsigned sched_ctxs[nsched_ctxs],
    double vmax )
```
linear program that returns 1/tmax, and computes in table res the nr of workers needed by each context st the system ends up in the smallest tmax.
30.36.12  \textit{sc\_hypervisor\_lp\_simulate\_distrib\_tasks()}

\begin{verbatim}
double sc_hypervisor_lp_simulate_distrib_tasks ( 
  int ns, 
  int nw, 
  int nt, 
  double w_in_s[ns][nw], 
  double tasks[nw][nt], 
  double times[nw][nt], 
  unsigned in_integer, 
  double tmax, 
  unsigned * in_sched_ctxs, 
  struct sc_hypervisor_policy_task_pool * tmp_task_pools )
\end{verbatim}

linear program that simulates a distribution of tasks that minimises the execution time of the tasks in the pool

30.36.13  \textit{sc\_hypervisor\_lp\_simulate\_distrib\_flops\_on\_sample()}

\begin{verbatim}
double sc_hypervisor_lp_simulate_distrib_flops_on_sample ( 
  int ns, 
  int nw, 
  double final_w_in_s[ns][nw], 
  unsigned in_integer, 
  double tmax, 
  double ** speed, 
  double flops[ns], 
  double ** final_flops_on_w )
\end{verbatim}

linear program that simulates a distribution of flops over the workers on particular sample of the execution of the application such that the entire sample would finish in a minimum amount of time

30.37  Modularized Scheduler Interface

\textbf{Data Structures}

- struct starpu_sched_component
- struct starpu_sched_tree
- struct starpu_sched_component_fifo_data
- struct starpu_sched_component_prio_data
- struct starpu_sched_component_mct_data
- struct starpu_sched_component_perfmodel_select_data
- struct starpu_sched_component_specs

\textbf{Macros}

- #define STARPU_SCHED_COMPONENT_IS_HOMOGENEOUS(component)
- #define STARPU_SCHED_COMPONENT_IS_SINGLE_MEMORY_NODE(component)
- #define STARPU_COMPONENT_MUTEX_LOCK(m)
- #define STARPU_COMPONENT_MUTEX_TRYLOCK(m)
- #define STARPU_COMPONENT_MUTEX_UNLOCK(m)

\textbf{Enumerations}

- enum starpu_sched_component_properties { STARPU_SCHED_COMPONENT_HOMOGENEOUS, STARPU_SCHED_COMPONENT_SINGLE_MEMORY_NODE }

\textbf{Functions}

- void starpu_initialize_prio_center_policy (unsigned sched_ctx_id)
Scheduling Tree API

- struct starpu_sched_tree * starpu_sched_tree_create (unsigned sched_ctx_id) STARPU_ATTRIBUTE_MALLOC
- void starpu_sched_tree_destroy (struct starpu_sched_tree *tree)
- struct starpu_sched_tree * starpu_sched_tree_get (unsigned sched_ctx_id)
- void starpu_sched_tree_update_workers (struct starpu_sched_tree *t)
- int starpu_sched_tree_push_task (struct starpu_task *task)
- struct starpu_task * starpu_sched_tree_pop_task (unsigned sched_ctx)
- int starpu_sched_component_push_task (struct starpu_sched_component *from, struct starpu_sched_component *to, struct starpu_task *task)
- struct starpu_task * starpu_sched_component_pull_task (struct starpu_sched_component *from, struct starpu_sched_component *to)
- struct starpu_task * starpu_sched_component_pump_to (struct starpu_sched_component *component, struct starpu_sched_component *to)
- int starpu_sched_component_pump_downstream (struct starpu_sched_component *component, int *success)
- void starpu_sched_component_send_can_push_to_parents (struct starpu_sched_component *component)
- void starpu_sched_tree_add_workers (unsigned sched_ctx_id, int *workerids, unsigned nworkers)
- void starpu_sched_tree_remove_workers (unsigned sched_ctx_id, int *workerids, unsigned nworkers)
- void starpu_sched_component_connect (struct starpu_sched_component *parent, struct starpu_sched_component *child)

Generic Scheduling Component API

- typedef struct starpu_sched_component *(*starpu_sched_component_create_t) (struct starpu_sched_tree *tree, void *data)
- struct starpu_sched_component * starpu_sched_component_create (struct starpu_sched_tree *tree, const char *name) STARPU_ATTRIBUTE_MALLOC
- void starpu_sched_component_destroy (struct starpu_sched_component *component)
- void starpu_sched_component_destroy_rec (struct starpu_sched_component *component)
- void starpu_sched_component_add_child (struct starpu_sched_component *component, struct starpu_sched_component *child)
- int starpu_sched_component_can_execute_task (struct starpu_sched_component *component, struct starpu_task *task)
- int STARPU_WARN_UNUSED_RESULT starpu_sched_component_execute_preds (struct starpu_sched_component *component, struct starpu_task *task, double *length)
- double starpu_sched_component_transfer_length (struct starpu_sched_component *component, struct starpu_task *task)
- void starpu_sched_component_prefetch_on_node (struct starpu_sched_component *component, struct starpu_task *task)

Worker Component API

- struct starpu_sched_component * starpu_sched_component_worker_get (unsigned sched_ctx, int workerid)
- struct starpu_sched_component * starpu_sched_component_worker_new (unsigned sched_ctx, int workerid)
- struct starpu_sched_component * starpu_sched_component_parallel_worker_create (struct starpu_sched_tree *tree, unsigned nworkers, unsigned *workers)
- int starpu_sched_component_worker_get_workerid (struct starpu_sched_component *worker_component)
- int starpu_sched_component_is_worker (struct starpu_sched_component *component)
- int starpu_sched_component_is_simple_worker (struct starpu_sched_component *component)
- int starpu_sched_component_is_combined_worker (struct starpu_sched_component *component)
- void starpu_sched_component_worker_pre_exec_hook (struct starpu_task *task, unsigned sched_ctx_id)
- void starpu_sched_component_worker_post_exec_hook (struct starpu_task *task, unsigned sched_ctx_id)
Flow-control Fifo Component API

- int starpu_sched_component_can_push (struct starpu_sched_component *component, struct starpu_sched_component *to)
- int starpu_sched_component_can_pull (struct starpu_sched_component *component)
- int starpu_sched_component_can_pull_all (struct starpu_sched_component *component)
- double starpu_sched_component_estimated_load (struct starpu_sched_component *component)
- double starpu_sched_component_estimated_end_min (struct starpu_sched_component *component, double exp_len)
- double starpu_sched_component_estimated_end_average (struct starpu_sched_component *component)
- struct starpu_sched_component * starpu_sched_component_fifo_create (struct starpu_sched_tree *tree, struct starpu_sched_component_fifo_data *fifo_data) STARPU_ATTRIBUTE_MALLOC
- int starpu_sched_component_is_fifo (struct starpu_sched_component *component)

Flow-control Prio Component API

- struct starpu_sched_component * starpu_sched_component_prio_create (struct starpu_sched_tree *tree, struct starpu_sched_component_prio_data *prio_data) STARPU_ATTRIBUTE_MALLOC
- int starpu_sched_component_is_prio (struct starpu_sched_component *component)

Resource-mapping Work-Stealing Component API

- struct starpu_sched_component * starpu_sched_component_work_stealing_create (struct starpu_sched_tree *tree, void *arg) STARPU_ATTRIBUTE_MALLOC
- int starpu_sched_component_is_work_stealing (struct starpu_sched_component *component)
- int starpu_sched_tree_work_stealing_push_task (struct starpu_task *task)

Resource-mapping Random Component API

- struct starpu_sched_component * starpu_sched_component_random_create (struct starpu_sched_tree *tree, void *arg) STARPU_ATTRIBUTE_MALLOC
- int starpu_sched_component_is_random (struct starpu_sched_component *)

Resource-mapping Eager Component API

- struct starpu_sched_component * starpu_sched_component_eager_create (struct starpu_sched_tree *tree, void *arg) STARPU_ATTRIBUTE_MALLOC
- int starpu_sched_component_is_eager (struct starpu_sched_component *)

Resource-mapping Eager-Calibration Component API

- struct starpu_sched_component * starpu_sched_component_eager_calibration_create (struct starpu_sched_tree *tree, void *arg) STARPU_ATTRIBUTE_MALLOC
- int starpu_sched_component_is_eager_calibration (struct starpu_sched_component *)

Resource-mapping MCT Component API

- struct starpu_sched_component * starpu_sched_component_mct_create (struct starpu_sched_tree *tree, struct starpu_sched_component_mct_data *mct_data) STARPU_ATTRIBUTE_MALLOC
- int starpu_sched_component_is_mct (struct starpu_sched_component *component)

Resource-mapping Heft Component API

- struct starpu_sched_component * starpu_sched_component_heft_create (struct starpu_sched_tree *tree, struct starpu_sched_component_mct_data *mct_data) STARPU_ATTRIBUTE_MALLOC
- int starpu_sched_component_is_heft (struct starpu_sched_component *component)
Special-purpose Best Implementation Component API

- struct starpu_sched_component * starpu_sched_component_best_implementation_create (struct starpu_sched_tree *tree, void *arg) STARPU_ATTRIBUTE_MALLOC

Special-purpose Perfmodel Select Component API

- struct starpu_sched_component * starpu_sched_component_perfmodel_select_create (struct starpu_sched_tree *tree, struct starpu_sched_component_perfmodel_select_data *perfmodel_select_data) STARPU_ATTRIBUTE_MALLOC
- int starpu_sched_component_is_perfmodel_select (struct starpu_sched_component *component)

Recipe Component API

- struct starpu_sched_component_composed_recipe * starpu_sched_component_composed_recipe_create (void) STARPU_ATTRIBUTE_MALLOC
- struct starpu_sched_component_composed_recipe * starpu_sched_component_composed_recipe_create_singleton (struct starpu_sched_component *(*create_component)(struct starpu_sched_tree *tree, void *arg), void *arg) STARPU_ATTRIBUTE_MALLOC
- void starpu_sched_component_composed_recipe_add (struct starpu_sched_component_composed_recipe *recipe, struct starpu_sched_component *(*create_component)(struct starpu_sched_tree *tree, void *arg), void *arg)
- void starpu_sched_component_composed_recipe_destroy (struct starpu_sched_component_composed_recipe *)
- struct starpu_sched_component * starpu_sched_component_composed_component_create (struct starpu_sched_tree *tree, struct starpu_sched_component_composed_recipe *recipe) STARPU_ATTRIBUTE_MALLOC
- struct starpu_sched_tree * starpu_sched_component_make_scheduler (unsigned sched_ctx_id, struct starpu_sched_component_specs s)

Basic API

- void starpu_sched_component_initialize_simple_scheduler (starpu_sched_component_create_t create_decision_component, void *data, unsigned flags, unsigned sched_ctx_id)
- #define STARPU_SCHED_SIMPLE_DECIDE_MASK
- #define STARPU_SCHED_SIMPLE_DECIDE_WORKERS
- #define STARPU_SCHED_SIMPLE_DECIDE_MEMNODES
- #define STARPU_SCHED_SIMPLE_DECIDE_ARCHS
- #define STARPU_SCHED_SIMPLE_PERFMODEL
- #define STARPU_SCHED_SIMPLE_IMPL
- #define STARPU_SCHED_SIMPLE_FIFO_ABOVE
- #define STARPU_SCHED_SIMPLE_FIFO_ABOVE_PRIO
- #define STARPU_SCHED_SIMPLE_FIFOS_BELOW
- #define STARPU_SCHED_SIMPLE_FIFOS_BELOW_PRIO
- #define STARPU_SCHED_SIMPLE_WS_BELOW
- #define STARPU_SCHED_SIMPLE_COMBINED_WORKERS

30.37.1 Detailed Description

30.37.2 Data Structure Documentation

30.37.2.1 struct starpu_sched_component

Structure for a scheduler module. A scheduler is a tree-like structure of them, some parts of scheduler can be shared by several contexts to perform some local optimisations, so, for all components, a list of parent is defined by sched_ctx_id. They embed there specialised method in a pseudo object-style, so calls are like component->push_task(component,task)
Data Fields

- struct starpu_sched_tree * tree
- struct starpu_bitmap * workers
- struct starpu_bitmap * workers_in_ctx
- void * data
- char * name
- unsigned nchildren
- struct starpu_sched_component ** children
- unsigned nparents
- struct starpu_sched_component ** parents
- void(* add_child)(struct starpu_sched_component *component, struct starpu_sched_component *child)
- void(* remove_child)(struct starpu_sched_component *component, struct starpu_sched_component *child)
- void(* add_parent)(struct starpu_sched_component *component, struct starpu_sched_component *parent)
- void(* remove_parent)(struct starpu_sched_component *component, struct starpu_sched_component *parent)
- int(* push_task)(struct starpu_sched_component *, struct starpu_task *)
- struct starpu_task *(* pull_task)(struct starpu_sched_component *from, struct starpu_sched_component *to)
- int(* can_push)(struct starpu_sched_component *from, struct starpu_sched_component *to)
- int(* can_pull)(struct starpu_sched_component *component)
- int(* notify)(struct starpu_sched_component *component, int message_ID, void *arg)
- double(* estimated_load)(struct starpu_sched_component *component)
- double(* estimated_end)(struct starpu_sched_component *component)
- void(* deinit_data)(struct starpu_sched_component *component)
- void(* notify_change_workers)(struct starpu_sched_component *component)
- int properties
- hwloc_obj_t obj

30.37.2.1 Field Documentation

30.37.2.1.1 tree

struct starpu_sched_tree* starpu_sched_component::tree
The tree containing the component

30.37.2.1.2 workers

struct starpu_bitmap* starpu_sched_component::workers
set of underlying workers

30.37.2.1.3 workers_in_ctx

struct starpu_bitmap* starpu_sched_component::workers_in_ctx
subset of starpu_sched_component::workers that is currently available in the context
The push method should take this value into account, it is set with: component->workers UNION tree->workers UNION component->child[i]>
>workers_in_ctx iff exist x such as component->children[i]->parents[x] == component

30.37.2.1.4 data

void* starpu_sched_component::data
private data

30.37.2.1.5 nchildren

unsigned starpu_sched_component::nchildren
number of components's children

30.37.2.1.6 children

struct starpu_sched_component** starpu_sched_component::children
vector of component's children
30.37.2.1.7 nparents

unsigned starpu_sched_component::nparents
number of component's parents

30.37.2.1.8 parents

struct starpu_sched_component** starpu_sched_component::parents
vector of component's parents

30.37.2.1.9 add_child

void(* starpu_sched_component::add_child) (struct starpu_sched_component *component, struct starpu_sched_component *child)
add a child to component

30.37.2.1.10 remove_child

void(* starpu_sched_component::remove_child) (struct starpu_sched_component *component, struct starpu_sched_component *child)
remove a child from component

30.37.2.1.11 push_task

int(* starpu_sched_component::push_task) (struct starpu_sched_component *, struct starpu_task *)
push a task in the scheduler module. This function is called to push a task on component subtree, this can either perform a recursive call on a child or store the task in the component, then it will be returned by a further pull_task call. The caller must ensure that component is able to execute task. This method must either return 0 if the task was properly stored or passed over to a child component, or return a value different from 0 if the task could not be consumed (e.g. the queue is full).

30.37.2.1.12 pull_task

struct starpu_task *(* starpu_sched_component::pull_task) (struct starpu_sched_component *from, struct starpu_sched_component *to)
pop a task from the scheduler module. This function is called by workers to get a task from their parents. This function should first return a locally stored task or perform a recursive call on the parents. the task returned by this function should be executable by the caller

30.37.2.1.13 can_push

int(* starpu_sched_component::can_push) (struct starpu_sched_component *from, struct starpu_sched_component *to)
This function is called by a component which implements a queue, allowing it to signify to its parents that an empty slot is available in its queue. This should return 1 if some tasks could be pushed. The basic implementation of this function is a recursive call to its parents, the user has to specify a personally-made function to catch those calls.

30.37.2.1.14 can_pull

int(* starpu_sched_component::can_pull) (struct starpu_sched_component *component)
This function allow a component to wake up a worker. It is currently called by component which implements a queue, to signify to its children that a task have been pushed in its local queue, and is available to be popped by a worker, for example. This should return 1 if some some container or worker could (or will) pull some tasks. The basic implementation of this function is a recursive call to its children, until at least one worker have been woken up.

30.37.2.1.15 estimated_load

double(* starpu_sched_component::estimated_load) (struct starpu_sched_component *component)
heuristic to compute load of scheduler module. Basically the number of tasks divided by the sum of relatives speedup of workers available in context. estimated_load(component) = sum(estimated_load(component_children)) + nb_local_tasks / average(relative_speedup(underlying_worker))

30.37.2.1.16 estimated_end

double(* starpu_sched_component::estimated_end) (struct starpu_sched_component *component)
return the time when a worker will enter in starvation. This function is relevant only if the task->predicted member has been set.
30.37.2.1.17 deinit_data

```c
void(* starpu_sched_component::deinit_data) (struct starpu_sched_component *component)
```
called by starpu_sched_component_destroy. Should free data allocated during creation

30.37.2.1.18 notify_change_workers

```c
void(* starpu_sched_component::notify_change_workers) (struct starpu_sched_component *component)
```
this function is called for each component when workers are added or removed from a context

30.37.2.1.19 obj

```c
hwloc_obj_t starpu_sched_component::obj
```

the hwloc object associated to scheduler module. points to the part of topology that is binded to this component, eg: a numa node for a ws component that would balance load between underlying sockets

30.37.2.2 struct starpu_sched_tree

The actual scheduler

### Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>struct starpu_sched_component *</td>
<td>root</td>
<td>entry module of the scheduler</td>
</tr>
<tr>
<td>struct starpu_bitmap *</td>
<td>workers</td>
<td>set of workers available in this context, this value is used to mask workers in modules</td>
</tr>
<tr>
<td>unsigned</td>
<td>sched_ctx_id</td>
<td>context id of the scheduler</td>
</tr>
<tr>
<td>starpu pthread_mutex_t</td>
<td>lock</td>
<td>lock used to protect the scheduler, it is taken in read mode pushing a task and in write mode for adding or removing workers</td>
</tr>
</tbody>
</table>

30.37.2.3 struct starpu_sched_component_fifo_data

### Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>unsigned</td>
<td>ntasks_threshold</td>
<td></td>
</tr>
<tr>
<td>double</td>
<td>exp_len_threshold</td>
<td></td>
</tr>
</tbody>
</table>

30.37.2.4 struct starpu_sched_component_prio_data

### Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>unsigned</td>
<td>ntasks_threshold</td>
<td></td>
</tr>
<tr>
<td>double</td>
<td>exp_len_threshold</td>
<td></td>
</tr>
</tbody>
</table>

30.37.2.5 struct starpu_sched_component_mct_data

### Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>double</td>
<td>alpha</td>
<td></td>
</tr>
<tr>
<td>double</td>
<td>beta</td>
<td></td>
</tr>
<tr>
<td>double</td>
<td>_gamma</td>
<td></td>
</tr>
<tr>
<td>double</td>
<td>idle_power</td>
<td></td>
</tr>
</tbody>
</table>

30.37.2.6 struct starpu_sched_component_perfmodel_select_data
### Data Fields

<table>
<thead>
<tr>
<th>struct starpu_sched_component *</th>
<th>calibrator_component</th>
</tr>
</thead>
<tbody>
<tr>
<td>struct starpu_sched_component *</td>
<td>no_perfmodel_component</td>
</tr>
<tr>
<td>struct starpu_sched_component *</td>
<td>perfmodel_component</td>
</tr>
</tbody>
</table>

#### 30.37.2.7 struct starpu_sched_component_specs

Define how build a scheduler according to topology. Each level (except for hwloc_machine_composed_sched_component) can be NULL, then the level is just skipped. Bugs everywhere, do not rely on.

#### Data Fields

- struct starpu_sched_component_composed_recipe * hwloc_machine_composed_sched_component
- struct starpu_sched_component_composed_recipe * hwloc_component_composed_sched_component
- struct starpu_sched_component_composed_recipe * hwloc_socket_composed_sched_component
- struct starpu_sched_component_composed_recipe * hwloc_cache_composed_sched_component
- struct starpu_sched_component_composed_recipe * (enum starpu_worker_archtype archtype)
  - int mix_heterogeneous_workers

#### 30.37.2.7.1 Field Documentation

##### 30.37.2.7.1.1 hwloc_machine_composed_sched_component

The composed component to put on the top of the scheduler this member must not be NULL as it is the root of the topology.

##### 30.37.2.7.1.2 hwloc_component_composed_sched_component

The composed component to put for each memory component.

##### 30.37.2.7.1.3 hwloc_socket_composed_sched_component

The composed component to put for each socket.

##### 30.37.2.7.1.4 hwloc_cache_composed_sched_component

The composed component to put for each cache.

##### 30.37.2.7.1.5 worker_composed_sched_component

A function that return a starpu_sched_component_composed_recipe to put on top of a worker of type archtype. NULL is a valid return value, then no component will be added on top.

##### 30.37.2.7.1.6 mix_heterogeneous_workers

This flag is a dirty hack because of the poor expressivity of this interface. As example, if you want to build a heft component with a fifo component per numa component, and you also have GPUs, if this flag is set, GPUs will share those fifos. If this flag is not set, a new fifo will be built for each of them (if they have the same starpu_perf_arch and the same numa component it will be shared. It indicates if heterogenous workers should be brothers or cousins, as example, if a gpu and a cpu should share or not there numa node.
30.37.3 Macro Definition Documentation

30.37.3.1 STARPU_SCHED_COMPONENT_IS_HOMOGENEOUS

#define STARPU_SCHED_COMPONENT_IS_HOMOGENEOUS(component)
indicate if component is homogeneous

30.37.3.2 STARPU_SCHED_COMPONENT_IS_SINGLE_MEMORY_NODE

#define STARPU_SCHED_COMPONENT_IS_SINGLE_MEMORY_NODE(component)
indicate if all workers have the same memory component

30.37.3.3 STARPU_SCHED_SIMPLE_DECIDE_WORKERS

#define STARPU_SCHED_SIMPLE_DECIDE_WORKERS
Request to create downstream queues per worker, i.e. the scheduling decision-making component will choose
exactly which workers tasks should got to.

30.37.3.4 STARPU_SCHED_SIMPLE_DECIDE_MEMNODES

#define STARPU_SCHED_SIMPLE_DECIDE_MEMNODES
Request to create downstream queues per memory nodes, i.e. the scheduling decision-making component will
choose which memory node tasks will go to.

30.37.3.5 STARPU_SCHED_SIMPLE_DECIDE_ARCHS

#define STARPU_SCHED_SIMPLE_DECIDE_ARCHS
Request to create downstream queues per computation arch, i.e. the scheduling decision-making component will
choose whether tasks go to CPUs, or CUDA, or OpenCL, etc.

30.37.3.6 STARPU_SCHED_SIMPLE_PERFMODEL

#define STARPU_SCHED_SIMPLE_PERFMODEL
Request to add a perfmodel selector above the scheduling decision-making component. That way, only tasks with
a calibrated performance model will be given to the component, other tasks will go to an eager branch that will
distributed tasks so that their performance models will get calibrated. In other words, this is needed when using a
component which needs performance models for tasks.

30.37.3.7 STARPU_SCHED_SIMPLE_IMPL

#define STARPU_SCHED_SIMPLE_IMPL
Request that a component be added just above workers, that chooses the best task implementation.

30.37.3.8 STARPU_SCHED_SIMPLE_FIFO_ABOVE

#define STARPU_SCHED_SIMPLE_FIFO_ABOVE
Request to create a fifo above the scheduling decision-making component, otherwise tasks will be pushed directly
to the component.
This is useful to store tasks if there is a fifo below which limits the number of tasks to be schedul in advance. The
scheduling decision-making component can also store tasks itself, in which case this flag is not useful.

30.37.3.9 STARPU_SCHED_SIMPLE_FIFO_ABOVE_PRIO

#define STARPU_SCHED_SIMPLE_FIFO_ABOVE_PRIO
Request that the fifo above be sorted by priorities
30.37.3.10 STARPU_SCHED_SIMPLE_FIFOS_BELOW

#define STARPU_SCHED_SIMPLE_FIFOS_BELOW
Request to create fifos below the scheduling decision-making component, otherwise tasks will be pulled directly from workers.
This is useful to be able to schedule a (tunable) small number of tasks in advance only.

30.37.3.11 STARPU_SCHED_SIMPLE_FIFOS_BELOW_PRIO

#define STARPU_SCHED_SIMPLE_FIFOS_BELOW_PRIO
Request that the fifos below be sorted by priorities

30.37.3.12 STARPU_SCHED_SIMPLE_WS_BELOW

#define STARPU_SCHED_SIMPLE_WS_BELOW
Request that work between workers using the same fifo below be distributed using a work stealing component.

30.37.3.13 STARPU_SCHED_SIMPLE_COMBINED_WORKERS

#define STARPU_SCHED_SIMPLE_COMBINED_WORKERS
Request to not only choose between simple workers, but also choose between combined workers.

30.37.4 Enumeration Type Documentation

30.37.4.1 starpu_sched_component_properties

enum starpu_sched_component_properties
flags for starpu_sched_component::properties

<table>
<thead>
<tr>
<th>Enumerator</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>STARPU_SCHED_COMPONENT_HOMOGENEOUS</td>
<td>indicate that all workers have the same starpu_worker_archtype</td>
</tr>
<tr>
<td>STARPU_SCHED_COMPONENT_SINGLE_MEMORY_NODE</td>
<td>indicate that all workers have the same memory component</td>
</tr>
</tbody>
</table>

30.37.5 Function Documentation

30.37.5.1 starpu_sched_tree_create()

struct starpu_sched_tree* starpu_sched_tree_create (unsigned sched_ctx_id)
create a empty initialized starpu_sched_tree

30.37.5.2 starpu_sched_tree_destroy()

void starpu_sched_tree_destroy (struct starpu_sched_tree * tree)
destroy tree and free all non shared component in it.

30.37.5.3 starpu_sched_tree_update_workers()

void starpu_sched_tree_update_workers (struct starpu_sched_tree * t)
recursively set all starpu_sched_component::workers, do not take into account shared parts (except workers).
30.37.5.4 starpu_sched_tree_update_workers_in_ctx()

void starpu_sched_tree_update_workers_in_ctx (
    struct starpu_sched_tree * t )
recursively set all starpu_sched_component::workers_in_ctx, do not take into account shared parts (except workers)

30.37.5.5 starpu_sched_tree_push_task()

int starpu_sched_tree_push_task ( 
    struct starpu_task * task )
compatibility with starpu_sched_policy interface

30.37.5.6 starpu_sched_tree_pop_task()

struct starpu_task* starpu_sched_tree_pop_task ( 
    unsigned sched_ctx )
compatibility with starpu_sched_policy interface

30.37.5.7 starpu_sched_component_push_task()

int starpu_sched_component_push_task ( 
    struct starpu_sched_component * from, 
    struct starpu_sched_component * to, 
    struct starpu_task * task )
Push a task to a component. This is a helper for component->push_task(component, task) plus tracing.

30.37.5.8 starpu_sched_component_pull_task()

struct starpu_task* starpu_sched_component_pull_task ( 
    struct starpu_sched_component * from, 
    struct starpu_sched_component * to )
Pull a task from a component. This is a helper for component->pull_task(component) plus tracing.

30.37.5.9 starpu_sched_tree_add_workers()

void starpu_sched_tree_add_workers ( 
    unsigned sched_ctx_id, 
    int * workerids, 
    unsigned nworkers )
compatibility with starpu_sched_policy interface

30.37.5.10 starpu_sched_tree_remove_workers()

void starpu_sched_tree_remove_workers ( 
    unsigned sched_ctx_id, 
    int * workerids, 
    unsigned nworkers )
compatibility with starpu_sched_policy interface

30.37.5.11 starpu_sched_component_connect()

void starpu_sched_component_connect ( 
    struct starpu_sched_component * parent, 
    struct starpu_sched_component * child )
Attach component child to parent parent. Some component may accept only one child, others accept several (e.g. MCT)
30.37.5.12  
```
starpu_sched_component_create()
```

```c
struct starpu_sched_component* starpu_sched_component_create (  
struct starpu_sched_tree  * tree,
const char  * name )  
```

allocate and initialize component field with defaults values : .pop_task make recursive call on father .estimated←
_load compute relative speedup and tasks in sub tree .estimated_end return the minimum of recursive call on children .add_child is starpu_sched_component_add_child .remove_child is starpu_sched_component_remove←
child .notify_change_workers does nothing .deinit_data does nothing

30.37.5.13  
```
starpu_sched_component_destroy()
```

```c
void starpu_sched_component_destroy (  
struct starpu_sched_component  * component  
```

free data allocated by starpu_sched_component_create and call component->deinit_data(component) set to NULL

the member starpu_sched_component::fathers[sched_ctx_id] of all child if its equal to component

30.37.5.14  
```
starpu_sched_component_destroy_rec()
```

```c
void starpu_sched_component_destroy_rec (  
struct starpu_sched_component  * component  
```

recursively destroy non shared parts of a component ’s tree

30.37.5.15  
```
starpu_sched_component_can_execute_task()
```

```c
int starpu_sched_component_can_execute_task (  
struct starpu_sched_component  * component,
struct starpu_task  * task  
```

return true iff component can execute task, this function take into account the workers available in the scheduling context

30.37.5.16  
```
starpu_sched_component_execute_preds()
```

```c
int STARPU_WARN_UNUSED_RESULT starpu_sched_component_execute_preds (  
struct starpu_sched_component  * component,
struct starpu_task  * task,
double  * length  
```

return a non NULL value if component can execute task. write the execution prediction length for the best implementation of the best worker available and write this at length address. this result is more relevant if starpu_sched_component::is_homogeneous is non NULL. if a worker need to be calibrated for an implementation, nan is set to length.

30.37.5.17  
```
starpu_sched_component_transfer_length()
```

```c
double starpu_sched_component_transfer_length (  
struct starpu_sched_component  * component,
struct starpu_task  * task  
```

return the average time to transfer task data to underlying component workers.

30.37.5.18  
```
starpu_sched_component_worker_get()
```

```c
struct starpu_sched_component* starpu_sched_component_worker_get (  
unsigned  sched_ctx,
int  workerid  
```

return the struct starpu_sched_component corresponding to workerid. Undefined if workerid is not a valid workerid
30.37.5.19 starpu_sched_component_parallel_worker_create()

```c
struct starpu_sched_component* starpu_sched_component_parallel_worker_create (  
    struct starpu_sched_tree * tree,  
    unsigned nworkers,  
    unsigned * workers )
```

Create a combined worker that pushes tasks in parallel to workers `workers` (size `nworkers`).

30.37.5.20 starpu_sched_component_worker_get_workerid()

```c
int starpu_sched_component_worker_get_workerid (  
    struct starpu_sched_component * worker_component )
```

return the workerid of `worker_component`, undefined if `starpu_sched_component_is_worker(worker←  
    component) == 0`

30.37.5.21 starpu_sched_component_is_worker()

```c
int starpu_sched_component_is_worker (  
    struct starpu_sched_component * component )
```

return true iff `component` is a worker component

30.37.5.22 starpu_sched_component_is_simple_worker()

```c
int starpu_sched_component_is_simple_worker (  
    struct starpu_sched_component * component )
```

return true iff `component` is a simple worker component

30.37.5.23 starpu_sched_component_is_combined_worker()

```c
int starpu_sched_component_is_combined_worker (  
    struct starpu_sched_component * component )
```

return true iff `component` is a combined worker component

30.37.5.24 starpu_sched_component_worker_pre_exec_hook()

```c
void starpu_sched_component_worker_pre_exec_hook (  
    struct starpu_task * task,  
    unsigned sched_ctx_id )
```

compatibility with `starpu_sched_policy` interface update predictions for workers

30.37.5.25 starpu_sched_component_worker_post_exec_hook()

```c
void starpu_sched_component_worker_post_exec_hook (  
    struct starpu_task * task,  
    unsigned sched_ctx_id )
```

compatibility with `starpu_sched_policy` interface

30.37.5.26 starpu_sched_component_can_push()

```c
int starpu_sched_component_can_push (  
    struct starpu_sched_component * component,  
    struct starpu_sched_component * to )
```

default function for the `can_push` component method, just call `can_push` of parents until one of them returns non-zero

30.37.5.27 starpu_sched_component_can_pull()

```c
int starpu_sched_component_can_pull (  
    struct starpu_sched_component * component )
```
default function for the can_pull component method, just call can_pull of children until one of them returns non-zero

30.37.5.28 starpu_sched_component_can_pull_all()

```c
int starpu_sched_component_can_pull_all {
    struct starpu_sched_component * component
}
```

function for the can_pull component method, call can_pull of all children

30.37.5.29 starpu_sched_component_estimated_load()

```c
double starpu_sched_component_estimated_load {
    struct starpu_sched_component * component
}
```

default function for the estimated_load component method, just sum up the loads of the children of the component.

30.37.5.30 starpu_sched_component_estimated_end_min()

```c
double starpu_sched_component_estimated_end_min {
    struct starpu_sched_component * component
}
```

function that can be used for the estimated_end component method, compute the minimum completion time of the children.

30.37.5.31 starpu_sched_component_estimated_end_min_add()

```c
double starpu_sched_component_estimated_end_min_add {
    struct starpu_sched_component * component,
    double exp_len
}
```

function that can be used for the estimated_end component method, compute the minimum completion time of the children, and add to it an estimation of how existing queued work, plus the exp_len work, can be completed. This is typically used instead of starpu_sched_component_estimated_end_min when the component contains a queue of tasks, which thus needs to be added to the estimations.

30.37.5.32 starpu_sched_component_estimated_end_average()

```c
double starpu_sched_component_estimated_end_average {
    struct starpu_sched_component * component
}
```

default function for the estimated_end component method, compute the average completion time of the children.

30.37.5.33 starpu_sched_component_fifo_create()

```c
struct starpu_sched_component * starpu_sched_component_fifo_create {
    struct starpu_sched_tree * tree,
    struct starpu_sched_component_fifo_data * fifo_data
}
```

Return a struct starpu_sched_component with a fifo. A stable sort is performed according to tasks priorities. A push_task call on this component does not perform recursive calls, underlying components will have to call pop_task to get it. starpu_sched_component::estimated_end function compute the estimated length by dividing the sequential length by the number of underlying workers.

30.37.5.34 starpu_sched_component_is_fifo()

```c
int starpu_sched_component_is_fifo {
    struct starpu_sched_component * component
}
```

return true iff component is a fifo component

30.37.5.35 starpu_sched_component_work_stealing_create()

```c
struct starpu_sched_component * starpu_sched_component_work_stealing_create {
    struct starpu_sched_tree * tree,
    void * arg
}
```
return a component that perform a work stealing scheduling. Tasks are pushed in a round robin way. estimated_end
return the average of expected length of fifos, starting at the average of the expected_end of his children. When a
worker have to steal a task, it steal a task in a round robin way, and get the last pushed task of the higher priority.

30.37.5.36  starpu_sched_component_is_work_stealing()

int starpu_sched_component_is_work_stealing (  
    struct starpu_sched_component * component )
return true iff component is a work stealing component

30.37.5.37  starpu_sched_tree_work_stealing_push_task()

int starpu_sched_tree_work_stealing_push_task (  
    struct starpu_task * task )
undefined if there is no work stealing component in the scheduler. If any, task is pushed in a default way if the
caller is the application, and in the caller's fifo if its a worker.

30.37.5.38  starpu_sched_component_random_create()

struct starpu_sched_component* starpu_sched_component_random_create (  
    struct starpu_sched_tree * tree,  
    void * arg )
create a component that perform a random scheduling

30.37.5.39  starpu_sched_component_is_random()

int starpu_sched_component_is_random (  
    struct starpu_sched_component * )
return true iff component is a random component

30.37.5.40  starpu_sched_component_mct_create()

struct starpu_sched_component* starpu_sched_component_mct_create (  
    struct starpu_sched_tree * tree,  
    struct starpu_sched_component_mct_data * mct_data )
create a component with mct_data paremeters. the mct component doesn't do anything but pushing tasks on no-
_perf_model_component and calibrating_component

30.37.5.41  starpu_sched_component_best_implementation_create()

struct starpu_sched_component* starpu_sched_component_best_implementation_create (  
    struct starpu_sched_tree * tree,  
    void * arg )
Select the implementation that offer the shortest computation length for the first worker that can execute the task.
Or an implementation that need to be calibrated. Also set starpu_task::predicted and starpu_task::predicted_
transfer for memory component of the first suitable workerid. If starpu_sched_component::push method is called
and starpu_sched_component::nchild > 1 the result is undefined.

30.37.5.42  starpu_sched_component_composed_recipe_create()

struct starpu_sched_component_composed_recipe* starpu_sched_component_composed_recipe_create (  
    void )
return an empty recipe for a composed component, it should not be used without modification

30.37.5.43  starpu_sched_component_composed_recipe_create_singleton()

struct starpu_sched_component_composed_recipe* starpu_sched_component_composed_recipe_create_singleton (  
    struct starpu_sched_component * (*)(struct starpu_sched_tree *tree, void *arg)
return a recipe to build a composed component with a create_component

```c
void starpu_sched_component_composed_recipe_add (struct starpu_sched_component_composed_recipe * recipe, struct starpu_sched_component *(*)(struct starpu_sched_tree *tree, void *arg) create_component, void * arg )
add create_component under all previous components in recipe
```

```c
void starpu_sched_component_composed_recipe_destroy (struct starpu_sched_component_composed_recipe * )
destroy composed_sched_component, this should be done after starpu_sched_component_composed_component_create was called
```

```c
struct starpu_sched_component* starpu_sched_component_composed_component_create (struct starpu_sched_tree * tree, struct starpu_sched_component_composed_recipe * recipe )
create a component that behave as all component of recipe where linked. Except that you can't use starpu_sched_component_is_foo function if recipe contain a single create_foo arg_foo pair, create_foo(arg_foo) is returned instead of a composed component
```

```c
struct starpu_sched_tree* starpu_sched_component_make_scheduler (unsigned sched_ctx_id, struct starpu_sched_component_specs s )
build a scheduler for sched_ctx_id according to s and the hwloc topology of the machine.
```

```c
void starpu_sched_component_initialize_simple_scheduler ( starpu_sched_component_create_t create_decision_component, void * data, unsigned flags, unsigned sched_ctx_id )
Create a simple modular scheduler tree around a scheduling decision-making component. The details of what should be built around component is described by flags. The different STARPU_SCHED_SIMPL_DECIDE_* flags are mutually exclusive. data is passed to the create_decision_component function when creating the decision component.
```

30.38 Clustering Machine

Macros

- `#define STARPU_CLUSTER_MIN_NB`
- `#define STARPU_CLUSTER_MAX_NB`
- `#define STARPU_CLUSTER_NB`
- `#define STARPU_CLUSTER_PREFERE_MIN`
- `#define STARPU_CLUSTER_KEEP_HOMOGENEOUS`
- `#define STARPU_CLUSTER_POLICY_NAME`
• #define STARPU_CLUSTER_POLICY_STRUCT
• #define STARPU_CLUSTER_CREATE_FUNC
• #define STARPU_CLUSTER_CREATE_FUNC_ARG
• #define STARPU_CLUSTER_TYPE
• #define STARPU_CLUSTER_AWAKE_WORKERS
• #define STARPU_CLUSTER_PARTITION_ONE
• #define STARPU_CLUSTER_NEW
• #define STARPU_CLUSTER_NCORES
• #define starpu_intel_openmp_mkl_prologue

Enumerations

• enum starpu_cluster_types { STARPU_CLUSTER_OPENMP, STARPU_CLUSTER_INTEL_OPENMP_MKL, STARPU_CLUSTER_GNU_OPENMP_MKL }

Functions

• struct starpu_cluster_machine * starpu_cluster_machine (hwloc_obj_type_t cluster_level,...)
• int starpu_uncluster_machine (struct starpu_cluster_machine *clusters)
• int starpu_cluster_print (struct starpu_cluster_machine *clusters)
• void starpu_openmp_prologue (void *)
• void starpu_gnu_openmp_mkl_prologue (void *)

30.38.1 Detailed Description

30.38.2 Enumeration Type Documentation

30.38.2.1 starpu_cluster_types

enum starpu_cluster_types
These represent the default available functions to enforce cluster use by the sub-runtime

<table>
<thead>
<tr>
<th>Enumerators</th>
<th>Details</th>
</tr>
</thead>
<tbody>
<tr>
<td>STARPU_CLUSTER_OPENMP</td>
<td>todo</td>
</tr>
<tr>
<td>STARPU_CLUSTER_INTEL_OPENMP_MKL</td>
<td>todo</td>
</tr>
<tr>
<td>STARPU_CLUSTER_GNU_OPENMP_MKL</td>
<td>todo</td>
</tr>
</tbody>
</table>

30.39 Interoperability Support

This section describes the interface supplied by StarPU to interoperate with other runtime systems.

Typedefs

• typedef int starpurm_drs_ret_t
• typedef void * starpurm_drs_desc_t
• typedef void * starpurm_drs_cbs_t
• typedef void(* starpurm_drs_cb_t) (void *)
• typedef void * starpurm_block_cond_t
• typedef int(* starpurm_polling_t) (void *)
Environments

- enum e_starpurm_drs_ret { starpurm_DRS_SUCCESS, starpurm_DRS_DISABLD, starpurm_DRS_PERM, starpurm_DRS_EINVAL }

Initialisation

- void starpurm_initialize_with_cpuset (hwloc_cpuset_t initially_owned_cpuset)
- void starpurm_initialize (void)
- void starpurm_shutdown (void)

Spawn

- void starpurm_spawn_kernel_on_cpus (void ∗ data, void (∗) (void ∗), void ∗ args, hwloc_cpuset_t cpuset)
- void starpurm_spawn_kernel_on_cpus_callback (void ∗ data, void (∗) (void ∗), void ∗ args, hwloc_cpuset_t cpuset, void (∗ cb_f) (void ∗), void ∗ cb_args)
- void starpurm_spawn_kernel_callback (void ∗ data, void (∗) (void ∗), void ∗ args, void (∗ cb_f) (void ∗), void ∗ cb_args)

DynamicResourceSharing

- starpurm_drs_ret_t starpurm_set_drs_enable (starpurm_drs_desc_t ∗ spd)
- starpurm_drs_ret_t starpurm_set_drs_disable (starpurm_drs_desc_t ∗ spd)
- int starpurm_drs_enabled_p (void)
- starpurm_drs_ret_t starpurm_set_max_parallelism (starpurm_drs_desc_t ∗ spd, int max)
- starpurm_drs_ret_t starpurm_assign_cpu_to_starpu (starpurm_drs_desc_t ∗ spd, int cpuid)
- starpurm_drs_ret_t starpurm_assign_cpus_to_starpu (starpurm_drs_desc_t ∗ spd, int ncpus)
- starpurm_drs_ret_t starpurm_assign_cpu_mask_to_starpu (starpurm_drs_desc_t ∗ spd, const hwloc_cpuset_t mask)
- starpurm_drs_ret_t starpurm_assign_all_cpus_to_starpu (starpurm_drs_desc_t ∗ spd)
- starpurm_drs_ret_t starpurm_withdraw_cpu_from_starpu (starpurm_drs_desc_t ∗ spd, int cpuid)
- starpurm_drs_ret_t starpurm_withdraw_cpus_from_starpu (starpurm_drs_desc_t ∗ spd, int ncpus)
- starpurm_drs_ret_t starpurm_withdraw_cpu_mask_from_starpu (starpurm_drs_desc_t ∗ spd, const hwloc_cpuset_t mask)
- starpurm_drs_ret_t starpurm_withdraw_all_cpus_from_starpu (starpurm_drs_desc_t ∗ spd)
- starpurm_drs_ret_t starpurm_lend (starpurm_drs_desc_t ∗ spd)
- starpurm_drs_ret_t starpurm_lend_cpu (starpurm_drs_desc_t ∗ spd, int cpuid)
- starpurm_drs_ret_t starpurm_lend_cpus (starpurm_drs_desc_t ∗ spd, int ncpus)
- starpurm_drs_ret_t starpurm_lend_cpu_mask (starpurm_drs_desc_t ∗ spd, const hwloc_cpuset_t mask)
- starpurm_drs_ret_t starpurm_reclaim (starpurm_drs_desc_t ∗ spd)
- starpurm_drs_ret_t starpurm_reclaim_cpu (starpurm_drs_desc_t ∗ spd, int cpuid)
- starpurm_drs_ret_t starpurm_reclaim_cpus (starpurm_drs_desc_t ∗ spd, int ncpus)
- starpurm_drs_ret_t starpurm_reclaim_cpu_mask (starpurm_drs_desc_t ∗ spd, const hwloc_cpuset_t mask)
- starpurm_drs_ret_t starpurm_acquire (starpurm_drs_desc_t ∗ spd)
- starpurm_drs_ret_t starpurm_acquire_cpu (starpurm_drs_desc_t ∗ spd, int cpuid)
- starpurm_drs_ret_t starpurm_acquire_cpus (starpurm_drs_desc_t ∗ spd, int ncpus)
- starpurm_drs_ret_t starpurm_acquire_cpu_mask (starpurm_drs_desc_t ∗ spd, const hwloc_cpuset_t mask)
- starpurm_drs_ret_t starpurm_return_all (starpurm_drs_desc_t ∗ spd)
- starpurm_drs_ret_t starpurm_return_cpu (starpurm_drs_desc_t ∗ spd, int cpuid)
Module Documentation a.k.a StarPU’s API

Devices

- int starpurm_get_device_type_id (const char *type_str)
- const char * starpurm_get_device_type_name (int type_id)
- int starpurm_get_nb_devices_by_type (int type_id)
- int starpurm_get_device_id (int type_id, int device_rank)
- starpurm_drs_ret_t starpurm_assign_device_to_starpu (starpurm_drs_desc_t *spd, int type_id, int unit_rank)
- starpurm_drs_ret_t starpurm_assign_devices_to_starpu (starpurm_drs_desc_t *spd, int type_id, int ndevices)
- starpurm_drs_ret_t starpurm_assign_device_mask_to_starpu (starpurm_drs_desc_t *spd, const hwloc_cpuset_t mask)
- starpurm_drs_ret_t starpurm_assign_all_devices_to_starpu (starpurm_drs_desc_t *spd, int type_id)
- starpurm_drs_ret_t starpurm_withdraw_device_from_starpu (starpurm_drs_desc_t *spd, int type_id, int unit_rank)
- starpurm_drs_ret_t starpurm_withdraw_devices_from_starpu (starpurm_drs_desc_t *spd, int type_id, int ndevices)
- starpurm_drs_ret_t starpurm_withdraw_device_mask_from_starpu (starpurm_drs_desc_t *spd, const hwloc_cpuset_t mask)
- starpurm_drs_ret_t starpurm_withdraw_all_devices_from_starpu (starpurm_drs_desc_t *spd, int type_id)
- starpurm_drs_ret_t starpurm_lend_device (starpurm_drs_desc_t *spd, int type_id, int unit_rank)
- starpurm_drs_ret_t starpurm_lend_devices (starpurm_drs_desc_t *spd, int type_id, int ndevices)
- starpurm_drs_ret_t starpurm_lend_device_mask (starpurm_drs_desc_t *spd, const hwloc_cpuset_t mask)
- starpurm_drs_ret_t starpurm_lend_all_devices (starpurm_drs_desc_t *spd, int type_id)
- starpurm_drs_ret_t starpurm_reclaim_device (starpurm_drs_desc_t *spd, int type_id, int unit_rank)
- starpurm_drs_ret_t starpurm_reclaim_devices (starpurm_drs_desc_t *spd, int type_id, int ndevices)
- starpurm_drs_ret_t starpurm_reclaim_device_mask (starpurm_drs_desc_t *spd, const hwloc_cpuset_t mask)
- starpurm_drs_ret_t starpurm_reclaim_all_devices (starpurm_drs_desc_t *spd, int type_id)
- starpurm_drs_ret_t starpurm_acquire_device (starpurm_drs_desc_t *spd, int type_id, int unit_rank)
- starpurm_drs_ret_t starpurm_acquire_devices (starpurm_drs_desc_t *spd, int type_id, int ndevices)
- starpurm_drs_ret_t starpurm_acquire_device_mask (starpurm_drs_desc_t *spd, const hwloc_cpuset_t mask)
- starpurm_drs_ret_t starpurm_acquire_all_devices (starpurm_drs_desc_t *spd, int type_id)
- starpurm_drs_ret_t starpurm_return_all_devices (starpurm_drs_desc_t *spd, int type_id)
- starpurm_drs_ret_t starpurm_return_device (starpurm_drs_desc_t *spd, int type_id, int unit_rank)

CpusetsQueries

- hwloc_cpuset_t starpurm_get_device_worker_cpuset (int type_id, int unit_rank)
- hwloc_cpuset_t starpurm_get_global_cpuset (void)
- hwloc_cpuset_t starpurm_get_selected_cpuset (void)
- hwloc_cpuset_t starpurm_get_all_cpu_workers_cpuset (void)
- hwloc_cpuset_t starpurm_get_all_device_workers_cpuset (void)
- hwloc_cpuset_t starpurm_get_all_device_workers_cpuset_by_type (int typeid)

30.39.1 Detailed Description
This section describes the interface supplied by StarPU to interoperate with other runtime systems.

30.39.2 Enumeration Type Documentation

30.39.2.1 e_starpurm_drs_ret

enum e_starpurm_drs_ret
StarPU Resource Manager return type.
## 30.39 Interoperability Support

### Enumerator

<table>
<thead>
<tr>
<th>Enumerator</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>starpurm_DRS_SUCCESS</td>
<td>Dynamic resource sharing operation succeeded.</td>
</tr>
<tr>
<td>starpurm_DRS_DISABLD</td>
<td>Dynamic resource sharing is disabled.</td>
</tr>
<tr>
<td>starpurm_DRS_PERM</td>
<td>Dynamic resource sharing operation is not authorized or implemented.</td>
</tr>
<tr>
<td>starpurm_DRS_EINVAL</td>
<td>Dynamic resource sharing operation has been called with one or more invalid parameters.</td>
</tr>
</tbody>
</table>

### 30.39.3 Function Documentation

#### 30.39.3.1 starpurm_initialize_with_cpuset()

```c
void starpurm_initialize_with_cpuset (
    hwloc_cpuset_t initially_owned_cpuset)
```

**Resource enforcement**

#### 30.39.3.2 starpurm_initialize()

```c
void starpurm_initialize (
    void)
```

Initialize StarPU and the StarPU-RM resource management module. The `starpu_init()` function should not have been called before the call to `starpurm_initialize()`. The `starpurm_initialize()` function will take care of this.

#### 30.39.3.3 starpurm_shutdown()

```c
void starpurm_shutdown (
    void)
```

Shutdown StarPU-RM and StarPU. The `starpu_shutdown()` function should not be called before. The `starpurm_shutdown()` function will take care of this.

#### 30.39.3.4 starpurm_spawn_kernel_on_cpus()

```c
void starpurm_spawn_kernel_on_cpus (
    void * data,
    void(*)(void *) f,
    void * args,
    hwloc_cpuset_t cpuset)
```

Allocate a temporary context spanning the units selected in the cpuset bitmap, set it as the default context for the current thread, and call user function `f`. Upon the return of user function `f`, the temporary context is freed and the previous default context for the current thread is restored.

#### 30.39.3.5 starpurm_spawn_kernel_on_cpus_callback()

```c
void starpurm_spawn_kernel_on_cpus_callback (
    void * data,
    void(*)(void *) f,
    void * args,
    hwloc_cpuset_t cpuset,
    void(*)(void *) cb_f,
    void * cb_args)
```

Spawn a POSIX thread and returns immediately. The thread spawned will allocate a temporary context spanning the units selected in the cpuset bitmap, set it as the default context for the current thread, and call user function `f`. Upon the return of user function `f`, the temporary context will be freed and the previous default context for the current thread restored. A user specified callback `cb_f` will be called just before the termination of the thread.
30.39.3.6  starpurm_set_drs_enable()

starpurm_drs_ret_t starpurm_set_drs_enable ( 
    starpurm_drs_desc_t * spd )

Turn-on dynamic resource sharing support.

30.39.3.7  starpurm_set_drs_disable()

starpurm_drs_ret_t starpurm_set_drs_disable ( 
    starpurm_drs_desc_t * spd )

Turn-off dynamic resource sharing support.

30.39.3.8  starpurm_drs_enabled_p()

int starpurm_drs_enabled_p ( 
    void )

Return the state of the dynamic resource sharing support (=!0 enabled, =0 disabled).

30.39.3.9  starpurm_set_max_parallelism()

starpurm_drs_ret_t starpurm_set_max_parallelism ( 
    starpurm_drs_desc_t * spd, 
    int max )

Set the maximum number of CPU computing units available for StarPU computations to max. This number cannot exceed the maximum number of StarPU's CPU worker allocated at start-up time.

30.39.3.10  starpurm_assign_cpu_to_starpu()

starpurm_drs_ret_t starpurm_assign_cpu_to_starpu ( 
    starpurm_drs_desc_t * spd, 
    int cpuid )

Extend StarPU's default scheduling context to execute tasks on worker corresponding to logical unit cpuid. If StarPU does not have a worker thread initialized for logical unit cpuid, do nothing.

30.39.3.11  starpurm_assign_cpus_to_starpu()

starpurm_drs_ret_t starpurm_assign_cpus_to_starpu ( 
    starpurm_drs_desc_t * spd, 
    int ncpus )

Extend StarPU's default scheduling context to execute tasks on ncpus more workers, up to the number of StarPU worker threads initialized.

30.39.3.12  starpurm_assign_cpu_mask_to_starpu()

starpurm_drs_ret_t starpurm_assign_cpu_mask_to_starpu ( 
    starpurm_drs_desc_t * spd, 
    const hwloc_cpuset_t mask )

Extend StarPU's default scheduling context to execute tasks on the additional logical units selected in mask. Logical units of mask for which no StarPU worker is initialized are silently ignored.

30.39.3.13  starpurm_assign_all_cpus_to_starpu()

starpurm_drs_ret_t starpurm_assign_all_cpus_to_starpu ( 
    starpurm_drs_desc_t * spd )

Set StarPU's default scheduling context to execute tasks on all available logical units for which a StarPU worker has been initialized.
30.39.3.14  *starpurm_withdraw_cpu_from_starpu()*

```c
cnstarpurm_drs_ret_t starpurm_withdraw_cpu_from_starpu (  
    starpurm_drs_desc_t * spd,  
    int cpuid  
)
```

Shrink StarPU's default scheduling context so as to not execute tasks on worker corresponding to logical unit cpuid. If StarPU does not have a worker thread initialized for logical unit cpuid, do nothing.

30.39.3.15  *starpurm_withdraw_cpus_from_starpu()*

```c
cnstarpurm_drs_ret_t starpurm_withdraw_cpus_from_starpu (  
    starpurm_drs_desc_t * spd,  
    int ncpus  
)
```

Shrink StarPU's default scheduling context to execute on ncpus less workers.

30.39.3.16  *starpurm_withdraw_cpu_mask_from_starpu()*

```c
cnstarpurm_drs_ret_t starpurm_withdraw_cpu_mask_from_starpu (  
    starpurm_drs_desc_t * spd,  
    const hwloc_cpuset_t mask  
)
```

Shrink StarPU's default scheduling context so as to not execute tasks on the logical units selected in mask. Logical units of mask for which no StarPU worker is initialized are silently ignored.

30.39.3.17  *starpurm_withdraw_all_cpus_from_starpu()*

```c
cnstarpurm_drs_ret_t starpurm_withdraw_all_cpus_from_starpu (  
    starpurm_drs_desc_t * spd  
)
```

Shrink StarPU's default scheduling context so as to remove all logical units.

30.39.3.18  *starpurm_lend()*

```c
cnstarpurm_drs_ret_t starpurm_lend (  
    starpurm_drs_desc_t * spd  
)
```

Synonym for *starpurm_assign_all_cpus_to_starpu().*

30.39.3.19  *starpurm_lend_cpu()*

```c
cnstarpurm_drs_ret_t starpurm_lend_cpu (  
    starpurm_drs_desc_t * spd,  
    int cpuid  
)
```

Synonym for *starpurm_assign_cpu_to_starpu().*

30.39.3.20  *starpurm_lend_cpus()*

```c
cnstarpurm_drs_ret_t starpurm_lend_cpus (  
    starpurm_drs_desc_t * spd,  
    int ncpus  
)
```

Synonym for *starpurm_assign_cpus_to_starpu().*

30.39.3.21  *starpurm_lend_cpu_mask()*

```c
cnstarpurm_drs_ret_t starpurm_lend_cpu_mask (  
    starpurm_drs_desc_t * spd,  
    const hwloc_cpuset_t mask  
)
```

Synonym for *starpurm_assign_cpu_mask_to_starpu().*

30.39.3.22  *starpurm_reclaim()*

```c
cnstarpurm_drs_ret_t starpurm_reclaim (  
    starpurm_drs_desc_t * spd  
)
```

Generated by Doxygen
Synonym for \texttt{starpurm\_withdraw\_all\_cpus\_from\_starpu()}. 

30.39.3.23 \texttt{starpurm\_reclaim\_cpu()}

\begin{verbatim}
starpurm\_drs\_ret\_t starpurm\_reclaim\_cpu \( \{ \)
    starpurm\_drs\_desc\_t \* spd,
    int cpuid \)
\end{verbatim}

Synonym for \texttt{starpurm\_withdraw\_cpu\_from\_starpu()}. 

30.39.3.24 \texttt{starpurm\_reclaim\_cpus()}

\begin{verbatim}
starpurm\_drs\_ret\_t starpurm\_reclaim\_cpus \( \{ \)
    starpurm\_drs\_desc\_t \* spd,
    int ncpus \)
\end{verbatim}

Synonym for \texttt{starpurm\_withdraw\_cpus\_from\_starpu()}. 

30.39.3.25 \texttt{starpurm\_reclaim\_cpu\_mask()}

\begin{verbatim}
starpurm\_drs\_ret\_t starpurm\_reclaim\_cpu\_mask \( \{ \)
    starpurm\_drs\_desc\_t \* spd,
    const hwloc\_cpuset\_t mask \)
\end{verbatim}

Synonym for \texttt{starpurm\_withdraw\_cpu\_mask\_from\_starpu()}. 

30.39.3.26 \texttt{starpurm\_acquire()}

\begin{verbatim}
starpurm\_drs\_ret\_t starpurm\_acquire \( \{ \)
    starpurm\_drs\_desc\_t \* spd \)
\end{verbatim}

Synonym for \texttt{starpurm\_withdraw\_all\_cpus\_from\_starpu()}. 

30.39.3.27 \texttt{starpurm\_acquire\_cpu()}

\begin{verbatim}
starpurm\_drs\_ret\_t starpurm\_acquire\_cpu \( \{ \)
    starpurm\_drs\_desc\_t \* spd,
    int cpuid \)
\end{verbatim}

Synonym for \texttt{starpurm\_withdraw\_cpu\_from\_starpu()}. 

30.39.3.28 \texttt{starpurm\_acquire\_cpus()}

\begin{verbatim}
starpurm\_drs\_ret\_t starpurm\_acquire\_cpus \( \{ \)
    starpurm\_drs\_desc\_t \* spd,
    int ncpus \)
\end{verbatim}

Synonym for \texttt{starpurm\_withdraw\_cpus\_from\_starpu()}. 

30.39.3.29 \texttt{starpurm\_acquire\_cpu\_mask()}

\begin{verbatim}
starpurm\_drs\_ret\_t starpurm\_acquire\_cpu\_mask \( \{ \)
    starpurm\_drs\_desc\_t \* spd,
    const hwloc\_cpuset\_t mask \)
\end{verbatim}

Synonym for \texttt{starpurm\_withdraw\_cpu\_mask\_from\_starpu()}. 

30.39.3.30 \texttt{starpurm\_return\_all()}

\begin{verbatim}
starpurm\_drs\_ret\_t starpurm\_return\_all \( \{ \)
    starpurm\_drs\_desc\_t \* spd \)
\end{verbatim}

Synonym for \texttt{starpurm\_assign\_all\_cpus\_to\_starpu()}. 

---
30.39.3.31 starpurm_return_cpu()

```
starpurm_drs_ret_t starpurm_return_cpu (  
    starpurm_drs_desc_t * spd,  
    int cpuid )
```

Synonym for starpurm_assign_cpu_to_starpu().

30.39.3.32 starpurm_get_device_type_id()

```
int starpurm_get_device_type_id (  
    const char * type_str )
```

Return the device type ID constant associated to the device type name. Valid names for `type_str` are:

- "cpu": regular CPU unit;
- "opencl": OpenCL device unit;
- "cuda": nVidia CUDA device unit;
- "mic": Intel KNC type device unit.

30.39.3.33 starpurm_get_device_type_name()

```
const char* starpurm_get_device_type_name (  
    int type_id )
```

Return the device type name associated to the device type ID constant.

30.39.3.34 starpurm_get_nb_devices_by_type()

```
int starpurm_get_nb_devices_by_type (  
    int type_id )
```

Return the number of initialized StarPU worker for the device type `type_id`.

30.39.3.35 starpurm_get_device_id()

```
int starpurm_get_device_id (  
    int type_id,  
    int device_rank )
```

Return the unique ID assigned to the `device_rank` nth device of type `type_id`.

30.39.3.36 starpurm_assign_device_to_starpu()

```
starpurm_drs_ret_t starpurm_assign_device_to_starpu (  
    starpurm_drs_desc_t * spd,  
    int type_id,  
    int unit_rank )
```

Extend StarPU's default scheduling context to use `unit_rank` nth device of type `type_id`.

30.39.3.37 starpurm_assign_devices_to_starpu()

```
starpurm_drs_ret_t starpurm_assign_devices_to_starpu (  
    starpurm_drs_desc_t * spd,  
    int type_id,  
    int ndevices )
```

Extend StarPU's default scheduling context to use `ndevices` more devices of type `type_id`, up to the number of StarPU workers initialized for such device type.
30.39.3.38 starpurm_assign_device_mask_to_starpu()

```c
starpurm_drs_ret_t starpurm_assign_device_mask_to_starpu(
    starpurm_drs_desc_t * spd,
    const hwloc_cpuset_t mask )
```

Extend StarPU's default scheduling context to use additional devices as designated by their corresponding StarPU worker thread(s) CPU-set mask.

30.39.3.39 starpurm_assign_all_devices_to_starpu()

```c
starpurm_drs_ret_t starpurm_assign_all_devices_to_starpu(
    starpurm_drs_desc_t * spd,
    int type_id )
```

Extend StarPU's default scheduling context to use all devices of type `type_id` for which it has a worker thread initialized.

30.39.3.40 starpurm_withdraw_device_from_starpu()

```c
starpurm_drs_ret_t starpurm_withdraw_device_from_starpu(
    starpurm_drs_desc_t * spd,
    int type_id,
    int unit_rank )
```

Shrink StarPU's default scheduling context to not use `unit_rank` nth device of type `type_id`.

30.39.3.41 starpurm_withdraw_devices_from_starpu()

```c
starpurm_drs_ret_t starpurm_withdraw_devices_from_starpu(
    starpurm_drs_desc_t * spd,
    int type_id,
    int ndevices )
```

Shrink StarPU's default scheduling context to use `ndevices` less devices of type `type_id`.

30.39.3.42 starpurm_withdraw_device_mask_from_starpu()

```c
starpurm_drs_ret_t starpurm_withdraw_device_mask_from_starpu(
    starpurm_drs_desc_t * spd,
    const hwloc_cpuset_t mask )
```

Shrink StarPU's default scheduling context to not use devices designated by their corresponding StarPU worker thread(s) CPU-set mask.

30.39.3.43 starpurm_withdraw_all_devices_from_starpu()

```c
starpurm_drs_ret_t starpurm_withdraw_all_devices_from_starpu(
    starpurm_drs_desc_t * spd,
    int type_id )
```

Shrink StarPU's default scheduling context to use no devices of type `type_id`.

30.39.3.44 starpurm_lend_device()

```c
starpurm_drs_ret_t starpurm_lend_device(
    starpurm_drs_desc_t * spd,
    int type_id,
    int unit_rank )
```

Synonym for `starpurm_assign_device_to_starpu()`.

30.39.3.45 starpurm_lend_devices()

```c
starpurm_drs_ret_t starpurm_lend_devices(
    starpurm_drs_desc_t * spd,
```
30.39 Interoperability Support

```c
int type_id,
int ndevices
```

Synonym for `starpurm_assign_devices_to_starpu()`.

30.39.3.46 `starpurm_lend_device_mask()`

```c
starpurm_drs_ret_t starpurm_lend_device_mask {
    starpurm_drs_desc_t * spd,
    const hwloc_cpuset_t mask
}
```

Synonym for `starpurm_assign_device_mask_to_starpu()`.

30.39.3.47 `starpurm_lend_all_devices()`

```c
starpurm_drs_ret_t starpurm_lend_all_devices {
    starpurm_drs_desc_t * spd,
    int type_id
}
```

Synonym for `starpurm_assign_all_devices_to_starpu()`.

30.39.3.48 `starpurm_reclaim_device()`

```c
starpurm_drs_ret_t starpurm_reclaim_device {
    starpurm_drs_desc_t * spd,
    int type_id,
    int unit_rank
}
```

Synonym for `starpurm_withdraw_device_from_starpu()`.

30.39.3.49 `starpurm_reclaim_devices()`

```c
starpurm_drs_ret_t starpurm_reclaim_devices {
    starpurm_drs_desc_t * spd,
    int type_id,
    int ndevices
}
```

Synonym for `starpurm_withdraw_devices_from_starpu()`.

30.39.3.50 `starpurm_reclaim_device_mask()`

```c
starpurm_drs_ret_t starpurm_reclaim_device_mask {
    starpurm_drs_desc_t * spd,
    const hwloc_cpuset_t mask
}
```

Synonym for `starpurm_withdraw_device_mask_from_starpu()`.

30.39.3.51 `starpurm_reclaim_all_devices()`

```c
starpurm_drs_ret_t starpurm_reclaim_all_devices {
    starpurm_drs_desc_t * spd,
    int type_id
}
```

Synonym for `starpurm_withdraw_all_devices_from_starpu()`.

30.39.3.52 `starpurm_acquire_device()`

```c
starpurm_drs_ret_t starpurm_acquire_device {
    starpurm_drs_desc_t * spd,
    int type_id,
    int unit_rank
}
```

Synonym for `starpurm_withdraw_device_from_starpu()`.

---

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30.39.3.53 starpurm_acquire_devices()

```c
starpurm_drs_ret_t starpurm_acquire_devices ( 
    starpurm_drs_desc_t * spd,
    int type_id,
    int ndevices )
```

Synonym for `starpurm_withdraw_devices_from_starpu()`.

30.39.3.54 starpurm_acquire_device_mask()

```c
starpurm_drs_ret_t starpurm_acquire_device_mask ( 
    starpurm_drs_desc_t * spd,
    const hwloc_cpuset_t mask )
```

Synonym for `starpurm_withdraw_device_mask_from_starpu()`.

30.39.3.55 starpurm_acquire_all_devices()

```c
starpurm_drs_ret_t starpurm_acquire_all_devices ( 
    starpurm_drs_desc_t * spd,
    int type_id )
```

Synonym for `starpurm_withdraw_all_devices_from_starpu()`.

30.39.3.56 starpurm_return_all_devices()

```c
starpurm_drs_ret_t starpurm_return_all_devices ( 
    starpurm_drs_desc_t * spd,
    int type_id )
```

Synonym for `starpurm_assign_all_devices_to_starpu()`.

30.39.3.57 starpurm_return_device()

```c
starpurm_drs_ret_t starpurm_return_device ( 
    starpurm_drs_desc_t * spd,
    int type_id,
    int unit_rank )
```

Synonym for `starpurm_assign_device_to_starpu()`.

30.39.3.58 starpurm_get_device_worker_cpuset()

```c
hwloc_cpuset_t starpurm_get_device_worker_cpuset ( 
    int type_id,
    int unit_rank )
```

Return the CPU-set of the StarPU worker associated to the `unit_rank` nth unit of type `type_id`.

30.39.3.59 starpurm_get_global_cpuset()

```c
hwloc_cpuset_t starpurm_get_global_cpuset ( 
    void )
```

Return the cumulated CPU-set of all StarPU worker threads.

30.39.3.60 starpurm_get_selected_cpuset()

```c
hwloc_cpuset_t starpurm_get_selected_cpuset ( 
    void )
```

Return the CPU-set of the StarPU worker threads currently selected in the default StarPU’s scheduling context.

30.39.3.61 starpurm_get_all_cpu_workers_cpuset()

```c
hwloc_cpuset_t starpurm_get_all_cpu_workers_cpuset ( 
    void )
```
Return the cumulated CPU-set of all CPU StarPU worker threads.

30.39.3.62 starpurm_get_all_device_workers_cpuset()

hwloc_cpuset_t starpurm_get_all_device_workers_cpuset ( void )

Return the cumulated CPU-set of all "non-CPU" StarPU worker threads.

30.39.3.63 starpurm_get_all_device_workers_cpuset_by_type()

hwloc_cpuset_t starpurm_get_all_device_workers_cpuset_by_type ( int typeid )

Return the cumulated CPU-set of all StarPU worker threads for devices of type typeid.
# Chapter 31

## File Index

### 31.1 File List

Here is a list of all documented files with brief descriptions:

<table>
<thead>
<tr>
<th>File Name</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>sc_hypervisor.h</td>
<td>494</td>
</tr>
<tr>
<td>sc_hypervisor_config.h</td>
<td>495</td>
</tr>
<tr>
<td>sc_hypervisor_ip.h</td>
<td>496</td>
</tr>
<tr>
<td>sc_hypervisor_monitoring.h</td>
<td>497</td>
</tr>
<tr>
<td>sc_hypervisor_policy.h</td>
<td>499</td>
</tr>
<tr>
<td>starpu.h</td>
<td>449</td>
</tr>
<tr>
<td>starpu_bitmap.h</td>
<td>450</td>
</tr>
<tr>
<td>starpu_bound.h</td>
<td>450</td>
</tr>
<tr>
<td>starpu_clusters.h</td>
<td>451</td>
</tr>
<tr>
<td>starpu_config.h</td>
<td>451</td>
</tr>
<tr>
<td>starpu_cublas.h</td>
<td>454</td>
</tr>
<tr>
<td>starpu_cuda.h</td>
<td>454</td>
</tr>
<tr>
<td>starpu_cusparse.h</td>
<td>454</td>
</tr>
<tr>
<td>starpu_data.h</td>
<td>454</td>
</tr>
<tr>
<td>starpu_data_filters.h</td>
<td>456</td>
</tr>
<tr>
<td>starpu_data_interfaces.h</td>
<td>458</td>
</tr>
<tr>
<td>starpu_deprecated_api.h</td>
<td>462</td>
</tr>
<tr>
<td>starpu_disk.h</td>
<td>462</td>
</tr>
<tr>
<td>starpu_driver.h</td>
<td>463</td>
</tr>
<tr>
<td>starpu_expert.h</td>
<td>463</td>
</tr>
<tr>
<td>starpu_fxt.h</td>
<td>463</td>
</tr>
<tr>
<td>starpu_hash.h</td>
<td>464</td>
</tr>
<tr>
<td>starpu_helper.h</td>
<td>??</td>
</tr>
<tr>
<td>starpu_mic.h</td>
<td>464</td>
</tr>
<tr>
<td>starpu_mod.f90</td>
<td>464</td>
</tr>
<tr>
<td>starpu_mpi.h</td>
<td>465</td>
</tr>
<tr>
<td>starpu_mpi_lib.h</td>
<td>467</td>
</tr>
<tr>
<td>starpu_opencl.h</td>
<td>467</td>
</tr>
<tr>
<td>starpu_openmp.h</td>
<td>469</td>
</tr>
<tr>
<td>starpu_perfm model.h</td>
<td>471</td>
</tr>
<tr>
<td>starpu_profiling.h</td>
<td>473</td>
</tr>
<tr>
<td>starpu_rand.h</td>
<td>474</td>
</tr>
<tr>
<td>starpu_sched_component.h</td>
<td>474</td>
</tr>
<tr>
<td>starpu_sched_ctx.h</td>
<td>477</td>
</tr>
<tr>
<td>starpu_sched_ctx_hypervisor.h</td>
<td>479</td>
</tr>
<tr>
<td>starpu_scheduler.h</td>
<td>480</td>
</tr>
<tr>
<td>starpu_simgrid_wrap.h</td>
<td>481</td>
</tr>
<tr>
<td>starpu_sink.h</td>
<td>481</td>
</tr>
<tr>
<td>starpu_stlili.h</td>
<td>481</td>
</tr>
<tr>
<td>starpu_task.h</td>
<td>482</td>
</tr>
<tr>
<td>File Name</td>
<td>Page</td>
</tr>
<tr>
<td>--------------------</td>
<td>------</td>
</tr>
<tr>
<td>starpu_task_bundle.h</td>
<td>484</td>
</tr>
<tr>
<td>starpu_task_dep.h</td>
<td>??</td>
</tr>
<tr>
<td>starpu_task_list.h</td>
<td>484</td>
</tr>
<tr>
<td>starpu_task_util.h</td>
<td>485</td>
</tr>
<tr>
<td>starpu_thread.h</td>
<td>486</td>
</tr>
<tr>
<td>starpu_thread_util.h</td>
<td>489</td>
</tr>
<tr>
<td>starpu_tree.h</td>
<td>490</td>
</tr>
<tr>
<td>starpu_util.h</td>
<td>490</td>
</tr>
<tr>
<td>starpu_worker.h</td>
<td>491</td>
</tr>
<tr>
<td>starpufft.h</td>
<td>493</td>
</tr>
<tr>
<td>starpurm.h</td>
<td>500</td>
</tr>
</tbody>
</table>
Chapter 32

File Documentation

32.1 starpu.h File Reference

#include <stdlib.h>
#include <stdint.h>
#include <starpu_config.h>
#include <starpu_openci.h>
#include <starpu_thread.h>
#include <starpu_thread_util.h>
#include <starpu_util.h>
#include <starpu_data.h>
#include <starpu_disk.h>
#include <starpu_data_interfaces.h>
#include <starpu_data_filters.h>
#include <starpu_stdlib.h>
#include <starpu_task_bundle.h>
#include <starpu_task_dep.h>
#include <starpu_task.h>
#include <starpu_worker.h>
#include <starpu_perfmodel.h>
#include <starpu_task_list.h>
#include <starpu_task_util.h>
#include <starpu_scheduler.h>
#include <starpu_sched_ctx.h>
#include <starpu_expert.h>
#include <starpu_rand.h>
#include <starpu_cuda.h>
#include <starpu_cublas.h>
#include <starpu_cusparse.h>
#include <starpu_bound.h>
#include <starpu_hash.h>
#include <starpu_profiling.h>
#include <starpu_fxt.h>
#include <starpu_driver.h>
#include <starpu_tree.h>
#include <starpu_openmp.h>
#include <starpu_simgrid_wrap.h>
#include <starpu_bitmap.h>
#include <starpu_clusters.h>
#include "starpu_deprecated_api.h"
Data Structures

- struct starpu_conf

Macros

- #define STARPU_THREAD_ACTIVE

Functions

- int starpu_conf_init (struct starpu_conf *conf)
- int starpu_init (struct starpu_conf *conf) STARPU_WARN_UNUSED_RESULT
- int starpu_initialize (struct starpu_conf *user_conf, int *argc, char ***argv)
- int starpu_is_initialized (void)
- void starpu_wait_initialized (void)
- void starpu_shutdown (void)
- void starpu_pause (void)
- void starpu_resume (void)
- unsigned starpu_get_next_bindid (unsigned flags, unsigned *preferred, unsigned npreferred)
- int starpu_bind_thread_on (int cpuid, unsigned flags, const char *name)
- void starpu_topology_print (FILE *f)
- int starpu_asynchronous_copy_disabled (void)
- int starpu_asynchronous_cuda_copy_disabled (void)
- int starpu_asynchronous_opencl_copy_disabled (void)
- int starpu_asynchronous_mic_copy_disabled (void)
- int starpu_asynchronous_mpi_ms_copy_disabled (void)
- void starpu_display_stats (void)
- void starpu_get_version (int *major, int *minor, int *release)

32.2 starpu_bitmap.h File Reference

Functions

- struct starpu_bitmap * starpu_bitmap_create (void) STARPU_ATTRIBUTE_MALLOC
- void starpu_bitmap_destroy (struct starpu_bitmap *b)
- void starpu_bitmap_set (struct starpu_bitmap *b, int e)
- void starpu_bitmap_unset (struct starpu_bitmap *b, int e)
- void starpu_bitmap_unset_all (struct starpu_bitmap *b)
- int starpu_bitmap_get (struct starpu_bitmap *b, int e)
- void starpu_bitmap_unset_and (struct starpu_bitmap *a, struct starpu_bitmap *b, struct starpu_bitmap *c)
- void starpu_bitmap_or (struct starpu_bitmap *a, struct starpu_bitmap *b)
- int starpu_bitmap_and_get (struct starpu_bitmap *b1, struct starpu_bitmap *b2, int e)
- int starpu_bitmap_cardinal (struct starpu_bitmap *b)
- int starpu_bitmap_first (struct starpu_bitmap *b)
- int starpu_bitmap_last (struct starpu_bitmap *b)
- int starpu_bitmap_next (struct starpu_bitmap *b, int e)
- int starpu_bitmap_has_next (struct starpu_bitmap *b, int e)

32.3 starpu_bound.h File Reference

#include <stdio.h>
Functions

- void starpu_bound_start (int deps, int prio)
- void starpu_bound_stop (void)
- void starpu_bound_print_dot (FILE *output)
- void starpu_bound_compute (double *res, double *integer_res, int integer)
- void starpu_bound_print_lp (FILE *output)
- void starpu_bound_print_mps (FILE *output)
- void starpu_bound_print (FILE *output, int integer)

32.4 starpu_clusters.h File Reference

```c
#include <starpu_config.h>
#include <hwloc.h>
```

Macros

- #define STARPU_CLUSTER_MIN_NB
- #define STARPU_CLUSTER_MAX_NB
- #define STARPU_CLUSTER_NB
- #define STARPU_CLUSTER_PREFERE_MIN
- #define STARPU_CLUSTER_KEEP_HOMOGENEOUS
- #define STARPU_CLUSTER_POLICY_NAME
- #define STARPU_CLUSTER_POLICY_STRUCT
- #define STARPU_CLUSTER_CREATE_FUNC
- #define STARPU_CLUSTER_CREATE_FUNC_ARG
- #define STARPU_CLUSTER_TYPE
- #define STARPU_CLUSTER_AWAKE_WORKERS
- #define STARPU_CLUSTER_PARTITION_ONE
- #define STARPU_CLUSTER_NEW
- #define STARPU_CLUSTER_NCORES
- #define starpu_intel_openmp_mkl_prologue

Enumerations

- enum starpu_cluster_types { STARPU_CLUSTER_OPENMP, STARPU_CLUSTER_INTEL_OPENMP_MKL, STARPU_CLUSTER_GNU_OPENMP_MKL }

Functions

- struct starpu_cluster_machine *starpu_cluster_machine (hwloc_obj_type_t cluster_level,...)
- int starpu_uncluster_machine (struct starpu_cluster_machine *clusters)
- int starpu_cluster_print (struct starpu_cluster_machine *clusters)
- void starpu_openmp_prologue (void *)
- void starpu_gnu_openmp_mkl_prologue (void *)

32.5 starpu_config.h File Reference

```c
#include <sys/types.h>
```
Macros

- `#define STARPU_MAJOR_VERSION`
- `#define STARPU_MINOR_VERSION`
- `#define STARPU_RELEASE_VERSION`
- `#define STARPU_USE_CPU`
- `#define STARPU_USE_CUDA`
- `#define STARPU_USE_OPENCL`
- `#define STARPU_USE_MIC`
- `#define STARPU_OPENMP`
- `#define STARPU_CLUSTER`
- `#define STARPU_SIMGRID`
- `#define STARPU_SIMGRID_MC`
- `#define STARPU_SIMGRID_HAVE_XBT_BARRIER_INIT`
- `#define STARPU_HAVE_SIMGRID_MSG_H`
- `#define STARPU_HAVE_XBT_SYNCHRO_H`
- `#define STARPU_HAVE_VALGRIND_H`
- `#define STARPU_HAVE_MEMCHECK_H`
- `#define STARPU_VALGRIND_FULL`
- `#define STARPU_SANITIZE_LEAK`
- `#define STARPU_NON_BLOCKING_DRIVERS`
- `#define STARPU_WORKER_CALLBACKS`
- `#define STARPU_HAVE_ICC`
- `#define STARPU_USE_MPI`
- `#define STARPU_USE_MPI_MPI`
- `#define STARPU_USE_MPI_NMAD`
- `#define STARPU_ATLAS`
- `#define STARPU_GOTO`
- `#define STARPU_OPENBLAS`
- `#define STARPU_MKL`
- `#define STARPU_ARMPL`
- `#define STARPU_SYSTEM_BLAS`
- `#define STARPU_OPENCL_DATADIR`
- `#define STARPU_HAVE_MAGMA`
- `#define STARPU_OPENGL_RENDER`
- `#define STARPU_USE_GTK`
- `#define STARPU_HAVE_X11`
- `#define STARPU_HAVE_POSIX_MEMALIGN`
- `#define STARPU_HAVE_MEMALIGN`
- `#define STARPU_HAVE_MALLOC_H`
- `#define STARPU_HAVE_SYNC_BOOL_COMPARE_AND_SWAP`
- `#define STARPU_HAVE_SYNC_VAL_COMPARE_AND_SWAP`
- `#define STARPU_HAVE_SYNC_FETCH_AND_ADD`
- `#define STARPU_HAVE_SYNC_FETCH_AND_OR`
- `#define STARPU_HAVE_SYNC_LOCK_TEST_AND_SET`
- `#define STARPU_HAVE_SYNC_SYNCHRONIZE`
- `#define STARPU_DEVEL`
- `#define STARPU_MODEL_DEBUG`
- `#define STARPU_NO_ASSERT`
- `#define STARPU_DEBUG`
- `#define STARPU_VERBOSE`
- `#define STARPU_GDB_PATH`
- `#define STARPU_HAVE_FFTW`
- `#define STARPU_HAVE_FFTWF`
• `#define STARPU_HAVE_CUFFTDOUBLECOMPLEX`
• `#define STARPU_HAVE_CURAND`
• `#define STARPU_MAXNODES`
• `#define STARPU_NMAXBUFS`
• `#define STARPU_MAXCPUS`
• `#define STARPU_MAXNUMANODES`
• `#define STARPU_MAXCUDADEVCS`
• `#define STARPU_MAXOPENCLDEVCS`
• `#define STARPU_MAXMICDEVCS`
• `#define STARPU_NMAXWORKERS`
• `#define STARPU_NMAX_SCHED_CTXS`
• `#define STARPU_MAXIMPLEMENTATIONS`
• `#define STARPU_MAXMPKERNELS`
• `#define STARPU_USE_SC_HYPERVISOR`
• `#define STARPU_SC_HYPERVISOR_DEBUG`
• `#define STARPU_HAVE_GLPK_H`
• `#define STARPU_HAVE_CUDA_MEMCPY_PEER`
• `#define STARPU_HAVE_LIBNUMA`
• `#define STARPU_HAVE_WINDOWS`
• `#define STARPU_LINUX_SYS`
• `#define STARPU_HAVE_SETENV`
• `#define STARPU_HAVE_UNSETENV`
• `#define STARPU_HAVE_UNISTD_H`
• `#define STARPU_HAVE_HDF5`
• `#define STARPU_USE_FXT`
• `#define STARPU_FXT_LOCK_TRACES`
• `#define __starpu_func__`
• `#define __starpu_inline`
• `#define STARPU_QUICK_CHECK`
• `#define STARPU_LONG_CHECK`
• `#define STARPU_USE_DRAND48`
• `#define STARPU_USE_ERAND48_R`
• `#define STARPU_HAVE_NEARBYINTF`
• `#define STARPU_HAVE_RINTF`
• `#define STARPU_HAVE_HWLOC`
• `#define STARPU_HAVE_PTHREAD_SPIN_LOCK`
• `#define STARPU_HAVE_PTHREAD_BARRIER`
• `#define STARPU_HAVE_PTHREAD_SETNAME_NP`
• `#define STARPU_HAVE_STRUCT_TIMESPEC`
• `#define STARPU_HAVE_HELGRIND_H`
• `#define HAVE_MPI_COMM_F2C`
• `#define STARPU_HAVE_DARWIN`
• `#define STARPU_HAVE_CXX11`
• `#define STARPU_HAVE_STRError_R`
• `#define STARPU_HAVE_STATEMENT_EXPRESSIONS`
• `#define STARPU_PERF_MODEL_DIR`

MPI Master Slave

• `#define STARPU_USE_MPI_MASTER_SLAVE`

Typedefs

• `typedef ssize_t starpu_ssize_t`
32.6  starpu_cublas.h File Reference

Functions

- void starpu_cublas_init (void)
- void starpu_cublas_set_stream (void)
- void starpu_cublas_shutdown (void)

32.7  starpu_cusparse.h File Reference

```c
#include <cusparse.h>
```

Functions

- void starpu_cusparse_init (void)
- void starpu_cusparse_shutdown (void)
- cusparseHandle_t starpu_cusparse_get_local_handle (void)

32.8  starpu_cuda.h File Reference

```c
#include <starpu_config.h>
#include <cuda.h>
#include <cuda_runtime.h>
#include <cuda_runtime_api.h>
```

Macros

- #define STARPU_CUBLAS_REPORT_ERROR(status)
- #define STARPU_CUDA_REPORT_ERROR(status)

Functions

- void starpu_cublas_report_error (const char *func, const char *file, int line, int status)
- void starpu_cuda_report_error (const char *func, const char *file, int line, cudaError_t status)
- cudaStream_t starpu_cuda_get_local_stream (void)
- const struct cudaDeviceProp *starpu_cuda_get_device_properties (unsigned workerid)
- int starpu_cuda_copy_async_sync (void *src_ptr, unsigned src_node, void *dst_ptr, unsigned dst_node, size_t ssize, cudaStream_t stream, enum cudaMemcpyKind kind)
- void starpu_cuda_set_device (unsigned devid)

32.9  starpu_data.h File Reference

```c
#include <starpu.h>
```

Typedefs

- typedef struct _starpu_data_state * starpu_data_handle_t
- typedef struct starpu_arbiter * starpu_arbiter_t
Enumerations

- **enum starpu_data_access_mode {**
  - **STARPU_NONE, STARPU_R, STARPU_W, STARPU_RW,**
  - **STARPU_SCRATCH, STARPU_REDUX, STARPU_COMMUTE, STARPU_SSEND,**
  - **STARPU_LOCALITY, STARPU_ACCESS_MODE_MAX }**

Functions

- **void starpu_data_set_name (starpu_data_handle_t handle, const char ∗name)**
- **void starpu_data_set_coordinates_array (starpu_data_handle_t handle, int dimensions, int dims[ ])**
- **void starpu_data_set_coordinates (starpu_data_handle_t handle, unsigned dimensions,...)**
- **void starpu_data_unregister (starpu_data_handle_t handle)**
- **void starpu_data_unregister_no_coherency (starpu_data_handle_t handle)**
- **void starpu_data_unregister_submit (starpu_data_handle_t handle)**
- **void starpu_data_invalidate (starpu_data_handle_t handle)**
- **void starpu_data_invalidate_submit (starpu_data_handle_t handle)**
- **void starpu_data_advise_as_important (starpu_data_handle_t handle, unsigned is_important)**
- **starpu_arbiter_t starpu_arbiter_create (void) STARPU_ATTRIBUTE_MALLOC**
- **void starpu_data_assign_arbiter (starpu_data_handle_t handle, starpu_arbiter_t arbiter)**
- **void starpu_arbiter_destroy (starpu_arbiter_t arbiter)**
- **int starpu_data_request_allocation (starpu_data_handle_t handle, unsigned node)**
- **int starpu_data_fetch_on_node (starpu_data_handle_t handle, unsigned node, unsigned async)**
- **int starpu_data_prefetch_on_node (starpu_data_handle_t handle, unsigned node, unsigned async)**
- **int starpu_data_idle_prefetch_on_node (starpu_data_handle_t handle, unsigned node, unsigned async)**
- **unsigned starpu_data_is_on_node (starpu_data_handle_t handle, unsigned node)**
- **void starpu_data_wont_use (starpu_data_handle_t handle)**
- **void starpu_data_set_wt_mask (starpu_data_handle_t handle, uint32_t wt_mask)**
- **void starpu_data_set_ooc_flag (starpu_data_handle_t handle, unsigned flag)**
- **unsigned starpu_data_query_status (starpu_data_handle_t handle, int memory_node, int ∗is_allocated, int ∗is←_valid, int ∗is←_requested)**
- **void starpu_data_set_reduction_methods (starpu_data_handle_t handle, struct starpu_codelet ∗redux_cl,**
  - **struct starpu_codelet ∗init_cl)**
- **unsigned starpu_data_test_if_allocated_on_node (starpu_data_handle_t handle, unsigned memory_node)**
- **void starpu_memchunk_tidy (unsigned memory_node)**
- **void starpu_data_set_user_data (starpu_data_handle_t handle, void ∗user_data)**
- **void ∗starpu_data_get_user_data (starpu_data_handle_t handle)**

Implicit Data Dependencies

*In this section, we describe how StarPU makes it possible to insert implicit task dependencies in order to enforce sequential data consistency. When this data consistency is enabled on a specific data handle, any data access will appear as sequentially consistent from the application. For instance, if the application submits two tasks that access the same piece of data in read-only mode, and then a third task that access it in write mode, dependencies will be added between the two first tasks and the third one. Implicit data dependencies are also inserted in the case of data accesses from the application.*

- **void starpu_data_set_sequential_consistency_flag (starpu_data_handle_t handle, unsigned flag)**
- **unsigned starpu_data_get_sequential_consistency_flag (starpu_data_handle_t handle)**
- **unsigned starpu_data_get_default_sequential_consistency_flag (void)**
- **void starpu_data_set_default_sequential_consistency_flag (unsigned flag)**
Access registered data from the application

- `#define STARPU_ACQUIRE_NO_NODE`
- `#define STARPU_ACQUIRE_NO_NODE_LOCK_ALL`
- `#define STARPU_DATA_ACQUIRE_CB(handle, mode, code)`
- `int starpu_data_acquire (starpu_data_handle_t handle, enum starpu_data_access_mode mode)`
- `int starpu_data_acquire_on_node (starpu_data_handle_t handle, int node, enum starpu_data_access_mode mode)`
- `int starpu_data_acquire_cb (starpu_data_handle_t handle, enum starpu_data_access_mode mode, void(∗callback)(void ∗), void ∗arg)`
- `int starpu_data_acquire_on_node_cb (starpu_data_handle_t handle, int node, enum starpu_data_access_mode mode, void(∗callback)(void ∗), void ∗arg)`
- `int starpu_data_acquire_cb_sequential_consistency (starpu_data_handle_t handle, enum starpu_data_access_mode mode, void(∗callback)(void ∗), void ∗arg, int sequential_consistency)`
- `int starpu_data_acquire_on_node_cb_sequential_consistency (starpu_data_handle_t handle, int node, enum starpu_data_access_mode mode, void(∗callback)(void ∗), void ∗arg, int sequential_consistency)`
- `int starpu_data_acquire_on_node_cb_sequential_consistency_quick (starpu_data_handle_t handle, int node, enum starpu_data_access_mode mode, void(∗callback)(void ∗), void ∗arg, int sequential_consistency, int quick)`
- `int starpu_data_acquire_on_node_cb_sequential_consistency_sync_jobids (starpu_data_handle_t handle, int node, enum starpu_data_access_mode mode, void(∗callback)(void ∗), void ∗arg, int sequential_consistency, int quick, int pre_sync_jobid, int post_sync_jobid)`
- `int starpu_data_acquire_try (starpu_data_handle_t handle, enum starpu_data_access_mode mode)`
- `int starpu_data_acquire_on_node_try (starpu_data_handle_t handle, int node, enum starpu_data_access_mode mode)`
- `void starpu_data_release (starpu_data_handle_t handle)`
- `void starpu_data_release_on_node (starpu_data_handle_t handle, int node)`

### 32.10 starpu_data_filters.h File Reference

```
#include <starpu.h>
#include <stdarg.h>
```

**Data Structures**

- `struct starpu_data_filter`

**Functions**

#### Basic API

- `void starpu_data_partition (starpu_data_handle_t initial_handle, struct starpu_data_filter ∗f)`
- `void starpu_data_unpartition (starpu_data_handle_t root_data, unsigned gathering_node)`
- `starpu_data_handle_t starpu_data_get_child (starpu_data_handle_t handle, unsigned i)`
- `int starpu_data_get_nb_children (starpu_data_handle_t handle)`
- `starpu_data_handle_t starpu_data_get_sub_data (starpu_data_handle_t root_data, unsigned depth,...)`
- `starpu_data_handle_t starpu_data_vget_sub_data (starpu_data_handle_t root_data, unsigned depth, va_list pa)`
- `void starpu_data_map_filters (starpu_data_handle_t root_data, unsigned nfilters,...)`
- `void starpu_data_vmap_filters (starpu_data_handle_t root_data, unsigned nfilters, va_list pa)`

#### Asynchronous API

- `void starpu_data_partition_plan (starpu_data_handle_t initial_handle, struct starpu_data_filter ∗f, starpu_data_handle_t ∗children)`
- `void starpu_data_partition_submit (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t ∗children)`

Generated by Doxygen
• void starpu_data_partition_readonly_submit (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t *children)
• void starpu_data_partition_readwrite_upgrade_submit (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t *children)
• void starpu_data_unpartition_submit (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t *children, int gathering_node)
• void starpu_data_unpartition_submit_r (starpu_data_handle_t initial_handle, int gathering_node)
• void starpu_data_unpartition_readonly_submit (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t *children, int gathering_node)
• void starpu_data_partition_clean (starpu_data_handle_t root_data, unsigned nparts, starpu_data_handle_t *children)
• void starpu_data_unpartition_submit_sequential_consistency_cb (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t *children, int gather_node, int sequential_consistency, void(*callback_func)(void *), void *callback_arg)
• void starpu_data_partition_submit_sequential_consistency (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t *children, int sequential_consistency)
• void starpu_data_unpartition_submit_sequential_consistency (starpu_data_handle_t initial_handle, unsigned nparts, starpu_data_handle_t *children, int gathering_node, int sequential_consistency)
• void starpu_data_partition_not_automatic (starpu_data_handle_t handle)

Predefined BCSR Filter Functions
Predefined partitioning functions for BCSR data. Examples on how to use them are shown in Partitioning Data.

• void starpu_bcsr_filter_canonical_block (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)

struct starpu_data_interface_ops * starpu_bcsr_filter_canonical_block_child_ops (struct starpu_data_filter *f, unsigned child)

Predefined CSR Filter Functions
Predefined partitioning functions for CSR data. Examples on how to use them are shown in Partitioning Data.

• void starpu_csr_filter_vertical_block (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)

Predefined Matrix Filter Functions
Predefined partitioning functions for matrix data. Examples on how to use them are shown in Partitioning Data.

• void starpu_matrix_filter_block (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)

• void starpu_matrix_filter_block_shadow (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)

• void starpu_matrix_filter_vertical_block (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)

• void starpu_matrix_filter_vertical_block_shadow (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)

Predefined Vector Filter Functions
Predefined partitioning functions for vector data. Examples on how to use them are shown in Partitioning Data.

• void starpu_vector_filter_block (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)

• void starpu_vector_filter_block_shadow (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)

• void starpu_vector_filter_list_long (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)

• void starpu_vector_filter_list (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)

• void starpu_vector_filter_divide_in_2 (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
Predefined Block Filter Functions

Predefined partitioning functions for block data. Examples on how to use them are shown in Partitioning Data. An example is available in examples/filters/shadow3d.c

- void starpu_block_filter_block (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void starpu_block_filter_block_shadow (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void starpu_block_filter_vertical_block (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void starpu_block_filter_vertical_block_shadow (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void starpu_block_filter_depth_block (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void starpu_block_filter_depth_block_shadow (void *father_interface, void *child_interface, struct starpu_data_filter *f, unsigned id, unsigned nparts)
- void starpu_filter_nparts_compute_chunk_size_and_offset (unsigned n, unsigned nparts, size_t elemsize, unsigned id, unsigned Id, unsigned *chunk_size, size_t *offset)

32.11 starpu_data_interfaces.h File Reference

```
#include <starpu.h>
#include <cuda_runtime.h>
```

Data Structures

- struct starpu_data_copy_methods
- struct starpu_data_interface_ops
- struct starpu_matrix_interface
- struct starpu_coo_interface
- struct starpu_block_interface
- struct starpu_vector_interface
- struct starpu_variable_interface
- struct starpu_csr_interface
- struct starpu_bcsr_interface
- struct starpu_multiformat_data_interface_ops
- struct starpu_multiformat_interface

Typedefs

- typedef cudaStream_t starpu_cudaStream_t

Enumerations

- enum starpu_data_interface_id {
  STARPU_UNKNOWN_INTERFACE_ID, STARPU_MATRIX_INTERFACE_ID, STARPU_BLOCK_INTERFACE_ID, STARPU_VECTOR_INTERFACE_ID,
  STARPU_CSR_INTERFACE_ID, STARPU_BCSR_INTERFACE_ID, STARPU_VARIABLE_INTERFACE_ID,
  STARPU_VOID_INTERFACE_ID,
  STARPU_MAX_INTERFACE_ID
}
Functions

Basic API

- void starpu_data_register (starpu_data_handle_t *handleptr, int home_node, void *data_interface, struct starpu_data_interface_ops *ops)
- void starpu_data_ptr_register (starpu_data_handle_t handle, unsigned node)
- void starpu_data_register_same (starpu_data_handle_t *handledst, starpu_data_handle_t handlesrc)
- void *starpu_data_handle_to_pointer (starpu_data_handle_t handle, unsigned node)
- int starpu_data_pointer_is_inside (starpu_data_handle_t handle, unsigned node, void *ptr)
- void *starpu_data_get_local_ptr (starpu_data_handle_t handle)
- void *starpu_data_get_interface_on_node (starpu_data_handle_t handle, unsigned memory_node)
- enum starpu_data_interface_id starpu_data_get_interface_id (starpu_data_handle_t handle)
- int starpu_data_pack (starpu_data_handle_t handle, void **ptr, starpu_ssize_t *count)
- int starpu_data_unpack (starpu_data_handle_t handle, void *ptr, size_t count)
- size_t starpu_data_get_size (starpu_data_handle_t handle)
- size_t starpu_data_get_alloc_size (starpu_data_handle_t handle)
- starpu_data_handle_t starpu_data_lookup (const void *ptr)
- int starpu_data_get_home_node (starpu_data_handle_t handle)
- int starpu_data_interface_get_next_id (void)
- int starpu_interface_copy (uintptr_t src, size_t src_offset, unsigned src_node, uintptr_t dst, size_t dst_offset, unsigned dst_node, void *async_data)
- void starpu_interface_start_driver_copy_async (unsigned src_node, unsigned dst_node, double *start)
- void starpu_interface_end_driver_copy_async (unsigned src_node, unsigned dst_node, double start)
- void starpu_interface_data_copy (unsigned src_node, unsigned dst_node, size_t size)
- uintptr_t starpu_malloc_on_node_flags (unsigned dst_node, size_t size, int flags)
- void starpu_free_on_node_flags (unsigned dst_node, uintptr_t addr, size_t size, int flags)
- void starpu_free_on_node (unsigned dst_node, uintptr_t addr, size_t size)
- void starpu_malloc_on_node_set_default_flags (unsigned node, int flags)

Accessing Matrix Data Interfaces

- #define STARPU_MATRIX_GET_PTR(interface)
- #define STARPU_MATRIX_GET_DEV_HANDLE(interface)
- #define STARPU_MATRIX_GET_OFFSET(interface)
- #define STARPU_MATRIX_GET_NX(interface)
- #define STARPU_MATRIX_GET_NY(interface)
- #define STARPU_MATRIX_GET_LD(interface)
- #define STARPU_MATRIX_GET_ELEMSIZE(interface)
- #define STARPU_MATRIX_GET_ALLOCSIZE(interface)
- #define STARPU_MATRIX_SET_NX(interface, newnx)
- #define STARPU_MATRIX_SET_NY(interface, newny)
- #define STARPU_MATRIX_SET_LD(interface, newld)

- struct starpu_data_interface_ops starpu_interface_matrix_ops
- void starpu_matrix_data_register (starpu_data_handle_t *handle, int home_node, uintptr_t ptr, uint32_t ld, uint32_t nx, uint32_t ny, size_t elemsize)
- void starpu_matrix_data_register_allocsize (starpu_data_handle_t *handle, int home_node, uintptr_t ptr, uint32_t ld, uint32_t nx, uint32_t ny, size_t elemsize, size_t allocsize)
- void starpu_matrix_ptr_register (starpu_data_handle_t handle, unsigned node, uintptr_t ptr, uintptr_t devptr, size_t offset, int flags)
- uint32_t starpu_matrix_get_nx (starpu_data_handle_t handle)
- uint32_t starpu_matrix_get_ny (starpu_data_handle_t handle)
- uint32_t starpu_matrix_get_local_ld (starpu_data_handle_t handle)
- size_t starpu_matrix_get_local_ptr (starpu_data_handle_t handle)
- size_t starpu_matrix_get_elemsize (starpu_data_handle_t handle)
- size_t starpu_matrix_get_allocsize (starpu_data_handle_t handle)
Accessing COO Data Interfaces

- \#define STARPU_COO_GET_COLUMNS(interface)
- \#define STARPU_COO_GET_COLUMNS_DEV_HANDLE(interface)
- \#define STARPU_COO_GET_ROWS(interface)
- \#define STARPU_COO_GET_ROWS_DEV_HANDLE(interface)
- \#define STARPU_COO_GET_VALUES(interface)
- \#define STARPU_COO_GET_VALUES_DEV_HANDLE(interface)
- \#define STARPU_COO_GET_OFFSET
- \#define STARPU_COO_GET_NX(interface)
- \#define STARPU_COO_GET_NY(interface)
- \#define STARPU_COO_GET_NVALUES(interface)
- \#define STARPU_COO_GET_ELEMSIZE(interface)

- struct starpu_data_interface_ops
  - starpu_coo_ops

- void starpu_coo_data_register (starpu_data_handle_t *handleptr, int home_node, uint32_t nx, uint32_t ny, uint32_t n_values, uint32_t *columns, uint32_t *rows, uintptr_t values, size_t elemsize)

Block Data Interface

- \#define STARPU_BLOCK_GET_PTR(interface)
- \#define STARPU_BLOCK_GET_DEV_HANDLE(interface)
- \#define STARPU_BLOCK_GET_OFFSET(interface)
- \#define STARPU_BLOCK_GET_NX(interface)
- \#define STARPU_BLOCK_GET_NY(interface)
- \#define STARPU_BLOCK_GET_NZ(interface)
- \#define STARPU_BLOCK_GET_LDY(interface)
- \#define STARPU_BLOCK_GET_LDZ(interface)
- \#define STARPU_BLOCK_GET_ELEMSIZE(interface)

- struct starpu_data_interface_ops
  - starpu_block_ops

- void starpu_block_data_register (starpu_data_handle_t *handle, int home_node, uintptr_t ptr, uint32_t ldy, uint32_t ldz, uint32_t nx, uint32_t ny, uint32_t nz, size_t elemsize)

- void starpu_block_ptr_register (starpu_data_handle_t handle, unsigned node, uintptr_t ptr, uintptr_t dev_handle, size_t offset, uint32_t ldy, uint32_t ldz)

- uint32_t starpu_block_get_nx (starpu_data_handle_t handle)
- uint32_t starpu_block_get_ny (starpu_data_handle_t handle)
- uint32_t starpu_block_get_nz (starpu_data_handle_t handle)
- uint32_t starpu_block_get_local_ldy (starpu_data_handle_t handle)
- uint32_t starpu_block_get_local_ldz (starpu_data_handle_t handle)

- uintptr_t starpu_block_get_local_ptr (starpu_data_handle_t handle)
- size_t starpu_block_get_elemsize (starpu_data_handle_t handle)

Vector Data Interface

- \#define STARPU_VECTOR_GET_PTR(interface)
- \#define STARPU_VECTOR_GET_DEV_HANDLE(interface)
- \#define STARPU_VECTOR_GET_OFFSET(interface)
- \#define STARPU_VECTOR_GET_NX(interface)
- \#define STARPU_VECTOR_GET_ELEMSIZE(interface)
- \#define STARPU_VECTOR_GET_ALLOCSIZE(interface)
- \#define STARPU_VECTOR_GET_SLICE_BASE(interface)
- \#define STARPU_VECTOR_SET_NX(interface, newnx)

- struct starpu_data_interface_ops
  - starpu_vector_ops

- void starpu_vector_data_register (starpu_data_handle_t *handle, int home_node, uintptr_t ptr, uint32_t nx, size_t elemsize)

- void starpu_vector_data_register_allocsize (starpu_data_handle_t *handle, int home_node, uintptr_t ptr, uint32_t nx, size_t elemsize, size_t allocsize)
• void starpu_vector_ptr_register (starpu_data_handle_t handle, unsigned node, uintptr_t ptr, uintptr_t dev_handle, size_t offset)
• uint32_t starpu_vector_get_nx (starpu_data_handle_t handle)
• size_t starpu_vector_get elemsize (starpu_data_handle_t handle)
• size_t starpu_vector_get allocsize (starpu_data_handle_t handle)
• uintptr_t starpu_vector_get local_ptr (starpu_data_handle_t handle)

Variable Data Interface

• #define STARPU_VARIABLE_GET_PTR(interface)
• #define STARPU_VARIABLE_GET_OFFSET(interface)
• #define STARPU_VARIABLE_GET_ELEM_SIZE(interface)
• #define STARPU_VARIABLE_GET_DEV_HANDLE(interface)
• struct starpu_data_interface_ops starpu_interface_variable_ops
  • void starpu_variable_data_register (starpu_data_handle_t *handle, int home_node, uintptr_t ptr, size_t size)
  • void starpu_variable_ptr_register (starpu_data_handle_t handle, unsigned node, uintptr_t ptr, uintptr_t dev_handle, size_t offset)
  • size_t starpu_variable_get elemsize (starpu_data_handle_t handle)
  • uintptr_t starpu_variable_get local_ptr (starpu_data_handle_t handle)

Void Data Interface

• struct starpu_data_interface_ops starpu_interface_void_ops
• void starpu_void_data_register (starpu_data_handle_t *handle)

CSR Data Interface

• #define STARPU_CSR_GET_NNZ(interface)
• #define STARPU_CSR_GET_NROW(interface)
• #define STARPU_CSR_GET_NZVAL(interface)
• #define STARPU_CSR_GET_NZVAL_DEV_HANDLE(interface)
• #define STARPU_CSR_GET_COLIND(interface)
• #define STARPU_CSR_GET_COLIND_DEV_HANDLE(interface)
• #define STARPU_CSR_GET_ROWPTR(interface)
• #define STARPU_CSR_GET_ROWPTR_DEV_HANDLE(interface)
• #define STARPU_CSR_GET_OFFSET
• #define STARPU_CSR_GET_FIRSTENTRY(interface)
• #define STARPU_CSR_GET_ELEM_SIZE(interface)
• struct starpu_data_interface_ops starpu_interface_csr_ops
  • void starpu_csr_data_register (starpu_data_handle_t *handle, int home_node, uint32_t nnz, uint32_t nrow, uintptr_t nzval, uint32_t *colind, uint32_t *rowptr, uint32_t firstentry, size_t elemsize)
  • uint32_t starpu_csr_get nnz (starpu_data_handle_t handle)
  • uint32_t starpu_csr_get nrow (starpu_data_handle_t handle)
  • uint32_t starpu_csr_get firstentry (starpu_data_handle_t handle)
  • uintptr_t starpu_csr_get local nzval (starpu_data_handle_t handle)
  • uint32_t * starpu_csr_get local colind (starpu_data_handle_t handle)
  • uint32_t * starpu_csr_get local rowptr (starpu_data_handle_t handle)
  • size_t starpu_csr_get elemsize (starpu_data_handle_t handle)
BCSR Data Interface

- `#define STARPU_BCSR_GET_NNZ(interface)`
- `#define STARPU_BCSR_GET_NZVAL(interface)`
- `#define STARPU_BCSR_GET_NZVAL_DEV_HANDLE(interface)`
- `#define STARPU_BCSR_GET_COLIND(interface)`
- `#define STARPU_BCSR_GET_COLIND_DEV_HANDLE(interface)`
- `#define STARPU_BCSR_GET_ROWPTR(interface)`
- `#define STARPU_BCSR_GET_ROWPTR_DEV_HANDLE(interface)`
- `#define STARPU_BCSR_GET_OFFSET`

```c
struct starpu_data_interface_ops
starpu_interface_bcsr_ops
```

```c
void starpu_bcsr_data_register (starpu_data_handle_t *handle, int home_node, uint32_t nnz, uint32_t nrow, uintptr_t nzval, uint32_t *colind, uint32_t *rowptr, uint32_t firstentry, uint32_t r, uint32_t c, size_t elemsize)
```

```c
uint32_t starpu_bcsr_get_nnz (starpu_data_handle_t handle)
```

```c
uint32_t starpu_bcsr_get_nrow (starpu_data_handle_t handle)
```

```c
uint32_t starpu_bcsr_get_firstentry (starpu_data_handle_t handle)
```

```c
uintptr_t starpu_bcsr_get_local_nzval (starpu_data_handle_t handle)
```

```c
uint32_t *starpu_bcsr_get_local_colind (starpu_data_handle_t handle)
```

```c
uint32_t *starpu_bcsr_get_local_rowptr (starpu_data_handle_t handle)
```

```c
uint32_t starpu_bcsr_get_r (starpu_data_handle_t handle)
```

```c
uint32_t starpu_bcsr_get_c (starpu_data_handle_t handle)
```

```c
size_t starpu_bcsr_get_elemsize (starpu_data_handle_t handle)
```

Multiformat Data Interface

- `#define STARPU_MULTIFORMAT_GET_CPU_PTR(interface)`
- `#define STARPU_MULTIFORMAT_GET_CUDA_PTR(interface)`
- `#define STARPU_MULTIFORMAT_GET_OPENCL_PTR(interface)`
- `#define STARPU_MULTIFORMAT_GET_MIC_PTR(interface)`
- `#define STARPU_MULTIFORMAT_GET_NX(interface)`

```c
void starpu_multiformat_data_register (starpu_data_handle_t *handle, int home_node, void *ptr, uint32_t nobjects, struct starpu_multiformat_data_interface_ops *format_ops)
```

32.12 starpu_deprecated_api.h File Reference

Macros

- `#define starpu_permodel_history_based_expected_perf`

32.13 starpu_disk.h File Reference

```c
#include <sys/types.h>
#include <starpu_config.h>
```

Data Structures

- `struct starpu_disk_ops`

Macros

- `#define STARPU_DISK_SIZE_MIN`
Functions

- void starpu_disk_close (unsigned node, void *obj, size_t size)
- void *starpu_disk_open (unsigned node, void *pos, size_t size)
- int starpu_disk_register (struct starpu_disk_ops *func, void *parameter, starpu_ssize_t size)

Variables

- struct starpu_disk_ops starpu_disk_stdio_ops
- struct starpu_disk_ops starpu_disk_hdf5_ops
- struct starpu_disk_ops starpu_disk_unistd_ops
- struct starpu_disk_ops starpu_disk_unistd_o_direct_ops
- struct starpu_disk_ops starpu_disk_leveldb_ops
- int starpu_disk_swap_node

32.14 starpu_driver.h File Reference

#include <starpu_config.h>
#include <starpu_opencl.h>

Data Structures

- struct starpu_driver
- union starpu_driver.id

Functions

- int starpu_driver_run (struct starpu_driver *d)
- void starpu_drivers_request_termination (void)
- int starpu_driver_init (struct starpu_driver *d)
- int starpu_driver_run_once (struct starpu_driver *d)
- int starpu_driver_deinit (struct starpu_driver *d)

32.15 starpu_expert.h File Reference

Functions

- void starpu_wake_all_blocked_workers (void)
- int starpu_progression_hook_register (unsigned(*)(void*)func)(void *arg), void *arg)
- void starpu_progression_hook_deregister (int hook_id)
- int starpu_idle_hook_register (unsigned(*)(void*)func)(void *arg), void *arg)
- void starpu_idle_hook_deregister (int hook_id)

32.16 starpu_fxt.h File Reference

#include <starpu_perfmodel.h>

Data Structures

- struct starpu_fxt_codelet_event
- struct starpu_fxt_options
Macros

- `#define STARPU_FXT_MAXFILES`

Functions

- `void starpu_fxt_options_init (struct starpu_fxt_options *options)`
- `void starpu_fxt_generate_trace (struct starpu_fxt_options *options)`
- `void starpu_fxt_autostart_profiling (int autostart)`
- `void starpu_fxt_start_profiling (void)`
- `void starpu_fxt_stop_profiling (void)`
- `void starpu_fxt_write_data_trace (char *filename_in)`
- `void starpu_fxt_trace_user_event (unsigned long code)`
- `void starpu_fxt_trace_user_event_string (const char *s)`

32.17 starpu_hash.h File Reference

```c
#include <stdint.h>
#include <stddef.h>
```

Functions

- `uint32_t starpu_hash_crc32c_be_n (const void *input, size_t n, uint32_t inputcrc)`
- `uint32_t starpu_hash_crc32c_be (uint32_t input, uint32_t inputcrc)`
- `uint32_t starpu_hash_crc32c_string (const char *str, uint32_t inputcrc)`

32.18 starpu_mic.h File Reference

```c
#include <starpu_config.h>
```

Typedefs

- `typedef void *starpu_mic_func_symbol_t`

Functions

- `int starpu_mic_register_kernel (starpu_mic_func_symbol_t *symbol, const char *func_name)`
- `starpu_mic_kernel_t starpu_mic_get_kernel (starpu_mic_func_symbol_t symbol)`

32.19 starpu_mod.f90 File Reference

Data Types

- `interface starpu_mod::starpu_conf_init`
- `interface starpu_mod::starpu_init`
- `interface starpu_mod::starpu_pause`
- `interface starpu_mod::starpu_resume`
- `interface starpu_mod::starpu_shutdown`
- `interface starpu_mod::starpu_asynchronous_copy_disabled`
- `interface starpu_mod::starpu_asynchronous_cuda_copy_disabled`
- `interface starpu_mod::starpu_asynchronous_opencl_copy_disabled`
- `interface starpu_mod::starpu_asynchronous_mic_copy_disabled`
- interface `starpu_mod:starpu_display_stats`
- interface `starpu_mod:starpu_get_version`
- interface `starpu_mod:starpu_cpu_worker_get_count`
- interface `starpu_mod:starpu_task_wait_for_all`

### 32.20 `starpu_mpi.h` File Reference

```c
#include <starpu.h>
#include <mpi.h>
#include <stdint.h>
```

#### Functions

- `int starpu_mpi_pre_submit_hook_register (void (*)(struct starpu_task *))`
- `int starpu_mpi_pre_submit_hook_unregister ()`

#### Communication Cache

- `int starpu_mpi_cache_is_enabled ()`
- `int starpu_mpi_cache_set (int enabled)`
- `void starpu_mpi_cache_flush (MPI_Comm comm, starpu_data_handle_t data_handle)`
- `void starpu_mpi_cache_flush_all_data (MPI_Comm comm)`
- `int starpu_mpi_cached_receive (starpu_data_handle_t data_handle)`
- `int starpu_mpi_cached_send (starpu_data_handle_t data_handle, int dest)`

#### Collective Operations

- `void starpu_mpi_redux_data (MPI_Comm comm, starpu_data_handle_t data_handle)`
- `void starpu_mpi_redux_data_prio (MPI_Comm comm, starpu_data_handle_t data_handle, int prio)`
- `int starpu_mpi_scatter_detached (starpu_data_handle_t *data_handles, int count, int root, MPI_Comm comm, void (*)(void *) scallback, void * sarg, void (*)(void *) rcallback, void * rarg)`
- `int starpu_mpi_gather_detached (starpu_data_handle_t *data_handles, int count, int root, MPI_Comm comm, void (*)(void *) scallback, void * sarg, void (*)(void *) rcallback, void * rarg)`

#### Initialisation

- `#define STARPU_MPI_TAG_UB`
- `int starpu_mpi_init_conf (int *argc, char ***argv, int initialize_mpi, MPI_Comm comm, struct starpu_conf *conf)`
- `int starpu_mpi_init (int *argc, char ***argv, int initialize_mpi)`
- `int starpu_mpi_init (int(argc) > 0)`
- `int starpu_mpi_backup (void)`
- `int starpu_mpi_initialize (void)`
- `int starpu_mpi_initialize_extended (int rank, int world_size)`
- `int starpu_mpi_shutdown (void)`
- `void starpu_mpi_comm_amounts_retrieve (size_t *comm_amounts)`
- `int starpu_mpi_comm_size (MPI_Comm comm, int *size)`
- `int starpu_mpi_comm_rank (MPI_Comm comm, int *rank)`
- `int starpu_mpi_world_rank (void)`
- `int starpu_mpi_world_size (void)`
- `int starpu_mpi_get_communication_tag (void)`
- `void starpu_mpi_set_communication_tag (int tag)`

Generated by Doxygen
• typedef void * starpu_mpi_tag_t
• typedef int64_t starpu_mpi_tag_t
• typedef void(
  * starpu_mpi_datatype_allocate_func_t
) (starpu_data_handle_t, MPI_Datatype *
  )
• typedef void(
  * starpu_mpi_datatype_free_func_t
) (MPI_Datatype *
  )

int starpu_mpi_isend (starpu_data_handle_t data_handle, starpu_mpi_req *req, int dest, starpu_mpi_tag_t
data_tag, MPI_Comm comm)

int starpu_mpi_isend_prio (starpu_data_handle_t data_handle, starpu_mpi_req *req, int dest, starpu_mpi_tag_t
data_tag, int prio, MPI_Comm comm)

int starpu_mpi_irecv (starpu_data_handle_t data_handle, starpu_mpi_req *req, int source, starpu_mpi_tag_t
data_tag, MPI_Comm comm)

int starpu_mpi_send (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag, MPI_Comm comm)

int starpu_mpi_send_prio (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag, int prio,
  MPI_Comm comm)

int starpu_mpi_recv (starpu_data_handle_t data_handle, int source, starpu_mpi_tag_t data_tag, MPI_Comm comm,
  MPI_Status *status)

int starpu_mpi_isend_detached (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag,
  MPI_Comm comm, void(*callback)(void *), void *arg)

int starpu_mpi_isend_detached_prio (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag,
  int prio, MPI_Comm comm, void(*callback)(void *), void *arg)

int starpu_mpi_irecv_detached (starpu_data_handle_t data_handle, int source, starpu_mpi_tag_t data_tag,
  MPI_Comm comm, void(*callback)(void *), void *arg)

int starpu_mpi_irecv_detached_sequential_consistency (starpu_data_handle_t data_handle, int source,
  starpu_mpi_tag_t data_tag, MPI_Comm comm, void(*callback)(void *), void *arg, int sequential_consistency)

int starpu_mpi_issend (starpu_data_handle_t data_handle, starpu_mpi_req *req, int dest, starpu_mpi_tag_t
data_tag, MPI_Comm comm)

int starpu_mpi_issend_prio (starpu_data_handle_t data_handle, starpu_mpi_req *req, int dest, starpu_mpi_tag_t
data_tag, int prio, MPI_Comm comm)

int starpu_mpi_wait (starpu_mpi_req *req, MPI_Status *status)

int starpu_mpi_test (starpu_mpi_req *req, int *flag, MPI_Status *status)

int starpu_mpi_barrier (MPI_Comm comm)

int starpu_mpi_wait_for_all (MPI_Comm comm)

int starpu_mpi_isend_detached_unlock_tag (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag,
  MPI_Comm comm, starpu_tag_t tag)

int starpu_mpi_isend_detached_unlock_tag_prio (starpu_data_handle_t data_handle, int dest, starpu_mpi_tag_t data_tag,
  int prio, MPI_Comm comm, starpu_tag_t tag)

int starpu_mpi_irecv_detached_unlock_tag (starpu_data_handle_t data_handle, int source, starpu_mpi_tag_t data_tag,
  MPI_Comm comm, starpu_tag_t tag)

int starpu_mpi_isend_array_detached_unlock_tag (unsigned array_size, starpu_data_handle_t *data_handle,
  int *dest, starpu_mpi_tag_t *data_tag, MPI_Comm *comm, starpu_tag_t tag)

int starpu_mpi_isend_array_detached_unlock_tag_prio (unsigned array_size, starpu_data_handle_t *data_handle,
  int *dest, starpu_mpi_tag_t *data_tag, int *prio, MPI_Comm *comm, starpu_tag_t tag)

int starpu_mpi_irecv_array_detached_unlock_tag (unsigned array_size, starpu_data_handle_t *data_handle,
  int *source, starpu_mpi_tag_t *data_tag, MPI_Comm *comm, starpu_tag_t tag)

int starpu_mpi_datatype_register (starpu_data_handle_t handle, starpu_mpi_datatype_allocate_func_t allocate_datatype_func,
  starpu_mpi_datatype_free_func_t free_datatype_func)

int starpu_mpi_datatype_unregister (starpu_data_handle_t handle)
MPI Insert Task

- #define STARPU_MPI_PER_NODE
- #define starpu_mpi_data_register(data_handle, data_tag, rank)
- #define starpu_mpi_data_set_tag
- #define starpu_mpi_data_set_rank(handle, rank)
- #define starpu_data_set_tag
- #define starpu_data_get_rank

void starpu_mpi_data_register_comm (starpu_data_handle_t data_handle, starpu_mpi_tag_t data_tag, int rank, MPI_Comm comm)
void starpu_mpi_data_set_tag (starpu_data_handle_t handle, starpu_mpi_tag_t data_tag)
void starpu_mpi_data_set_rank_comm (starpu_data_handle_t handle, int rank, MPI_Comm comm)
int starpu_mpi_data_get_rank (starpu_data_handle_t handle)

starpu_mpi_tag_t starpu_mpi_data_get_tag (starpu_data_handle_t handle)

int starpu_mpi_task_insert (MPI_Comm comm, struct starpu_codelet *codelet,...)
int starpu_mpi_insert_task (MPI_Comm comm, struct starpu_codelet *codelet,...)

struct starpu_task * starpu_mpi_task_build (MPI_Comm comm, struct starpu_codelet *codelet,...)
int starpu_mpi_task_post_build (MPI_Comm comm, struct starpu_codelet *codelet,...)

void starpu_mpi_get_data_on_node (MPI_Comm comm, starpu_data_handle_t data_handle, int node)
void starpu_mpi_get_data_on_node_detached (MPI_Comm comm, starpu_data_handle_t data_handle, int node, void (*callback)(void *), void *arg)
void starpu_mpi_get_data_on_all_nodes_detached (MPI_Comm comm, starpu_data_handle_t data_handle)
void starpu_mpi_data_migrate (MPI_Comm comm, starpu_data_handle_t data_handle, int new_rank)

Node Selection Policy

- #define STARPU_MPI_NODE_SELECTION_CURRENT_POLICY
- #define STARPU_MPI_NODE_SELECTION_MOST_R_DATA

typedef int (*)(starpu_mpi_select_node_policy_func_t) (int me, int nb_nodes, struct starpu_data_descr *descr, int nb_data)

int starpu_mpi_node_selection_register_policy (starpu_mpi_select_node_policy_func_t policy_func)
int starpu_mpi_node_selection_unregister_policy (int policy)
int starpu_mpi_node_selection_get_current_policy ()
int starpu_mpi_node_selection_set_current_policy (int policy)

32.21 starpu_mpi_lb.h File Reference

#include <starpu.h>

Data Structures

- struct starpu_mpi_lb_conf

Functions

- void starpu_mpi_lb_init (const char *lb_policy_name, struct starpu_mpi_lb_conf *)
- void starpu_mpi_lb_shutdown ()

32.22 starpu_opencl.h File Reference

#include <starpu config.h>
#include <CL/cl.h>
#include <assert.h>
Data Structures

- struct starpu_opencl_program

Macros

- \#define CL_TARGET_OPENCL_VERSION

Functions

Writing OpenCL kernels

- void starpu_opencl_get_context (int devid, cl_context ∗context)
- void starpu_opencl_get_device (int devid, cl_device_id ∗device)
- void starpu_opencl_get_queue (int devid, cl_command_queue ∗queue)
- void starpu_opencl_get_current_context (cl_context ∗context)
- void starpu_opencl_get_current_queue (cl_command_queue ∗queue)
- int starpu_opencl_set_kernel_args (cl_int ∗err, cl_kernel ∗kernel,...)

Compiling OpenCL kernels

Source codes for OpenCL kernels can be stored in a file or in a string. StarPU provides functions to build the program executable for each available OpenCL device as a cl_program object. This program executable can then be loaded within a specific queue as explained in the next section. These are only helpers. Applications can also fill a starpu_opencl_program array by hand for more advanced use (e.g. different programs on the different OpenCL devices, for relocation purpose for instance).

- void starpu_opencl_load_program_source (const char ∗source_file_name, char ∗located_file_name, char ∗located_dir_name, char ∗opencl_program_source)
- void starpu_opencl_load_program_source_malloc (const char ∗source_file_name, char ∗∗located_file_name, char ∗∗located_dir_name, char ∗∗opencl_program_source)
- int starpu_opencl_compile_opencl_from_file (const char ∗source_file_name, const char ∗build_options)
- int starpu_opencl_compile_opencl_from_string (const char ∗opencl_program_source, const char ∗file_name, const char ∗build_options)
- int starpu_opencl_load_binary_opencl (const char ∗kernel_id, struct starpu_opencl_program ∗opencl_programs)
- int starpu_opencl_load_opencl_from_file (const char ∗source_file_name, struct starpu_opencl_program ∗opencl_programs, const char ∗build_options)
- int starpu_opencl_load_opencl_from_string (const char ∗opencl_program_source, struct starpu_opencl_program ∗opencl_programs, const char ∗build_options)
- int starpu_opencl_unload_opencl (struct starpu_opencl_program ∗opencl_programs)

Loading OpenCL kernels

- int starpu_opencl_load_kernel (cl_kernel ∗kernel, cl_command_queue ∗queue, struct starpu_opencl_program ∗opencl_programs, const char ∗kernel_name, int devid)
- int starpu_opencl_release_kernel (cl_kernel kernel)

OpenCL Statistics

- int starpu_opencl_collect_stats (cl_event event)

OpenCL Utilities

- \#define STARPU_OPENCL_DISPLAY_ERROR(status)
- \#define STARPU_OPENCL_REPORT_ERROR(status)
- \#define STARPU_OPENCL_REPORT_ERROR_WITH_MSG(msg, status)
- const char ∗starpu_opencl_error_string (cl_int status)
- void starpu_opencl_display_error (const char ∗func, const char ∗file, int line, const char ∗msg, cl_int status)
- static __starpu_inline void starpu_opencl_report_error (const char ∗func, const char ∗file, int line, const char ∗msg, cl_int status)
- cl_int starpu_opencl_allocate_memory (int devid, cl_mem ∗addr, size_t size, cl_mem_flags flags)
32.23 starpu_openmp.h File Reference

```c
#include <starpu_config.h>
```

**Data Structures**

- `struct starpu_omp_lock_t`
- `struct starpu_omp_nest_lock_t`
- `struct starpu_omp_parallel_region_attr`
- `struct starpu_omp_task_region_attr`

**Macros**

- `#define __STARPU_OMP_NOTHROW`

**Enumerations**

- `enum starpu_omp_sched_value {
  starpu_omp_sched_undefined, starpu_omp_sched_static, starpu_omp_sched_dynamic,
  starpu_omp_sched_guided,
  starpu_omp_sched_auto, starpu_omp_sched_runtime }
- `enum starpu_omp_proc_bind_value {
  starpu_omp_proc_bind_undefined, starpu_omp_proc_bind_false, starpu_omp_proc_bind_true,
  starpu_omp_proc_bind_master,
  starpu_omp_proc_bind_close, starpu_omp_proc_bind_spread }

**Functions**

**Initialisation**

- `int starpu_omp_init (void) __STARPU_OMP_NOTHROW`
- `void starpu_omp_shutdown (void) __STARPU_OMP_NOTHROW`

**Parallel**

- `void starpu_omp_parallel_region (const struct starpu_omp_parallel_region_attr *attr) __STARPU_OMP_NOTHROW`
- `void starpu_omp_master (void(*)(void *arg), void *arg) __STARPU_OMP_NOTHROW`
- `int starpu_omp_master_inline (void) __STARPU_OMP_NOTHROW`

**Synchronization**

- `void starpu_omp_barrier (void) __STARPU_OMP_NOTHROW`
- `void starpu_omp_critical (void(*)(void *arg), void *arg, const char *name) __STARPU_OMP_NOTHROW`
- `void starpu_omp_critical_inline_begin (const char *name) __STARPU_OMP_NOTHROW`
- `void starpu_omp_critical_inline_end (const char *name) __STARPU_OMP_NOTHROW`

**Worksharing**

Generated by Doxygen
• void starpu_omp_single (void(*f)(void *arg), void *arg, int nowait) __STARPU_OMP_NOTHROW
• int starpu_omp_single (void(*)void *arg) __STARPU_OMP_NOTHROW
• void starpu_omp_single_copyprivate (void(*)(void *data, unsigned long long data_size), void *arg, void *data, unsigned long long data_size) __STARPU_OMP_NOTHROW
• void * starpu_omp_single_copyprivate_inline_begin (void *data) __STARPU_OMP_NOTHROW
• void starpu_omp_single_copyprivate_inline_end (void) __STARPU_OMP_NOTHROW
• void starpu_omp_for (void(*)(unsigned long long _first_i, unsigned long long _nb_i, void *arg), void *arg, unsigned long long nb_iterations, unsigned long long chunk, int schedule, int ordered, int nowait) __STARPU_OMP_NOTHROW
• int starpu_omp_for_inline_first (unsigned long long nb_iterations, unsigned long long chunk, int schedule, int ordered, unsigned long long *_first_i, unsigned long long *_nb_i) __STARPU_OMP_NOTHROW
• int starpu_omp_for_inline_next (unsigned long long nb_iterations, unsigned long long chunk, int schedule, int ordered, unsigned long long *_first_i, unsigned long long *_nb_i) __STARPU_OMP_NOTHROW
• void starpu_omp_for_alt (void(*)(unsigned long long _begin_i, unsigned long long _end_i, void *arg), void *arg, unsigned long long nb_iterations, unsigned long long chunk, int schedule, int ordered, int nowait) __STARPU_OMP_NOTHROW
• int starpu_omp_for_inline_first_alt (unsigned long long nb_iterations, unsigned long long chunk, int schedule, int ordered, unsigned long long *_begin_i, unsigned long long *_end_i) __STARPU_OMP_NOTHROW
• int starpu_omp_for_inline_next_alt (unsigned long long nb_iterations, unsigned long long chunk, int schedule, int ordered, unsigned long long *_begin_i, unsigned long long *_end_i) __STARPU_OMP_NOTHROW
• void starpu_omp_ordered (void(*)(void *arg), void *arg) __STARPU_OMP_NOTHROW
• void starpu_omp_ordered_inline_begin (void) __STARPU_OMP_NOTHROW
• void starpu_omp_ordered_inline_end (void) __STARPU_OMP_NOTHROW
• void starpu_omp_sections (unsigned long long nb_sections, void (*)(void *arg), void **section_arg, int nowait) __STARPU_OMP_NOTHROW
• void starpu_omp_sections_combined (unsigned long long nb_sections, void (*)(unsigned long section_num, void *arg), void *section_arg, int nowait) __STARPU_OMP_NOTHROW
• void starpu_omp_task_region (const struct starpu_omp_task_region_attr *attr) __STARPU_OMP_NOTHROW
• void starpu_omp_taskwait (void) __STARPU_OMP_NOTHROW
• void starpu_omp_taskgroup (void(*)(void *arg), void *arg) __STARPU_OMP_NOTHROW
• void starpu_omp_taskgroup_inline_begin (void) __STARPU_OMP_NOTHROW
• void starpu_omp_taskgroup_inline_end (void) __STARPU_OMP_NOTHROW
• void starpu_omp_taskloop_inline_begin (struct starpu_omp_task_region_attr *attr) __STARPU_OMP_NOTHROW
• void starpu_omp_taskloop_inline_end (const struct starpu_omp_task_region_attr *attr) __STARPU_OMP_NOTHROW
• void starpu_omp_set_num_threads (int threads) __STARPU_OMP_NOTHROW
• int starpu_omp_get_num_threads () __STARPU_OMP_NOTHROW
• int starpu_omp_get_thread_num () __STARPU_OMP_NOTHROW
• int starpu_omp_get_max_threads () __STARPU_OMP_NOTHROW
• int starpu_omp_get_num_procs (void) __STARPU_OMP_NOTHROW
• int starpu_omp_in_parallel (void) __STARPU_OMP_NOTHROW
• void starpu_omp_set_dynamic (int dynamic_threads) __STARPU_OMP_NOTHROW
• int starpu_omp_get_dynamic (void) __STARPU_OMP_NOTHROW
• void starpu_omp_set_nested (int nested) __STARPU_OMP_NOTHROW
• int starpu_omp_get_nested (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_cancellation (void) __STARPU_OMP_NOTHROW
• void starpu_omp_set_schedule (enum starpu_omp_sched_value kind, int modifier) __STARPU_OMP_NOTHROW
• void starpu_omp_get_schedule (enum starpu_omp_sched_value *kind, int *modifier) __STARPU_OMP_NOTHROW
• int starpu_omp_get_thread_limit (void) __STARPU_OMP_NOTHROW
• void starpu_omp_set_max_active_levels (int max_levels) __STARPU_OMP_NOTHROW
• int starpu_omp_get_max_active_levels (void) __STARPU_OMP_NOTHROW

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• int starpu_omp_get_level (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_ancestor_thread_num (int level) __STARPU_OMP_NOTHROW
• int starpu_omp_get_team_size (int level) __STARPU_OMP_NOTHROW
• int starpu_omp_get_active_level (void) __STARPU_OMP_NOTHROW
• int starpu_omp_in_final (void) __STARPU_OMP_NOTHROW
• enum starpu_omp_proc_bind_value starpu_omp_get_proc_bind (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_num_places (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_place_num_procs (int place_num) __STARPU_OMP_NOTHROW
• void starpu_omp_get_place_proc_ids (int place_num, int *ids) __STARPU_OMP_NOTHROW
• int starpu_omp_get_place_num (void) __STARPU_OMP_NOTHROW
• void starpu_omp_get_partition_num_places (void) __STARPU_OMP_NOTHROW
• void starpu_omp_set_default_device (int device_num) __STARPU_OMP_NOTHROW
• int starpu_omp_get_num_devices (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_num_teams (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_team_num (void) __STARPU_OMP_NOTHROW
• int starpu_omp_is_initial_device (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_initial_device (void) __STARPU_OMP_NOTHROW
• int starpu_omp_get_max_task_priority (void) __STARPU_OMP_NOTHROW
• void starpu_omp_init_lock (starpu_omp_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_destroy_lock (starpu_omp_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_set_lock (starpu_omp_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_unset_lock (starpu_omp_lock_t *lock) __STARPU_OMP_NOTHROW
• int starpu_omp_test_lock (starpu_omp_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_init_nest_lock (starpu_omp_nest_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_destroy_nest_lock (starpu_omp_nest_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_set_nest_lock (starpu_omp_nest_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_unset_nest_lock (starpu_omp_nest_lock_t *lock) __STARPU_OMP_NOTHROW
• int starpu_omp_test_nest_lock (starpu_omp_nest_lock_t *lock) __STARPU_OMP_NOTHROW
• void starpu_omp_atomic_fallback_inline_begin (void) __STARPU_OMP_NOTHROW
• void starpu_omp_atomic_fallback_inline_end (void) __STARPU_OMP_NOTHROW
• double starpu_omp_get_wtime (void) __STARPU_OMP_NOTHROW
• double starpu_omp_get_wtick (void) __STARPU_OMP_NOTHROW
• struct starpu_arbiter + starpu_omp_get_default_arbiter (void) __STARPU_OMP_NOTHROW

32.24 starpu_perfmodel.h File Reference

#include <starpu.h>
#include <stdio.h>

Data Structures

• struct starpu_perfmodel_device
• struct starpu_perfmodel_arch
• struct starpu_perfmodel_history_entry
• struct starpu_perfmodel_history_list
• struct starpu_perfmodel_regression_model
• struct starpu_perfmodel_per_arch
• struct starpu_perfmodel

Macros

• #define STARPU_NARCH
• #define starpu_per_arch_perfmodel

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Typedefs

- typedef double(* starpu_perfmodel_per_arch_cost_function) (struct starpu_task *task, struct starpu_perfmodel_arch *arch, unsigned nimpl)
- typedef size_t(* starpu_perfmodel_per_arch_size_base) (struct starpu_task *task, struct starpu_perfmodel_arch *arch, unsigned nimpl)
- typedef struct _starpu_perfmodel_state * starpu_perfmodel_state_t

Enumerations

- enum starpu_perfmodel_type {
  STARPU_PERFMODEL_INVALID, STARPU_PER_ARCH, STARPU_COMMON, STARPU_HISTORY_BASED, STARPU_REGRESSION_BASED, STARPU_NL_REGRESSION_BASED, STARPU_MULTIPLE_REGRESSION_BASED }

Functions

- void starpu_perfmodel_init (struct starpu_perfmodel *model)
- int starpu_perfmodel_load_file (const char *filename, struct starpu_perfmodel *model)
- int starpu_perfmodel_load_symbol (const char *symbol, struct starpu_perfmodel *model)
- int starpu_perfmodel_unload_model (struct starpu_perfmodel *model)
- void starpu_perfmodel_get_model_path (const char *symbol, char *path, size_t maxlen)
- void starpu_perfmodel_dump_xml (FILE *output, struct starpu_perfmodel *model)
- void starpu_perfmodel_free_sampling_directories (void)
- struct starpu_perfmodel_arch * starpu_worker_get_perf_archtype (int workerid, unsigned sched_ctx_id)
- int starpu_perfmodel_get_narch_combs (void)
- int starpu_perfmodel_arch_comb_add (int ndevices, struct starpu_perfmodel_device *devices)
- int starpu_perfmodel_arch_comb_get (int ndevices, struct starpu_perfmodel_device *devices)
- struct starpu_perfmodel_arch * starpu_perfmodel_arch_comb_fetch (int comb)
- struct starpu_perfmodel_per_arch * starpu_perfmodel_get_model_per_arch (struct starpu_perfmodel *model, struct starpu_perfmodel_arch *arch, unsigned impl)
- struct starpu_perfmodel_per_arch * starpu_perfmodel_get_model_per_devices (struct starpu_perfmodel *model, int impl,...)
- int starpu_perfmodel_set_per_devices_cost_function (struct starpu_perfmodel *model, int impl, starpu_perfmodel_per_arch_cost_function func, ...)
- int starpu_perfmodel_set_per_devices_size_base (struct starpu_perfmodel *model, int impl, starpu_perfmodel_per_arch_size_base func,...)
- void starpu_perfmodel_debugfilepath (struct starpu_perfmodel *model, struct starpu_perfmodel_arch *arch, char *path, size_t maxlen, unsigned nimpl)
- char * starpu_perfmodel_get_archtype_name (enum starpu_worker_archtype archtype)
- void starpu_perfmodel_get_arch_name (struct starpu_perfmodel_arch *arch, char *archname, size_t maxlen, unsigned nimpl)
- double starpu_perfmodel_history_based_expected_perf (struct starpu_perfmodel *model, struct starpu_perfmodel_arch *arch, uint32_t footprint)
- void starpu_perfmodel_initialize (void)
- int starpu_perfmodel_list (FILE *output)
- void starpu_perfmodel_print (struct starpu_perfmodel *model, struct starpu_perfmodel_arch *arch, unsigned nimpl, char *parameter, uint32_t *footprint, FILE *output)
- void starpu_perfmodel_print_all (struct starpu_perfmodel *model, char *arch, char *parameter, uint32_t *footprint, FILE *output)
- int starpu_perfmodel_print_estimations (struct starpu_perfmodel *model, uint32_t footprint, FILE *output)
- int starpu_perfmodel_list_combos (FILE *output, struct starpu_perfmodel *model)
- void starpu_perfmodel_update_history (struct starpu_perfmodel *model, struct starpu_task *task, struct starpu_perfmodel_arch *arch, unsigned cpuid, unsigned nimpl, double measured)
- void starpu_perfmodel_directory (FILE *output)
- void starpu_bus_print_bandwidth (FILE *f)
32.25 starpu_profiling.h File Reference

• void starpu_bus_print_affinity (FILE *)
• void starpu_bus_print_filenames (FILE *)
• double starpu_transfer_bandwidth (unsigned src_node, unsigned dst_node)
• double starpu_transfer_latency (unsigned src_node, unsigned dst_node)
• double starpu_transfer_predict (unsigned src_node, unsigned dst_node, size_t size)

Variables

• struct starpu_perfmodel starpu_perfmodel_nop

32.25 starpu_profiling.h File Reference

#include <starpu.h>
#include <errno.h>
#include <time.h>

Data Structures

• struct starpu_profiling_task_info
• struct starpu_profiling_worker_info
• struct starpu_profiling_bus_info

Macros

• #define STARPU_PROFILING_DISABLE
• #define STARPU_PROFILING_ENABLE
• #define STARPU_NS_PER_S
• #define starpu_timespec_cmp(a, b, CMP)

Functions

• void starpu_profiling_init (void)
• void starpu_profiling_set_id (int new_id)
• int starpu_profiling_status_set (int status)
• int starpu_profiling_status_get (void)
• int starpu_profiling_worker_get_info (int workerid, struct starpu_profiling_worker_info *worker_info)
• int starpu_bus_get_count (void)
• int starpu_bus_get_id (int src, int dst)
• int starpu_bus_get_src (int busid)
• int starpu_bus_get_dst (int busid)
• void starpu_bus_set_direct (int busid, int direct)
• int starpu_bus_get_direct (int busid)
• void starpu_bus_set_ngpus (int busid, int ngpus)
• int starpu_bus_get_ngpus (int busid)
• int starpu_bus_get_profiling_info (int busid, struct starpu_profiling_bus_info *bus_info)
• static __starpu_inline void starpu_timespec_clear (struct timespec *tsp)
• static __starpu_inline void starpu_timespec_add (struct timespec *a, struct timespec *b, struct timespec *result)
• static __starpu_inline void starpu_timespec_accumulate (struct timespec *result, struct timespec *a)
• static __starpu_inline void starpu_timespec_sub (const struct timespec *a, const struct timespec *b, struct timespec *result)
• double starpu_timing_timespec_delay_us (struct timespec *start, struct timespec *end)
• double starpu_timing_timespec_to_us (struct timespec *ts)
• void starpu_profiling_bus_helper_display_summary (void)
• void starpu_profiling_worker_helper_display_summary (void)
• void starpu_data_display_memory_stats ()

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32.26  starpu_rand.h File Reference

#include <stdlib.h>
#include <starpu_config.h>

Macros

• #define starpu_seed(seed)
• #define starpu_srand48(seed)
• #define starpu_drand48()
• #define starpu_lrand48()
• #define starpu_erand48(xsubi)
• #define starpu_srand48_r(seed, buffer)
• #define starpu_erand48_r(xsubi, buffer, result)

Typedefs

• typedef int starpu_drand48_data

32.27  starpu_sched_component.h File Reference

#include <starpu.h>
#include <hwloc.h>

Data Structures

• struct starpu_sched_component
• struct starpu_sched_tree
• struct starpu_sched_component_fifo_data
• struct starpu_sched_component_prio_data
• struct starpu_sched_component_mct_data
• struct starpu_sched_component_perfmodel_select_data
• struct starpu_sched_component_specs

Macros

• #define STARPU_SCHED_COMPONENT_IS_HOMOGENEOUS(component)
• #define STARPU_SCHED_COMPONENT_IS_SINGLE_MEMORY_NODE(component)
• #define STARPU_COMPONENT_MUTEX_LOCK(m)
• #define STARPU_COMPONENT_MUTEX_TRYLOCK(m)
• #define STARPU_COMPONENT_MUTEX_UNLOCK(m)

Enumerations

• enum starpu_sched_component_properties { STARPU_SCHED_COMPONENT_HOMOGENEOUS, STARPU_SCHED_COMPONENT_SINGLE_MEMORY_NODE }

Functions

• void starpu_initialize_prio_center_policy (unsigned sched_ctx_id)

Scheduling Tree API

• struct starpu_sched_tree * starpu_sched_tree_create (unsigned sched_ctx_id) STARPU_ATTRIBUTE_MALLOC
• void starpu_sched_tree_destroy (struct starpu_sched_tree *tree)
• struct starpu_sched_tree * starpu_sched_tree_get (unsigned sched_ctx_id)
• void starpu_sched_tree_update_workers (struct starpu_sched_tree *t)
• void starpu_sched_tree_update_workers_in_ctx (struct starpu_sched_tree *t)
• int starpu_sched_tree_push_task (struct starpu_task *task)
• struct starpu_task * starpu_sched_tree_pop_task (unsigned sched_ctx)
• int starpu_sched_component_push_task (struct starpu_sched_component *from, struct starpu_sched_component *to, struct starpu_task *task)
• struct starpu_task * starpu_sched_component_pull_task (unsigned sched_ctx)
• struct starpu_task * starpu_sched_component_pump_to (struct starpu_sched_component *component, struct starpu_sched_component *to, int *success)
• struct starpu_task * starpu_sched_component_pump_downstream (struct starpu_sched_component *component, int *success)
• int starpu_sched_component_send_can_push_to_parents (struct starpu_sched_component *component)
• void starpu_sched_tree_add_workers (unsigned sched_ctx_id, int *workerids, unsigned nworkers)
• void starpu_sched_tree_remove_workers (unsigned sched_ctx_id, int *workerids, unsigned nworkers)
• void starpu_sched_component_connect (struct starpu_sched_component *parent, struct starpu_sched_component *child)

Worker Component API

• struct starpu_sched_component * starpu_sched_component_worker_get (unsigned sched_ctx, int workerid)
• struct starpu_sched_component * starpu_sched_component_worker_new (unsigned sched_ctx, int workerid)
• struct starpu_sched_component * starpu_sched_component_parallel_worker_create (struct starpu_sched_tree *tree, unsigned nworkers, unsigned *workers)
• int starpu_sched_component_worker_get_workerid (struct starpu_sched_component *component)
• int starpu_sched_component_is_worker (struct starpu_sched_component *component)
• int starpu_sched_component_is_simple_worker (struct starpu_sched_component *component)
• int starpu_sched_component_is_combined_worker (struct starpu_sched_component *component)
• void starpu_sched_component_worker_pre_exec_hook (struct starpu_task *task, unsigned sched_ctx_id)
• void starpu_sched_component_worker_post_exec_hook (struct starpu_task *task, unsigned sched_ctx_id)

Flow-control Fifo Component API

• int starpu_sched_component_can_push (struct starpu_sched_component *component, struct starpu_sched_component *to)
• int starpu_sched_component_can_pull (struct starpu_sched_component *component)
• int starpu_sched_component_can_pull_all (struct starpu_sched_component *component)
• double starpu_sched_component_estimated_load (struct starpu_sched_component *component)
• double starpu_sched_component_estimated_end_min (struct starpu_sched_component *component)
• double starpu_sched_component_estimated_end_min_add (struct starpu_sched_component *component, double exp_len)
• double starpu_sched_component_estimated_end_average (struct starpu_sched_component *component)
• struct starpu_sched_component * starpu_sched_component_fifo_create (struct starpu_sched_tree *tree, struct starpu_sched_component_fifo_data *fifo_data) STARPU_ATTRIBUTE_MALLOC
• int starpu_sched_component_is_fifo (struct starpu_sched_component *component)

Flow-control Prio Component API

• struct starpu_sched_component * starpu_sched_component_prio_create (struct starpu_sched_tree *tree, struct starpu_sched_component_prio_data *prio_data) STARPU_ATTRIBUTE_MALLOC
• int starpu_sched_component_is_prio (struct starpu_sched_component *component)

Resource-mapping Work-Stealing Component API

• struct starpu_sched_component * starpu_sched_component_work_stealing_create (struct starpu_sched_tree *tree, void *arg) STARPU_ATTRIBUTE_MALLOC
• int starpu_sched_component_is_work_stealing (struct starpu_sched_component *component)
• int starpu_sched_tree_work_stealing_push_task (struct starpu_task *task)

Resource-mapping Random Component API

• struct starpu_sched_component * starpu_sched_component_random_create (struct starpu_sched_tree *tree, void *arg) STARPU_ATTRIBUTE_MALLOC
• int starpu_sched_component_is_random (struct starpu_sched_component *)

Resource-mapping Eager Component API

• struct starpu_sched_component * starpu_sched_component_eager_create (struct starpu_sched_tree *tree, void *arg) STARPU_ATTRIBUTE_MALLOC
• int starpu_sched_component_is_eager (struct starpu_sched_component *)

Resource-mapping Eager-Calibration Component API

• struct starpu_sched_component * starpu_sched_component_eager_calibration_create (struct starpu_sched_tree *tree, void *arg) STARPU_ATTRIBUTE_MALLOC
• int starpu_sched_component_is_eager_calibration (struct starpu_sched_component *)

Resource-mapping MCT Component API

• struct starpu_sched_component * starpu_sched_component_mct_create (struct starpu_sched_tree *tree, struct starpu_sched_component_mct_data *mct_data) STARPU_ATTRIBUTE_MALLOC
• int starpu_sched_component_is_mct (struct starpu_sched_component *component)

Resource-mapping Heft Component API

• struct starpu_sched_component * starpu_sched_component_heft_create (struct starpu_sched_tree *tree, struct starpu_sched_component_mct_data *mct_data) STARPU_ATTRIBUTE_MALLOC
• int starpu_sched_component_is_heft (struct starpu_sched_component *component)

Special-purpose Best_Implementation Component API

• struct starpu_sched_component * starpu_sched_component_best_implementation_create (struct starpu_sched_tree *tree, void *arg) STARPU_ATTRIBUTE_MALLOC

Special-purpose Perfmodel_Select Component API

• struct starpu_sched_component * starpu_sched_component_perfmodel_select_create (struct starpu_sched_tree *tree, struct starpu_sched_component_perfmodel_select_data *perfmodel_select_data) STARPU_ATTRIBUTE_MALLOC
• int starpu_sched_component_is_perfmodel_select (struct starpu_sched_component *component)

Recipe Component API

• struct starpu_sched_component_composed_recipe * starpu_sched_component_composed_recipe_create (void) STARPU_ATTRIBUTE_MALLOC
• struct starpu_sched_component_composed_recipe * starpu_sched_component_composed_recipe_create_singleton (struct starpu_sched_component *(*create_component)(struct starpu_sched_tree *tree, void *arg), void *arg) STARPU_ATTRIBUTE_MALLOC
• void starpu_sched_component_composed_recipe_add (struct starpu_sched_component_composed_recipe *recipe, struct starpu_sched_component *(*create_component)(struct starpu_sched_tree *tree, void *arg), void *arg)
• void starpu_sched_component_composed_recipe_destroy (struct starpu_sched_component_composed_recipe *recipe)
• struct starpu_sched_component * starpu_sched_component_composed_component_create (struct starpu_sched_tree *tree, struct starpu_sched_component_composed_recipe *recipe) STARPU_ATTRIBUTE_MALLOC
• struct starpu_sched_tree * starpu_sched_component_make_scheduler (unsigned sched_ctx_id, struct starpu_sched_component_specs s)
Generic Scheduling Component API

- typedef struct starpu_sched_component *(*starpu_sched_component_create_t)(struct starpu_sched_tree *tree, void *data)
- struct starpu_sched_component *starpu_sched_component_create(struct starpu_sched_tree *tree, const char *name) STARPU_ATTRIBUTE_MALLOC
- void starpu_sched_component_destroy(struct starpu_sched_component *component)
- void starpu_sched_component_destroy_rec(struct starpu_sched_component *component)
- void starpu_sched_component_add_child(struct starpu_sched_component *component, struct starpu_sched_component *child)
- int starpu_sched_component_can_execute_task(struct starpu_sched_component *component, struct starpu_task *task)
- int STARPU_WARN_UNUSED_RESULT starpu_sched_component_execute_preds(struct starpu_sched_component *component, struct starpu_task *task, double *length)
- double starpu_sched_component_transfer_length(struct starpu_sched_component *component, struct starpu_task *task)
- void starpu_sched_component_prefetch_on_node(struct starpu_sched_component *component, struct starpu_task *task)

Basic API

- #define STARPU_SCHED_SIMPLE_DECIDE_MASK
- #define STARPU_SCHED_SIMPLE_DECIDE_WORKERS
- #define STARPU_SCHED_SIMPLE_DECIDE_MEMNODES
- #define STARPU_SCHED_SIMPLE_DECIDE_ARCHS
- #define STARPU_SCHED_SIMPLE_PERFMODEL
- #define STARPU_SCHED_SIMPLE_IMPL
- #define STARPU_SCHED_SIMPLE_FIFO_ABOVE
- #define STARPU_SCHED_SIMPLE_FIFO_ABOVE_PRIO
- #define STARPU_SCHED_SIMPLE_FIFOS_BELOW
- #define STARPU_SCHED_SIMPLE_FIFOS_BELOW_PRIO
- #define STARPU_SCHED_SIMPLE_WS_BELOW
- #define STARPU_SCHED_SIMPLE_COMBINED_WORKERS
- void starpu_sched_component_initialize_simple_scheduler(starpu_sched_component_create_t create_component, void *data, unsigned flags, unsigned sched_ctx_id)

32.28 starpu_sched_ctx.h File Reference

#include <starpu.h>

Functions

Scheduling Context Worker Collection

- struct starpu_worker_collection *starpu_sched_ctx_create_worker_collection(unsigned sched_ctx_id, enum starpu_worker_collection_type type) STARPU_ATTRIBUTE_MALLOC
- void starpu_sched_ctx_delete_worker_collection(unsigned sched_ctx_id)
- struct starpu_worker_collection *starpu_sched_ctx_get_worker_collection(unsigned sched_ctx_id)

Scheduling Contexts Basic API

- #define STARPU_SCHED_CTX_POLICY_NAME
- #define STARPU_SCHED_CTX_POLICY_STRUCT
- #define STARPU_SCHED_CTX_POLICY_MIN_PRIO
- #define STARPU_SCHED_CTX_POLICY_MAX_PRIO
- #define STARPU_SCHED_CTX_HIERARCHY_LEVEL
• #define STARPU_SCHED_CTX_NESTED
• #define STARPU_SCHED_CTX_AWAKE_WORKERS
• #define STARPU_SCHED_CTX_POLICY_INIT
• #define STARPU_SCHED_CTX_USER_DATA
• #define STARPU_SCHED_CTX_CUDA_NSMS
• #define STARPU_SCHED_CTX_SUB_CTXS

• void(∗)(unsigned) starpu_sched_ctx_get_sched_policy_init (unsigned sched_ctx_id)
• unsigned starpu_sched_ctx_create (int ∗workerids_ctx, int nworkers_ctx, const char ∗sched_ctx_name,...)
• unsigned starpu_sched_ctx_create_inside_interval (const char ∗policy_name, const char ∗sched_ctx_name, int min_ncpus, int max_ncpus, int min_ngpus, int max_ngpus, unsigned allow_overlap)
• void starpu_sched_ctx_register_close_callback (unsigned sched_ctx_id, void(∗close_callback)(unsigned sched_ctx_id, void ∗args), void ∗args)
• void starpu_sched_ctx_add_workers (int ∗workerids_ctx, unsigned nworkers_ctx, unsigned sched_ctx_id)
• void starpu_sched_ctx_remove_workers (int ∗workerids_ctx, unsigned nworkers_ctx, unsigned sched_ctx_id)
• void starpu_sched_ctx_display_workers (unsigned sched_ctx_id, FILE ∗f)
• void starpu_sched_ctx_delete (unsigned sched_ctx_id)
• void starpu_sched_ctx_set_inheritor (unsigned sched_ctx_id, unsigned inheritor)
• unsigned starpu_sched_ctx_get_inheritor (unsigned sched_ctx_id)
• unsigned starpu_sched_ctx_get_hierarchy_level (unsigned sched_ctx_id)
• void starpu_sched_ctx_set_context (unsigned ∗sched_ctx_id)
• unsigned starpu_sched_ctx_get_context (void)
• void starpu_sched_ctx_stop_task_submission (void)
• void starpu_sched_ctx_finished_submit (unsigned sched_ctx_id)
• unsigned starpu_sched_ctx_get_workers_list (unsigned sched_ctx_id, int ∗∗workerids)
• unsigned starpu_sched_ctx_get_workers_list_raw (unsigned sched_ctx_id, int ∗∗workerids)
• unsigned starpu_sched_ctx_get_nworkers (unsigned sched_ctx_id)
• unsigned starpu_sched_ctx_get_nshared_workers (unsigned sched_ctx_id, unsigned sched_ctx_id2)
• unsigned starpu_sched_ctx_contains_worker (int workerid, unsigned sched_ctx_id)
• unsigned starpu_sched_ctx_contains_type_of_worker (enum starpu_worker_archtype arch, unsigned sched_ctx_id)
• unsigned starpu_sched_ctx_worker_get_id (unsigned sched_ctx_id)
• unsigned starpu_sched_ctx_get_ctx_for_task (struct starpu_task ∗task)
• unsigned starpu_sched_ctx_overlapping_ctxs_on_worker (int workerid)
• void ∗starpu_sched_ctx_get_user_data (unsigned sched_ctx_id)
• void ∗starpu_sched_ctx_set_user_data (unsigned sched_ctx_id, void ∗user_data)
• void ∗starpu_sched_ctx_get_policy_data (unsigned sched_ctx_id)
• struct starpu_sched_policy ∗starpu_sched_ctx_get_sched_policy (unsigned sched_ctx_id)
• void ∗starpu_sched_ctx_exec_parallel_code (void ∗(∗func)(void ∗), void ∗param, unsigned sched_ctx_id)
• int starpu_sched_ctx_get_nready_tasks (unsigned sched_ctx_id)
• double starpu_sched_ctx_get_nready_flops (unsigned sched_ctx_id)
• void starpu_sched_ctx_list_task_counts_increment (unsigned sched_ctx_id, int ∗∗workerids)
• void starpu_sched_ctx_list_task_counts_decrement (unsigned sched_ctx_id, int ∗∗workerids)
• void starpu_sched_ctx_list_task_counts_reset (unsigned sched_ctx_id, int ∗∗workerids)
• void starpu_sched_ctx_list_task_counts_increment_all_ctx_locked (struct starpu_task ∗task, unsigned sched_ctx_id)
• void starpu_sched_ctx_list_task_counts_decrement_all_ctx_locked (struct starpu_task ∗task, unsigned sched_ctx_id)
• void starpu_sched_ctx_list_task_counts_reset_all (struct starpu_task ∗task, unsigned sched_ctx_id)
• void starpu_sched_ctx_set_priority (int ∗workers, int nworkers, unsigned sched_ctx_id, unsigned priority)
• unsigned starpu_sched_ctx_get_priority (int worker, unsigned sched_ctx_id)
• void starpu_sched_ctx_get_available_cpuids (unsigned sched_ctx_id, int ∗∗cpuids, int ∗ncpuids)
• void starpu_sched_ctx_bind_current_thread_to_cpuid (unsigned cpuid)
• int starpu_sched_ctx_book_workers_for_task (unsigned sched_ctx_id, int ∗workerids, int nworkers)
**32.29 starpu_sched_ctx_hypervisor.h File Reference**

- void *starpu_sched_ctx_unbook_workers_for_task (unsigned sched_ctx_id, int master)
- unsigned starpu_sched_ctx_worker_is_master_for_child_ctx (int workerid, unsigned sched_ctx_id)
- unsigned starpu_sched_ctx_master_get_context (int masterid)
- void *starpu_sched_ctx_revert_task_counters_ctx_locked (unsigned sched_ctx_id, double flops)
- void *starpu_sched_ctx_move_task_to_ctx_locked (struct starpu_task *task, unsigned sched_ctx, unsigned with_repush)
- int starpu_sched_ctx_get_worker_rank (unsigned sched_ctx_id)
- unsigned starpu_sched_ctx_has_starpu_scheduler (unsigned sched_ctx_id, unsigned *awake_workers)
- int starpu_sched_ctx_get_stream_worker (unsigned sub_ctx)
- int starpu_sched_ctx_get_nsms (unsigned sched_ctx)
- void *starpu_sched_ctx_get_sms_interval (int stream_workerid, int *start, int *end)

**Scheduling Context Priorities**

- #define STARPU_MIN_PRIO
- #define STARPU_MAX_PRIO
- #define STARPU_DEFAULT_PRIO
- int starpu_sched_ctx_get_min_priority (unsigned sched_ctx_id)
- int starpu_sched_ctx_get_max_priority (unsigned sched_ctx_id)
- int starpu_sched_ctx_set_min_priority (unsigned sched_ctx_id, int min_prio)
- int starpu_sched_ctx_set_max_priority (unsigned sched_ctx_id, int max_prio)
- int starpu_sched_ctx_min_priority_is_set (unsigned sched_ctx_id)
- int starpu_sched_ctx_max_priority_is_set (unsigned sched_ctx_id)

**Data Structures**

- struct starpu_sched_ctx_performance_counters

**Functions**

**Scheduling Context Link with Hypervisor**

- void starpu_sched_ctx_set_perf_counters (unsigned sched_ctx_id, void *perf_counters)
- void starpu_sched_ctx_call_pushed_task_cb (int workerid, unsigned sched_ctx_id)
- void starpu_sched_ctx_notify_hypervisor_exists (void)
- unsigned starpu_sched_ctx_check_if_hypervisor_exists (void)
- void starpu_sched_ctx_update_start_resizing_sample (unsigned sched_ctx_id, double start_sample)

**32.29.1 Function Documentation**

**32.29.1.1 starpu_sched_ctx_set_perf_counters()**

```c
void starpu_sched_ctx_set_perf_counters {
    unsigned sched_ctx_id,
    void * perf_counters }
```

Indicate to starpu the pointer to the performance counter

**32.29.1.2 starpu_sched_ctx_call_pushed_task_cb()**

```c
void starpu_sched_ctx_call_pushed_task_cb {
    int workerid,
    unsigned sched_ctx_id }
```

Callback that lets the scheduling policy tell the hypervisor that a task was pushed on a worker
### 32.29.1.3 starpu_sched_ctx_notify_hypervisor_exists()

```c
void starpu_sched_ctx_notify_hypervisor_exists (void)
```

Allow the hypervisor to let starpu know it's initialised.

### 32.29.1.4 starpu_sched_ctx_check_if_hypervisor_exists()

```c
unsigned starpu_sched_ctx_check_if_hypervisor_exists (void)
```

Ask starpu if it is informed if the hypervisor is initialised.

### 32.30 starpu_scheduler.h File Reference

```c
#include "starpu.h"
```

#### Data Structures

- `struct starpu_sched_policy`

#### Typedefs

- `typedef void(∗starpu_notify_ready_soon_func)(void ∗data, struct starpu_task ∗task, double delay)`

#### Functions

- `struct starpu_sched_policy ∗∗starpu_sched_get_predefined_policies ()`
- `void starpu_worker_get_sched_condition (int workerid, starpu_pthread_mutex_t ∗∗sched_mutex, starpu_← pthread_cond_t ∗∗sched_cond)`
- `unsigned long starpu_task_get_job_id (struct starpu_task ∗task)`
- `int starpu_sched_get_min_priority (void)`
- `int starpu_sched_get_max_priority (void)`
- `int starpu_sched_set_min_priority (int min_prio)`
- `int starpu_sched_set_max_priority (int max_prio)`
- `int starpu_worker_can_execute_task (unsigned workerid, struct starpu_task ∗task, unsigned nimpl)`
- `int starpu_worker_can_execute_task_impl (unsigned workerid, struct starpu_task ∗task, unsigned ∗impl_← mask)`
- `int starpu_worker_can_execute_task_first_impl (unsigned workerid, struct starpu_task ∗task, unsigned ∗nimpl)`
- `int starpu_push_local_task (int workerid, struct starpu_task ∗task, int back)`
- `int starpu_push_task_end (struct starpu_task ∗task)`
- `int starpu_get_prefetch_flag (void)`
- `int starpu_prefetch_task_input_on_node_prio (struct starpu_task ∗task, unsigned node, int prio)`
- `int starpu_prefetch_task_input_on_node (struct starpu_task ∗task, unsigned node)`
- `int starpu_idle_prefetch_task_input_on_node_prio (struct starpu_task ∗task, unsigned node, int prio)`
- `int starpu_idle_prefetch_task_input_for_prio (struct starpu_task ∗task, unsigned worker, int prio)`
- `int starpu_idle_prefetch_task_input_for (struct starpu_task ∗task, unsigned worker)`
- `uint32_t starpu_task_footprint (struct starpu_perfmodel ∗model, struct starpu_task ∗task, struct starpu_← perfmodel_arch ∗arch, unsigned nimpl)`
- `uint32_t starpu_task_data_footprint (struct starpu_task ∗task)`
- `double starpu_task_expected_length (struct starpu_task ∗task, struct starpu_perfmodel_arch ∗arch, unsigned nimpl)`
• double starpu_worker_get_relative_speedup (struct starpu_perfmodel_arch *perf_arch)
• double starpu_task_expected_data_transfer_time (unsigned memory_node, struct starpu_task *task)
• double starpu_task_expected_data_transfer_time_for (struct starpu_task *task, unsigned worker)
• double starpu_data_expected_transfer_time (starpu_data_handle_t handle, unsigned memory_node, enum starpu_data_access_mode mode)
• double starpu_task_expected_energy (struct starpu_task *task, struct starpu_perfmodel_arch *arch, unsigned nimpl)
• double starpu_task_expected_conversion_time (struct starpu_task *task, struct starpu_perfmodel_arch *arch, unsigned nimpl)
• void starpu_task_notify_ready_soon_register (starpu_notify_ready_soon_func f, void *data)
• void starpu_sched_ctx_worker_shares_tasks_lists (int workerid, int sched_ctx_id)
• void starpu_sched_task_break (struct starpu_task *task)

Worker operations

• int starpu_wake_worker_relax (int workerid)
• int starpu_wake_worker_no_relax (int workerid)
• int starpu_wake_worker_locked (int workerid)
• int starpu_wake_worker_relax_light (int workerid)

32.31 starpu_simgrid_wrap.h File Reference

#include <starpu_config.h>

Macros

• #define main

32.32 starpu_sink.h File Reference

Functions

• void starpu_sink_common_worker (int argc, char **argv)

32.33 starpu_stdlib.h File Reference

#include <starpu.h>

Macros

• #define STARPU_MALLOC_PINNED
• #define STARPU_MALLOC_COUNT
• #define STARPU_MALLOC_NORECLAIM
• #define STARPU_MEMORY_WAIT
• #define STARPU_MEMORY_OVERFLOW
• #define STARPU_MALLOC_SIMULATION_FOLDED
• #define starpu_data_malloc_pinned_if_possible
• #define starpu_data_free_pinned_if_possible

Typedefs

• typedef int(* starpu_malloc_hook) (unsigned dst_node, void **A, size_t dim, int flags)
• typedef int(* starpu_free_hook) (unsigned dst_node, void *A, size_t dim, int flags)
Functions

- void `starpu_malloc_set_align (size_t align)`
- int `starpu_malloc (void **A, size_t dim)`
- int `starpu_free (void *A)`
- int `starpu_malloc_flags (void **A, size_t dim, int flags)`
- int `starpu_free_flags (void *A, size_t dim, int flags)`
- void `starpu_malloc_set_hooks (starpu_malloc_hook malloc_hook, starpu_free_hook free_hook)`
- int `starpu_memory_pin (void *addr, size_t size)`
- int `starpu_memory_unpin (void *addr, size_t size)`
- starpu_ssize_t `starpu_memory_get_total (unsigned node)`
- starpu_ssize_t `starpu_memory_get_available (unsigned node)`
- starpu_ssize_t `starpu_memory_get_total_all_nodes (void)`
- starpu_ssize_t `starpu_memory_get_available_all_nodes (void)`
- int `starpu_memory_allocate (unsigned node, size_t size, int flags)`
- void `starpu_sleep (float nb_sec)`
- void `starpu_usleep (float nb_micro_sec)`

32.34 starpu_task.h File Reference

```c
#include <starpu.h>
#include <errno.h>
#include <assert.h>
#include <cuda.h>
```

Data Structures

- struct `starpu_codelet`
- struct `starpu_data_descr`
- struct `starpu_task`

Macros

- #define `STARPU_NOWHERE`
- #define `STARPU_CPU`
- #define `STARPU_CUDA`
- #define `STARPU_OPENCL`
- #define `STARPU_MIC`
- #define `STARPU_MPI_MS`
- #define `STARPU_CODELET_SIMGRID_EXECUTE`
- #define `STARPU_CODELET_SIMGRID_EXECUTE_AND_INJECT`
- #define `STARPU_CODELET_NOPLANS`
- #define `STARPU_CUDA_ASYNC`
- #define `STARPU_OPENCL_ASYNC`
- #define `STARPU_MAIN_RAM`
- #define `STARPU_TASK_INVALID`
- #define `STARPU_MULTIPLE_CPU_IMPLEMENTATIONS`
- #define `STARPU_MULTIPLE_CUDA_IMPLEMENTATIONS`
- #define `STARPU_MULTIPLE_OPENCL_IMPLEMENTATIONS`
- #define `STARPU_VARIABLE_NBUFFERS`
- #define `STARPU_SPECIFIC_NODE_LOCAL`
- #define `STARPU_SPECIFIC_NODE_CPU`
• #define STARPU_SPECIFIC_NODE_SLOW
• #define STARPU_SPECIFIC_NODE_FAST
• #define STARPU_TASK_TYPE_NORMAL
• #define STARPU_TASK_TYPE_INTERNAL
• #define STARPU_TASK_TYPE_DATA_ACQUIRE
• #define STARPU_TASK_INITIALIZER
• #define STARPU_TASK_GET_NBUFFERS(task)
• #define STARPU_TASK_GET_HANDLE(task, i)
• #define STARPU_TASK_GET_HANDLES(task)
• #define STARPU_TASK_SET_HANDLE(task, handle, i)
• #define STARPU_CODELET_GET_MODE(codelet, i)
• #define STARPU_CODELET_SET_MODE(codelet, mode, i)
• #define STARPU_TASK_GET_MODE(task, i)
• #define STARPU_TASK_SET_MODE(task, mode, i)
• #define STARPU_CODELET_GET_NODE(codelet, i)
• #define STARPU_CODELET_SET_NODE(codelet, __node, i)

Typedefs

• typedef void(* starpu_cpu_func_t) (void **, void *)
• typedef void(* starpu_cuda_func_t) (void **, void *)
• typedef void(* starpu_opencl_func_t) (void **, void *)
• typedef void(* starpu_mic_kernel_t) (void **, void *)
• typedef starpu_mic_kernel_t(* starpu_mic_func_t) (void)
• typedef void(* starpu_mpi_ms_kernel_t) (void **, void *)
• typedef starpu_mpi_ms_kernel_t(* starpu_mpi_ms_func_t) (void)

Enumerations

• enum starpu_codelet_type { STARPU_SEQ, STARPU_SPMD, STARPU_FORKJOIN }
• enum starpu_task_status {
  STARPU_TASK_INVALID, STARPU_TASK_INVALID, STARPU_TASK_BLOCKED, STARPU_TASK_READY,
  STARPU_TASK_RUNNING, STARPU_TASK_FINISHED, STARPU_TASK_BLOCKED_ON_TAG, STARPU_TASK_BLOCKED_ON_TASK,
  STARPU_TASK_BLOCKED_ON_DATA, STARPU_TASK_STOPPED }

Functions

• void starpu_task_init (struct starpu_task *task)
• void starpu_task_clean (struct starpu_task *task)
• struct starpu_task * starpu_task_create (void) STARPU_ATTRIBUTE_MALLOC
• void starpu_task_destroy (struct starpu_task *task)
• int starpu_task_submit (struct starpu_task *task) STARPU_WARN_UNUSED_RESULT
• int starpu_task_submit_to_ctx (struct starpu_task *task, unsigned sched_ctx_id)
• int starpu_task_finished (struct starpu_task *task) STARPU_WARN_UNUSED_RESULT
• int starpu_task_wait (struct starpu_task *task) STARPU_WARN_UNUSED_RESULT
• int starpu_task_wait_array (struct starpu_task **tasks, unsigned nb_tasks) STARPU_WARN_UNUSED_RESULT
• int starpu_task_wait_for_all (void)
• int starpu_task_nready (void)
• int starpu_task_nsubmitted (void)
• void starpu_iteration_push (unsigned long iteration)
• void starpu_iteration_pop (void)
• void starpu_do_schedule (void)
• void starpu_codelet_init (struct starpu_codelet *cl)
• void starpu_codelet_display_stats (struct starpu_codelet *cl)
• struct starpu_task * starpu_task_get_current (void)
• int starpu_task_get_current_data_node (unsigned i)
• const char * starpu_task_get_model_name (struct starpu_task *task)
• const char * starpu_task_get_name (struct starpu_task *task)
• struct starpu_task * starpu_task_dup (struct starpu_task *task)
• void starpu_task_set_implementation (struct starpu_task *task, unsigned impl)
• unsigned starpu_task_get_implementation (struct starpu_task *task)
• void starpu_create_sync_task (starpu_tag_t sync_tag, unsigned ndeps, starpu_tag_t *deps, void(*callback)(void *), void *callback_arg)

32.35 starpu_task_bundle.h File Reference

Typedefs

• typedef struct _starpu_task_bundle * starpu_task_bundle_t

Functions

• void starpu_task_bundle_create (starpu_task_bundle_t *bundle)
• int starpu_task_bundle_insert (starpu_task_bundle_t bundle, struct starpu_task *task)
• int starpu_task_bundle_remove (starpu_task_bundle_t bundle, struct starpu_task *task)
• void starpu_task_bundle_close (starpu_task_bundle_t bundle)
• double starpu_task_bundle_expected_length (starpu_task_bundle_t bundle, struct starpu_perfmodel_arch *arch, unsigned nimpl)
• double starpu_task_bundle_expected_data_transfer_time (starpu_task_bundle_t bundle, unsigned memory_node)
• double starpu_task_bundle_expected_energy (starpu_task_bundle_t bundle, struct starpu_perfmodel_arch *arch, unsigned nimpl)

32.36 starpu_task_list.h File Reference

#include <starpu_task.h>
#include <starpu_util.h>

Data Structures

• struct starpu_task_list

Functions

• void starpu_task_list_init (struct starpu_task_list *list)
• void starpu_task_list_push_front (struct starpu_task_list *list, struct starpu_task *task)
• void starpu_task_list_push_back (struct starpu_task_list *list, struct starpu_task *task)
• struct starpu_task * starpu_task_list_front (const struct starpu_task_list *list)
• struct starpu_task * starpu_task_list_back (const struct starpu_task_list *list)
• int starpu_task_list_empty (const struct starpu_task_list *list)
• void starpu_task_list_erase (struct starpu_task_list *list, struct starpu_task *task)
• struct starpu_task * starpu_task_list_pop_front (struct starpu_task_list *list)
• struct starpu_task * starpu_task_list_pop_back (struct starpu_task_list *list)
• struct starpu_task * starpu_task_list_begin (const struct starpu_task_list *list)
• struct starpu_task * starpu_task_list_end (const struct starpu_task_list *list STARPU_ATTRIBUTE_UNUSED)
• struct starpu_task * starpu_task_list_next (const struct starpu_task_list *task)
• int starpu_task_list_ismember (const struct starpu_task_list *list, const struct starpu_task *look)
• void starpu_task_list_move (struct starpu_task_list *ldst, struct starpu_task_list *lsrc)

32.37  starpu_task_util.h File Reference

#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <assert.h>
#include <starpu.h>

Data Structures

• struct starpu_codelet_pack_arg_data

Macros

• #define STARPU_MODE_SHIFT
• #define STARPU_VALUE
• #define STARPU_CALLBACK
• #define STARPU_CALLBACK_WITH_ARG
• #define STARPU_CALLBACK_ARG
• #define STARPU_PRIORITY
• #define STARPU_EXECUTE_ON_NODE
• #define STARPU_EXECUTE_ON_DATA
• #define STARPU_DATA_ARRAY
• #define STARPU_DATA_MODE_ARRAY
• #define STARPU_HYPERVERISOR_TAG
• #define STARPU_FLOPS
• #define STARPU_SCHED_CTX
• #define STARPU_PROLOGUE_CALLBACK
• #define STARPU_PROLOGUE_CALLBACK_ARG
• #define STARPU_PROLOGUE_CALLBACK_POP
• #define STARPU_PROLOGUE_CALLBACK_POP_ARG
• #define STARPU_EXECUTE_ON_WORKER
• #define STARPU_EXECUTE_WHERE
• #define STARPU_TAG_ONLY
• #define STARPU_POSSIBLY_PARALLEL
• #define STARPU_WORKER_ORDER
• #define STARPU_NODE_SELECTION_POLICY
• #define STARPU_NAME
• #define STARPU_CL_ARGS
• #define STARPU_CL_ARGS_NFREE
• #define STARPU_TASK_DEPS_ARRAY
• #define STARPU_TASK_COLOR
• #define STARPU_HANDLES_SEQUENTIAL_CONSISTENCY
• #define STARPU_TASK_SYNCHRONOUS
• #define STARPU_TASK_END_DEPS_ARRAY
• #define STARPU_TASK_END_DEP
• #define STARPU_SHIFTED_MODE_MAX
Functions

- int starpu_task_set (struct starpu_task *task, struct starpu_codelet *cl,...)
- struct starpu_task = starpu_task_build (struct starpu_codelet *cl,...)
- int starpu_task_insert (struct starpu_codelet *cl,...)
- int starpu_insert_task (struct starpu_codelet *cl,...)
- void starpu_task_insert_data_make_room (struct starpu_codelet *cl, struct starpu_task *task, int *allocated_buffers, int current_buffer, int room)
- void starpu_task_insert_data_process_arg (struct starpu_codelet *cl, struct starpu_task *task, int *allocated_buffers, int *current_buffer, int arg_type, starpu_data_handle_t handle)
- void starpu_task_insert_data_process_array_arg (struct starpu_codelet *cl, struct starpu_task *task, int *allocated_buffers, int *current_buffer, int nb_handles, starpu_data_handle_t *handles)
- void starpu_task_insert_data_process_mode_array_arg (struct starpu_codelet *cl, struct starpu_task *task, int *allocated_buffers, int *current_buffer, int nb_descrs, struct starpu_data_descr *descrs)
- void starpu_codelet_pack_args (void **arg_buffer, size_t **arg_buffer_size,...)
- void starpu_codelet_pack_arg_init (struct starpu_codelet_pack_arg_data *state)
- void starpu_codelet_pack_arg (struct starpu_codelet_pack_arg_data *state, const void *ptr, size_t ptr_size)
- void starpu_codelet_pack_arg_fini (struct starpu_codelet_pack_arg_data *state, void **cl_arg, size_t **cl_arg_size)
- void starpu_codelet_unpack_args (void *cl_arg,...)
- void starpu_codelet_unpack_args_and_copyleft (void *cl_arg, void *buffer, size_t buffer_size,...)

32.38 starpu_thread.h File Reference

#include <starpu_config.h>
#include <starpu_util.h>
#include <pthread.h>
#include <xbt/synchro_core.h>
#include <msg/msg.h>
#include <stdint.h>

Data Structures

- struct starpu_pthread_barrier_t
- struct starpu_pthread_spinlock_t
- struct starpu_pthread_wait_t
- struct starpu_pthread_queue_t

Macros

- #define starpu_pthread_setname(name)
- #define STARPU_PTHREAD_MUTEX_INITIALIZER
- #define STARPU_PTHREAD_COND_INITIALIZER
- #define STARPU_PTHREAD_BARRIER_SERIAL_THREAD

Typedefs

- typedef msg_process_t starpu_pthread_t
- typedef int starpu_pthread_attr_t
- typedef xbt_mutex_t starpu_pthread_mutex_t
- typedef int starpu_pthread_mutexattr_t
- typedef int starpu_pthread_key_t
- typedef xbt_cond_t starpu_pthread_cond_t
- typedef int starpu_pthread_condattr_t
- typedef xbt_mutex_t starpu_pthread_rwlock_t
typedef int starpu_pthread_rwlockattr_t
typedef int starpu_pthread_barrierattr_t
typedef msg_sem_t starpu_sem_t

Functions

int starpu_pthread_equal(starpu_pthread_t t1, starpu_pthread_t t2)
starpu_pthread_t starpu_pthread_self(void)

int starpu_pthread_create_on(char *name, starpu_pthread_t *thread, const starpu_pthread_attr_t *attr, void *(*start_routine)(void *), void *arg, msg_host_t host)
int starpu_pthread_create(starpu_pthread_t *thread, const starpu_pthread_attr_t *attr, void *(*start_routine)(void *), void *arg)

int starpu_pthread_join(starpu_pthread_t thread, void **retval)
int starpu_pthread_exit(void *retval) STARPU_ATTRIBUTE_NORETURN
int starpu_pthread_attr_init(starpu_pthread_attr_t *attr)
int starpu_pthread_attr_destroy(starpu_pthread_attr_t *attr)
int starpu_pthread_attr_setdetachstate(starpu_pthread_attr_t *attr, int detachstate)

int starpu_pthread_mutex_init(starpu_pthread_mutex_t *mutex, const starpu_pthread_mutexattr_t *mutexattr)
int starpu_pthread_mutex_destroy(starpu_pthread_mutex_t *mutex)
int starpu_pthread_mutex_lock(starpu_pthread_mutex_t *mutex)
int starpu_pthread_mutex_unlock(starpu_pthread_mutex_t *mutex)
int starpu_pthread_mutex_trylock(starpu_pthread_mutex_t *mutex)
int starpu_pthread_mutexattr_gettype(const starpu_pthread_mutexattr_t *attr, int *type)
int starpu_pthread_mutexattr_settype(starpu_pthread_mutexattr_t *attr, int type)
int starpu_pthread_mutexattr_destroy(starpu_pthread_mutexattr_t *attr)
int starpu_pthread_mutexattr_init(starpu_pthread_mutexattr_t *attr)
int starpu_pthread_mutex_lock_sched(starpu_pthread_mutex_t *mutex)
int starpu_pthread_mutex_unlock_sched(starpu_pthread_mutex_t *mutex)
int starpu_pthread_mutex_trylock_sched(starpu_pthread_mutex_t *mutex)
void starpu_pthread_mutex_check_sched(starpu_pthread_mutex_t *mutex, char *file, int line)
int starpu_pthread_key_create(starpu_pthread_key_t *key, void(*destr_function)(void *))
int starpu_pthread_key_delete(starpu_pthread_key_t key)
int starpu_pthread_setspecific(starpu_pthread_key_t key, const void *pointer)
void *starpu_pthread_getspecific(starpu_pthread_key_t key, const void *pointer)
int starpu_pthread_cond_init(starpu_pthread_cond_t *cond, starpu_pthread_condattr_t *cond_attr)
int starpu_pthread_cond_signal(starpu_pthread_cond_t *cond)
int starpu_pthread_cond_broadcast(starpu_pthread_cond_t *cond)
int starpu_pthread_cond_wait(starpu_pthread_cond_t *cond, starpu_pthread_mutex_t *mutex)
int starpu_pthread_cond_timedwait(starpu_pthread_cond_t *cond, starpu_pthread_mutex_t *mutex, const struct timespec *abstime)
int starpu_pthread_cond_destroy(starpu_pthread_cond_t *cond)
int starpu_pthread_rwlock_init(starpu_pthread_rwlock_t *rwlock, const starpu_pthread_rwlockattr_t *attr)
int starpu_pthread_rwlock_destroy(starpu_pthread_rwlock_t *rwlock)
int starpu_pthread_rwlock_rdlock(starpu_pthread_rwlock_t *rwlock)
int starpu_pthread_rwlock_tryrdlock(starpu_pthread_rwlock_t *rwlock)
int starpu_pthread_rwlock_wrlock(starpu_pthread_rwlock_t *rwlock)
int starpu_pthread_rwlock_trywrlock(starpu_pthread_rwlock_t *rwlock)
int starpu_pthread_rwlock_unlock(starpu_pthread_rwlock_t *rwlock)
int starpu_pthread_barrier_init(starpu_pthread_barrier_t *barrier, const starpu_pthread_barrierattr_t *attr, unsigned count)
int starpu_pthread_barrier_destroy(starpu_pthread_barrier_t *barrier)
int starpu_pthread_barrier_wait(starpu_pthread_barrier_t *barrier)
int starpu_pthread_spin_init(starpu_pthread_spinlock_t *lock, int pshared)
int starpu_pthread_spin_destroy(starpu_pthread_spinlock_t *lock)
• int starpu_pthread_spin_lock (starpu_pthread_spinlock_t *lock)
• int starpu_pthread_spin_trylock (starpu_pthread_spinlock_t *lock)
• int starpu_pthread_spin_unlock (starpu_pthread_spinlock_t *lock)
• int starpu_pthread_queue_init (starpu_pthread_queue_t *q)
• int starpu_pthread_queue_signal (starpu_pthread_queue_t *q)
• int starpu_pthread_queue_broadcast (starpu_pthread_queue_t *q)
• int starpu_pthread_queue_destroy (starpu_pthread_queue_t *q)
• int starpu_pthread_wait_init (starpu_pthread_wait_t *w)
• int starpu_pthread_queue_register (starpu_pthread_wait_t *w, starpu_pthread_queue_t *q)
• int starpu_pthread_queue_unregister (starpu_pthread_wait_t *w, starpu_pthread_queue_t *q)
• int starpu_pthread_wait_reset (starpu_pthread_wait_t *w)
• int starpu_pthread_wait_wait (starpu_pthread_wait_t *w)
• int starpu_pthread_wait_timedwait (starpu_pthread_wait_t *w, const struct timespec *abstime)
• int starpu_pthread_wait_destroy (starpu_pthread_wait_t *w)
• int starpu_sem_destroy (starpu_sem_t *s)
• int starpu_sem_getvalue (starpu_sem_t *, int *)
• int starpu_sem_init (starpu_sem_t *, int, unsigned)
• int starpu_sem_post (starpu_sem_t *)
• int starpu_sem_trywait (starpu_sem_t *)
• int starpu_sem_wait (starpu_sem_t *)

32.38.1 Data Structure Documentation

32.38.1.1 struct starpu_pthread_barrier_t

Data Fields

<table>
<thead>
<tr>
<th>starpu_pthread_mutex_t</th>
<th>mutex</th>
</tr>
</thead>
<tbody>
<tr>
<td>starpu_pthread_cond_t</td>
<td>cond</td>
</tr>
<tr>
<td>starpu_pthread_cond_t</td>
<td>cond_destroy</td>
</tr>
<tr>
<td>unsigned</td>
<td>count</td>
</tr>
<tr>
<td></td>
<td>done</td>
</tr>
<tr>
<td></td>
<td>busy</td>
</tr>
</tbody>
</table>

32.38.1.2 struct starpu_pthread_spinlock_t

Data Fields

| int | taken |

32.38.1.3 struct starpu_pthread_wait_t

Data Fields

<table>
<thead>
<tr>
<th>starpu_pthread_mutex_t</th>
<th>mutex</th>
</tr>
</thead>
<tbody>
<tr>
<td>starpu_pthread_cond_t</td>
<td>cond</td>
</tr>
<tr>
<td></td>
<td>block</td>
</tr>
</tbody>
</table>

32.38.1.4 struct starpu_pthread_queue_t

Data Fields

| starpu_pthread_mutex_t | mutex |
Data Fields

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>starpu_pthread_wait_t <strong>queue</strong></td>
<td>unsigned allocqueue</td>
</tr>
<tr>
<td></td>
<td>unsigned nqueue</td>
</tr>
</tbody>
</table>

32.39 starpu_thread_util.h File Reference

#include <starpu_util.h>
#include <starpu_thread.h>
#include <errno.h>

Macros

- #define STARPU_PTHREAD_CREATE(name, thread, attr, routine, arg, where)
- #define STARPU_PTHREAD_CREATE_ON(name, thread, attr, routine, arg, where)
- #define STARPU_PTHREAD_CREATE(thread, attr, routine, arg)
- #define STARPU_PTHREAD_JOIN(thread, retval)
- #define STARPU_PTHREAD_MUTEX_INIT(mutex, attr)
- #define STARPU_PTHREAD_MUTEX_DESTROY(mutex)
- #define _STARPU_CHECK_NOT_SCHED_MUTEX(mutex, file, line)
- #define STARPU_PTHREAD_MUTEX_LOCK(mutex)
- #define STARPU_PTHREAD_MUTEX_LOCK_SCHED(mutex)
- #define STARPU_PTHREAD_MUTEX_TRYLOCK(mutex)
- #define STARPU_PTHREAD_MUTEX_TRYLOCK_SCHED(mutex)
- #define STARPU_PTHREAD_MUTEX_UNLOCK(mutex)
- #define STARPU_PTHREAD_MUTEX_UNLOCK_SCHED(mutex)
- #define STARPU_PTHREAD_KEY_CREATE(key, destr)
- #define STARPU_PTHREAD_KEY_DELETE(key)
- #define STARPU_PTHREAD_SETSPECIFIC(key, ptr)
- #define STARPU_PTHREAD_GETSPECIFIC(key)
- #define STARPU_PTHREAD_RWLOCK_INIT(rwlock, attr)
- #define STARPU_PTHREAD_RWLOCK_RDLOCK(rwlock)
- #define STARPU_PTHREAD_RWLOCK_TRYRDLOCK(rwlock)
- #define STARPU_PTHREAD_RWLOCK_WRLOCK(rwlock)
- #define STARPU_PTHREAD_RWLOCK_TRYWRLOCK(rwlock)
- #define STARPU_PTHREAD_RWLOCK_UNLOCK(rwlock)
- #define STARPU_PTHREAD_RWLOCK_DESTROY(rwlock)
- #define STARPU_PTHREAD_COND_INIT(cond, attr)
- #define STARPU_PTHREAD_COND_DESTROY(cond)
- #define STARPU_PTHREAD_COND_SIGNAL(cond)
- #define STARPU_PTHREAD_COND_BROADCAST(cond)
- #define STARPU_PTHREAD_COND_WAIT(cond, mutex)
- #define STARPU_PTHREAD_COND_TIMEDWAIT(cond, mutex, abstime)
- #define STARPU_PTHREAD_BARRIER_INIT(barrier, attr, count)
- #define STARPU_PTHREAD_BARRIER_DESTROY(barrier)
- #define STARPU_PTHREAD_BARRIER_WAIT(barrier)
Functions

• static STARPU_INLINE int _starpu_pthread_mutex_trylock (starpu_pthread_mutex_t *mutex, char *file, int line)
• static STARPU_INLINE int _starpu_pthread_mutex_trylock_sched (starpu_pthread_mutex_t *mutex, char *file, int line)
• static STARPU_INLINE int _starpu_pthread_rwlock_tryrdlock (starpu_pthread_rwlock_t *rwlock, char *file, int line)
• static STARPU_INLINE int _starpu_pthread_rwlock_trywrlock (starpu_pthread_rwlock_t *rwlock, char *file, int line)
• static STARPU_INLINE int _starpu_pthread_cond_timedwait (starpu_pthread_cond_t *cond, starpu_pthread_mutex_t *mutex, const struct timespec *abstime, char *file, int line)

32.40 starpu_tree.h File Reference

Data Structures

• struct starpu_tree

Functions

• void starpu_tree_reset_visited (struct starpu_tree *tree, char *visited)
• void starpu_tree_prepare_children (unsigned arity, struct starpu_tree *father)
• void starpu_tree_insert (struct starpu_tree *tree, int id, int level, int is_pu, int arity, struct starpu_tree *father)
• struct starpu_tree * starpu_tree_get (struct starpu_tree *tree, int id)
• struct starpu_tree * starpu_tree_get_neighbour (struct starpu_tree *tree, struct starpu_tree *node, char *visited, char *present)
• void starpu_tree_free (struct starpu_tree *tree)

32.41 starpu_util.h File Reference

#include <stdio.h>
#include <stdlib.h>
#include <stdint.h>
#include <string.h>
#include <assert.h>
#include <starpu_config.h>
#include <sys/time.h>

Macros

• #define STARPU_GNUC_PREREQ(maj, min)
• #define STARPU_UNLIKELY(expr)
• #define STARPU_LIKELY(expr)
• #define STARPU_ATTRIBUTE_UNUSED
• #define STARPU_ATTRIBUTE_NORETURN
• #define STARPU_ATTRIBUTE_INTERNAL
• #define STARPU_ATTRIBUTE_MALLOC
• #define STARPU_ATTRIBUTE_WARN_UNUSED_RESULT
• #define STARPU_ATTRIBUTE_PURE
• #define STARPU_ATTRIBUTE_ALIGNED(size)
• #define STARPU_ATTRIBUTE_FORMAT(type, string, first)
• #define STARPU_ATTRIBUTE_INLINE
• #define STARPU_ATTRIBUTE_CALLOC_SIZE(num, size)
• #define STARPU_ATTRIBUTE_AlLOC_SIZE(size)
• define endif
• define STARPU_WARN_UNUSED_RESULT
• define STARPU_BACKTRACE_LENGTH
• define STARPU_DUMP_BACKTRACE()
• define STARPU_SIMGRID_ASSERT(x)
• define STARPU_ASSERT(x)
• define STARPU_ASSERT_ACCESSIBLE(ptr)
• define STARPU_ASSERT_MSG(x, msg, ...)
• define _starpu_abort()
• define STARPU_ABORT()
• define STARPU_ABORT_MSG(msg, ...)
• define STARPU_CHECK_RETURN_VALUE(err, message, ...)
• define STARPU_CHECK_RETURN_VALUE_IS(err, value, message, ...)
• define STARPU_ATOMIC_SOMETHING(name, expr)
• define STARPU_ATOMIC_SOMETHINGL(name, expr)
• define STARPU_RMB()
• define STARPU_WMB()

32.42 starpu_worker.h File Reference

#include <stdlib.h>
#include <starpu_config.h>
#include <starpu_thread.h>
#include <starpu_task.h>
#include <hwloc.h>

Data Structures

• struct starpu_sched_ctx_iterator
• struct starpu_worker_collection

Macros

• define starpu_worker_get_id_check()

Enumerations

• enum starpu_node_kind {
  STARPU_UNUSED, STARPU_CPU_RAM, STARPU_CUDA_RAM, STARPU_OPENCL_RAM,
  STARPU_DISK_RAM, STARPU_MIC_RAM, STARPU_MPI_MS_RAM
}
• enum starpu_worker_archtype {
  STARPU_CPU_WORKER, STARPU_CUDA_WORKER, STARPU_OPENCL_WORKER, STARPU_MIC←
  WORKER,
  STARPU_MPI_MS_WORKER, STARPU_ANY_WORKER
}
• enum starpu_worker_collection_type { STARPU_WORKER_TREE, STARPU_WORKER_LIST }

Functions

• unsigned starpu_worker_get_count (void)
• unsigned starpu_cpu_worker_get_count (void)
• unsigned starpu_cuda_worker_get_count (void)
• unsigned starpu_opencl_worker_get_count (void)
• unsigned starpu_mic_worker_get_count (void)
• unsigned starpu_mpi_ms_worker_get_count (void)
• unsigned starpu_mic_device_get_count (void)
• int starpu_worker_get_id (void)
• unsigned _starpu_worker_get_id_check (const char *f, int l)
• int starpu_worker_get_bindid (int workerid)
• void starpu_sched_find_all_worker_combinations (void)
• enum starpu_worker_archtype starpu_worker_get_type (int id)
• int starpu_worker_get_count_by_type (enum starpu_worker_archtype type)
• unsigned starpu_worker_get_ids_by_type (enum starpu_worker_archtype type, int *workerids, unsigned maxsize)
• int starpu_worker_get_by_type (enum starpu_worker_archtype type, int num)
• int starpu_worker_get_devid (enum starpu_worker_archtype type, int devid)
• void starpu_worker_get_name (int id, char *dst, size_t maxlen)
• void starpu_worker_display_names (FILE *output, enum starpu_worker_archtype type)
• int starpu_worker_get_devid (int id)
• int starpu_worker_get_mp_nodeid (int id)
• struct starpu_tree * starpu_workers_get_tree (void)
• unsigned starpu_worker_get_sched_ctx_list (int worker, unsigned **sched_ctx)
• unsigned starpu_worker_is_blocked_in_parallel (int workerid)
• unsigned starpu_worker_is_slave_somewhere (int workerid)
• char * starpu_worker_get_type_as_string (enum starpu_worker_archtype type)
• int starpu_bindid_get_workerids (int bindid, int **workerids)
• int starpu_worker_get_devids (enum starpu_worker_archtype type, int *devids, int num)
• int starpu_worker_get_stream_workerids (unsigned devid, int *workerids, enum starpu_worker_archtype type)
• unsigned starpu_worker_get_sched_ctx_id_stream (unsigned stream_workerid)
• hwloc_cpuset_t starpu_worker_get_hwloc_cpuset (int workerid)
• hwloc_obj_t starpu_worker_get_hwloc_obj (int workerid)
• int starpu_memory_node_get_devid (unsigned node)
• unsigned starpu_worker_get_local_memory_node (void)
• unsigned starpu_worker_get_memory_node (unsigned workerid)
• unsigned starpu_memory_nodes_get_count (void)
• int starpu_memory_node_get_name (unsigned node, char *name, size_t size)
• int starpu_memory_nodes_get_numa_count (void)
• int starpu_memory_nodes_numa_id_to_devid (int osid)
• int starpu_memory_nodes_numa_devid_to_id (unsigned id)
• enum starpu_node_kind starpu_node_get_kind (unsigned node)
• unsigned starpu_combined_worker_get_count (void)
• unsigned starpu_worker_is_combined_worker (int id)
• int starpu_combined_worker_get_id (void)
• int starpu_combined_worker_get_name (void)
• int starpu_combined_worker_get_size (void)
• int starpu_combined_worker_get_rank (void)
• int starpu_combined_worker_assign_workerid (int nworkers, int workerid_array[])
• int starpu_combined_worker_get_description (int workerid, int *worker_size, int **combined_workerid)
• int starpu_combined_worker_can_execute_task (unsigned workerid, struct starpu_task *task, unsigned nimpl)
• void starpu_parallel_task_barrier_init (struct starpu_task *task, int workerid)
• void starpu_parallel_task_barrier_init_n (struct starpu_task *task, int worker_size)

Scheduling operations

• int starpu_worker_sched_op_pending (void)
• void starpu_worker_relax_on (void)
• void starpu_worker_relax_off (void)
• int starpu_worker_get_relax_state (void)
• void starpu_worker_lock (int workerid)
• void starpu_worker_unlock (int workerid)
• void starpu_worker_lock_self (void)
• void starpu_worker_unlock_self (void)
• void starpu_worker_set_going_to_sleep_callback (void(*callback)(unsigned workerid))
• void starpu_worker_set_waking_up_callback (void(*callback)(unsigned workerid))
Variables
- struct starpu_worker_collection worker_list
- struct starpu_worker_collection worker_tree

32.43 starpufft.h File Reference

Typedefs
- typedef double _Complex starpufft_complex
- typedef struct starpufft_plan * starpufft_plan
- typedef float _Complex starpufftf_complex
- typedef struct starpufftf_plan * starpufftf_plan
- typedef struct starpufftl_plan * starpufftl_plan

Functions
- starpufft_plan starpufft_plan_dft_1d (int n, int sign, unsigned flags)
- starpufft_plan starpufft_plan_dft_2d (int n, int m, int sign, unsigned flags)
- starpufft_plan starpufft_plan_dft_r2c_1d (int n, unsigned flags)
- starpufft_plan starpufft_plan_dft_c2r_1d (int n, unsigned flags)
- void * starpufft_malloc (size_t n)
- void starpufft_free (void * p)
- int starpufft_execute (starpufft_plan p, void * in, void * out)
- struct starpu_task * starpufft_start (starpufft_plan p, void *in, void *out)
- int starpufft_execute_handle (starpufft_plan p, starpu_data_handle_t in, starpu_data_handle_t out)
- struct starpu_task * starpufft_start_handle (starpufft_plan p, starpu_data_handle_t in, starpu_data_handle_t __t out)
- void starpufft_cleanup (starpufft_plan p)
- void starpufft_destroy_plan (starpufft_plan p)
- void starpufft_startstats (void)
- void starpufft_stopstats (void)
- void starpufft_showstats (FILE * out)
- starpufft_plan starpufft_plan_dft_1d (int n, int sign, unsigned flags)
- starpufft_plan starpufft_plan_dft_2d (int n, int m, int sign, unsigned flags)
- starpufft_plan starpufft_plan_dft_r2c_1d (int n, unsigned flags)
- starpufft_plan starpufft_plan_dft_c2r_1d (int n, unsigned flags)
- void * starpufft_malloc (size_t n)
- void starpufft_free (void * p)
- int starpufft_execute (starpufft_plan p, void * in, void * out)
- struct starpu_task * starpufft_start (starpufft_plan p, void *in, void *out)
- int starpufft_execute_handle (starpufft_plan p, starpu_data_handle_t in, starpu_data_handle_t out)
- struct starpu_task * starpufft_start_handle (starpufft_plan p, starpu_data_handle_t in, starpu_data_handle_t __t out)
- void starpufft_cleanup (starpufft_plan p)
- void starpufft_destroy_plan (starpufft_plan p)
- void starpufft_startstats (void)
- void starpufft_stopstats (void)
- void starpufft_showstats (FILE *out)
- starpufftt_plan starpufftt_plan_dft_1d (int n, int sign, unsigned flags)
- starpufftt_plan starpufftt_plan_dft_2d (int n, int m, int sign, unsigned flags)
- starpufftt_plan starpufftt_plan_dft_r2c_1d (int n, unsigned flags)
- starpufftt_plan starpufftt_plan_dft_c2r_1d (int n, unsigned flags)
- void * starpufftt_malloc (size_t n)
• void **starpuftl_free** (void *p)
• int **starpuftl_execute** (starpufftl_plan p, void *in, void *out)
• struct **starpu_task** * **starpuftl_start** (starpufftl_plan p, void *in, void *out)
• int **starpuftl_execute_handle** (starpufftl_plan p, starpu_data_handle_t in, starpu_data_handle_t out)
• struct **starpu_task** * **starpuftl_start_handle** (starpufftl_plan p, starpu_data_handle_t in, starpu_data_handle_t out)
• void **starpuftl_cleanup** (starpufftl_plan p)
• void **starpuftl_destroy_plan** (starpufftl_plan p)
• void **starpuftl_startstats** (void)
• void **starpuftl_stopstats** (void)
• void **starpuftl_showstats** (FILE *out)

**Variables**

• int **starpuftl_last_plan_number**

### 32.44  *sc_hypervisor.h* File Reference

```c
#include <starpu.h>
#include <starpu_sched_ctx_hypervisor.h>
#include <sc_hypervisor_config.h>
#include <sc_hypervisor_monitoring.h>
#include <math.h>
```

**Data Structures**

• struct **sc_hypervisor_policy**

**Functions**

• void * **sc_hypervisor_init** (struct sc_hypervisor_policy *policy)
• void **sc_hypervisor_shutdown** (void)
• void **sc_hypervisor_register_ctx** (unsigned sched_ctx, double total_flops)
• void **sc_hypervisor_unregister_ctx** (unsigned sched_ctx)
• void **sc_hypervisor_post_resize_request** (unsigned sched_ctx, int task_tag)
• void **sc_hypervisor_resize_ctxs** (unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)
• void **sc_hypervisor_stop_resize** (unsigned sched_ctx)
• void **sc_hypervisor_start_resize** (unsigned sched_ctx)
• const char * **sc_hypervisor_get_policy** ()
• void **sc_hypervisor_add_workers_to_sched_ctx** (int *workers_to_add, unsigned nworkers_to_add, unsigned sched_ctx)
• void **sc_hypervisor_remove_workers_from_sched_ctx** (int *workers_to_remove, unsigned nworkers_to_remove, unsigned sched_ctx, unsigned now)
• void **sc_hypervisor_move_workers** (unsigned sender_sched_ctx, unsigned receiver_sched_ctx, int *workers_to_move, unsigned nworkers_to_move, unsigned now)
• unsigned **sc_hypervisor_size_ctxs** (unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)
• unsigned **sc_hypervisor_get_size_req** (unsigned **sched_ctxs, int *nsched_ctxs, int *workers, int nworkers)
• void **sc_hypervisor_save_size_req** (unsigned *sched_ctxs, int nsched_ctxs, int *workers, int nworkers)
• void **sc_hypervisor_free_size_req** (void)
• unsigned **sc_hypervisor_can_resize** (unsigned sched_ctx)
• void **sc_hypervisor_set_type_of_task** (struct starpu_codelet *cl, unsigned sched_ctx, uint32_t footprint, size_t data_size)
• void **sc_hypervisor_update_diff_total_flops** (unsigned sched_ctx, double diff_total_flops)
• void sc_hypervisor_update_diff_elapsed_flops (unsigned sched_ctx, double diff_task_flops)
• void sc_hypervisor_update_resize_interval (unsigned *sched_ctxs, int nsched_ctxs, int max_nworkers)
• void sc_hypervisor_get_ctxs_on_level (unsigned **sched_ctxs, int *nsched_ctxs, unsigned hierarchy_level, unsigned father_sched_ctx_id)
• unsigned sc_hypervisor_get_nhierarchy_levels (void)
• void sc_hypervisor_get_leaves (unsigned *sched_ctxs, int nsched_ctxs, unsigned *leaves, int *nleaves)
• double sc_hypervisor_get_nready_flops_of_all_sons_of_sched_ctx (unsigned sched_ctx)
• void sc_hypervisor_print_overhead ()
• void sc_hypervisor_init_worker (int workerid, unsigned sched_ctx)

Variables

• starpu_pthread_mutex_t act_hypervisor_mutex

32.45 sc_hypervisor_config.h File Reference

#include <sc_hypervisor.h>

Data Structures

• struct sc_hypervisor_policy_config

  • #define SC_HYPERVISOR_MAX_IDLE
  • #define SC_HYPERVISOR_MIN_WORKING
  • #define SC_HYPERVISOR_PRIORITY
  • #define SC_HYPERVISOR_MIN_WORKERS
  • #define SC_HYPERVISOR_MAX_WORKERS
  • #define SC_HYPERVISOR_GRANULARITY
  • #define SC_HYPERVISOR_FIXED_WORKERS
  • #define SC_HYPERVISOR_MIN_TASKS
  • #define SC_HYPERVISOR_NEW_WORKERS_MAX_IDLE
  • #define SC_HYPERVISOR_TIME_TO_APPLY
  • #define SC_HYPERVISOR_NULL
  • #define SC_HYPERVISOR_ISPEED_W_SAMPLE
  • #define SC_HYPERVISOR_ISPEED_CTX_SAMPLE
  • #define SC_HYPERVISOR_TIME_SAMPLE
  • #define MAX_IDLE_TIME
  • #define MIN_WORKING_TIME
  • void sc_hypervisor_set_config (unsigned sched_ctx, void *config)
  • struct sc_hypervisor_policy_config * sc_hypervisor_get_config (unsigned sched_ctx)
  • void sc_hypervisor_ctl (unsigned sched_ctx,...)

32.45.1 Data Structure Documentation

32.45.1.1 struct sc_hypervisor_policy_config

Methods that implement a hypervisor resizing policy.

Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>min_nworkers</td>
<td>Indicate the minimum number of workers needed by the context</td>
</tr>
<tr>
<td>int</td>
<td>max_nworkers</td>
<td>Indicate the maximum number of workers needed by the context</td>
</tr>
<tr>
<td>int</td>
<td>granularity</td>
<td>Indicate the workers granularity of the context</td>
</tr>
</tbody>
</table>
Data Fields

<table>
<thead>
<tr>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>priority[STARPU_NMAXWORKERS]</td>
<td>Indicate the priority of each worker to stay in the context. The smaller the priority, the faster it will be moved to another context.</td>
</tr>
<tr>
<td>double</td>
<td>max_idle[STARPU_NMAXWORKERS]</td>
<td>Indicate the maximum idle time accepted before a resize is triggered. Above this limit, the priority of the worker is reduced.</td>
</tr>
<tr>
<td>double</td>
<td>min_working[STARPU_NMAXWORKERS]</td>
<td>Indicate that underneath this limit, the priority of the worker is reduced.</td>
</tr>
<tr>
<td>int</td>
<td>fixed_workers[STARPU_NMAXWORKERS]</td>
<td>Indicate which workers can be moved and which ones are fixed.</td>
</tr>
<tr>
<td>double</td>
<td>new_workers_max_idle</td>
<td>Indicate the maximum idle time accepted before a resize is triggered for the workers that just arrived in the new context.</td>
</tr>
<tr>
<td>double</td>
<td>ispeed_w_sample[STARPU_NMAXWORKERS]</td>
<td>Indicate the sample used to compute the instant speed per worker.</td>
</tr>
<tr>
<td>double</td>
<td>ispeed_ctx_sample</td>
<td>Indicate the sample used to compute the instant speed per ctxs.</td>
</tr>
<tr>
<td>double</td>
<td>time_sample</td>
<td>Indicate the sample used to compute the instant speed per ctx (in seconds).</td>
</tr>
</tbody>
</table>

32.46 sc_hypervisor_lp.h File Reference

```c
#include <sc_hypervisor.h>
#include <starpu_config.h>
#include <glpk.h>
```

Functions

- `double sc_hypervisor_lp_get_nworkers_per_ctx (int nsched_ctxs, int ntypes_of_workers, double res[nsched_ctxs][ntypes_of_workers], int total_nw[ntypes_of_workers], struct types_of_workers *tw, unsigned *in_sched_ctxs)`
- `double sc_hypervisor_lp_get_tmax (int nw, int *workers)`
- `void sc_hypervisor_lp_round_double_to_int (int ns, int nw, double res[ns][nw], int res_rounded[ns][nw])`
- `void sc_hypervisor_lp_redistribute_resources_in_ctxs (int ns, int nw, int res_rounded[ns][nw], double res[ns][nw], unsigned *sched_ctxs, struct types_of_workers *tw)`
- `void sc_hypervisor_lp_distribute_resources_in_ctxs (unsigned *sched_ctxs, int ns, int nw, double res[ns][nw], int *workers, int nworkers, struct types_of_workers *tw)`
- `void sc_hypervisor_lp_distribute_floating_no_resources_in_ctxs (unsigned *sched_ctxs, int ns, int nw, double res[ns][nw], int *workers, unsigned do_size, struct types_of_workers *tw)`
- `void sc_hypervisor_lp_place_resources_in_ctx (int ns, int nw, double w_in_s[ns][nw], unsigned *workers)`
- `unsigned sc_hypervisor_lp_share_remaining_resources (int ns, unsigned *sched_ctxs, int nworkers, int *workers)`
- `double sc_hypervisor_lp_find_tmax (double t1, double t2)`
- `unsigned sc_hypervisor_lp_execute_dichotomy (int ns, int nw, double w_in_s[ns][nw], unsigned solve_lp_integer, void *specific_data, double tmin, double tmax, double smallest_tmax, double(*lp_estimated_distrib_func)(int ns, int nw, double draft_w_in_s[ns][nw], unsigned is_integer, double tmax, void *specific_data))`
- `double sc_hypervisor_lp_simulate_distrib_flops (int nsched_ctxs, int ntypes_of_workers, double speed[nsched_ctxs][ntypes_of_workers], double flops[nsched_ctxs], double res[nsched_ctxs][ntypes_of_workers], int total_nw[ntypes_of_workers], unsigned sched_ctxs[nsched_ctxs], double vmax)`
- `double sc_hypervisor_lp_simulate_distrib_tasks (int ns, int nw, int nt, double w_in_s[ns][nw], double tasks[nw][nt], double times[nw][nt], unsigned is_integer, double tmax, unsigned *in_sched_ctxs, struct sc_hypervisor_policy_task_pool *tmp_task_pools)"
double sc_hypervisor_lp_simulate_distrib_flops_on_sample (int ns, int nw, double final_w_in_s[ns][nw], unsigned is_integer, double tmax, double *speed, double flops[ns], double **final_flops_on_w)

32.47 sc_hypervisor_monitoring.h File Reference

#include <sc_hypervisor.h>

Data Structures

- struct sc_hypervisor_resize_ack
- struct sc_hypervisor_wrapper

Functions

- struct sc_hypervisor_wrapper * sc_hypervisor_get_wrapper (unsigned sched_ctx)
- unsigned * sc_hypervisor_get_sched_ctxs ()
- int sc_hypervisor_get_nsched_ctxs ()
- int sc_hypervisor_get_nworkers_ctx (unsigned sched_ctx, enum starpu_worker_archtype arch)
- double sc_hypervisor_get_elapsed_flops_per_sched_ctx (struct sc_hypervisor_wrapper *sc_w)
- double sc_hypervisor_get_total_elapsed_flops_per_sched_ctx (struct sc_hypervisor_wrapper *sc_w)
- double sc_hypervisor_get_speed_per_worker_type (struct sc_hypervisor_wrapper *sc_w, enum starpu_worker_archtype arch)
- double sc_hypervisor_get_speed (struct sc_hypervisor_wrapper *sc_w, enum starpu_worker_archtype arch)

32.47.1 Data Structure Documentation

32.47.1.1 struct sc_hypervisor_wrapper

Wrapper of the contexts available in StarPU which contains all information about a context obtained by incrementing the performance counters. It is attached to a sched_ctx storing monitoring information.

Data Fields

<table>
<thead>
<tr>
<th>unsigned</th>
<th>sched_ctx</th>
<th>the monitored context</th>
</tr>
</thead>
<tbody>
<tr>
<td>struct</td>
<td>config</td>
<td>The corresponding resize configuration</td>
</tr>
<tr>
<td>double</td>
<td>start_time_w[STARPU_NMAXWORKERS]</td>
<td>time of the resizing sample of the workers of this context</td>
</tr>
<tr>
<td>double</td>
<td>current_idle_time[STARPU_NMAXWORKERS]</td>
<td>idle time counter of each worker of the context</td>
</tr>
<tr>
<td>double</td>
<td>idle_time[STARPU_NMAXWORKERS]</td>
<td>The time the workers were idle from the last resize</td>
</tr>
<tr>
<td>double</td>
<td>idle_start_time[STARPU_NMAXWORKERS]</td>
<td>moment when the workers started being idle</td>
</tr>
<tr>
<td>double</td>
<td>exec_time[STARPU_NMAXWORKERS]</td>
<td>time during which the worker executed tasks</td>
</tr>
<tr>
<td>double</td>
<td>exec_start_time[STARPU_NMAXWORKERS]</td>
<td>moment when the worker started executing a task</td>
</tr>
<tr>
<td>int</td>
<td>worker_to_be_removed[STARPU_NMAXWORKERS]</td>
<td>list of workers that will leave the context (lazy resizing process)</td>
</tr>
<tr>
<td>int</td>
<td>pushed_tasks[STARPU_NMAXWORKERS]</td>
<td>number of tasks pushed on each worker in this context</td>
</tr>
</tbody>
</table>
### Data Fields

<table>
<thead>
<tr>
<th>Data Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td><code>poped_tasks[STARPU_NMAXWORKERS]</code> Number of tasks popped from each worker in this context</td>
</tr>
<tr>
<td>double</td>
<td><code>total_flops</code> The total number of flops to execute by the context</td>
</tr>
<tr>
<td>double</td>
<td><code>total_elapsed_flops[STARPU_NMAXWORKERS]</code> Number of flops executed by each workers of the context</td>
</tr>
<tr>
<td>double</td>
<td><code>elapsed_flops[STARPU_NMAXWORKERS]</code> Number of flops executed since last resizing</td>
</tr>
<tr>
<td>size_t</td>
<td><code>elapsed_data[STARPU_NMAXWORKERS]</code> Quantity of data (in bytes) used to execute tasks on each worker in this context</td>
</tr>
<tr>
<td>int</td>
<td><code>elapsed_tasks[STARPU_NMAXWORKERS]</code> Number of tasks executed on each worker in this context</td>
</tr>
<tr>
<td>double</td>
<td><code>ref_speed[2]</code> the average speed of the type of workers when they belonged to this context 0 - cuda 1 - cpu</td>
</tr>
<tr>
<td>double</td>
<td><code>submitted_flops</code> Number of flops submitted to this context</td>
</tr>
<tr>
<td>double</td>
<td><code>remaining_flops</code> Number of flops that still have to be executed by the workers in this context</td>
</tr>
<tr>
<td>double</td>
<td><code>start_time</code> Start time of the resizing sample of this context</td>
</tr>
<tr>
<td>double</td>
<td><code>real_start_time</code> First time a task was pushed to this context</td>
</tr>
<tr>
<td>double</td>
<td><code>hyp React start time</code> Start time for sample in which the hypervisor is not allowed to react bc too expensive</td>
</tr>
<tr>
<td>struct sc_hypervisor_resize_ack</td>
<td><code>resize_ack</code> Structure confirming the last resize finished and a new one can be done. Workers do not leave the current context until the receiver context does not ack the receive of these workers</td>
</tr>
<tr>
<td>starpu_pthread_mutex_t</td>
<td><code>mutex</code> Mutex needed to synchronize the acknowledgment of the workers into the receiver context</td>
</tr>
<tr>
<td>unsigned</td>
<td><code>total_flops_available</code> Boolean indicating if the hypervisor can use the flops corresponding to the entire execution of the context</td>
</tr>
<tr>
<td>unsigned</td>
<td><code>to_be_sized</code> Boolean indicating that a context is being sized</td>
</tr>
<tr>
<td>unsigned</td>
<td><code>compute_idle[STARPU_NMAXWORKERS]</code> Boolean indicating if we add the idle of this worker to the idle of the context</td>
</tr>
<tr>
<td>unsigned</td>
<td><code>compute_partial_idle[STARPU_NMAXWORKERS]</code> Boolean indicating if we add the entire idle of this worker to the idle of the context or just half</td>
</tr>
<tr>
<td>unsigned</td>
<td><code>consider_max</code> consider the max in the lp</td>
</tr>
</tbody>
</table>
#include <sc_hypervisor.h>

Data Structures

- struct types_of_workers
- struct sc_hypervisor_policy_task_pool

Macros

- #define HYPERVISOR_REDIM_SAMPLE
- #define HYPERVISOR_START_REDIM_SAMPLE
- #define SC_NOTHING
- #define SC_IDLE
- #define SC_SPEED

Functions

- void sc_hypervisor_policy_add_task_to_pool (struct starpu_codelet *cl, unsigned sched_ctx, uint32_t footprint, struct sc_hypervisor_policy_task_pool **task_pools, size_t data_size)
- void sc_hypervisor_policy_remove_task_from_pool (struct starpu_task *task, uint32_t footprint, struct sc_hypervisor_policy_task_pool **task_pools)
- struct sc_hypervisor_policy_task_pool * sc_hypervisor_policy_clone_task_pool (struct sc_hypervisor_policy_task_pool *tp)
- void sc_hypervisor_get_tasks_times (int nw, int nt, double times[nw][nt], int *workers, unsigned size_ctxs, struct sc_hypervisor_policy_task_pool *task_pools)
- unsigned sc_hypervisor_find_lowest_prio_sched_ctx (unsigned req_sched_ctx, int nworkers_to_move)
- int * sc_hypervisor_get_idlest_workers (unsigned sched_ctx, int *nworkers, enum starpu_worker_archtype arch)
- int * sc_hypervisor_get_idlest_workers_in_list (int *start, int *workers, int nall_workers, int *nworkers, enum starpu_worker_archtype arch)
- int sc_hypervisor_get_movable_nworkers (struct sc_hypervisor_policy_config *config, unsigned sched_ctx, enum starpu_worker_archtype arch)
- int sc_hypervisor_compute_nworkers_to_move (unsigned req_sched_ctx)
- unsigned sc_hypervisor_policy_resize (unsigned sender_sched_ctx, unsigned receiver_sched_ctx, unsigned force_resize, unsigned now)
- unsigned sc_hypervisor_policy_resize_to_unknown_receiver (unsigned sender_sched_ctx, unsigned now)
- double sc_hypervisor_get_ctx_speed (struct sc_hypervisor_wrapper *sc_w)
- double sc_hypervisor_get_slowest_ctx_exec_time (void)
- double sc_hypervisor_get_fastest_ctx_exec_time (void)
- double sc_hypervisor_get_speed_per_worker (struct sc_hypervisor_wrapper *sc_w, unsigned worker)
- double sc_hypervisor_get_speed_per_worker_type (struct sc_hypervisor_wrapper *sc_w, enum starpu_worker_archtype arch)
- double sc_hypervisor_get_ref_speed_per_worker_type (struct sc_hypervisor_wrapper *sc_w, enum starpu_worker_archtype arch)
- double sc_hypervisor_get_avg_speed (enum starpu_worker_archtype arch)
- void sc_hypervisor_check_if_consider_max (struct types_of_workers *tw)
- void sc_hypervisor_group_workers_by_type (struct types_of_workers *tw, int *total_nw)
- enum starpu_worker_archtype sc_hypervisor_get_arch_for_index (unsigned w, struct types_of_workers *tw)
- unsigned sc_hypervisor_get_index_for_arch (enum starpu_worker_archtype arch, struct types_of_workers *tw)
- unsigned sc_hypervisor_criteria_fulfilled (unsigned sched_ctx, int worker)
- unsigned sc_hypervisor_check_idle (unsigned sched_ctx, int worker)
• unsigned sc_hypervisor_check_speed_gap_btw_ctxs (unsigned ∗sched_ctxs, int nsched_ctxs, int ∗workers, int nworkers)
• unsigned sc_hypervisor_check_speed_gap_btw_ctxs_on_level (int level, int ∗workers_in, int nworkers_in, unsigned father_sched_ctx_id, unsigned ∗∗sched_ctxs, int ∗nsched_ctxs)
• unsigned sc_hypervisor_get_resize_criteria ()
• struct types_of_workers ∗ sc_hypervisor_get_types_of_workers (int ∗workers, unsigned nworkers)

32.49 starpurm.h File Reference

#include <hwloc.h>
#include <starpurm_config.h>

TypeDefs

• typedef int starpurm_drs_ret_t
• typedef void ∗ starpurm_drs_desc_t
• typedef void ∗ starpurm_drs_cbs_t
• typedef void(∗ starpurm_drs_cb_t) (void ∗)
• typedef void ∗ starpurm_block_cond_t
• typedef int(∗ starpurm_polling_t) (void ∗)

Enumerations

• enum e_starpurm_drs_ret { starpurm_DRS_SUCCESS, starpurm_DRS_DISABLD, starpurm_DRS_PERM, starpurm_DRS_EINVAL }

Functions

Initialisation

• void starpurm_initialize_with_cpuset (hwloc_cpuset_t initially_owned_cpuset)
• void starpurm_initialize (void)
• void starpurm_shutdown (void)

Spawn

• void starpurm_spawn_kernel_on_cpus (void ∗data, void(∗f)(void ∗), void ∗args, hwloc_cpuset_t cpuset)
• void starpurm_spawn_kernel_on_cpus_callback (void ∗data, void(∗f)(void ∗), void ∗args, hwloc_cpuset_t cpuset, void (∗cb_f)(void ∗), void ∗cb_args)
• void starpurm_spawn_kernel_callback (void ∗data, void(∗f)(void ∗), void ∗args, void (∗cb_f)(void ∗), void ∗cb_args)

DynamicResourceSharing

• starpurm_drs_ret_t starpurm_set_drs_enable (starpurm_drs_desc_t ∗spd)
• starpurm_drs_ret_t starpurm_set_drs_disable (starpurm_drs_desc_t ∗spd)
• int starpurm_drs_enabled_p (void)
• starpurm_drs_ret_t starpurm_set_max_parallelism (starpurm_drs_desc_t ∗spd, int max)
• starpurm_drs_ret_t starpurm_assign_cpu_to_starpu (starpurm_drs_desc_t ∗spd, int cpuid)
• starpurm_drs_ret_t starpurm_assign_cpus_to_starpu (starpurm_drs_desc_t ∗spd, int ncpus)
• starpurm_drs_ret_t starpurm_assign_cpu_mask_to_starpu (starpurm_drs_desc_t ∗spd, const hwloc_cpuset_t mask)
• starpurm_drs_ret_t starpurm_withdraw_cpu_from_starpu (starpurm_drs_desc_t ∗spd, int cpuid)
• starpurm_drs_ret_t starpurm_withdraw_cpu_from_starpu (starpurm_drs_desc_t ∗spd, int ncpus)
• starpurm_drs_ret_t starpurm_withdraw_cpu_mask_from_starpu (starpurm_drs_desc_t ∗spd, const hwloc_cpuset_t mask)
• starpurm_drs_ret_t starpurm_withdraw_all_cpus_from_starpu (starpurm_drs_desc_t ∗spd)
• starpurm_drs_ret_t starpurm_lend (starpurm_drs_desc_t ∗spd)
starpurm.drs_ret_t starpurm_lend_cpu (starpurm.drs_desc_t *spd, int cpuid)
starpurm.drs_ret_t starpurm_lend_cpus (starpurm.drs_desc_t *spd, int ncpus)
starpurm.drs_ret_t starpurm_lend_cpu_mask (starpurm.drs_desc_t *spd, const hwloc_cpuset_t mask)
starpurm.drs_ret_t starpurm_reclaim (starpurm.drs_desc_t *spd)
starpurm.drs_ret_t starpurm_reclaim_cpu (starpurm.drs_desc_t *spd, int cpuid)
starpurm.drs_ret_t starpurm_reclaim_cpus (starpurm.drs_desc_t *spd, int ncpus)
starpurm.drs_ret_t starpurm_reclaim_cpu_mask (starpurm.drs_desc_t *spd, const hwloc_cpuset_t mask)
starpurm.drs_ret_t starpurm_acquire (starpurm.drs_desc_t *spd)
starpurm.drs_ret_t starpurm_acquire_cpu (starpurm.drs_desc_t *spd, int cpuid)
starpurm.drs_ret_t starpurm_acquire_cpus (starpurm.drs_desc_t *spd, int ncpus)
starpurm.drs_ret_t starpurm_acquire_cpu_mask (starpurm.drs_desc_t *spd, const hwloc_cpuset_t mask)
starpurm.drs_ret_t starpurm_return_all (starpurm.drs_desc_t *spd)
starpurm.drs_ret_t starpurm_return_cpu (starpurm.drs_desc_t *spd, int cpuid)

Devices

int starpurm_get_device_type_id (const char *type_str)
const char * starpurm_get_device_type_name (int type_id)
int starpurm_get_nb_devices_by_type (int type_id)
int starpurm_get_device_id (int type_id, int device_rank)
starpurm.drs_ret_t starpurm_assign_device_to_starpu (starpurm.drs_desc_t *spd, int type_id, int unit_rank)
starpurm.drs_ret_t starpurm_assign_devices_to_starpu (starpurm.drs_desc_t *spd, int type_id, int ndevices)
starpurm.drs_ret_t starpurm_assign_device_mask_to_starpu (starpurm.drs_desc_t *spd, const hwloc_cpuset_t mask)
starpurm.drs_ret_t starpurm_assign_all_devices_to_starpu (starpurm.drs_desc_t *spd, int type_id)
starpurm.drs_ret_t starpurm_withdraw_device_from_starpu (starpurm.drs_desc_t *spd, int type_id, int unit_rank)
starpurm.drs_ret_t starpurm_withdraw_devices_from_starpu (starpurm.drs_desc_t *spd, int type_id, int ndevices)
starpurm.drs_ret_t starpurm_withdraw_device_mask_from_starpu (starpurm.drs_desc_t *spd, const hwloc_cpuset_t mask)
starpurm.drs_ret_t starpurm_withdraw_all_devices_from_starpu (starpurm.drs_desc_t *spd, int type_id)
starpurm.drs_ret_t starpurm_lend_device (starpurm.drs_desc_t *spd, int unit_rank)
starpurm.drs_ret_t starpurm_lend_devices (starpurm.drs_desc_t *spd, int ncpus)
starpurm.drs_ret_t starpurm_lend_device_mask (starpurm.drs_desc_t *spd, const hwloc_cpuset_t mask)
starpurm.drs_ret_t starpurm_lend_all_devices (starpurm.drs_desc_t *spd, int type_id)
starpurm.drs_ret_t starpurm_reclaim_device (starpurm.drs_desc_t *spd, int type_id, int unit_rank)
starpurm.drs_ret_t starpurm_reclaim_devices (starpurm.drs_desc_t *spd, int type_id, int ndevices)
starpurm.drs_ret_t starpurm_reclaim_device_mask (starpurm.drs_desc_t *spd, const hwloc_cpuset_t mask)
starpurm.drs_ret_t starpurm_reclaim_all_devices (starpurm.drs_desc_t *spd, int type_id)
starpurm.drs_ret_t starpurm_acquire_device (starpurm.drs_desc_t *spd, int type_id, int unit_rank)
starpurm.drs_ret_t starpurm_acquire_devices (starpurm.drs_desc_t *spd, int type_id, int ndevices)
starpurm.drs_ret_t starpurm_acquire_device_mask (starpurm.drs_desc_t *spd, const hwloc_cpuset_t mask)
starpurm.drs_ret_t starpurm_acquire_all_devices (starpurm.drs_desc_t *spd, int type_id)
starpurm.drs_ret_t starpurm_return_all_devices (starpurm.drs_desc_t *spd, int type_id)
starpurm.drs_ret_t starpurm_return_device (starpurm.drs_desc_t *spd, int type_id, int unit_rank)

CpusetsQueries

hwloc_cpuset_t starpurm_get_device_worker_cpuset (int type_id, int unit_rank)
hwloc_cpuset_t starpurm_get_global_cpuset (void)
hwloc_cpuset_t starpurm_get_selected_cpuset (void)
hwloc_cpuset_t starpurm_get_all_cpu_workers_cpuset (void)
hwloc_cpuset_t starpurm_get_all_device_workers_cpuset (void)
hwloc_cpuset_t starpurm_get_all_device_workers_cpuset_by_type (int typeid)
Chapter 33

Deprecated List

**Global starpu_codelet::cpu_func**
Optional field which has been made deprecated. One should use instead the field `starpu_codelet::cpu_funcs`.

**Global starpu_codelet::cuda_func**
Optional field which has been made deprecated. One should use instead the `starpu_codelet::cuda_funcs` field.

**Global starpu_codelet::opencl_func**
Optional field which has been made deprecated. One should use instead the `starpu_codelet::opencl_funcs` field.

**Global starpu_data_free_pinned_if_possible**
Equivalent to `starpu_free()`. This macro is provided to avoid breaking old codes.

**Global starpu_data_interface_ops::handle_to_pointer(starpu_data_handle_t handle, unsigned node)**
Use `starpu_data_interface_ops::to_pointer` instead. Return the current pointer (if any) for the handle on the given node.

**Global starpu_data_malloc_pinned_if_possible**
Equivalent to `starpu_malloc()`. This macro is provided to avoid breaking old codes.

**Global starpu_mpi_initialize (void)**
This function has been made deprecated. One should use instead the function `starpu_mpi_init()`. This function does not call `MPI_Init()`, it should be called beforehand.

**Global starpu_mpi_initialize_extended (int ∗rank, int ∗world_size)**
This function has been made deprecated. One should use instead the function `starpu_mpi_init()`. MPI will be initialized by starpumpi by calling `MPI_Init_Thread(argc, argv, MPI_THREAD_SERIALIZED, ...)`.

**Global STARPU_MULTIPLE_CPU_IMPLEMENTATIONS**
Setting the field `starpu_codelet::cpu_func` with this macro indicates the codelet will have several implementations. The use of this macro is deprecated. One should always only define the field `starpu_codelet::cpu_funcs`.

**Global STARPU_MULTIPLE_CUDA_IMPLEMENTATIONS**
Setting the field `starpu_codelet::cuda_func` with this macro indicates the codelet will have several implementations. The use of this macro is deprecated. One should always only define the field `starpu_codelet::cuda_funcs`.

**Global STARPU_MULTIPLE_OPENCL_IMPLEMENTATIONS**
Setting the field `starpu_codelet::opencl_func` with this macro indicates the codelet will have several implementations. The use of this macro is deprecated. One should always only define the field `starpu_codelet::opencl_funcs`.  


Part VI

Appendix
Chapter 34

Full Source Code for the 'Scaling a Vector' Example

34.1 Main Application

/*
 * This example demonstrates how to use StarPU to scale an array by a factor.
 * It shows how to manipulate data with StarPU's data management library.
 * 1- how to declare a piece of data to StarPU (starpu_vector_data_register)
 * 2- how to describe which data are accessed by a task (task->handles[0])
 * 3- how a kernel can manipulate the data (buffers[0].vector.ptr)
 */

#include <starpu.h>

#define NX 2048
extern void scal_cpu_func(void *buffers[], void *__args);
extern void scal_sse_func(void *buffers[], void *__args);
extern void scal_cuda_func(void *buffers[], void *__args);
extern void scal_opencl_func(void *buffers[], void *__args);

static struct starpu_codelet cl =
{
    .where = STARPU_CPU | STARPU_CUDA | STARPU_OPENCL,
    /* CPU implementation of the codelet */
    .cpu_funcs = { scal_cpu_func, scal_sse_func },
    .cpu_funcs_name = { "scal_cpu_func", "scal_sse_func" },
#ifdef STARPU_USE_CUDA
    /* CUDA implementation of the codelet */
    .cuda_funcs = { scal_cuda_func },
#endif
#ifdef STARPU_USE_OPENCL
    /* OpenCL implementation of the codelet */
    .opencl_funcs = { scal_opencl_func },
#endif
    .nbuffers = 1,
    .modes = { STARPU_RW }
};

#ifdef STARPU_USE_OPENCL
struct starpu_opencl_program programs;
#endif

int main(int argc, char **argv)
{
    /* We consider a vector of float that is initialized just as any of C
     * data */
    float vector[NX];
    unsigned i;
    for (i = 0; i < NX; i++)
        vector[i] = 1.0f;
    fprintf(stderr, "BEFORE: First element was %f \n", vector[0]);

    /* Initialize StarPU with default configuration */
    starpu_init(NULL);

#ifdef STARPU_USE_OPENCL
    starpu_opencl_load_opencl_from_file("examples/basic_examples/vector_scal_opencl_kernel.cl", &programs, NULL);
#endif

    /* Tell StarPU to associate the "vector" vector with the "vector_handle"
     * identifier. When a task needs to access a piece of data, it should
     * refer to the handle that is associated to it.*/
    /* In the case of the "vector" data interface:
     * - the first argument of the registration method is a pointer to the

...
```c
float factor = 3.14;

// create a synchronous task: any call to starpu_task_submit will block
// until it is terminated */
struct starpu_task *task = starpu_task_create();
task->synchronous = 1;
task->cl = &cl;

/* the codelet manipulates one buffer in RW mode */
task->handles[0] = vector_handle;

/* an argument is passed to the codelet, beware that this is a
* READ-ONLY buffer and that the codelet may be given a pointer to a
* COPY of the argument */
task->cl_arg = &factor;
task->cl_arg_size = sizeof(factor);

/* execute the task on any eligible computational resource */
starpu_task_submit(task);

/* StarPU does not need to manipulate the array anymore so we can stop
* monitoring it */
starpu_data_unregister(vector_handle);

/* terminate StarPU, no task can be submitted after */
starpu_shutdown();

fprintf(stderr, "AFTER First element is %f\n", vector[0]);
return 0;
```

34.2 CPU Kernel

```c
#include <starpu.h>
#include <xmmintrin.h>

/* This kernel takes a buffer and scales it by a constant factor */
void scal_cpu_func(void *buffers[], void *cl_arg)
{
  unsigned i;
  float *factor = cl_arg;

  /* The "buffers" array matches the task->handles array: for instance
   * task->handles[0] is a handle that corresponds to a data with
   * vector "interface", so that the first entry of the array in the
   * codelet is a pointer to a structure describing such a vector (ie.
   * struct starpu_vector_interface *). Here, we therefore manipulate
   * the buffers[0] element as a vector: nx gives the number of elements
   * in the array, ptr gives the location of the array (that was possibly
   * migrated/replicated), and elemsize gives the size of each elements.
   */
  struct starpu_vector_interface *vector = buffers[0];

  /* length of the vector */
  unsigned n = STARPU_VECTOR_GET_NX(vector);

  /* get a pointer to the local copy of the vector: note that we have to
   * cast it in (float *) since a vector could contain any type of
   * elements so that the .ptr field is actually a uintptr_t */
  float *val = (float *)STARPU_VECTOR_GET_PTR(vector);

  /* scale the vector */
  for (i = 0; i < n; i++)
    val[i] *= *factor;
}
```
void scal_sse_func(void *buffers[], void *cl_arg)
{
    float *vector = (float *) STARPU_VECTOR_GET_PTR(buffers[0]);
    unsigned int n = STARPU_VECTOR_GET_NX(buffers[0]);
    unsigned int n_iterations = n/4;

    _m128 *VECTOR = (__m128*) vector;
    __m128 FACTOR STARPU_ATTRIBUTE_ALIGNED(16);
    float factor = *((float *) cl_arg);
    FACTOR = _mm_set1_ps(factor);

    unsigned int i;
    for (i = 0; i < n_iterations; i++)
    {
        VECTOR[i] = _mm_mul_ps(FACTOR, VECTOR[i]);
    }
    unsigned int remainder = n%4;
    if (remainder != 0)
    {
        unsigned int start = 4 * n_iterations;
        for (i = start; i < start+remainder; ++i)
        {
            vector[i] = factor * vector[i];
        }
    }
}

34.3 CUDA Kernel

#include <starpu.h>

static __global__ void vector_mult_cuda(unsigned n, float *val, float factor)
{
    unsigned i = blockIdx.x *blockDim.x + threadIdx.x;
    if (i < n)
        val[i] *= factor;
}

extern "C" void scal_cuda_func(void *buffers[], void *cl_arg)
{
    float *factor = (float *) cl_arg;
    /* length of the vector */
    unsigned n = STARPU_VECTOR_GET_NX(buffers[0]);
    /* local copy of the vector pointer */
    float *val = (float *) STARPU_VECTOR_GET_PTR(buffers[0]);
    unsigned threads_per_block = 64;
    unsigned nblocks = (n + threads_per_block-1) / threads_per_block;
    vector_mult_cuda<<<nblocks,threads_per_block, 0, starpu_cuda_get_local_stream()>>>(n, val, *factor);
    cudaMemcpyInStream(starpu_cuda_get_local_stream(), starpu_cuda_get_local_stream());
}

34.4 OpenCL Kernel

34.4.1 Invoking the Kernel

#include <starpu.h>

extern struct starpu_opencl_program programs;

void scal_opencl_func(void *buffers[], void *cl_arg)
{
    float *factor = _args;
    int id, devid, err; /* OpenCL specific code */
    cl_kernel kernel; /* OpenCL specific code */
    cl_command_queue queue; /* OpenCL specific code */
    cl_event event; /* OpenCL specific code */

    /* length of the vector */
    unsigned n = STARPU_VECTOR_GET_NX(buffers[0]);
    /* OpenCL copy of the vector pointer */
    cl_mem val = (cl_mem) STARPU_VECTOR_GET_DEV_HANDLE(buffers[0]);

    err = starpu_opencl_load_kernel(&kernel, &queue, &programs,
    { /* OpenCL specific code */
        id = starpu_worker_get_id();
        devid = starpu_worker_get_devid(id);
        err = starpu_opencl_load_kernel(&kernel, &queue, &programs,

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"vector_mult_opencl", /* Name of the codelet */
devid);
if (err != CL_SUCCESS) STARPU_OPENCL_REPORT_ERROR(err);
err = clSetKernelArg(kernel, 0, sizeof(n), &n);
err |= clSetKernelArg(kernel, 1, sizeof(val), &val);
err |= clSetKernelArg(kernel, 2, sizeof(*factor), factor);
if (err) STARPU_OPENCL_REPORT_ERROR(err);
}
{ /* OpenCL specific code */
size_t global=n;
size_t local;
siize_t s;
cl_device_id device;

starpu_opencl_get_device(devid, &device);
err = clGetKernelWorkGroupInfo(kernel, device, CL_KERNEL_WORK_GROUP_SIZE, sizeof(local), &local, &s);
if (err != CL_SUCCESS) STARPU_OPENCL_REPORT_ERROR(err);
if (local > global) local=global;
err = clEnqueueNDRangeKernel(queue, kernel, 1, NULL, &global, &local, 0, NULL, &event);
if (err != CL_SUCCESS) STARPU_OPENCL_REPORT_ERROR(err);
}
{ /* OpenCL specific code */
clFinish(queue);
starpu_opencl_collect_stats(event);
clReleaseEvent(event);
starpu_opencl_release_kernel(kernel);
}
}

34.4.2 Source of the Kernel

__kernel void vector_mult_opencl(int nx, __global float* val, float factor)
{
    const int i = get_global_id(0);
    if (i < nx)
    {
        val[i] *= factor;
    }
}
Chapter 35

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Part VII

Index
Index

__configure__--disable-asynchronous-copy, 172
__configure__--disable-asynchronous-cuda-copy, 172
__configure__--disable-asynchronous-mic-copy, 173
__configure__--disable-asynchronous-mpi-master-slave-copy, 173
__configure__--disable-asynchronous-opencl-copy, 172
__configure__--disable-build-doc, 171
__configure__--disable-build-examples, 174
__configure__--disable-build-tests, 174
__configure__--disable-cpu, 172
__configure__--disable-cuda, 172
__configure__--disable-cuda-memcpy-peer, 172
__configure__--disable-fortran, 173
__configure__--disable-glpk, 174
__configure__--disable-hdf5, 174
__configure__--disable-icc, 171
__configure__--disable-mpi, 173
__configure__--disable-opencl, 172
__configure__--disable-socl, 173
__configure__--disable-starpufft, 174
__configure__--enable-allocation-cache, 173
__configure__--enable-blas-lib, 174
__configure__--enable-blocking-drivers, 172
__configure__--enable-calibration-heuristic, 175
__configure__--enable-cluster, 173
__configure__--enable-coverage, 171
__configure__--enable-debug, 171
__configure__--enable-fast, 171
__configure__--enable-fxt-lock, 173
__configure__--enable-leveldb, 174
__configure__--enable-long-check, 171
__configure__--enable-max-sched-ctxs, 172
__configure__--enable-maxbuffers, 173
__configure__--enable-maxcpu, 172
__configure__--enable-maxcudadev, 172
__configure__--enable-maximplementations, 172
__configure__--enable-maxmichthreads, 173
__configure__--enable-maxnodes, 173
__configure__--enable-maxnumanodes, 172
__configure__--enable-maxopenh264, 172
__configure__--enable-memory-stats, 174
__configure__--enable-model-debug, 173
__configure__--enable-mpi-master-slave, 173
__configure__--enable-mpi-pedantic-ism, 173
__configure__--enable-mpi-verbose, 173
__configure__--enable-new-check, 171
__configure__--enable-nmad, 173
__configure__--enable-opencl-simulator, 172
__configure__--enable-opengl-render, 173
__configure__--enable-openssl, 173
__configure__--enable-openssl-pkg, 173
__configure__--enable-openssl-sse2, 173
__configure__--enable-perf-debug, 173
__configure__--enable-quick-check, 171
__configure__--enable-sc-hypervisor, 174
__configure__--enable-simgrid, 174
__configure__--enable-simgrid-mc, 175
__configure__--enable-spinlock-check, 171
__configure__--enable-starpuft-examples, 174
__configure__--enable-verbose, 171
__configure__--enable-workerr-callbacks, 172
__configure__--mic-host, 173
__configure__--with-atlas-dir, 174
__configure__--with-cc-dir, 173
__configure__--with-cuda-dir, 172
__configure__--with-cuda-include-dir, 172
__configure__--with-cuda-lib-dir, 172
__configure__--with-fxt, 174
__configure__--with-goto-dir, 174
__configure__--with-hwloc, 171
__configure__--with-mkl-cflags, 174
__configure__--with-mkl-ldflags, 174
__configure__--with-mpi-master-slave-multiple-thread, 173
__configure__--with-mpicc, 173
__configure__--with-opencl-dir, 172
__configure__--with-opencl-lib-dir, 172
__configure__--with-perf-model-dir, 174
__configure__--with-simgrid-dir, 174
__configure__--with-simgrid-include-dir, 175
__configure__--with-simgrid-lib-dir, 175
__configure__--with-smpirun, 175
__configure__--without-hwloc, 171
__env__OCL_ICD_VENDORS, 164
__env__SC_HYPERVISOR_LAZY_RESIZE, 169
__env__SC_HYPERVISOR_MAX_SPEED_GAP, 169
__env__SC_HYPERVISOR_POLICY, 169
__env__SC_HYPERVISOR_SAMPLE_CRITERIA, 169
__env__SC_HYPERVISOR_START_RESIZE, 169
__env__SC_HYPERVISOR_STOP_PRINT, 169
__env__SC_HYPERVISOR_TRIGGER_RESIZE, 169
__env__SOCL_OCL_LIB_OPENCL, 164
__env__STARPU_BUS_CALIBRATE, 164
__env__STARPU_BUS_SUMMARY, 164
__env__STARPU_CALIBRATE, 164
__env__STARPU_CALIBRATE_MINIMUM, 164
__env__STARPU_CATCH_SIGNALS, 169
__env__STARPU_COMM_STATS, 164
__env__STARPU_CUDA_PIPELINE, 161
__env__STARPU_CUDA_THREAD_PER_DEV, 161
__env__STARPU_CUDA_THREAD_PER_WORKER, 161
__env__STARPU_DIDUSE_BARRIER, 167
__env__STARPU_DISABLE_ASYNCHRONOUS_COPY, 163
__env__STARPU_DISABLE_ASYNCHRONOUS_CUDA_COPY, 163
__env__STARPU_DISABLE_ASYNCHRONOUS_MIC_COPY, 163
__env__STARPU_DISABLE_ASYNCHRONOUS_MPI_MS_COPY, 163
__env__STARPU_DISABLE_ASYNCHRONOUS_OPENCL_COPY, 163
__env__STARPU_DISABLE_KERNELS, 168
__env__STARPU_DISABLE_PINNING, 163
__env__STARPU_DISK_SWAP, 167
__env__STARPU_DISK_SWAP_BACKEND, 167
__env__STARPU_DISK_SWAP_SIZE, 167
__env__STARPU_ENABLE_CUDA_GPU_GPU_DIRECT, 163
__env__STARPU_ENABLE_STATS, 167
__env__STARPU_FXT_PREFIX, 166
__env__STARPU_FXT_TRACE, 166
__env__STARPU_GENERATE_TRACE, 167
__env__STARPU_GENERATE_TRACE_OPTIONS, 167
__env__STARPU_GLOBAL_ARBITER, 168
__env__STARPU_HISTORY_MAX_ERROR, 168
__env__STARPU_HOME, 165
__env__STARPU_HOSTNAME, 166
__env__STARPU_HWLOC_INPUT, 168
__env__STARPU_IDLE_FILE, 168
__env__STARPU_IDLE_POWER, 164
__env__STARPU_IDLE_TIME, 168
__env__STARPU_LIMIT_CPU_MEM, 166
__env__STARPU_LIMIT_CPU_NUMA_devid_MEM, 167
__env__STARPU_LIMIT_CUDA_MEM, 166
__env__STARPU_LIMIT_CUDA_devid_MEM, 166
__env__STARPU_LIMIT_MAX_SUBMITTED_TASKS, 167
__env__STARPU_LIMIT_MIN_SUBMITTED_TASKS, 167
__env__STARPU_MEMORY_STATS, 167
__env__STARPU_MIC_PROGRAM_PATH, 163
__env__STARPU_MIC_SINK_PROGRAM_PATH, 163
__env__STARPU_MIC_SINK_PROGRAM_NAME, 163
__env__STARPU_MIC_SINK_PROGRAM_NAME, 163
__env__STARPU_MINIMUM_AVAILABLE_MEM, 167
__env__STARPU_MINIMUM_CLEAN_BUFFERS, 167
__env__STARPU_MIN_PRIO, 164
__env__STARPU_MIN_WORKERSIZE, 163
__env__STARPU_MPI_CACHE, 164
__env__STARPU_MPI_CACHE_STATS, 164
__env__STARPU_MPI_COMM, 164
__env__STARPU_MPI_DRIVER_CALL_FREQUENCY, 165
__env__STARPU_MPI_DRIVER_TASK_FREQUENCY, 165
__env__STARPU_MPI_FAKE_RANK, 165
__env__STARPU_MPI_FAKE_SIZE, 165
__env__STARPU_MPI_MASTER_NODE, 162
__env__STARPU_MPI_PRIORITIES, 165
__env__STARPU_MPI_THREAD_CPUID, 162
__env__STARPU_NPCU, 161
__env__STARPU_NCPUS, 161
__env__STARPU_NCUDA, 161
__env__STARPU_NMIC, 162
__env__STARPU_NMICTHREADS, 162
__env__STARPU_NMPISTHREADS, 162
__env__STARPU_NMPI_MS, 162
__env__STARPU_NOPENCL, 161
__env__STARPU_NWORKER_PER_CUDA, 161
__env__STARPU_OPENCL_ONLY_ON_CPUS, 162
__env__STARPU_OPENCL_ON_CPUS, 162
__env__STARPU_OPENCL_PIPELINE, 161
__env__STARPU_OPENCL_PROGRAM_DIR, 166
__env__STARPU_OPENCL_PROGRAM_DIR, 166
__env__STARPU_OPENCL_QUEUE_COST, 165
__env__STARPU_OPENCL_THREAD_CPUID, 165
__env__STARPU_PERF_MODEL_DIR, 166
__env__STARPU_PERF_MODEL_HOMOGENEOUS_CPU, 166
__env__STARPU_PERF_MODEL_HOMOGENEOUS_CUDA, 166
__env__STARPU_PERF_MODEL_HOMOGENEOUS_MIC, 166
__env__STARPU_PERF_MODEL_HOMOGENEOUS_MPI_MS, 166
__env__STARPU_PERF_MODEL_HOMOGENEOUS_OPENCL, 166
__env__STARPU_PREFETCH, 164
__env__STARPU_PROFILING, 164
__env__STARPU_RESERVE_NCPU, 161
__env__STARPU_RAND_SEED, 168
__env__STARPU_SIMGRID_CUDA_MALLOC_COST, 165
__env__STARPU_SIMGRID_CUDA_QUEUE_COST, 165
__env__STARPU_SIMGRID_FETCHING_INPUT_COST, 165
<table>
<thead>
<tr>
<th>Function/Method</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>starpu_data_copy_methods</td>
<td>233</td>
</tr>
<tr>
<td>custom</td>
<td></td>
</tr>
<tr>
<td>sc_hypervisor_policy</td>
<td>401</td>
</tr>
<tr>
<td>data</td>
<td></td>
</tr>
<tr>
<td>starpu_sched_component</td>
<td>422</td>
</tr>
<tr>
<td>Data Interfaces</td>
<td>226</td>
</tr>
<tr>
<td>STARPU_BCSR_GET_COLIND_DEV_HANDLE</td>
<td>246</td>
</tr>
<tr>
<td>STARPU_BCSR_GET_COLIND</td>
<td>246</td>
</tr>
<tr>
<td>STARPU_BCSR_GET_NNZ</td>
<td>246</td>
</tr>
<tr>
<td>STARPU_BCSR_GET_NZVAL_DEV_HANDLE</td>
<td>246</td>
</tr>
<tr>
<td>STARPU_BCSR_GET_NZVAL</td>
<td>246</td>
</tr>
<tr>
<td>STARPU_BCSR_GET_OFFSET</td>
<td>246</td>
</tr>
<tr>
<td>STARPU_BCSR_GET_ROWPTR_DEV_HANDLE</td>
<td>246</td>
</tr>
<tr>
<td>STARPU_BCSR_GET_ROWPTR</td>
<td>246</td>
</tr>
<tr>
<td>STARPU_BLOCK_GET_DEV_HANDLE</td>
<td>242</td>
</tr>
<tr>
<td>STARPU_BLOCK_GET_ELEMSIZE</td>
<td>243</td>
</tr>
<tr>
<td>STARPU_BLOCK_GET_LDY</td>
<td>243</td>
</tr>
<tr>
<td>STARPU_BLOCK_GET_LDZ</td>
<td>243</td>
</tr>
<tr>
<td>STARPU_BLOCK_GET_NX</td>
<td>243</td>
</tr>
<tr>
<td>STARPU_BLOCK_GET_NY</td>
<td>243</td>
</tr>
<tr>
<td>STARPU_BLOCK_GET_NZ</td>
<td>243</td>
</tr>
<tr>
<td>STARPU_BLOCK_GET_OFFSET</td>
<td>243</td>
</tr>
<tr>
<td>STARPU_BLOCK_GET_PTR</td>
<td>242</td>
</tr>
<tr>
<td>STARPU_COO_GET_COLUMNS_DEV_HANDLE</td>
<td>241</td>
</tr>
<tr>
<td>STARPU_COO_GET_COLUMNS</td>
<td>241</td>
</tr>
<tr>
<td>STARPU_COO_GET_ELEMSIZE</td>
<td>242</td>
</tr>
<tr>
<td>STARPU_COO_GET_NVALUES</td>
<td>242</td>
</tr>
<tr>
<td>STARPU_COO_GET_NX</td>
<td>242</td>
</tr>
<tr>
<td>STARPU_COO_GET_NY</td>
<td>242</td>
</tr>
<tr>
<td>STARPU_COO_GET_OFFSET</td>
<td>242</td>
</tr>
<tr>
<td>STARPU_COO_GET_ROWS_DEV_HANDLE</td>
<td>242</td>
</tr>
<tr>
<td>STARPU_COO_GET_ROWS</td>
<td>241</td>
</tr>
<tr>
<td>STARPU_COO_GET_VALUES_DEV_HANDLE</td>
<td>242</td>
</tr>
<tr>
<td>STARPU_COO_GET_VALUES</td>
<td>242</td>
</tr>
<tr>
<td>STARPU_CSR_GET_COLIND_DEV_HANDLE</td>
<td>245</td>
</tr>
<tr>
<td>STARPU_CSR_GET_COLIND</td>
<td>245</td>
</tr>
<tr>
<td>STARPU_CSR_GET_ELEMSIZE</td>
<td>246</td>
</tr>
<tr>
<td>STARPU_CSR_GET_FIRSTENTRY</td>
<td>246</td>
</tr>
<tr>
<td>STARPU_CSR_GET_NNZ</td>
<td>245</td>
</tr>
<tr>
<td>STARPU_CSR_GET_NROW</td>
<td>245</td>
</tr>
<tr>
<td>STARPU_CSR_GET_OFFSET</td>
<td>245</td>
</tr>
<tr>
<td>STARPU_CSR_GET_ROWPTR_DEV_HANDLE</td>
<td>245</td>
</tr>
<tr>
<td>STARPU_CSR_GET_ROWPTR</td>
<td>245</td>
</tr>
<tr>
<td>STARPU_MATRIX_GET_ALLOCSIZE</td>
<td>240</td>
</tr>
<tr>
<td>STARPU_MATRIX_GET_OFFSET</td>
<td>240</td>
</tr>
<tr>
<td>STARPU_MATRIX_GET_PTR</td>
<td>240</td>
</tr>
<tr>
<td>STARPU_MATRIX_GET_NX</td>
<td>241</td>
</tr>
<tr>
<td>STARPU_MATRIX_GET_NY</td>
<td>240</td>
</tr>
<tr>
<td>STARPU_MULTIFORMAT_GET_CPU_PTR</td>
<td>247</td>
</tr>
<tr>
<td>STARPU_MULTIFORMAT_GET_CUDA_PTR</td>
<td>247</td>
</tr>
<tr>
<td>STARPU_MULTIFORMAT_GET_MIC_PTR</td>
<td>247</td>
</tr>
<tr>
<td>STARPU_MULTIFORMAT_GET_OPENCL_PTR</td>
<td>247</td>
</tr>
<tr>
<td>STARPU_VARIABLE_GET_DEV_HANDLE</td>
<td>244</td>
</tr>
<tr>
<td>STARPU_VARIABLE_GET_ELEMENTSIZE</td>
<td>244</td>
</tr>
<tr>
<td>STARPU_VARIABLE_GET_OFFSET</td>
<td>244</td>
</tr>
<tr>
<td>STARPU_VARIABLE_GET_PTR</td>
<td>244</td>
</tr>
<tr>
<td>STARPU_VECTOR_GET_ALLOCSIZE</td>
<td>244</td>
</tr>
<tr>
<td>STARPU_VECTOR_GET_DEV_HANDLE</td>
<td>243</td>
</tr>
<tr>
<td>STARPU_VECTOR_GET_ELEMENTSIZE</td>
<td>243</td>
</tr>
<tr>
<td>STARPU_VECTOR_GET_OFFSET</td>
<td>243</td>
</tr>
<tr>
<td>STARPU_VECTOR_GET_PTR</td>
<td>243</td>
</tr>
<tr>
<td>STARPU_VECTOR_GET_SLICE_BASE</td>
<td>244</td>
</tr>
<tr>
<td>starpu_bcsr_data_register</td>
<td>257</td>
</tr>
<tr>
<td>starpu_bcsr_get_c</td>
<td>259</td>
</tr>
<tr>
<td>starpu_bcsr_get_elementsize</td>
<td>259</td>
</tr>
<tr>
<td>starpu_bcsr_get_firstentry</td>
<td>258</td>
</tr>
<tr>
<td>starpu_bcsr_get_local_colind</td>
<td>258</td>
</tr>
<tr>
<td>starpu_bcsr_get_local_nzval</td>
<td>258</td>
</tr>
<tr>
<td>starpu_bcsr_get_local_rowptr</td>
<td>259</td>
</tr>
<tr>
<td>starpu_bcsr_get_nnz</td>
<td>258</td>
</tr>
<tr>
<td>starpu_bcsr_get_nrow</td>
<td>258</td>
</tr>
<tr>
<td>starpu_bcsr_get_r</td>
<td>259</td>
</tr>
<tr>
<td>starpu_block_data_register</td>
<td>253</td>
</tr>
<tr>
<td>starpu_block_get_elemsize</td>
<td>254</td>
</tr>
<tr>
<td>starpu_block_get_local_ldy</td>
<td>254</td>
</tr>
<tr>
<td>starpu_block_get_local_ldz</td>
<td>254</td>
</tr>
<tr>
<td>starpu_block_get_local_ptr</td>
<td>254</td>
</tr>
<tr>
<td>starpu_block_get_nx</td>
<td>253</td>
</tr>
<tr>
<td>starpu_block_get_ny</td>
<td>254</td>
</tr>
<tr>
<td>starpu_block_get_ptr</td>
<td>253</td>
</tr>
<tr>
<td>starpu_coo_data_register</td>
<td>253</td>
</tr>
<tr>
<td>starpu_data_copy_methods</td>
<td>233</td>
</tr>
<tr>
<td>starpu_data_get_alloc_size</td>
<td>249</td>
</tr>
<tr>
<td>starpu_data_get_interface_id</td>
<td>249</td>
</tr>
<tr>
<td>starpu_data_get_interface_on_node</td>
<td>249</td>
</tr>
<tr>
<td>starpu_data_get_local_ptr</td>
<td>249</td>
</tr>
<tr>
<td>starpu_data_get_size</td>
<td>249</td>
</tr>
</tbody>
</table>
starpu_data_partition_readwrite_upgrade_submit, 265
starpu_data_partition_submit, 265
starpu_data_partition_submit_sequential_consistency, 266
starpu_data_unpartition, 263
starpu_data_unpartition_readonly_submit, 265
starpu_data_unpartition_submit, 265
starpu_data_unpartition_submit_sequential_consistency, 266
starpu_data_unpartition_submit_sequential_consistency_cb, 266
starpu_data_vget_sub_data, 264
starpu_data_vmap_filters, 264
starpu_filter_nparts_compute_chunk_size_and_offset, 270
starpu_matrix_filter_block, 267
starpu_matrix_filter_block_shadow, 267
starpu_matrix_filter_vertical_block, 267
starpu_matrix_filter_vertical_block_shadow, 268
starpu_vector_filter_block, 268
starpu_vector_filter_block_shadow, 268
starpu_vector_filter_divide_in_2, 269
starpu_vector_filter_list, 268
starpu_vector_filter_list_long, 268
deinit
starpu_worker_collection, 210
deinit_data
starpu_sched_component, 423
deinit_sched
starpu_sched_policy, 392
describe
starpu_data_interface_ops, 236
destroy
starpu_task, 285
detach
starpu_task, 285
disable_asynchronous_copy
starpu_conf, 185
disable_asynchronous_cuda_copy
starpu_conf, 185
disable_asynchronous_mic_copy
starpu_conf, 185
disable_asynchronous_mpi_ms_copy
starpu_conf, 186
disable_asynchronous_opencl_copy
starpu_conf, 185
display
starpu_data_interface_ops, 236
do_schedule
starpu_sched_policy, 393
dontcache
starpu_data_interface_ops, 237
dyn_handles
starpu_task, 282
dyn_interfaces
starpu_task, 282
dyn_modes
starpu_codelet, 279
starpu_task, 282
dyn_nodes
starpu_codelet, 279
e_starpm_drs_ret
Interoperability Support, 436
end_ctx
sc_hypervisor_policy, 402, 411
energy_model
starpu_codelet, 280
estimated_end
starpu_sched_component, 423
estimated_load
starpu_sched_component, 423
execute_on_a_specific_worker
starpu_task, 285
Expert Mode, 382
starpu_progression_hook_deregister, 383
starpu_progression_hook_register, 382
starpu_wake_all_blocked_workers, 382
Explicit Dependencies, 302
starpu_tag_declare_deps, 305
starpu_tag_declare_deps_array, 305
starpu_tag_notify_from_apps, 306
starpu_tag_remove, 306
starpu_tag_restart, 306
starpu_tag_t, 303
starpu_tag_wait, 305
starpu_tag_wait_array, 305
starpu_task_declare_deps, 303
starpu_task_declare_deps_array, 303
starpu_task_execute, 303
starpu_taskExecute_end_deps, 304
starpu_taskExecute_end_deps_array, 304
starpu_taskExecute_end_dep_add, 304
starpu_taskExecute_end_dep_release, 305
starpu_task_execute_get_task_scheduled_succecess, 304
starpu_tag_wait_array, 305
starpu_tag_wait_array, 305
FFT Support, 358
starpufft_cleanup, 359
starpufft_destroy_plan, 360
starpufft_execute, 359
starpufft_execute_handle, 359
starpufft_free, 358
starpufft_malloc, 358
starpufft_plan_dft_1d, 359
starpufft_plan_dft_2d, 359
starpufft_start, 359
starpufft_start_handle, 359
filter_arg
starpu_data_filter, 263
filter_arg_ptr
starpu_data_filter, 263
filter_func
starpu_data_filter, 262
flags
starpu_codelet, 282
flops
<table>
<thead>
<tr>
<th>Function Name</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>starpu_mpi_isend_detached_prio</td>
<td>367</td>
</tr>
<tr>
<td>starpu_mpi_isend_detached_unlock_tag</td>
<td>369</td>
</tr>
<tr>
<td>starpu_mpi_isend_detached_unlock_tag_prio</td>
<td>369</td>
</tr>
<tr>
<td>starpu_mpi_isend_prio</td>
<td>366</td>
</tr>
<tr>
<td>starpu_mpi_issend</td>
<td>368</td>
</tr>
<tr>
<td>starpu_mpi_issend_detached</td>
<td>368</td>
</tr>
<tr>
<td>starpu_mpi_issend_detached_prio</td>
<td>369</td>
</tr>
<tr>
<td>starpu_mpi_node_selection_get_current_policy</td>
<td>374</td>
</tr>
<tr>
<td>starpu_mpi_node_selection_register_policy</td>
<td>374</td>
</tr>
<tr>
<td>starpu_mpi_node_selection_set_current_policy</td>
<td>374</td>
</tr>
<tr>
<td>starpu_mpi_node_selection_unregister_policy</td>
<td>374</td>
</tr>
<tr>
<td>starpu_mpi_recv</td>
<td>367</td>
</tr>
<tr>
<td>starpu_mpi_redux_data</td>
<td>375</td>
</tr>
<tr>
<td>starpu_mpi_redux_data_prio</td>
<td>375</td>
</tr>
<tr>
<td>starpu_mpi_req</td>
<td>364</td>
</tr>
<tr>
<td>starpu_mpi_scatter_detached</td>
<td>375</td>
</tr>
<tr>
<td>starpu_mpi_send</td>
<td>366</td>
</tr>
<tr>
<td>starpu_mpi_send_prio</td>
<td>367</td>
</tr>
<tr>
<td>starpu_mpi_shutdown</td>
<td>365</td>
</tr>
<tr>
<td>starpu_mpi_tag_t</td>
<td>364</td>
</tr>
<tr>
<td>starpu_mpi_task_build</td>
<td>373</td>
</tr>
<tr>
<td>starpu_mpi_task_insert</td>
<td>372</td>
</tr>
<tr>
<td>starpu_mpi_task_post_build</td>
<td>373</td>
</tr>
<tr>
<td>starpu_mpi_test</td>
<td>369</td>
</tr>
<tr>
<td>starpu_mpi_wait</td>
<td>369</td>
</tr>
<tr>
<td>starpu_mpi_wait_for_all</td>
<td>369</td>
</tr>
<tr>
<td>starpu_mpi_world_rank</td>
<td>365</td>
</tr>
<tr>
<td>starpu_mpi_world_size</td>
<td>366</td>
</tr>
<tr>
<td>magic</td>
<td>183</td>
</tr>
<tr>
<td>starpu_conf</td>
<td>286</td>
</tr>
<tr>
<td>max_parallelism</td>
<td>286</td>
</tr>
<tr>
<td>starpu_codelet</td>
<td>277</td>
</tr>
<tr>
<td>mf_skip</td>
<td>285</td>
</tr>
<tr>
<td>mic_funcs</td>
<td>278</td>
</tr>
<tr>
<td>mic_sink_program_path</td>
<td>185</td>
</tr>
<tr>
<td>mic_to_ram</td>
<td>232</td>
</tr>
<tr>
<td>starpu_data_copy_methods</td>
<td>234</td>
</tr>
<tr>
<td>Miscellaneous Helpers, 354</td>
<td>354</td>
</tr>
<tr>
<td>STARPU_MAX</td>
<td>354</td>
</tr>
<tr>
<td>STARPU_MIN</td>
<td>354</td>
</tr>
<tr>
<td>STARPU_POISON_PTR</td>
<td>355</td>
</tr>
<tr>
<td>starpu_data_cpy</td>
<td>356</td>
</tr>
<tr>
<td>starpu_execute_on_each_worker</td>
<td>355</td>
</tr>
<tr>
<td>starpu_execute_on_each_worker_ex</td>
<td>355</td>
</tr>
<tr>
<td>starpu_execute_on_specific_workers</td>
<td>355</td>
</tr>
<tr>
<td>starpu_get_env_number</td>
<td>355</td>
</tr>
<tr>
<td>starpu_timing_now</td>
<td>355</td>
</tr>
<tr>
<td>mix_heterogeneous_workers</td>
<td>355</td>
</tr>
<tr>
<td>starpu_sched_component_specs</td>
<td>425</td>
</tr>
<tr>
<td>model</td>
<td>279</td>
</tr>
<tr>
<td>modes</td>
<td>279</td>
</tr>
<tr>
<td>starpu_task</td>
<td>282</td>
</tr>
<tr>
<td>Modularized Scheduler Interface, 418</td>
<td>426</td>
</tr>
<tr>
<td>STARPU_SCHED_COMPONENT_IS_HOMOGENEOUS</td>
<td>426</td>
</tr>
<tr>
<td>STARPU_SCHED_COMPONENT_IS_SINGLE_MEMORY_NODE</td>
<td>426</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_COMBINED_WORKERS, 427</td>
<td>426</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_DECIDE_ARCHS, 426</td>
<td>426</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_DECIDE_MEMORY_NODE, 426</td>
<td>426</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_FIFO_ABOVE_PRIORIO, 426</td>
<td>427</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_FIFO_ABOVE_FIFO BELOW PRIORIO, 426</td>
<td>427</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_FIFO BELOW FIFO, 426</td>
<td>427</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_FIFOS BELOW_FIFO, 426</td>
<td>427</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_PERFMODEL, 426</td>
<td>427</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_WS BELOW_FIFO, 427</td>
<td>427</td>
</tr>
<tr>
<td>starpu_sched_component_best_implementation_create, 432</td>
<td>432</td>
</tr>
<tr>
<td>starpu_sched_component_can_execute_task, 429</td>
<td>430</td>
</tr>
<tr>
<td>starpu_sched_component_can_pull, 430</td>
<td>430</td>
</tr>
<tr>
<td>starpu_sched_component_can_pull_all, 431</td>
<td>431</td>
</tr>
<tr>
<td>starpu_sched_component_can_push, 430</td>
<td>431</td>
</tr>
<tr>
<td>starpu_sched_component_composed_component_create, 433</td>
<td>433</td>
</tr>
<tr>
<td>starpu_sched_component_composed_recipe_add, 433</td>
<td>433</td>
</tr>
<tr>
<td>starpu_sched_component_composed_recipe_create, 432</td>
<td>432</td>
</tr>
<tr>
<td>starpu_sched_component_composed_recipe_create_singleton, 432</td>
<td>432</td>
</tr>
<tr>
<td>starpu_sched_component_composed_recipe_destroy, 433</td>
<td>433</td>
</tr>
<tr>
<td>starpu_sched_component_connect, 428</td>
<td>428</td>
</tr>
<tr>
<td>starpu_sched_component_create, 428</td>
<td>428</td>
</tr>
<tr>
<td>starpu_sched_component_destroy, 429</td>
<td>429</td>
</tr>
<tr>
<td>starpu_sched_component_destroy_rec, 429</td>
<td>430</td>
</tr>
<tr>
<td>starpu_sched_component_estimated_end_average, 431</td>
<td>431</td>
</tr>
<tr>
<td>starpu_sched_component_estimated_end_min, 431</td>
<td>431</td>
</tr>
<tr>
<td>starpu_sched_component_estimated_end_min_add, 431</td>
<td>431</td>
</tr>
<tr>
<td>starpu_sched_component_estimated_load, 431</td>
<td>431</td>
</tr>
<tr>
<td>starpu_sched_component_execute_preds, 429</td>
<td>429</td>
</tr>
<tr>
<td>starpu_sched_component_fifo_create, 431</td>
<td>431</td>
</tr>
</tbody>
</table>
| starpu_sched_component_initialize_simple
scheduler, 433
starpu_sched_component_is_combined_worker, 430
starpu_sched_component_is_fifo, 431
starpu_sched_component_is_random, 432
starpu_sched_component_is_simple_worker, 430
starpu_sched_component_is_work_stealing, 432
starpu_sched_component_is_worker, 430
starpu_sched_component_make_scheduler, 433
starpu_sched_component_mct_create, 432
starpu_sched_component_parallel_worker_create, 429
starpu_sched_component_properties, 427
starpu_sched_component_pull_task, 428
starpu_sched_component_push_task, 428
starpu_sched_component_random_create, 432
starpu_sched_component_transfer_length, 429
starpu_sched_component_work_stealing_create, 431
starpu_sched_component_worker_get, 429
starpu_sched_component_worker_get_workerid, 430
starpu_sched_component_worker_post_exec__hook, 430
starpu_sched_component_worker_pre_exec__hook, 430
starpu_sched_tree_add_workers, 428
starpu_sched_tree_create, 427
starpu_sched_tree_destroy, 427
starpu_sched_tree_pop_task, 428
starpu_sched_tree_push_task, 428
starpu_sched_tree_remove_workers, 428
starpu_sched_tree_update_workers, 427
starpu_sched_tree_update_workers_in_ctx, 427
starpu_sched_tree_work_stealing_push_task, 432
mpi_ms_funcs
starpu_codelet, 278
mpi_ms_to_mpi_ms
starpu_data_copy_methods, 232
mpi_ms_to_mpi_ms_async
starpu_data_copy_methods, 234
mpi_ms_to_ram
starpu_data_copy_methods, 232
mpi_ms_to_ram_async
starpu_data_copy_methods, 234
n__cuda_opengl__interoperability
starpu_conf, 186
n_not_launched_drivers
starpu_conf, 186
name
sc_hypervisor_policy, 401, 410
starpu_codelet, 280
starpu_data_interface_ops, 237
starpu_task, 281
nb_termination_call_required
starpu_task, 287
nbuffers
starpu_codelet, 279
starpu_task, 282
nchildren
starpu_data_filter, 262
starpu_sched_component, 422
ncombinations
starpu_perfmcrease, 311
ncpus
starpu_conf, 183
ncuda
starpu_conf, 183
next
starpu_task, 287
nmic
starpu_conf, 184
nmpl_ms
starpu_conf, 184
no_subm_border
starpu_task, 285
nodes
starpu_codelet, 279
nopenc
starpu_conf, 183
not_launched_drivers
starpu_conf, 186
notify_change_workers
starpu_sched_component, 424
nparameters
starpu_perfmcrease, 311
nparents
starpu_sched_component, 422
nworkers
starpu_worker_collection, 210
obj
starpu_sched_component, 424
omp_task
starpu_task, 287
open
starpu_disk_ops, 272
OpenCL Extensions, 323
STARPU_MAXOPENCLDEVS, 324
STARPU_OPENCL_DATADIR, 324
STARPU_OPENCL_DISPLAY_ERROR, 324
STARPU_OPENCL_REPORT_ERROR_WITH_MSG, 325
STARPU_OPENCL_REPORT_ERROR, 324
STARPU_USE_OPENCL, 324
starpu_opencl_allocate_memory, 328
starpu_opencl_collect_stats, 327
starpu_opencl_compile_opencl_from_file, 326
starpu_opencl_compile_opencl_from_string, 326
starpu_opencl_copy_async_sync, 329
starpu_opencl_copy_opencl_to_opencl, 329
starpu_opencl_copy_ram_to_opencl, 328
starpu_opencl_display_error, 328
starpu_opencl_error_string, 327
starpu_opencl_get_context, 325
starpu_opencl_get_current_context, 325
starpu_opengl_get_current_queue, 325
starpu_opengl_get_device, 325
starpu_opengl_get_queue, 325
starpu_opengl_load_binary_opencl, 326
starpu_opengl_load_kernel, 327
starpu_opengl_load_opengl_from_file, 327
starpu_opengl_load_opengl_from_string, 327
starpu_opengl_load_program_source, 326
starpu_opengl_release_kernel, 327
starpu_opengl_report_error, 328
starpu_opengl_set_kernel_args, 325
starpu_openglUnload_opengl, 327

OpenMP Runtime Support, 329
STARPU_OPENMP, 334
starpu_omp_atomic_fallback_inline_begin, 352
starpu_omp_atomic_fallback_inline_end, 352
starpu_omp_barrier, 336
starpu_omp_critical, 336
starpu_omp_critical_inline_begin, 336
starpu_omp_critical_inline_end, 336
starpu_omp_destroy_lock, 349
starpu_omp_destroy_nest_lock, 350
starpu_omp_for, 338
starpu_omp_for_alt, 339
starpu_omp_for_inital, 338
starpu_omp_for_inital1, 339
starpu_omp_for_inital2, 339
starpu_omp_for_inital3, 340
starpu_omp_get_active_level, 347
starpu_omp_get_ancestor_thread_num, 346
starpu_omp_get_cancellation, 345
starpu_omp_get_default_device, 348
starpu_omp_get_num_devices, 348
starpu_omp_get_num_procs, 343
starpu_omp_get_num_teams, 348
starpu_omp_get_num_threads, 342
starpu_omp_get_proc_bind, 347
starpu_omp_get_schedule, 345
starpu_omp_get_team_num, 348
starpu_omp_get_team_size, 347
starpu_omp_get_thread_limit, 345
starpu_omp_get_thread_num, 343
starpu_omp_get_rwlock, 352
starpu_omp_get_wtime, 352
starpu_omp_in_final, 347
starpu_omp_in_parallel, 343
starpu_omp_init, 335
starpu_omp_init_lock, 349
starpu_omp_init_nest_lock, 350
starpu_omp_is_initial_device, 349
starpu_omp_master, 335
starpu_omp_master_inline, 336
starpu_omp_ordered, 340
starpu_omp_ordered_inital, 340
starpu_omp_ordered_inital1, 340
starpu_omp_ordered_inital2, 340
starpu_omp_ordered_inital3, 340
starpu_omp_parallel_region, 335
starpu_omp_proc_bind_value, 335
starpu_omp_sched_value, 334
starpu_omp_sections, 341
starpu_omp_sections_combined, 341
starpu_omp_set_default_device, 347
starpu_omp_set_dynamic, 344
starpu_omp_set_lock, 349
starpu_omp_set_max_active_levels, 346
starpu_omp_set_nest_lock, 351
starpu_omp_set_nested, 344
starpu_omp_set_num_threads, 342
starpu_omp_set_schedule, 345
starpu_omp_shutdown, 335
starpu_omp_single, 336
starpu_omp_single_copyprivate, 337
starpu_omp_single_copyprivate_inital, 337
starpu_omp_single_copyprivate_inital1, 337
starpu_omp_single_inital, 337
starpu_omp_task_region, 341
starpu_omp_taskgroup, 341
starpu_omp_taskgroup_inital, 342
starpu_omp_taskgroup_inital1, 342
starpu_omp_taskwait, 341
starpu_omp_test_lock, 350
starpu_omp_test_nest_lock, 351
starpu_omp_unset_lock, 350
starpu_omp_unset_nest_lock, 351
starpu_omp_vector_annotate, 352

opencl_flags
starpu_codelet, 278
opencl_func
starpu_codelet, 278
openclfuncs
starpu_codelet, 278
opencl_to CUDA
starpu_data_copy_methods, 232
opencl_to opencl
starpu_data_copy_methods, 232
opencl_to opencl async
starpu_data_copy_methods, 232
opencl_to ram
starpu_data_copy_methods, 232
opencl_to ram async
starpu_data_copy_methods, 232

Out Of Core, 270
STARPU_DISK_SIZE_MIN, 273
starpu_disk_close, 273
starpu_disk_hdf5_ops, 274
starpu_disk_leveldb_ops, 274
starpu_disk_open, 273
starpu_disk_register, 273
starpu_disk_stdio_ops, 274
starpu_disk_swap_node, 274

Generated by Doxygen
starpu_disk_unistd_o_direct_ops, 274
starpu_disk_unistd_ops, 274

pack_data
starpu_data_interface_ops, 237

Parallel Tasks, 379
starpu_combined_worker_assign_workerid, 380
starpu_combined_worker_can_execute_task, 380
starpu_combined_worker_get_count, 380
starpu_combined_worker_get_description, 380
starpu_combined_worker_get_id, 380
starpu_combined_worker_get_rank, 380
starpu_combined_worker_get_size, 380
starpu_parallel_task_barrier_init, 380
starpu_parallel_task_barrier_init_n, 381

parameters_names
starpu_perfmodel, 311

parents
starpu_sched_component, 423

per_worker_stats
starpu_codelet, 280

Performance Model, 306
starpu_bus_print_affinity, 314
starpu_bus_print_bandwidth, 314
starpu_bus_print_filenames, 314
starpu_perfmodel_debugfilepath, 313
starpu_perfmodel_directory, 314
starpu_perfmodel_dump_xml, 312
starpu_perfmodel_free_sampling_directories, 313
starpu_perfmodel_get_arch_name, 313
starpu_perfmodel_history_based_expected_perf, 313
starpu_perfmodel_init, 312
starpu_perfmodel_list, 313
starpu_perfmodel_nop, 315
starpu_perfmodel_type, 311
starpu_perfmodel_unload_model, 312
starpu_perfmodel_update_history, 313
starpu_transfer_bandwidth, 314
starpu_transfer_latency, 314
starpu_transfer_predict, 314

plug
starpu_disk_ops, 271

pointer_is_inside
starpu_data_interface_ops, 236

policy_description
starpu_sched_policy, 394

policy_name
starpu_sched_policy, 393

pop_every_task
starpu_sched_policy, 393

pop_task
starpu_sched_policy, 393

possibly_parallel
starpu_task, 287

post_exec_hook
starpu_sched_policy, 393

pre_exec_hook
starpu_sched_policy, 393

predicted
starpu_task, 287

predicted_transfer
starpu_task, 287

prev
starpu_task, 287

priority
starpu_task, 286

Profiling, 315
STARPU_PROFILING_DISABLE, 317
STARPU_PROFILING_ENABLE, 317
starpu_bus_get_count, 318
starpu_bus_get_dst, 318
starpu_bus_get_id, 318
starpu_bus_get_profiling_info, 318
starpu_bus_get_src, 318
starpu_data_display_memory_stats, 319
starpu_profiling_bus_helper_display_summary, 318
starpu_profiling_init, 317
starpu_profiling_set_id, 317
starpu_profiling_status_get, 317
starpu_profiling_status_set, 317
starpu_profiling_worker_get_info, 318
starpu_profiling_worker_helper_display_summary, 319
starpu_timing_timespec_delay_us, 318
starpu_timing_timespec_to_us, 318

profiling_info
starpu_task, 287

prologue_callback_arg
starpu_task, 284

prologue_callback_arg_free
starpu_task, 284

prologue_callback_func
starpu_task, 283

prologue_callback_pop_arg_free
starpu_task, 284

pull_task
starpu_sched_component, 423

push_task
starpu_sched_component, 423

push_task_notify
starpu_sched_policy, 393

ram_to_cuda
starpu_data_copy_methods, 231

ram_to_cuda_async
starpu_data_copy_methods, 233

ram_to_mic
starpu_data_copy_methods, 231

ram_to_mic_async
starpu_data_copy_methods, 234
INDEX

ram_to_mpi_ms
  starpu_data_copy_methods, 232
ram_to_mpi_ms_async
  starpu_data_copy_methods, 233
ram_to_opencl
  starpu_data_copy_methods, 231
ram_to_opencl_async
  starpu_data_copy_methods, 233
ram_to_ram
  starpu_data_copy_methods, 231
read
  starpu_disk_ops, 272
regenerate
  starpu_task, 285
register_data_handle
  starpu_data_interface_ops, 235
regression
  starpu_perfmodel_per_arch, 310
remove
  starpu_worker_collection, 210
remove_child
  starpu_sched_component, 423
remove_workers
  starpu_sched_policy, 393
reserve_ncpus
  starpu_conf, 183
resize_ctxs
  sc_hypervisor_policy, 401, 411
Running Drivers, 381
  starpu_driver_deinit, 382
  starpu_driver_init, 382
  starpu_driver_run, 381
  starpu_driver_run_once, 382
  starpu_drivers_request_termination, 382
SC_HYPERVISOR_FIXED_WORKERS
  Scheduling Context Hypervisor - Building a new resizing policy, 403
SC_HYPERVISOR_GRANULARITY
  Scheduling Context Hypervisor - Building a new resizing policy, 403
SC_HYPERVISOR_ISPEED_CTX_SAMPLE
  Scheduling Context Hypervisor - Building a new resizing policy, 404
SC_HYPERVISOR_ISPEED_W_SAMPLE
  Scheduling Context Hypervisor - Building a new resizing policy, 404
SC_HYPERVISOR_MAX_IDLE
  Scheduling Context Hypervisor - Building a new resizing policy, 403
SC_HYPERVISOR_MAX-workers
  Scheduling Context Hypervisor - Building a new resizing policy, 403
SC_HYPERVISOR_MIN_TASKS
  Scheduling Context Hypervisor - Building a new resizing policy, 403
SC_HYPERVISOR_MIN_WORKERS
  Scheduling Context Hypervisor - Building a new resizing policy, 403
SC_HYPERVISOR_NEW_WORKERS_MAX_IDLE
  Scheduling Context Hypervisor - Building a new resizing policy, 404
SC_HYPERVISOR_NULL
  Scheduling Context Hypervisor - Building a new resizing policy, 404
SC_HYPERVISOR_PRIORITY
  Scheduling Context Hypervisor - Building a new resizing policy, 403
SC_HYPERVISOR_TIME_TO.Apply
  Scheduling Context Hypervisor - Building a new resizing policy, 404
STARPU_ABORT_MSG
  Toolbox, 195
STARPU_ABORT
  Toolbox, 195
STARPU_ACQUIRE_NO_NODE_LOCK_ALL
  Data Management, 218
STARPU_ACQUIRE_NO_NODE
  Data Management, 218
STARPU_ASSERT_MSG
  Toolbox, 194
STARPU_ASSERT
  Toolbox, 194
STARPU_ATTRIBUTEAligned
  Toolbox, 194
STARPU_ATTRIBUTE.Internal
  Toolbox, 194
STARPU_ATTRIBUTE.MALLOC
  Toolbox, 194
STARPU_ATTRIBUTE.NORETURN
  Toolbox, 194
STARPU_ATTRIBUTE.PURE
  Toolbox, 194
STARPU_ATTRIBUTE.UNUSED
  Toolbox, 194
STARPU_ATTRIBUTE.WARN UNUSED RESULT
  Toolbox, 194
STARPU_BCSR_GET_COLIND_DEV_HANDLE
  Data Interfaces, 246
STARPU_BCSR_GET_COLIND
  Data Interfaces, 246
STARPU_BCSR_GET_NNZ
  Data Interfaces, 246
STARPU_BCSR_GET_NZVAL_DEV_HANDLE
  Data Interfaces, 246
STARPU_BCSR_GET_NZVAL
  Data Interfaces, 246
STARPU_BCSR_GET_OFFSET
  Data Interfaces, 247
STARPU_BLOCKS_GET_OFFSET
  Data Interfaces, 247
STARPU_BCSR_GET_ROWPTR_DEV_HANDLE
  Data Interfaces, 246
STARPU_BCSR_GET_ROWPTR
  Data Interfaces, 246
STARPU_BLOCK_GET_DEV_HANDLE
  Data Interfaces, 242
STARPU_BLOCK_GET_ELEM_SIZE
  Data Interfaces, 243

Generated by Doxygen
INDEX 533

STARPU_BLOCK_GET_LDY
  Data Interfaces, 243
STARPU_BLOCK_GET_LDZ
  Data Interfaces, 243
STARPU_BLOCK_GET_NX
  Data Interfaces, 243
STARPU_BLOCK_GET_NY
  Data Interfaces, 243
STARPU_BLOCK_GET_NZ
  Data Interfaces, 243
STARPU_BLOCK_GET_OFFSET
  Data Interfaces, 243
STARPU_BLOCK_GET_PTR
  Data Interfaces, 242
STARPU_CALLBACK_ARG
  Task Insert Utility, 298
STARPU_CALLBACK_WITH_ARG
  Task Insert Utility, 298
STARPU_CALLBACK
  Task Insert Utility, 298
STARPU_CL_ARGS_NFREE
  Task Insert Utility, 299
STARPU_CL_ARGS
  Task Insert Utility, 299
STARPU_CODELET_GET_MODE
  Codelet And Tasks, 290
STARPU_CODELET_GET_NODE
  Codelet And Tasks, 291
STARPU_CODELET_NOPLANs
  Codelet And Tasks, 288
STARPU_CODELET_SET_MODE
  Codelet And Tasks, 290
STARPU_CODELET_SET_NODE
  Codelet And Tasks, 291
STARPU_CODELET_SIMGRID_EXECUTE_AND_INJECT
  Codelet And Tasks, 288
STARPU_CODELET_SIMGRID_EXECUTE
  Codelet And Tasks, 288
STARPU_COO_GET_COLUMNS_DEV_HANDLE
  Data Interfaces, 241
STARPU_COO_GET_COLUMNS
  Data Interfaces, 241
STARPU_COO_GET_ELEMSIZE
  Data Interfaces, 242
STARPU_COO_GET_NVALUES
  Data Interfaces, 242
STARPU_COO_GET_NX
  Data Interfaces, 242
STARPU_COO_GET_NY
  Data Interfaces, 242
STARPU_COO_GET_OFFSET
  Data Interfaces, 242
STARPU_COO_GET_ROWS
  Data Interfaces, 242
STARPU_COO_GET_ROWS_DEV_HANDLE
  Data Interfaces, 242
STARPU_COO_GET_VALUES_DEV_HANDLE
  Data Interfaces, 242
STARPU_COO_GET_VALUES
  Data Interfaces, 242
STARPU_CPU
  Codelet And Tasks, 288
STARPU_CSR_GET_COLIND_DEV_HANDLE
  Data Interfaces, 245
STARPU_CSR_GET_COLIND
  Data Interfaces, 245
STARPU_CSR_GET_ELEMSIZE
  Data Interfaces, 245
STARPU_CSR_GET_FIRSTENTRY
  Data Interfaces, 246
STARPU_CSR_GET_NNZ
  Data Interfaces, 245
STARPU_CSR_GET_NROW
  Data Interfaces, 245
STARPU_CSR_GET_NZVALUES_DEV_HANDLE
  Data Interfaces, 245
STARPU_CSR_GET_NVALUES
  Data Interfaces, 245
STARPU_CSR_GET_OFFSET
  Data Interfaces, 245
STARPU_CSR_GET_ROWPTR_DEV_HANDLE
  Data Interfaces, 245
STARPU_CSR_GET_ROWPTR
  Data Interfaces, 245
STARPU_CUBLAS_REPORT_ERROR
  CUDA Extensions, 321
STARPU_CUDA_ASYNC
  Codelet And Tasks, 289
STARPU_CUDA_REPORT_ERROR
  CUDA Extensions, 321
STARPU_CUDA
  Codelet And Tasks, 288
STARPU_DATA_ACQUIRE_CB
  Data Management, 218
STARPU_DEFAULT_PRIO
  Scheduling Contexts, 386
STARPU_DISK_SIZE_MIN
  Out Of Core, 273
STARPU_EXECUTE_ON_DATA
  MPI Support, 363
STARPU_EXECUTE_ON_NODE
  MPI Support, 363
STARPU_EXECUTE_ON_WORKER
  Task Insert Utility, 298
STARPU_FLOPS
  Task Insert Utility, 298
STARPU_GNUC_PREREQ
  Toolbox, 193
STARPU_HANDLES_SEQUENTIAL_CONSISTENCY

Generated by Doxygen
Task Insert Utility, 299
STARPU_LIKELY
Toolbox, 194
STARPU_MAIN_RAM
Codelet And Tasks, 289
STARPU_MAJOR_VERSION
Versioning, 181
STARPU_MALLOC_COUNT
Standard Memory Library, 189
STARPU_MALLOC_NORECLAIM
Standard Memory Library, 189
STARPU_MALLOC_PINNED
Standard Memory Library, 189
STARPU_MALLOC_SIMULATION_FOLDED
Standard Memory Library, 190
STARPU_MATRIX_GET_ALLOCSIZE
Data Interfaces, 241
STARPU_MATRIX_GET_DEV_HANDLE
Data Interfaces, 240
STARPU_MATRIX_GET_ELEM_SIZE
Data Interfaces, 241
STARPU_MATRIX_GET_LD
Data Interfaces, 241
STARPU_MATRIX_GET_NX
Data Interfaces, 240
STARPU_MATRIX_GET_NY
Data Interfaces, 240
STARPU_MATRIX_GET_OFFSET
Data Interfaces, 240
STARPU_MATRIX_SET_PTR
Data Interfaces, 240
STARPU_MATRIX_SET_LD
Data Interfaces, 241
STARPU_MATRIX_SET_NX
Data Interfaces, 241
STARPU_MATRIX_SET_NY
Data Interfaces, 241
STARPU_MAX_PRIO
Scheduling Contexts, 385
STARPU_MIN_PRIO
Scheduling Contexts, 385
STARPU_MINOR_VERSION
Versioning, 181
STARPU_MIC
Codelet And Tasks, 288
STARPU_MIN
Miscellaneous Helpers, 354
STARPU_MPI_MS
Codelet And Tasks, 288
STARPU_MPI_PER_NODE
MPI Support, 363
STARPU_MPI_TAG_UB
MPI Support, 363
STARPU_MULTIFORMAT_GET_CPU_PTR
Data Interfaces, 247
STARPU_MULTIFORMAT_GET_CUDA_PTR
Data Interfaces, 247
STARPU_MULTIFORMAT_GET_MIC_PTR
Data Interfaces, 247
STARPU_MULTIFORMAT_GET_NX
Data Interfaces, 247
STARPU_MULTIFORMAT_GET_OPENCL_PTR
Data Interfaces, 247
STARPU_MULTIPLE_CPU_IMPLEMENTATIONS
Codelet And Tasks, 289
STARPU_MULTIPLE_CUDA_IMPLEMENTATIONS
Codelet And Tasks, 289
STARPU_MULTIPLE_OPENCL_IMPLEMENTATIONS
Codelet And Tasks, 289
STARPU_NAME
Task Insert Utility, 299
STARPU_NMAX_SCHED_CTXS
Scheduling Policy, 394
STARPU_NMAXBUFS
Codelet And Tasks, 288
STARPU_NMAXWORKERS
Workers’ Properties, 210
STARPU_NODE_SELECTION_POLICY
MPI Support, 363
STARPU_NOWHERE
Codelet And Tasks, 288
STARPU_OPENCL_ASYNC
Codelet And Tasks, 289
STARPU_OPENCL_DATADIR
OpenCL Extensions, 324
STARPU_OPENCL_DISPLAY_ERROR
OpenCL Extensions, 324
STARPU_OPENCL_REPORT_ERROR_WITH_MSG
OpenCL Extensions, 325
STARPU_OPENCL_REPORT_ERROR
OpenCL Extensions, 324
STARPU_OPENCL
Codelet And Tasks, 288
STARPU_OPENMPP
OpenMP Runtime Support, 334
STARPU_POISON_PTR
Miscellaneous Helpers, 355
STARPU_PRIORITY

<table>
<thead>
<tr>
<th>Task Insert Utility</th>
<th>298</th>
</tr>
</thead>
<tbody>
<tr>
<td>STARPU_PROFILING_DISABLE</td>
<td>Profiling, 317</td>
</tr>
<tr>
<td>STARPU_PROFILING_ENABLE</td>
<td>Profiling, 317</td>
</tr>
<tr>
<td>STARPU_PTHREAD_BARRIER_DESTROY</td>
<td>Threads, 199</td>
</tr>
<tr>
<td>STARPU_PTHREAD_BARRIER_INIT</td>
<td>Threads, 199</td>
</tr>
<tr>
<td>STARPU_PTHREAD_BARRIER_WAIT</td>
<td>Threads, 199</td>
</tr>
<tr>
<td>STARPU_PTHREAD_COND.Broadcast</td>
<td>Threads, 199</td>
</tr>
<tr>
<td>STARPU_PTHREAD_COND_DESTROY</td>
<td>Threads, 199</td>
</tr>
<tr>
<td>STARPU_PTHREAD_COND_INITIALIZER</td>
<td>Threads, 200</td>
</tr>
<tr>
<td>STARPU_PTHREAD_COND_INIT</td>
<td>Threads, 199</td>
</tr>
<tr>
<td>STARPU_PTHREAD_COND_SIGNAL</td>
<td>Threads, 199</td>
</tr>
<tr>
<td>STARPU_PTHREAD_COND_WAIT</td>
<td>Threads, 199</td>
</tr>
<tr>
<td>STARPU_PTHREAD_CREATE &amp;</td>
<td>Threads, 197</td>
</tr>
<tr>
<td>STARPU_PTHREAD_CREATE</td>
<td>Threads, 197</td>
</tr>
<tr>
<td>STARPU_PTHREAD_GETSPECIFIC</td>
<td>Threads, 198</td>
</tr>
<tr>
<td>STARPU_PTHREAD_KEY_CREATE</td>
<td>Threads, 198</td>
</tr>
<tr>
<td>STARPU_PTHREAD_KEY_DELETE</td>
<td>Threads, 198</td>
</tr>
<tr>
<td>STARPU_PTHREAD_MUTEX_DESTROY</td>
<td>Threads, 197</td>
</tr>
<tr>
<td>STARPU_PTHREAD_MUTEX_INITIALIZER</td>
<td>Threads, 200</td>
</tr>
<tr>
<td>STARPU_PTHREAD_MUTEX_INIT</td>
<td>Threads, 197</td>
</tr>
<tr>
<td>STARPU_PTHREAD_MUTEX_LOCK</td>
<td>Threads, 197</td>
</tr>
<tr>
<td>STARPU_PTHREAD_MUTEX_UNLOCK</td>
<td>Threads, 198</td>
</tr>
<tr>
<td>STARPU_PTHREAD_RWLOCK_DESTROY</td>
<td>Threads, 199</td>
</tr>
<tr>
<td>STARPU_PTHREAD_RWLOCK_INIT</td>
<td>Threads, 198</td>
</tr>
<tr>
<td>STARPU_PTHREAD_RWLOCK_RDLOCK</td>
<td>Threads, 198</td>
</tr>
<tr>
<td>STARPU_PTHREAD_RWLOCK_UNLOCK</td>
<td>Threads, 198</td>
</tr>
<tr>
<td>STARPU_PTHREAD_RWLOCK_WRLOCK</td>
<td>Threads, 198</td>
</tr>
<tr>
<td>STARPU_PTHREAD_SETSPECIFIC</td>
<td>Threads, 198</td>
</tr>
<tr>
<td>STARPU_RELEASE_VERSION</td>
<td>Versioning, 181</td>
</tr>
<tr>
<td>STARPU_RMB</td>
<td>Toolbox, 195</td>
</tr>
<tr>
<td>STARPU_SCHED_COMPONENT_IS_HOMOGENOUS</td>
<td>Modularized Scheduler Interface, 426</td>
</tr>
<tr>
<td>STARPU_SCHED_COMPONENT_IS_SINGLE_MEMORY_NODE</td>
<td>Modularized Scheduler Interface, 426</td>
</tr>
<tr>
<td>STARPU_SCHED_CTX.AWAKE WORKERS</td>
<td>Scheduling Contexts, 385</td>
</tr>
<tr>
<td>STARPU_SCHED_CTX.CUDA_NSMS</td>
<td>Scheduling Contexts, 385</td>
</tr>
<tr>
<td>STARPU_SCHED_CTX.POLICY_INIT</td>
<td>Scheduling Contexts, 385</td>
</tr>
<tr>
<td>STARPU_SCHED_CTX.POLICY_MAX_PRIOR</td>
<td>Scheduling Contexts, 385</td>
</tr>
<tr>
<td>STARPU_SCHED_CTX.POLICY_MIN_PRIOR</td>
<td>Scheduling Contexts, 385</td>
</tr>
<tr>
<td>STARPU_SCHED_CTX.POLICY_NAME</td>
<td>Scheduling Contexts, 385</td>
</tr>
<tr>
<td>STARPU_SCHED_CTX.POLICY_STRUCT</td>
<td>Scheduling Contexts, 385</td>
</tr>
<tr>
<td>STARPU_SCHED_CTX.SUB_CTXS</td>
<td>Scheduling Contexts, 385</td>
</tr>
<tr>
<td>STARPU_SCHED_CTX.USER_DATA</td>
<td>Scheduling Contexts, 385</td>
</tr>
<tr>
<td>STARPU_SCHED_CTX</td>
<td>Task Insert Utility, 298</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_COMBINED_WORKERS</td>
<td>Modularized Scheduler Interface, 427</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_DECIDE_ARCHS</td>
<td>Modularized Scheduler Interface, 426</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_DECIDE_MEMNODES</td>
<td>Modularized Scheduler Interface, 426</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_DECIDE_WORKERS</td>
<td>Modularized Scheduler Interface, 426</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_FIFO_ABOVE_PRIOR</td>
<td>Modularized Scheduler Interface, 426</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_FIFO_ABOVE</td>
<td>Modularized Scheduler Interface, 426</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_FIFOS.BELOW_PRIOR</td>
<td>Modularized Scheduler Interface, 427</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_FIFOS.BELOW</td>
<td>Modularized Scheduler Interface, 427</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_IMM</td>
<td>Modularized Scheduler Interface, 426</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_PGMODEL</td>
<td>Modularized Scheduler Interface, 426</td>
</tr>
<tr>
<td>STARPU_SCHED_SIMPLE_WS.BELOW</td>
<td>Modularized Scheduler Interface, 427</td>
</tr>
<tr>
<td>STARPU_SPECIFIC.NODE_LOCAL</td>
<td>Codelet And Tasks, 289</td>
</tr>
<tr>
<td>STARPU_TAG.ONLY</td>
<td>Task Insert Utility, 298</td>
</tr>
<tr>
<td>STARPU_TASK.COLOR</td>
<td>Task Insert Utility, 298</td>
</tr>
<tr>
<td>STARPU_TASK.DEP.ARRAY</td>
<td>Task Insert Utility, 299</td>
</tr>
<tr>
<td>STARPU_TASK.END.DEP.ARRAY</td>
<td>Task Insert Utility, 299</td>
</tr>
<tr>
<td>Index Item</td>
<td>Page</td>
</tr>
<tr>
<td>-------------------------------------</td>
<td>------</td>
</tr>
<tr>
<td>Task Insert Utility</td>
<td>299</td>
</tr>
<tr>
<td>STARPU_TASK_END_DEP</td>
<td>299</td>
</tr>
<tr>
<td>Task Insert Utility</td>
<td>299</td>
</tr>
<tr>
<td>STARPU_TASK_GET_HANDLE</td>
<td>290</td>
</tr>
<tr>
<td>Codelet And Tasks</td>
<td>290</td>
</tr>
<tr>
<td>STARPU_TASK_GET_MODE</td>
<td>290</td>
</tr>
<tr>
<td>Codelet And Tasks</td>
<td>290</td>
</tr>
<tr>
<td>STARPU_TASK_GET_NBUFFERS</td>
<td>289</td>
</tr>
<tr>
<td>Codelet And Tasks</td>
<td>289</td>
</tr>
<tr>
<td>STARPU_TASK_INITIALIZER</td>
<td>289</td>
</tr>
<tr>
<td>Codelet And Tasks</td>
<td>289</td>
</tr>
<tr>
<td>STARPU_TASK_SET_HANDLE</td>
<td>290</td>
</tr>
<tr>
<td>Codelet And Tasks</td>
<td>290</td>
</tr>
<tr>
<td>STARPU_TASK_SET_MODE</td>
<td>290</td>
</tr>
<tr>
<td>Codelet And Tasks</td>
<td>290</td>
</tr>
<tr>
<td>STARPU_TASK_SYNCHRONOUS</td>
<td>299</td>
</tr>
<tr>
<td>Task Insert Utility</td>
<td>299</td>
</tr>
<tr>
<td>STARPU_TAG</td>
<td>298</td>
</tr>
<tr>
<td>Task Insert Utility</td>
<td>298</td>
</tr>
<tr>
<td>STARPU_THREAD_ACTIVE</td>
<td>186</td>
</tr>
<tr>
<td>Initialization and Termination</td>
<td></td>
</tr>
<tr>
<td>STARPU_UNLIKELY</td>
<td>194</td>
</tr>
<tr>
<td>Toolbox</td>
<td></td>
</tr>
<tr>
<td>STARPU_USE_MIC</td>
<td>353</td>
</tr>
<tr>
<td>MIC Extensions</td>
<td></td>
</tr>
<tr>
<td>STARPU_USE_MPI_MASTER_SLAVE</td>
<td>362</td>
</tr>
<tr>
<td>MPI Support</td>
<td></td>
</tr>
<tr>
<td>STARPU_USE_MPI</td>
<td>362</td>
</tr>
<tr>
<td>MPI Support</td>
<td></td>
</tr>
<tr>
<td>STARPU_USE_OPENCL</td>
<td>324</td>
</tr>
<tr>
<td>OpenCL Extensions</td>
<td></td>
</tr>
<tr>
<td>STARPU_VALUE</td>
<td>298</td>
</tr>
<tr>
<td>Task Insert Utility</td>
<td>298</td>
</tr>
<tr>
<td>STARPU_VARIABLE_GET_DEV_HANDLE</td>
<td>244</td>
</tr>
<tr>
<td>Data Interfaces</td>
<td></td>
</tr>
<tr>
<td>STARPU_VARIABLE_GET_ELEMSIZE</td>
<td>244</td>
</tr>
<tr>
<td>Data Interfaces</td>
<td></td>
</tr>
<tr>
<td>STARPU_VARIABLE_GET_OFFSET</td>
<td>244</td>
</tr>
<tr>
<td>Data Interfaces</td>
<td></td>
</tr>
<tr>
<td>STARPU_VARIABLE_GET_PTR</td>
<td>244</td>
</tr>
<tr>
<td>Data Interfaces</td>
<td></td>
</tr>
<tr>
<td>STARPU_VARIABLE_NBUFFERS</td>
<td>289</td>
</tr>
<tr>
<td>Codelet And Tasks</td>
<td></td>
</tr>
<tr>
<td>STARPU_VECTOR_GET_ALLOCSIZE</td>
<td>244</td>
</tr>
<tr>
<td>Data Interfaces</td>
<td></td>
</tr>
<tr>
<td>STARPU_VECTOR_GET_DEV_HANDLE</td>
<td>243</td>
</tr>
<tr>
<td>Data Interfaces</td>
<td></td>
</tr>
<tr>
<td>STARPU_VECTOR_GET_ELEMSIZE</td>
<td>244</td>
</tr>
<tr>
<td>Data Interfaces</td>
<td></td>
</tr>
<tr>
<td>STARPU_VECTOR_GET_NX</td>
<td>244</td>
</tr>
<tr>
<td>Data Interfaces</td>
<td></td>
</tr>
<tr>
<td>STARPU_VECTOR_GET_OFFSET</td>
<td>244</td>
</tr>
<tr>
<td>Data Interfaces</td>
<td></td>
</tr>
<tr>
<td>STARPU_VECTOR_GET_PTR</td>
<td>243</td>
</tr>
<tr>
<td>Data Interfaces</td>
<td></td>
</tr>
<tr>
<td>STARPU_VECTOR_GET_SLICE_BASE</td>
<td>244</td>
</tr>
<tr>
<td>Data Interfaces</td>
<td></td>
</tr>
<tr>
<td>STARPU_VECTOR_SET_NX</td>
<td></td>
</tr>
</tbody>
</table>
sc_hypervisor_get_fastest_ctx_exec_time
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 406

sc_hypervisor_get_idlest_workers
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 405

sc_hypervisor_get_idlest_workers_in_list
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 405

sc_hypervisor_get_index_for_arch
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 407

sc_hypervisor_get_leaves
  Scheduling Context Hypervisor - Regular usage, 414

sc_hypervisor_get_movable_nworkers
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 406

sc_hypervisor_get_nhierarchy_levels
  Scheduling Context Hypervisor - Regular usage, 414

sc_hypervisor_get_nready_flops_of_all_sons_of_s
  sched_ctx
  Scheduling Context Hypervisor - Regular usage, 414

sc_hypervisor_get_nsched_ctxs
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 404

sc_hypervisor_get_nworkers_ctx
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 408

sc_hypervisor_get_policy
  Scheduling Context Hypervisor - Regular usage, 412

sc_hypervisor_get_ref_speed_per_worker_type
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 407

sc_hypervisor_get_resize_criteria
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 408

sc_hypervisor_get_sched_ctxs
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 404

sc_hypervisor_get_size_req
  Scheduling Context Hypervisor - Regular usage, 413

sc_hypervisor_get_slowest_ctx_exec_time
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 406

sc_hypervisor_get_speed
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 409

sc_hypervisor_get_speed_per_worker
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 406

sc_hypervisor_get_speed_per_worker_type
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 406

sc_hypervisor_get_tasks_times
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 405

sc_hypervisor_get_total_elapsed_flops_per_sched_ctx
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 405

sc_hypervisor_get_types_of_workers
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 404

sc_hypervisor_get_wrapper
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 407

sc_hypervisor_group_workers_by_type
  Scheduling Context Hypervisor - Building a new re-
sizing policy, 404

sc_hypervisor_init
  Scheduling Context Hypervisor - Regular usage, 411

sc_hypervisor_lp.h, 496

sc_hypervisor_lp_distribute_floating_no_resources
  in_ctxs
  Scheduling Context Hypervisor - Linear Program-
ming, 416

sc_hypervisor_lp_distribute_resources_in_ctxs
  Scheduling Context Hypervisor - Linear Program-
ming, 416

sc_hypervisor_lp_execute_dichotomy
  Scheduling Context Hypervisor - Linear Program-
ming, 417

sc_hypervisor_lp_find_tmax
  Scheduling Context Hypervisor - Linear Program-
ming, 417

sc_hypervisor_lp_get_nworkers_per_ctx
  Scheduling Context Hypervisor - Linear Program-
ning, 415

sc_hypervisor_lp_get_tmax
  Scheduling Context Hypervisor - Linear Program-
ning, 416

sc_hypervisor_lp_place_resources_in_ctx
  Scheduling Context Hypervisor - Linear Program-
ming, 416

sc_hypervisor_lp_redistribute_resources_in_ctxs
  Scheduling Context Hypervisor - Linear Program-
ming, 416

sc_hypervisor_lp_round_double_to_int
  Scheduling Context Hypervisor - Linear Program-
ming, 416

sc_hypervisor_lp_share_remaining_resources
  Scheduling Context Hypervisor - Linear Program-
ming, 417

sc_hypervisor_lp_simulate_distrib_flops
  Scheduling Context Hypervisor - Linear Program-
ming, 417

sc_hypervisor_lp_simulate_distrib_flops_on_sample
  Scheduling Context Hypervisor - Linear Program-
ming, 418

sc_hypervisor_lp_simulate_distrib_tasks
  Scheduling Context Hypervisor - Linear Program-
Scheduling Context Hypervisor - Building a new resizing policy, 405
sc_hypervisor_policy_config, 495
sc_hypervisor_policy_remove_task_from_pool
Scheduling Context Hypervisor - Building a new resizing policy, 405
sc_hypervisor_policy_resize
Scheduling Context Hypervisor - Building a new resizing policy, 406
sc_hypervisor_policy_resize_to_unknown_receiver
Scheduling Context Hypervisor - Building a new resizing policy, 406
sc_hypervisor_policy_task_pool, 403
sc_hypervisor_post_resize_request
Scheduling Context Hypervisor - Regular usage, 412
sc_hypervisor_register_ctx
Scheduling Context Hypervisor - Regular usage, 412
sc_hypervisor_remove_workers_from_sched_ctx
Scheduling Context Hypervisor - Regular usage, 413
sc_hypervisor_resize_ack, 402
sc_hypervisor_resize_ctxs
Scheduling Context Hypervisor - Regular usage, 412
sc_hypervisor_save_size_req
Scheduling Context Hypervisor - Regular usage, 413
sc_hypervisor_set_config
Scheduling Context Hypervisor - Building a new resizing policy, 408
sc_hypervisor_set_type_of_task
Scheduling Context Hypervisor - Regular usage, 414
sc_hypervisor_shutdown
Scheduling Context Hypervisor - Regular usage, 411
sc_hypervisor_size_ctxs
Scheduling Context Hypervisor - Regular usage, 413
sc_hypervisor_start_resize
Scheduling Context Hypervisor - Regular usage, 412
sc_hypervisor_stop_resize
Scheduling Context Hypervisor - Regular usage, 412
sc_hypervisor_unregister_ctx
Scheduling Context Hypervisor - Regular usage, 412
sc_hypervisor_update_diff_elapsed_flops
Scheduling Context Hypervisor - Regular usage, 414
sc_hypervisor_update_diff_total_flops
Scheduling Context Hypervisor - Regular usage, 414
sc_hypervisor_update_resize_interval
Scheduling Context Hypervisor - Regular usage, 414
sc_hypervisor_wrapper, 497
sc_hypervisorsc_hypervisor_get_speed_per_worker_type
Scheduling Context Hypervisor - Building a new resizing policy, 409
sched_ctx
starpu_task, 286
sched_data
starpu_task, 287
sched_policy
starpu_conf, 183
sched_policy_name
starpu_conf, 183
scheduled
starpu_task, 285
Scheduling Context Hypervisor - Building a new resizing policy, 399
SC_HYPERVISOR_FIXED_WORKERS, 403
SC_HYPERVISOR_GRANULARITY, 403
SC_HYPERVISOR_ISPEED_CTX_SAMPLE, 404
SC_HYPERVISOR_ISPEED_W_SAMPLE, 404
SC_HYPERVISOR_MAX_IDLE, 403
SC_HYPERVISOR_MAX_WORKERS, 403
SC_HYPERVISOR_MIN_TASKS, 403
SC_HYPERVISOR_MIN_WORKERS, 403
SC_HYPERVISOR_NEW_WORKERS_MAX_ID LE, 404
SC_HYPERVISOR_NULL, 404
SC_HYPERVISOR_PRIORITY, 403
SC_HYPERVISOR_TIME_TO_APPLY, 404
sc_hypervisor_check_idle, 407
sc_hypervisor_check_if_consider_max, 407
sc_hypervisor_check_speed_gap_btw_ctxs, 407
<table>
<thead>
<tr>
<th>Function</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>get_nchildren</td>
<td>262</td>
</tr>
<tr>
<td>nchildren</td>
<td>262</td>
</tr>
<tr>
<td>starpu_data_filters.h</td>
<td>456</td>
</tr>
<tr>
<td>starpu_data_free_pinned_if_possible</td>
<td>190</td>
</tr>
<tr>
<td>Starpu Memory Library</td>
<td>190</td>
</tr>
<tr>
<td>starpu_data_get_alloc_size</td>
<td>249</td>
</tr>
<tr>
<td>starpu_data_get_child</td>
<td>263</td>
</tr>
<tr>
<td>starpu_data_get_default_sequential_consistency_flag</td>
<td>225</td>
</tr>
<tr>
<td>starpu_data_get_interface_id</td>
<td>249</td>
</tr>
<tr>
<td>starpu_data_get_interface_on_node</td>
<td>249</td>
</tr>
<tr>
<td>starpu_data_get_local_ptr</td>
<td>249</td>
</tr>
<tr>
<td>starpu_data_get_nb_children</td>
<td>263</td>
</tr>
<tr>
<td>starpu_data_get_ooc_flag</td>
<td>225</td>
</tr>
<tr>
<td>starpu_data_get_rank</td>
<td>364</td>
</tr>
<tr>
<td>starpu_data_get_sequential_consistency_flag</td>
<td>224</td>
</tr>
<tr>
<td>starpu_data_get_size</td>
<td>249</td>
</tr>
<tr>
<td>starpu_data_get_sub_data</td>
<td>264</td>
</tr>
<tr>
<td>starpu_data_get_tag</td>
<td>364</td>
</tr>
<tr>
<td>starpu_data_handle_t</td>
<td>218</td>
</tr>
<tr>
<td>starpu_data_handle_to_pointer</td>
<td>248</td>
</tr>
<tr>
<td>starpu_data_idle_prefetch_on_node</td>
<td>224</td>
</tr>
<tr>
<td>starpu_data_interface_get_next_id</td>
<td>250</td>
</tr>
<tr>
<td>starpu_data_interface_id</td>
<td>247</td>
</tr>
<tr>
<td>starpu_data_interface_ops</td>
<td>234</td>
</tr>
<tr>
<td>alloc_compare</td>
<td>236</td>
</tr>
<tr>
<td>alloc_footprint</td>
<td>236</td>
</tr>
<tr>
<td>allocate_data_on_node</td>
<td>235</td>
</tr>
<tr>
<td>compare</td>
<td>236</td>
</tr>
<tr>
<td>copy_methods</td>
<td>235</td>
</tr>
<tr>
<td>describe</td>
<td>236</td>
</tr>
<tr>
<td>display</td>
<td>236</td>
</tr>
<tr>
<td>dontcache</td>
<td>237</td>
</tr>
<tr>
<td>footprint</td>
<td>236</td>
</tr>
<tr>
<td>free_data_on_node</td>
<td>235</td>
</tr>
<tr>
<td>get_alloc_size</td>
<td>236</td>
</tr>
<tr>
<td>get_size</td>
<td>236</td>
</tr>
<tr>
<td>handle_to_pointer</td>
<td>235</td>
</tr>
<tr>
<td>init</td>
<td>235</td>
</tr>
<tr>
<td>interface_size</td>
<td>237</td>
</tr>
<tr>
<td>interfaceid</td>
<td>237</td>
</tr>
<tr>
<td>name</td>
<td>237</td>
</tr>
<tr>
<td>pack_data</td>
<td>237</td>
</tr>
<tr>
<td>pointer_is_inside</td>
<td>236</td>
</tr>
<tr>
<td>register_data_handle</td>
<td>235</td>
</tr>
<tr>
<td>to_pointer</td>
<td>236</td>
</tr>
<tr>
<td>unpack_data</td>
<td>237</td>
</tr>
<tr>
<td>starpu_data_interfaces.h</td>
<td>458</td>
</tr>
<tr>
<td>starpu_data_invalidate</td>
<td>220</td>
</tr>
<tr>
<td>starpu_data_invalidate_submit</td>
<td>220</td>
</tr>
<tr>
<td>starpu_data_is_on_node</td>
<td>224</td>
</tr>
<tr>
<td>starpu_data_lookup</td>
<td>249</td>
</tr>
<tr>
<td>starpu_data_malloc_pinned_if_possible</td>
<td>190</td>
</tr>
<tr>
<td>standard Memory Library</td>
<td>190</td>
</tr>
<tr>
<td>starpu_data_map_filters</td>
<td>264</td>
</tr>
<tr>
<td>starpu_data_pack</td>
<td>249</td>
</tr>
<tr>
<td>starpu_data_partition</td>
<td>249</td>
</tr>
<tr>
<td>starpu_data_partition_clean</td>
<td>266</td>
</tr>
<tr>
<td>starpu_data_partition_not_automatic</td>
<td>266</td>
</tr>
<tr>
<td>starpu_data_partition_plan</td>
<td>264</td>
</tr>
<tr>
<td>starpu_data_partition_readonly_submit</td>
<td>265</td>
</tr>
<tr>
<td>starpu_data_partition_readwrite_upgrade_submit</td>
<td>265</td>
</tr>
<tr>
<td>starpu_data_partition_submit</td>
<td>265</td>
</tr>
<tr>
<td>starpu_data_partition_submit_sequential_consistency</td>
<td>266</td>
</tr>
<tr>
<td>starpu_data_pointer_is_inside</td>
<td>248</td>
</tr>
<tr>
<td>starpu_data_prefetch_on_node</td>
<td>224</td>
</tr>
<tr>
<td>starpu_data_ptr_register</td>
<td>248</td>
</tr>
<tr>
<td>starpu_data_query_status</td>
<td>225</td>
</tr>
<tr>
<td>starpu_data_register</td>
<td>248</td>
</tr>
<tr>
<td>starpu_data_release</td>
<td>223</td>
</tr>
<tr>
<td>starpu_data_release_on_node</td>
<td>223</td>
</tr>
<tr>
<td>starpu_data_request_allocation</td>
<td>223</td>
</tr>
<tr>
<td>starpu_data_set_coordinates</td>
<td>223</td>
</tr>
</tbody>
</table>
INDEX

Data Management, 220
starpu_data_set_coordinates_array
    Data Management, 220
starpu_data_set_default_sequential_consistency_flag
    Data Management, 225
starpu_data_set_name
    Data Management, 219
starpu_data_set_ooc_flag
    Data Management, 225
starpu_data_set_reduction_methods
    Data Management, 225
starpu_data_set_sequential_consistency_flag
    Data Management, 224
starpu_data_set_tag
    MPI Support, 363
starpu_data_unregister
    Data Management, 220
starpu_data_unregister_no_coherency
    Data Management, 220
starpu_data_unregister_submit
    Data Management, 220
starpu_data_vget_sub_data
    Data Partition, 264
starpu_data_vmap_filters
    Data Partition, 264
starpu_data_wont_use
    Data Management, 224
starpu_deprecated_api.h, 462
starpu_disk.h, 462
starpu_disk_close
    Out Of Core, 273
starpu_disk_hdf5_ops
    Out Of Core, 274
starpu_disk_leveldb_ops
    Out Of Core, 274
starpu_disk_open
    Out Of Core, 273
starpu_disk_ops, 271
    alloc, 272
async_full_read, 272
async_full_write, 272
async_read, 272
async_write, 272
bandwidth, 271
close, 272
copy, 272
free_request, 273
full_read, 272
full_write, 272
open, 272
plug, 271
read, 272
test_request, 273
unplug, 271
wait_request, 273
write, 272
starpu_disk_register
    Out Of Core, 273
starpu_disk_stdio_ops
    Out Of Core, 274
starpu_disk_swap_node
    Out Of Core, 274
starpu_disk_unistd_o_direct_ops
    Out Of Core, 274
starpu_disk_unistd_ops
    Out Of Core, 274
starpu_driver, 381
starpu_driver.h, 463
starpu_driver.id, 381
starpu_driver_deinit
    Running Drivers, 382
starpu_driver_init
    Running Drivers, 382
starpu_driver_run
    Running Drivers, 381
starpu_driver_run_once
    Running Drivers, 382
starpu_drivers_request_termination
    Running Drivers, 382
starpu_execute_on_each_worker
    Miscellaneous Helpers, 355
starpu_execute_on_each_worker_ex
    Miscellaneous Helpers, 355
starpu_execute_on_specific_workers
    Miscellaneous Helpers, 355
starpu_expert.h, 463
starpu_filter_nparts_compute_chunk_size_and_offset
    Data Partition, 270
starpu_free
    Standard Memory Library, 191
starpu_free_flags
    Standard Memory Library, 191
starpu_free_on_node
    Data Interfaces, 251
starpu_free_on_node_flags
    Data Interfaces, 251
INDEX

Standard Memory Library, 191
starpu_memory_wait_available

Standard Memory Library, 192
starpu_mic.h, 464
starpu_mic_device_get_count

Workers' Properties, 212
starpu_mic_symbol_t

MIC Extensions, 353
starpu_mic_t

Codelet And Tasks, 291
starpu_mic_get_kernel

MIC Extensions, 354
starpu_mic_kernel_t

Codelet And Tasks, 291
starpu_mic_register_kernel

MIC Extensions, 353
starpu_mic_worker_get_count

Workers' Properties, 212
starpu_mod.f90, 464
starpu_mpi.h, 465
starpu_mpi_barrier

MPI Support, 369
starpu_mpi_cache_flush

MPI Support, 371
starpu_mpi_cache_flush_all_data

MPI Support, 371
starpu_mpi_cache_is_enabled

MPI Support, 371
starpu_mpi_cache_set

MPI Support, 371
starpu_mpiCached_receive

MPI Support, 371
starpu_mpiCached_send

MPI Support, 371
starpu_mpi_comm_amounts_retrieve

MPI Support, 365
starpu_mpi_comm_get_attr

MPI Support, 366
starpu_mpi_comm_rank

MPI Support, 365
starpu_mpi_comm_size

MPI Support, 365
starpu_mpi_data_get_rank

MPI Support, 372
starpu_mpi_data_get_tag

MPI Support, 372
starpu_mpi_data_migrate

MPI Support, 374
starpu_mpi_data_register

MPI Support, 363
starpu_mpi_data_register_comm

MPI Support, 371
starpu_mpi_data_set_rank

MPI Support, 363
starpu_mpi_data_set_rank_comm

MPI Support, 372
starpu_mpi_data_set_tag

MPI Support, 372
starpu_mpi_datatype_register

MPI Support, 370
starpu_mpi_datatype_unregister

MPI Support, 371
starpu_mpi_gather_detached

MPI Support, 375
starpu_mpi_get_data_on_all_nodes_detached

MPI Support, 374
starpu_mpi_get_data_on_node

MPI Support, 373
starpu_mpi_get_data_on_node_detached

MPI Support, 373
starpu_mpi_init

MPI Support, 364
starpu_mpi_init_comm

MPI Support, 364
starpu_mpi_init_conf

MPI Support, 364
starpu_mpi_initialize

MPI Support, 365
starpu_mpi_initialize_extended

MPI Support, 365
starpu_mpi_insert_task

MPI Support, 373
starpu_mpi_irecv

MPI Support, 366
starpu_mpi_irecv_array_detached_unlock_tag

MPI Support, 370
starpu_mpi_irecv_detached

MPI Support, 367
starpu_mpi_irecv_detached_prio

MPI Support, 367
starpu_mpi_irecv_detached_unlock_tag

MPI Support, 369
starpu_mpi_irecv_detached_unlock_tag_prio

MPI Support, 369
starpu_mpi_irecv_prio

MPI Support, 366
starpu_mpi_issend

MPI Support, 367
starpu_mpi_issend_array_detached_unlock_tag

MPI Support, 370
starpu_mpi_issend_array_detached_unlock_tag_prio

MPI Support, 370
starpu_mpi_issend_detached

MPI Support, 367
starpu_mpi_issend_detached_prio

MPI Support, 367
starpu_mpi_issend_detached_unlock_tag

MPI Support, 369
starpu_mpi_issend_detached_unlock_tag_prio

MPI Support, 369
starpu_mpi_issend_prio

MPI Support, 366
starpu_mpi_isend

MPI Support, 368
starpu_mpi_isend_array_detached_unlock_tag

MPI Support, 370
starpu_mpi_isend_array_detached_unlock_tag_prio

MPI Support, 370
starpu_mpi_isend_detached

MPI Support, 368
starpu_mpi_isend_detached_prio

MPI Support, 368
starpu_mpi_isend_prio

MPI Support, 368
starpu_omp_get_team_size
OpenMP Runtime Support, 347
starpu_omp_get_thread_limit
OpenMP Runtime Support, 345
starpu_omp_get_thread_num
OpenMP Runtime Support, 343
starpu_omp_get_wtick
OpenMP Runtime Support, 352
starpu_omp_get_wtime
OpenMP Runtime Support, 352
starpu_omp_in_final
OpenMP Runtime Support, 347
starpu_omp_in_parallel
OpenMP Runtime Support, 343
starpu_omp_init
OpenMP Runtime Support, 335
starpu_omp_init_lock
OpenMP Runtime Support, 349
starpu_omp_init_nest_lock
OpenMP Runtime Support, 350
starpu_omp_is_initial_device
OpenMP Runtime Support, 349
starpu_omp_lock_t, 332
starpu_omp_master
OpenMP Runtime Support, 335
starpu_omp_master_inline
OpenMP Runtime Support, 336
starpu_omp_nest_lock_t, 332
starpu_omp_ordered
OpenMP Runtime Support, 340
starpu_omp_ordered_inline_begin
OpenMP Runtime Support, 340
starpu_omp_ordered_inline_end
OpenMP Runtime Support, 340
starpu_omp_parallel_region
OpenMP Runtime Support, 335
starpu_omp_parallel_region_attr, 333
starpu_omp_sched_value
OpenMP Runtime Support, 335
starpu_omp_sched_value
OpenMP Runtime Support, 334
starpu_omp_sections
OpenMP Runtime Support, 341
starpu_omp_sections_combined
OpenMP Runtime Support, 341
starpu_omp_set_default_device
OpenMP Runtime Support, 347
starpu_omp_set_dynamic
OpenMP Runtime Support, 344
starpu_omp_set_lock
OpenMP Runtime Support, 349
starpu_omp_set_max_active_levels
OpenMP Runtime Support, 346
starpu_omp_set_nest_lock
OpenMP Runtime Support, 351
starpu_omp_set_nested
OpenMP Runtime Support, 344
starpu_omp_set_num_threads
OpenMP Runtime Support, 342
starpu_omp_set_schedule
OpenMP Runtime Support, 345
starpu_omp_shutdown
OpenMP Runtime Support, 335
starpu_omp_single
OpenMP Runtime Support, 336
starpu_omp_single_copyprivate
OpenMP Runtime Support, 337
starpu_omp_single_copyprivate_inline_begin
OpenMP Runtime Support, 337
starpu_omp_single_copyprivate_inline_end
OpenMP Runtime Support, 337
starpu_omp_single_inline
OpenMP Runtime Support, 337
starpu_omp_task_region
OpenMP Runtime Support, 341
starpu_omp_task_region_attr, 333
starpu_omp_taskgroup
OpenMP Runtime Support, 341
starpu_omp_taskgroup_inline_begin
OpenMP Runtime Support, 342
starpu_omp_taskgroup_inline_end
OpenMP Runtime Support, 342
starpu_omp_taskwait
OpenMP Runtime Support, 341
starpu_omp_test_lock
OpenMP Runtime Support, 350
starpu_omp_test_nest_lock
OpenMP Runtime Support, 351
starpu_omp_unset_lock
OpenMP Runtime Support, 350
starpu_omp_unset_nest_lock
OpenMP Runtime Support, 351
starpu_omp_vector_annotate
OpenMP Runtime Support, 352
starpu_opencl.h, 467
starpu_opencl_allocate_memory
OpenCL Extensions, 328
starpu_opencl_collect_stats
OpenCL Extensions, 327
starpu_opencl_compile_opencl_from_file
OpenCL Extensions, 326
starpu_opencl_compile_opencl_from_string
OpenCL Extensions, 326
starpu_opencl_copy_async_sync
OpenCL Extensions, 329
starpu_opencl_copy_opencl_to_opencl
OpenCL Extensions, 329
starpu_opencl_copy_opencl_to_ram
OpenCL Extensions, 328
starpu_opencl_copy_ram_to_opencl
OpenCL Extensions, 328
starpu_opencl_display_error
OpenCL Extensions, 328
starpu_opencl_error_string
OpenCL Extensions, 327
parents, 422
obj, 424
parents, 423
pull_task, 423
push_task, 423
remove_child, 423
tree, 422
workers, 422
workers_in_ctx, 422
starpu_sched_component.h, 474
starpu_sched_component_best_implementation_create
Modularized Scheduler Interface, 432
starpu_sched_component_can_execute_task
Modularized Scheduler Interface, 429
starpu_sched_component_can_pull
Modularized Scheduler Interface, 430
starpu_sched_component_can_pull_all
Modularized Scheduler Interface, 431
starpu_sched_component_can_push
Modularized Scheduler Interface, 430
starpu_sched_component_composed_component_create
Modularized Scheduler Interface, 433
starpu_sched_component_composed_recipe_add
Modularized Scheduler Interface, 433
starpu_sched_component_composed_recipe_create
Modularized Scheduler Interface, 432
starpu_sched_component_estimated_end_average
Modularized Scheduler Interface, 431
starpu_sched_component_estimated_end_min
Modularized Scheduler Interface, 431
starpu_sched_component_estimated_load
Modularized Scheduler Interface, 431
starpu_sched_component_execute_preds
Modularized Scheduler Interface, 431
starpu_sched_component_fifo_create
Modularized Scheduler Interface, 431
starpu_sched_component_fifo_data, 424
starpu_sched_component_initialize_simple_scheduler
Modularized Scheduler Interface, 433
starpu_sched_component_is_combined_worker
Modularized Scheduler Interface, 430
starpu_sched_component_is_fifo
starpu_sched_component_is_random
starpu_sched_component_is_simple_worker
starpu_sched_component_is_work_stealing
starpu_sched_component_make_scheduler
Modularized Scheduler Interface, 433
starpu_sched_component_mct_create
Modularized Scheduler Interface, 433
starpu_sched_component_mct_data, 424
starpu_sched_component_parallel_worker_create
Modularized Scheduler Interface, 432
starpu_sched_component_perfmodel_select_data, 424
starpu_sched_component_prio_data, 424
starpu_sched_component_properties
Modularized Scheduler Interface, 427
starpu_sched_component_push_task
Modularized Scheduler Interface, 428
starpu_sched_component_push_task
Modularized Scheduler Interface, 428
starpu_sched_component_random_create
Modularized Scheduler Interface, 432
starpu_sched_component_specs, 425
hwloc_cache_composed_sched_component, 425
hwloc_component_composed_sched_component,
starpu_sched_component_work_stealing_create
Modularized Scheduler Interface, 431
starpu_sched_component_worker_get
Modularized Scheduler Interface, 429
starpu_sched_component_worker_get_workerid
Modularized Scheduler Interface, 430
starpu_sched_component_worker_post_exec_hook
Modularized Scheduler Interface, 430
starpu_sched_component_worker_pre_exec_hook
Modularized Scheduler Interface, 430
starpu_sched_ctx.h, 477
starpu_sched_ctx_add_workers
Scheduling Contexts, 387
starpu_sched_ctx_call_pushed_task_cb
starpu_sched_ctx_hypervisor.h, 479
starpu_sched_ctx_check_if_hypervisor_exists
starpu_sched_ctx_hypervisor.h, 480
starpu_sched_ctx_contains_worker
Scheduling Contexts, 388
starpu_sched_ctx_create
Scheduling Contexts, 386
starpu_sched_ctx_create_inside_interval
    Scheduling Contexts, 386
starpu_sched_ctx_create_worker_collection
    Scheduling Contexts, 390
starpu_sched_ctx_delete
    Scheduling Contexts, 387
starpu_sched_ctx_delete_worker_collection
    Scheduling Contexts, 390
starpu_sched_ctx_display_workers
    Scheduling Contexts, 387
starpu_sched_ctx_exec_parallel_code
    Scheduling Contexts, 389
starpu_sched_ctx_finished_submit
    Scheduling Contexts, 388
starpu_sched_ctx_get_context
    Scheduling Contexts, 387
starpu_sched_ctx_get_max_priority
    Scheduling Contexts, 389
starpu_sched_ctx_get_min_priority
    Scheduling Contexts, 389
starpu_sched_ctx_get_nshared_workers
    Scheduling Contexts, 388
starpu_sched_ctx_get_nworkers
    Scheduling Contexts, 388
starpu_sched_ctx_get_policy_data
    Scheduling Contexts, 389
starpu_sched_ctx_get_user_data
    Scheduling Contexts, 389
starpu_sched_ctx_get_worker_collection
    Scheduling Contexts, 390
starpu_sched_ctx_get_workers_list
    Scheduling Contexts, 388
starpu_sched_ctx_get_workers_list_raw
    Scheduling Contexts, 388
starpu_sched_ctx_set_perf_counters
    starpu_sched_ctx_hypervisor.h, 479
starpu_sched_ctx_set_policy_data
    Scheduling Contexts, 389
starpu_sched_ctx_stop_task_submission
    Scheduling Contexts, 387
starpu_sched_ctx_worker_get_id
    Scheduling Contexts, 388
starpu_sched_ctx_worker_is_master_for_child_ctx
    Scheduling Contexts, 389
starpu_sched_ctx_worker_shares_tasks_lists
    Scheduling Policy, 398
starpu_sched_ctx_get_max_priority
    Scheduling Policy, 394
starpu_sched_ctx_get_min_priority
    Scheduling Policy, 394
starpu_sched_ctx_get_predefined_policies
    Scheduling Policy, 394
starpu_sched_policy
    add_workers, 393
deinit_sched, 392
do_schedule, 393
init_sched, 392
policy_description, 394
policy_name, 393
pop_every_task, 393
pop_task, 393
post_exec_hook, 393
pre_exec_hook, 393
push_task, 392
push_task_notify, 393
remove_workers, 393
submit_hook, 393
starpu_sched_set_max_priority
    Scheduling Policy, 395
starpu_sched_set_min_priority
    Scheduling Policy, 394
starpu_sched_tree
    starpu_sched_tree_add_workers
    Modularized Scheduler Interface, 428
starpu_sched_tree_create
    Modularized Scheduler Interface, 427
starpu_sched_tree_destroy
    Modularized Scheduler Interface, 427
starpu_sched_tree_pop_task
    Modularized Scheduler Interface, 428
starpu_sched_tree_push_task
    Modularized Scheduler Interface, 428
starpu_sched_tree_remove_workers
    Modularized Scheduler Interface, 428
starpu_sched_tree_update_workers
    Modularized Scheduler Interface, 428
starpu_sched_tree_update_workers_in_ctx
    Modularized Scheduler Interface, 427
starpu_sched_tree_work_stealing_push_task
    Modularized Scheduler Interface, 432
starpu_scheduler.h, 480
starpu_shutdown
Initialization and Termination, 187
starpu_simgrid_wrap.h, 481
starpu_simgrid_wrap.h, 481
starpu_sleep
Threads, 205
starpu_stdlib.h, 481
starpu_tag_declare_deps
Explicit Dependencies, 305
starpu_tag_declare_deps_array
Explicit Dependencies, 305
starpu_tag_notify_from_apps
Explicit Dependencies, 306
starpu_tag_remove
Explicit Dependencies, 306
starpu_tag_restart
Explicit Dependencies, 306
starpu_tag_t
Explicit Dependencies, 303
starpu_tag_wait
Explicit Dependencies, 305
starpu_tag_wait_array
Explicit Dependencies, 305
starpu_task, 280
bundle, 287
callback_arg, 283
callback_arg_free, 284
callback_func, 283
cl, 282
cl_arg, 283
cl_arg_free, 284
cl_arg_size, 283
color, 286
destroy, 285
detach, 285
dyn_handles, 282
dyn_interfaces, 282
dyn_modes, 282
eexecute_on_a_specific_worker, 285
flops, 287
handles, 282
handles_sequential_consistency, 283
hypervisor_tag, 286
interfaces, 282
magic, 286
mf_skip, 285
modes, 282
name, 281
nb_termination_call_required, 287
nbuffers, 282
next, 287
no_submitorder, 285
omp_task, 287
possibly_parallel, 287
predicted, 287
predicted_transfer, 287
prev, 287
priority, 286
profiling_info, 287
prologue_callback_arg, 284
prologue_callback_arg_free, 284
prologue_callback_func, 283
prologue_callback_pop_arg_free, 284
regenerate, 285
sched_ctx, 286
sched_data, 287
scheduled, 285
sequential_consistency, 284
starpu_private, 287
status, 286
synchronous, 284
tag_id, 284
type, 286
use_tag, 284
where, 282
workerid, 285
workerids, 286
workerids_len, 286
workerorder, 285
starpu_task.h, 482
starpu_task_build
Task Insert Utility, 300
starpu_task_bundle.h, 484
starpu_task_bundle_close
Task Bundles, 377
starpu_task_bundle_create
Task Bundles, 376
starpu_task_bundle_expected_data_transfer_time
Task Bundles, 377
starpu_task_bundle_expected_energy
Task Bundles, 377
starpu_task_bundle_expected_length
Task Bundles, 377
starpu_task_bundle_insert
Task Bundles, 376
starpu_task_bundle_remove
Task Bundles, 376
starpu_task_bundle_t
Task Bundles, 376
starpu_task_clean
Codelet And Tasks, 293
starpu_task_create
Codelet And Tasks, 293
starpu_task_data_footprint
Scheduling Policy, 397
starpu_task_declare_deps
Explicit Dependencies, 303
starpu_task_declare_deps_array
Explicit Dependencies, 303
starpu_task_declare_end_deps
Explicit Dependencies, 304
starpu_task_declare_end_deps_array
Explicit Dependencies, 304
starpu_task_destroy
Codelet And Tasks, 293
starpu_task_dup
Codelet And Tasks, 296
Performance Model, 314
starpu_tree, 399
starpu_tree.h, 490
starpu_util.h, 490
starpu_variable_data_register
  Data Interfaces, 255
starpu_variable_get_elmsize
  Data Interfaces, 256
starpu_variable_get_local_ptr
  Data Interfaces, 256
starpu_variable_interface, 238
starpu_variable_ptr_register
  Data Interfaces, 256
starpu_vector_data_register
  Data Interfaces, 256
starpu_vector_data_register_allocsize
  Data Interfaces, 254
starpu_vector_filter_block
  Data Partition, 268
starpu_vector_filter_block_shadow
  Data Partition, 268
starpu_vector_filter_divide_in_2
  Data Partition, 269
starpu_vector_filter_list
  Data Partition, 268
starpu_vector_filter_list_long
  Data Partition, 268
starpu_vector_get_allocsize
  Data Interfaces, 255
starpu_vector_get_elmsize
  Data Interfaces, 255
starpu_vector_get_local_ptr
  Data Interfaces, 255
starpu_vector_get_nx
  Data Interfaces, 255
starpu_vector_get_name
  Data Interfaces, 255
starpu_vector_ptr_register
  Data Interfaces, 255
starpu_void_data_register
  Data Interfaces, 256
starpu_wait_initialized
  Initialization and Termination, 187
starpu_wake_all_blocked_workers
  Expert Mode, 382
starpu_wake_worker_locked
  Scheduling Policy, 398
starpu_wake_worker_no_relax
  Scheduling Policy, 398
starpu_wake_worker_relax
  Scheduling Policy, 398
starpu_wake_worker_relax_light
  Scheduling Policy, 398
starpu_worker.h, 491
starpu_worker_archtype
  Workers’ Properties, 211
starpu_worker_can_execute_task
  Scheduling Policy, 395
starpu_worker_can_execute_task_first_impl
  Scheduling Policy, 395
starpu_worker_collection, 209
  add, 210
deinit, 210
get_next, 210
has_next, 210
init, 210
init_iterator, 210
nworkers, 210
remove, 210
type, 210
workerids, 210
starpu_worker_collection_type
  Workers’ Properties, 211
starpu_worker_display_names
  Workers’ Properties, 213
starpu_worker_get_by_devid
  Workers’ Properties, 213
starpu_worker_get_by_type
  Workers’ Properties, 213
starpu_worker_get_count
  Workers’ Properties, 213
starpu_worker_get_count_by_type
  Workers’ Properties, 213
starpu_worker_get_devid
  Workers’ Properties, 213
starpu_worker_get_relative_speedup
  Scheduling Policy, 397
starpu_worker_get_relax_state
  Workers’ Properties, 213
starpu_worker_get_sched_condition
  Scheduling Policy, 394
starpu_worker_get_type
  Workers’ Properties, 212
starpu_worker_get_type_as_string
  Workers’ Properties, 214
starpu_worker_lock
  Workers’ Properties, 215
starpurm_reclaim_all_devices
  Interoperability Support, 443
starpurm_reclaim_cpu
  Interoperability Support, 440
starpurm_reclaim_cpu_mask
  Interoperability Support, 440
starpurm_reclaim_cpus
  Interoperability Support, 440
starpurm_reclaim_device
  Interoperability Support, 443
starpurm_reclaim_device_mask
  Interoperability Support, 443
starpurm_reclaim_devices
  Interoperability Support, 443
starpurm_return_all
  Interoperability Support, 440
starpurm_return_all_devices
  Interoperability Support, 444
starpurm_return_cpu
  Interoperability Support, 440
starpurm_return_device
  Interoperability Support, 444
starpurm_set_drs_disable
  Interoperability Support, 438
starpurm_set_drs_enable
  Interoperability Support, 437
starpurm_set_max_parallelism
  Interoperability Support, 438
starpurm_shutdown
  Interoperability Support, 437
starpurm_spawn_kernel_on_cpus
  Interoperability Support, 437
starpurm_spawn_kernel_on_cpus_callback
  Interoperability Support, 437
starpurm_withdraw_all_cpus_from_starpu
  Interoperability Support, 437
starpurm_withdraw_all_devices_from_starpu
  Interoperability Support, 439
starpurm_withdraw_cpu_from_starpu
  Interoperability Support, 438
starpurm_withdraw_cpu_mask_from_starpu
  Interoperability Support, 439
starpurm_withdraw_cpus_from_starpu
  Interoperability Support, 439
starpurm_withdraw_device_from_starpu
  Interoperability Support, 439
starpurm_withdraw_device_mask_from_starpu
  Interoperability Support, 442
starpurm_withdraw_devices_from_starpu
  Interoperability Support, 442
start_ctx
  sc_hypervisor_policy, 402, 411
status
  starpu_task, 286
submit_hook
  starpu_sched_policy, 393
symbol
  starpu_perfmodel, 311
synchronous
  starpu_task, 284
tag_id
  starpu_task, 284
Task Bundles, 376
  starpu_task_bundle_close, 377
  starpu_task_bundle_create, 376
  starpu_task_bundle_expected_data_transfer_time, 377
  starpu_task_bundle_expected_energy, 377
  starpu_task_bundle_expected_length, 377
  starpu_task_bundle_insert, 376
  starpu_task_bundle_remove, 376
  starpu_task_bundle_t, 376
Task Insert Utility, 296
  STARPU_CALLBACK_ARG, 298
  STARPU_CALLBACK_WITH_ARG, 298
  STARPU_CALLBACK, 298
  STARPU_CL_ARGS_NFREE, 299
  STARPU_CL_ARGS, 299
  STARPU_EXECUTE_ON_WORKER, 298
  STARPU_EXECUTE_WHERE, 298
  STARPU_FLOPS, 298
  STARPU_HANDLES_SEQUENTIAL_CONSISTENCY, 299
  STARPU_NAME, 299
  STARPU_PRIORITY, 298
  STARPU_SCHED_CTX, 298
  STARPU_TAG_ONLY, 298
  STARPU_TASK_COLOR, 299
  STARPU_TASK_DEPS_ARRAY, 299
  STARPU_TASK_END_DEPS_ARRAY, 299
  STARPU_TASK_END_DEP, 299
  STARPU_TASK_Synchronous, 299
  STARPU_TAG, 298
  STARPU_VALUE, 298
  STARPU_WORKER_ORDER, 299
  starpu_codelet_pack_arg, 302
  starpu_codelet_pack_arg_fini, 302
  starpu_codelet_pack_arg_init, 302
  starpu_codelet_pack_args, 301
  starpu_codelet_unpack_args, 302
  starpu_codelet_unpack_args_and_copyleft, 302
  starpu_insert_task, 300
  starpu_task_build, 300
  starpu_task_insert, 300
  starpu_task_insert_data_make_room, 301
  starpu_task_insert_data_process_arg, 301
  starpu_task_insert_data_process_array_arg, 301
  starpu_task_insert_data_process_mode_array_arg, 301
  starpu_task_insert_data_process_mode_array, 301
  starpu_task_set, 300
Task Lists, 377
  starpu_task_list_back, 378
  starpu_task_list_begin, 379
  starpu_task_list_empty, 378
  starpu_task_list_end, 379
  starpu_task_list_erase, 378

Generated by Doxygen
starpu_worker_collection, 210
types_of_workers, 402

unpack_data
starpu_data_interface_ops, 237
unplug
starpu_disk_ops, 271
use_explicit_workers_bindid
starpu_conf, 184
use_explicit_workers_cuda_gpuid
starpu_conf, 184
use_explicit_workers_mic_deviceid
starpu_conf, 184
use_explicit_workers_mpi_ms_deviceid
starpu_conf, 184
use_explicit_workers_opencl_gpuid
starpu_conf, 184
use_tag
starpu_task, 284

Versioning, 181
STARPU_MAJOR_VERSION, 181
STARPU_MINOR_VERSION, 181
STARPU_RELEASE_VERSION, 181
starpu_get_version, 181

wait_request
starpu_disk_ops, 273
where
starpu_codelet, 277
starpu_task, 282
worker_composed_sched_component
starpu_sched_component_specs, 425
workerid
starpu_task, 285
workerids
starpu_task, 286
starpu_worker_collection, 210
workerids_len
starpu_task, 286
workerorder
starpu_task, 285
workers
starpu_sched_component, 422
workers_bindid
starpu_conf, 184
workers_cuda_gpuid
starpu_conf, 184
workers_in_ctxt
starpu_sched_component, 422
workers_mic_deviceid
starpu_conf, 184
workers_mpi_ms_deviceid
starpu_conf, 185
workers_opencl_gpuid
starpu_conf, 184

Workers’ Properties, 207
STARPU_MAXCPUS, 211
STARPU_MAXNUMANODES, 211
STARPU_NMAXWORKERS, 210
starpu_cpu_worker_get_count, 212
starpu_cuda_worker_get_count, 212
starpu_memory_nodes numa_devid_to_id, 214
starpu_memory_nodes numa_id_to_devid, 214
starpu_mem_device_get_count, 212
starpu_mic_worker_get_count, 212
starpu_mpi_ms_worker_get_count, 212
starpu_node_get_kind, 214
starpu_opencl_worker_get_count, 212
starpu_worker_archtype, 211
starpu_worker_collection_type, 211
starpu_worker_display_names, 213
starpu_worker_get_by_devid, 213
starpu_worker_get_by_type, 213
starpu_worker_get_count, 212
starpu_worker_get_count_by_type, 213
starpu_worker_get_devid, 214
starpu_worker_get_hwloc_cpuset, 214
starpu_worker_get_hwloc_obj, 214
starpu_worker_get_id, 212
starpu_worker_get_id_check, 210
starpu_worker_get_ids_by_type, 213
starpu_worker_get_local_memory_node, 214
starpu_worker_get_memory_node, 214
starpu_worker_get_name, 213
starpu_worker_get_relax_state, 215
starpu_worker_get_type, 212
starpu_worker_get_type_as_string, 214
starpu_worker_lock, 215
starpu_worker_lock_self, 216
starpu_worker_relax_off, 215
starpu_worker_relax_on, 215
starpu_worker_sched_op_pending, 215
starpu_worker_set_going_to_sleep_callback, 216
starpu_worker_set_waking_up_callback, 216
starpu_worker_trylock, 215
starpu_worker_unlock, 215
starpu_worker_unlock_self, 216
write
starpu_disk_ops, 272